

# Yanqi Liu

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<b>EDUCATION</b>	<b>UNIVERSITY OF MICHIGAN</b> <b>College of Engineering</b> <ul style="list-style-type: none"><li>• BSE in Computer Engineering 2017, Minor in Business</li><li>• Honors: Engineering Dean's list (Five consecutive terms), James B. Angell Scholar (Two consecutive terms), University Honors (Five consecutive terms)</li><li>• GPA: 3.92/4.00</li></ul>	<b>Ann Arbor, MI</b>
<b>COURSE</b>	Computer Vision (A+), Embedded Control, Introduction to Computer Organization, Programming and Data Structure (A+), Data Structure and Algorithm, Signal Processing	
<b>EXPERIENCE</b>	<b>APRIL Lab</b> <b>Undergraduate Researcher</b> <ul style="list-style-type: none"><li>• Utilize camera installed on robotic car to detect drivable area</li><li>• Devised HSI color detection algorithm with the implementation of illumination invariant to remove shadow interference achieving 90% accuracy</li><li>• Implemented Sobel edge detection method for indoor corridor area detection for up to 97% accuracy</li><li>• Enhanced research skills in data labeling, statistical analysis and paper writing</li></ul>	<b>Ann Arbor, MI</b>
Jun 2015-Present		
Summer 2014	<b>INTERNSHIP- A2B BIKESHARE</b> <b>Electrical Engineer</b> <ul style="list-style-type: none"><li>• Enhanced low-level programming skills through programing for decoding GPS command and communicating with other device using I2C</li><li>• Designed and programmed GPS tracker using cellular module to retain GPS information</li><li>• Learned programming in Arduino, AVR C and circuit board design using EAGLE</li><li>• Exercised engineering skills as well as skills in marketing and selling</li></ul>	<b>Ann Arbor, MI</b>
Fall&Winter 2013	<b>Undergraduate Research Opportunity Program- APRIL Lab</b> <b>Research Assistant</b> <ul style="list-style-type: none"><li>• Developed calibration system with camera and laser pointer to increase calibration accuracy for low-cost robotic building</li><li>• Wrote forward kinematics program using VIS to control a robotic arm</li><li>• Developed inverse kinematics algorithm to control arm gesture to reach object in given position</li><li>• Learned basic image processing technique to detect brightest spot of photo and video stream</li><li>• Built up research skills and teamwork experiences through weekly programing tasks</li></ul>	<b>Ann Arbor, MI</b>
2012-2015	<b>BLUELab-HAGLEY GAP</b> <b>Financial Chair</b> <ul style="list-style-type: none"><li>• Acquired financial experiences and skills of planning team budget, planning for travel for 6 people and applying for university funding for \$4000</li><li>• Traveled to Jamaica in May, 2013, built three Bio-sand filters, taught SODIS lessons in Minto school and Basic school and tested the water quality in the area</li><li>• Enhanced collaborative ability by designing, testing and building with a group of engineers with different engineering backgrounds</li></ul>	<b>Ann Arbor, MI</b>
Jan. 2016-Present	<b>EECS 370 Instructional Aide</b> <ul style="list-style-type: none"><li>• Taught 1-hour discussion and 3-hour office hour every week</li><li>• Designed homework and exams and answered questions online</li></ul>	<b>Ann Arbor, MI</b>
<b>ADDITIONAL</b>	Computer: C++, C, Java, Matlab Professional Organizations: member of IEEE and HKN Language: Fluent in Chinese	