

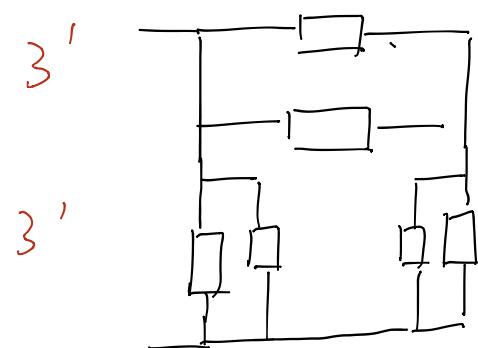
$$i_s = 2 \cos(100\pi t)$$

$$\omega = 1000 \text{ rad.s}^{-1}$$

$$10mH: Z = j\omega L = j10\Omega$$

$$4\mu F: Z = \frac{1}{j\omega C} = -j250\Omega$$

analysis 3'



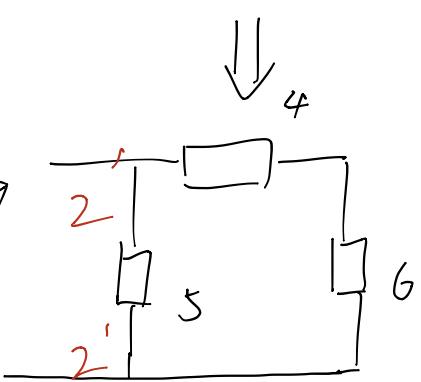
$$(1) Z_1 = \frac{6 \times j10 + 8 \times j10 + 6 \times 8}{j10} = 14 - j\frac{24}{5} \Omega$$

$$Z_2 = \frac{6 \times j10 + 8 \times j10 + 6 \times 8}{8} = 6 + j\frac{35}{2} \Omega$$

$$Z_3 = \frac{6 \times j10 + 8 \times j10 + 6 \times 8}{6} = 8 + j\frac{70}{3} \Omega$$

$$Z_4 = 2\Omega \parallel Z_1 = \frac{2Z_1}{2 + Z_1} = 1.771 - j0.069$$

$$Z_5 = 4\Omega \parallel Z_2 = \frac{4Z_2}{4 + Z_2} = 3.606 + j0.690$$



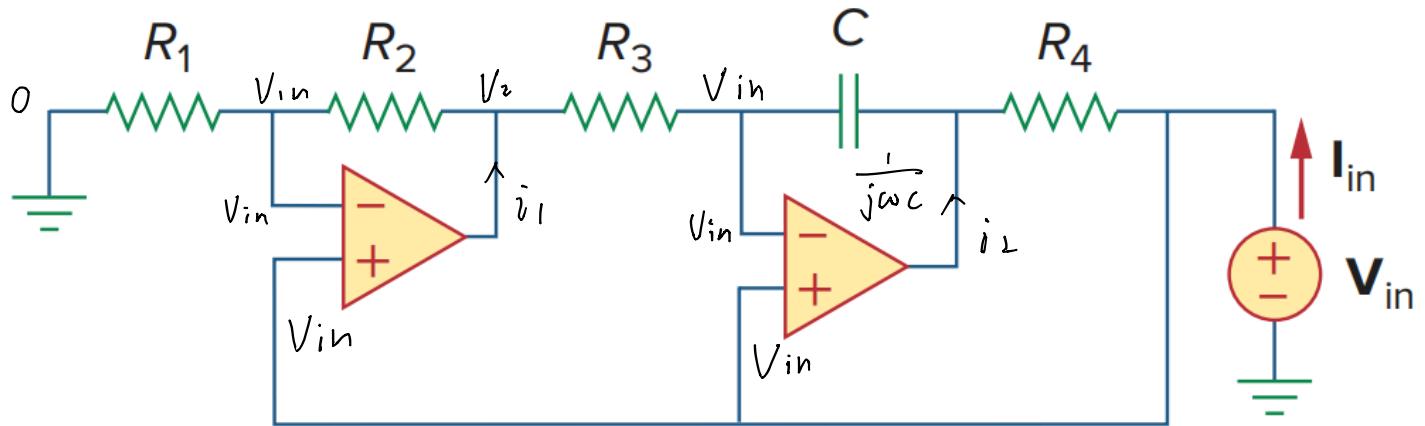
$$Z_6 = -j250\Omega \parallel Z_3 = \frac{-j250 \times Z_3}{-j250 + Z_3} = 9.720 + j25.392 \Omega$$

$$Z = Z_5 \parallel (Z_4 + Z_6) = \frac{Z_5(Z_4 + Z_6)}{Z_5 + Z_4 + Z_6} = 3.254 + j0.967 \Omega = 3.395 \angle 16.55^\circ$$

$$(2) i_2 = i_3 \frac{Y_2}{Y_1 + Y_2} = i_3 \frac{\frac{1}{Z_4 + Z_6}}{\frac{1}{Z_5} + \frac{1}{Z_4 + Z_6}} = 0.160 - j0.184 A$$

$$V_o = Z_6 i_2 = 6.638 \angle 20.015^\circ V$$

3'



$$V_{in} = V \cos \omega t$$

$$\underline{I_{in} + i_2} = \frac{(V_{in} - I_{in} R_4) - V_{in}}{\frac{1}{j\omega C}} \Rightarrow (I_{in} + i_2) Z = - I_{in} R_4$$

4'

$$\underline{i_1} + \frac{V_{in} - V_2}{R_1} = \frac{V_2 - V_{in}}{R_2} \leftarrow \text{no necessary}$$

4'

$$\frac{V_2 - V_{in}}{R_2} = \frac{V_{in}}{R_1} \Rightarrow V_2 = \left(1 + \frac{R_2}{R_1}\right) V_{in}$$

$$\frac{V_{in} - V_2}{R_3} = I_{in} + i_2 \Rightarrow V_{in} - V_2 = (I_{in} + i_2) R_3 \Rightarrow V_2 = V_{in} - (I_{in} + i_2) R_3$$

4'

$$\text{So } \left(1 + \frac{R_2}{R_1}\right) V_{in} = V_{in} - (I_{in} + i_2) R_3$$

$$\frac{R_2}{R_1 R_3} V_{in} = - I_{in} - i_2 \Rightarrow i_2 = - I_{in} - \frac{R_2}{R_1 R_3} V_{in}$$

$$\text{So } - \frac{R_2 Z}{R_1 R_3} V_{in} = - I_{in} R_4$$

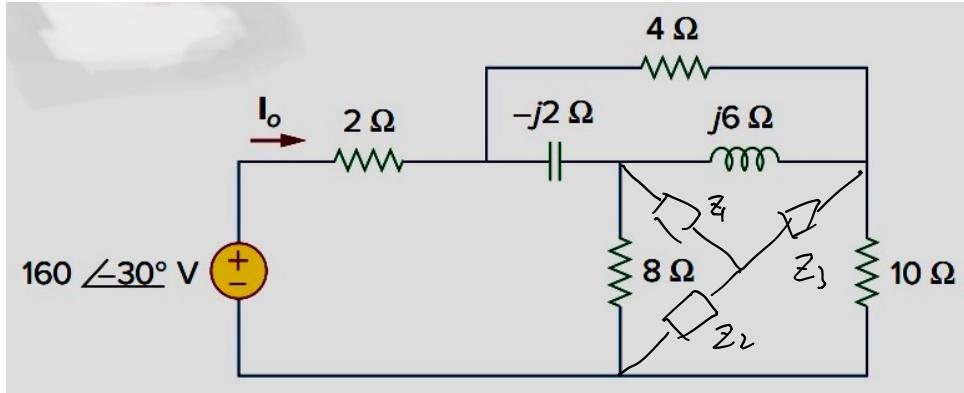
$$Z_{in} = \frac{V_{in}}{I_{in}} = \frac{R_1 R_3 R_4}{R_2 Z} = \frac{R_1 R_3 R_4}{R_2 \frac{1}{j\omega C}} = j\omega \underline{\frac{R_1 R_3 R_4 C}{R_2}}$$

process

10'

3'

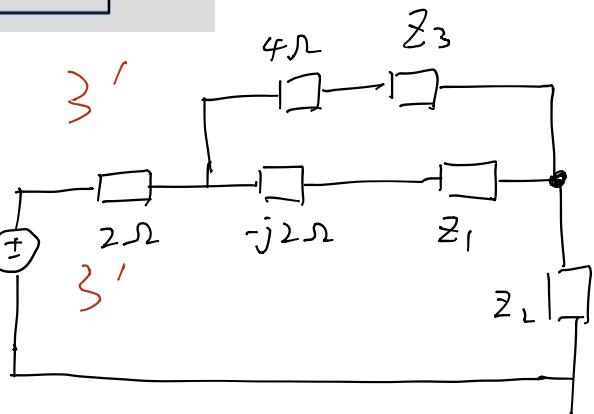
9.53



analysis 7'

$$Z_1 = \frac{8 \times j6}{8 + j6 + 10} = 2.530 \angle 71.565^\circ \quad 3'$$

$$Z_2 = \frac{10 \times 8}{8 + j6 + 10} = 4.216 \angle -18.435^\circ \quad 3'$$



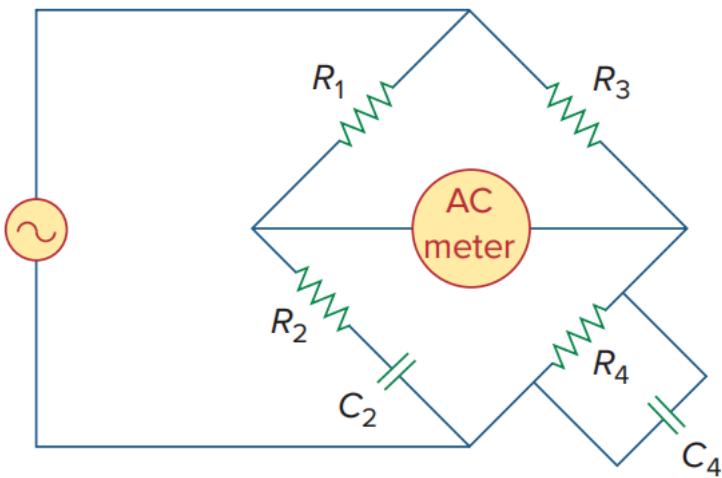
$$Z_3 = \frac{j6 \times 10}{8 + j6 + 10} = 3.162 \angle 71.565^\circ \quad 3'$$

$$Z_4 = \frac{(4 + Z_3) \times (-j2 + Z_1)}{4 + Z_3 + (-j2 + Z_1)} = 0.776 \angle 27.156^\circ \quad 3'$$

$$Z = 2 + Z_4 + Z_2 = 6.761 \angle -8.326^\circ \quad 3'$$

$$I_o = \frac{V}{Z} = 23.664 \angle -21.674^\circ \text{ A} \quad 3'$$

21.99 - j8.74



Assume  $V = V_0 \cos \omega t$ .

$$\text{balance} \Rightarrow \frac{R_2 + C_2}{R_4 \parallel C_4} = k \quad 5'$$

$$R_2 + C_2 = R_2 + \frac{1}{j\omega C_2} \quad 3$$

$$R_4 \parallel C_4 = \frac{R_4 \times \frac{1}{j\omega C_4}}{R_4 + \frac{1}{j\omega C_4}} = \frac{R_4}{j\omega R_4 C_4 + 1} \quad 3'$$

$$\frac{R_2 + \frac{1}{j\omega C_2}}{\frac{R_4}{j\omega R_4 C_4 + 1}} = \frac{(R_2 + \frac{1}{j\omega C_2})(j\omega R_4 C_4 + 1)}{R_4} \quad 3'$$

$$j \text{ part: } j\omega R_2 R_4 C_2 C_4 + \frac{1}{j\omega C_2} = 0 \quad 5'$$

$$\omega^2 R_2 R_4 C_2 C_4 = 1 \quad 3'$$

$$\omega = \frac{1}{\sqrt{R_2 R_4 C_2 C_4}} \quad 3' \quad f = \frac{\omega}{2\pi} = \frac{1}{2\pi \sqrt{R_2 R_4 C_2 C_4}} \quad 3'$$