

含时微扰论 (Time-Dependent Perturbation Theory)

$$|\Psi(t)\rangle = \hat{U}(t, t_0) |\Psi(t_0)\rangle$$

$$i\hbar \frac{\partial \hat{U}(t, t_0)}{\partial t} = \hat{H} \hat{U}(t, t_0)$$

H不显含t

$$\hat{U}(t, t_0) = e^{-\frac{i}{\hbar} \hat{H}(t-t_0)}$$

H显含t

$$\hat{U}(t, t_0) = \mathbf{1} - \frac{i}{\hbar} \int_{t_0}^t dt' \hat{H}(t') \hat{U}(t', t_0)$$

角度一：迭代形式

$$\begin{aligned} \hat{U}(t, t_0) &= \lim_{N \rightarrow \infty} e^{-\frac{i}{\hbar} \hat{H}(t) \frac{t-t_0}{N}} e^{-\frac{i}{\hbar} \hat{H}(t_{N-1}) \frac{t-t_0}{N}} \dots e^{-\frac{i}{\hbar} \hat{H}(t_0) \frac{t-t_0}{N}} \\ &= \lim_{N \rightarrow \infty} e^{-\frac{i}{\hbar} [\hat{H}(t) + \hat{H}(t_{N-1}) + \dots + \hat{H}(t_0)] \frac{t-t_0}{N}} \\ &= \mathcal{T} e^{-\frac{i}{\hbar} \int_{t_0}^t \hat{H}(t') dt'} \end{aligned}$$

角度二

\mathcal{T} 是编时算符⁺ 作用是被积算符微元对应的指数项按时间顺序排列

相互作用绘景

不含时H0给出U0表达式如上所示

$$\hat{H}(t) = \hat{H}_0 + \hat{V}(t)$$

$$\hat{U}(t, t_0) = \hat{U}_0(t, t_0) \hat{U}_I(t, t_0)$$

$$\langle \Psi(t) | \hat{O} | \Psi(t) \rangle = \langle \Psi(t_0) | \hat{U}_I^\dagger(t, t_0) \hat{U}_0^\dagger(t, t_0) \hat{O} \hat{U}_0(t, t_0) \hat{U}_I(t, t_0) | \Psi(t_0) \rangle$$

$$\begin{aligned} \hat{O}_I(t) &= \hat{U}_0^\dagger(t, t_0) \hat{O} \hat{U}_0(t, t_0) \\ |\Psi_I(t)\rangle &= \hat{U}_I(t, t_0) |\Psi(t_0)\rangle \end{aligned}$$

含时微扰论

到这里你可能会有疑问，因为我们知道 $\hat{U}_0(t, t_0)$ 的形式，所以相互作用绘景下的算符 \hat{O}_I 我们可以直接写出来。但 $\hat{U}_I(t, t_0)$ 该怎么确认呢？现在回忆一下前面 (4) 式

$i\hbar \frac{\partial \hat{U}(t, t_0)}{\partial t} = \hat{H} \hat{U}(t, t_0)$ ，现在我们把相互作用绘景下的时间演化算符代入并计算

$$i\hbar \frac{\partial \hat{U}_I(t, t_0)}{\partial t} = \hat{V}_I(t) \hat{U}_I(t, t_0)$$

$$\hat{V}_I(t) = \hat{U}_0^\dagger(t, t_0) \hat{V}(t) \hat{U}_0(t, t_0)$$

$$\hat{U}_I(t, t_0) = \mathbf{1} - \frac{i}{\hbar} \int_{t_0}^t dt' \hat{V}_I(t') \hat{U}_I(t', t_0)$$

展开到一阶 (V1很小时)

$$\hat{U}_I \approx \mathbf{1} + \frac{1}{i\hbar} \int_{t_0}^t \hat{V}_I(t_1) dt_1$$

将这个式子反复迭代，得到戴森级数

$$\hat{U}_I = \sum_{n=0}^{\infty} \left(\frac{1}{i\hbar} \right)^n \int_{t_0}^t dt_1 \int_{t_0}^{t_1} dt_2 \dots \int_{t_0}^{t_{n-1}} dt_n \hat{V}_I(t_1) \hat{V}_I(t_2) \dots \hat{V}_I(t_n)$$

经过时间演化后系统向各个态跃迁的概率

$$P_{n \leftarrow m} = \left| \langle \psi_n^0 | \hat{U}(t, t_0) | \psi_m^0 \rangle \right|^2$$

$$\begin{aligned} \langle \psi_n^0 | \hat{U}(t, t_0) | \psi_m^0 \rangle &= \langle \psi_n^0 | \hat{U}_0(t, t_0) \hat{U}_I(t, t_0) | \psi_m^0 \rangle \\ &= e^{-\frac{i}{\hbar} \hat{H}_0(t-t_0)} \langle \psi_n^0 | \hat{U}_I(t, t_0) | \psi_m^0 \rangle \end{aligned}$$

$$\begin{aligned} \langle \psi_n^0 | \hat{U}_I(t, t_0) | \psi_m^0 \rangle &= \delta_{mn} + \frac{1}{i\hbar} \int_{t_0}^t dt_1 \langle \psi_n^0 | \hat{U}_0^\dagger(t_1, t_0) \hat{V}(t_1) \hat{U}_0(t_1, t_0) | \psi_m^0 \rangle \\ &= \delta_{mn} + \frac{1}{i\hbar} \int_{t_0}^t dt_1 \langle \psi_n^0 | \hat{V}(t_1) | \psi_m^0 \rangle e^{-\frac{i}{\hbar} (E_m^0 - E_n^0)(t_1 - t_0)} \end{aligned}$$

$$P_{n \leftarrow m} = \left(\frac{1}{\hbar} \right)^2 \left| \int_{t_0}^t \langle \psi_n^0 | \hat{V}(t_1) | \psi_m^0 \rangle e^{-\frac{i}{\hbar} (E_m^0 - E_n^0)(t_1 - t_0)} dt_1 \right|^2$$

绝热近似 (Adiabatic Approximation)

缓慢变化的系统

$$\hat{H} = \hat{H}_0 + \hat{V}[\vec{\lambda}(t)]$$

慢变微扰 \hat{V}

$$\vec{\lambda}(t) \equiv [\lambda_1(t), \lambda_2(t), \dots, \lambda_n(t)]$$

$$\lambda_1(t) = B_x(t), \lambda_2(t) = E_z(t), \dots$$

$$\hat{H}(\lambda) |\psi_n(\lambda)\rangle = E_n(\lambda) |\psi_n(\lambda)\rangle$$

瞬时本征方程

酉变换

$$|\Psi(t)\rangle = \hat{U}(t) |\psi(t)\rangle$$

$$i\hbar \frac{\partial [\hat{U}(t) |\psi(t)\rangle]}{\partial t} = \hat{H}[\vec{\lambda}(t)] \hat{U}(t) |\psi(t)\rangle$$

$$\hat{H}_{eff} = \hat{U}^\dagger(t) \hat{H}[\vec{\lambda}(t)] \hat{U}(t) - i\hbar \hat{U}^\dagger(t) \frac{\partial \hat{U}(t)}{\partial t}$$

$$i\hbar \frac{\partial |\psi(t)\rangle}{\partial t} = \hat{H}_{eff} |\psi(t)\rangle$$

应用一: $\hat{U}(t)=\hat{U}(t, t_0)$ 为时间演化算子, 则变换后的态给出Heisenberg绘景下的态

应用二: $\hat{U}(t)=\hat{U}(t, t_0)$ 给出相互作用绘景

$$\begin{aligned} \hat{H}_{eff}(t) &= \hat{U}_0^\dagger(t, t_0) \hat{H}[\vec{\lambda}(t)] \hat{U}_0(t, t_0) - i\hbar \hat{U}_0^\dagger(t, t_0) \frac{\partial \hat{U}_0(t, t_0)}{\partial t} \\ &= \hat{U}_0^\dagger(t, t_0) \hat{H}[\vec{\lambda}(t)] \hat{U}_0(t, t_0) - \hat{U}_0^\dagger(t, t_0) \hat{H}_0 \hat{U}_0(t, t_0) \\ &= \hat{U}_0^\dagger(t, t_0) [\hat{H}[\vec{\lambda}(t)] - \hat{H}_0] \hat{U}_0(t, t_0) \\ &= \hat{U}_0^\dagger(t, t_0) \hat{V}[\vec{\lambda}(t)] \hat{U}_0(t, t_0) \\ &= \hat{V}_I[\vec{\lambda}(t)] \end{aligned}$$

绝热微扰

考虑酉变换 $\hat{U}(t) = \sum_n |\psi_n[\vec{\lambda}(t)]\rangle \langle \psi_n[\vec{\lambda}(0)]|$ (H不显含t时退化为 $\hat{U}(t, t_0)$)

$$i\hbar \frac{\partial |\psi(t)\rangle}{\partial t} = \sum_n E_n[\vec{\lambda}(t)] |\psi(t)\rangle - i\hbar \sum_{m,n} |\psi_n[\vec{\lambda}(0)]\rangle \langle \psi_m[\vec{\lambda}(0)]| \langle \psi_n[\vec{\lambda}(t)] | \frac{d\psi_m[\vec{\lambda}(t)]}{dt} \rangle |\psi(t)\rangle$$

用初始时刻m本征态左作用

$$i\hbar \frac{dD_m}{dt} = E_m[\vec{\lambda}(t)] D_m - i\hbar \sum_n \langle \psi_m[\vec{\lambda}(t)] | \frac{d\psi_n[\vec{\lambda}(t)]}{dt} \rangle D_n \quad D_n(t) = \langle \psi_n[\vec{\lambda}(0)] | \psi(t) \rangle$$

$$\frac{dy}{dx} + P(x)y = Q(x)$$

$$D_n = C_n e^{i\theta_n}$$

常数变易法, $C_n = C_n(t)$

$$\theta_n(t) = -\frac{1}{\hbar} \int_0^t E_n[\vec{\lambda}(t')] dt'$$

动力学项
瞬时本征
能量积累
的结果

$$\dot{C}_m = - \sum_n C_n \langle \psi_m[\vec{\lambda}(t)] | \frac{d\psi_n[\vec{\lambda}(t)]}{dt} \rangle e^{i(\theta_n - \theta_m)}$$

$$\int_0^T \dot{C}_m dt = \int_0^T -C_m \langle \psi_m[\vec{\lambda}(t)] | \frac{d\psi_m[\vec{\lambda}(t)]}{dt} \rangle dt - \int_0^T \sum_{n \neq m} C_n \langle \psi_m[\vec{\lambda}(t)] | \frac{d\psi_n[\vec{\lambda}(t)]}{dt} \rangle e^{i(\theta_n - \theta_m)} dt$$

从这里开始有近似, 注意到等式右边第二项可化为

$$\langle \psi_m[\vec{\lambda}(t)] | \frac{d\psi_n[\vec{\lambda}(t)]}{dt} \rangle = \frac{\langle \psi_m[\vec{\lambda}(t)] | \frac{d\hat{H}[\vec{\lambda}(t)]}{dt} | \psi_n[\vec{\lambda}(t)] \rangle}{E_n - E_m}$$

由于是慢变系统, dH/dt 很小, 且存在指数振荡, 因此较大时间尺度下这一项可忽略, 即

$$\dot{C}_m \approx -C_m \langle \psi_m[\vec{\lambda}(t)] | \frac{d\psi_m[\vec{\lambda}(t)]}{dt} \rangle$$

$$C_m(t) = C_m(0) e^{i\gamma_m}$$

$$\gamma_m(t) = i \int_0^t \langle \psi_m[\vec{\lambda}(t')] | \frac{d\psi_m[\vec{\lambda}(t')]}{dt'} \rangle dt'$$

几何项

几何相位实际上是由量子绝热过程在参数空间里的路径决定的, 和这个系统变化的多快多慢没什么关系, 所以叫几何相。

$$\begin{aligned} \gamma_m(t) &= i \int_0^t \langle \psi_m[\vec{\lambda}(t')] | \sum_i \frac{\partial \psi_m[\vec{\lambda}(t')]}{\partial \lambda_i} \rangle \frac{d\lambda_i}{dt'} dt' \\ &= i \int_{\lambda(0)}^{\lambda(t)} \langle \psi_m[\vec{\lambda}(t')] | \sum_i \frac{\partial \psi_m[\vec{\lambda}(t')]}{\partial \lambda_i} \rangle d\lambda_i \end{aligned}$$

假定一开始系统处在初始时刻的第m个瞬时本征态上

$$|\Psi(0)\rangle = |\psi_m[\vec{\lambda}(0)]\rangle$$

$$C_n(0) = \delta_{mn}$$

$$\begin{aligned} |\Psi(t)\rangle &= \delta_{mn} e^{i\theta_n(t)} e^{i\gamma_n(t)} \sum_m |\psi_m[\vec{\lambda}(t)]\rangle \\ &= e^{i\theta_m(t)} e^{i\gamma_m(t)} |\psi_m[\vec{\lambda}(t)]\rangle \end{aligned}$$

系统在t时刻的第m个瞬时本征态上! 只不过前面叠加了一个相位因子, 总的相位变化是动力学相和几何相的叠加。

这就是绝热近似的内容, 对于一个缓慢变化的系统, 如果初始时刻系统处在第m个本征态, 那么在经过一段时间后系统还是处在第m个本征态。

费曼路径积分表述 (Feynman Path Integral Formulation)

作用量

$$S = \int dt L$$

Feynman-Dirac解释

$$\phi[x(t)] = C e^{\frac{i}{\hbar} S[x(t)]}$$

在量子力学中，粒子从 (a, t_a) 运动到 (b, t_b) 有无穷多可能的轨迹，这些轨迹弥漫整个空间，每个轨迹都有一定的概率。如果粒子沿着每一条轨迹运动的概率幅为：

Feynman路径积分

$$K(b, a) = \int \mathcal{D}x(t) e^{\frac{i}{\hbar} S(b, a)}$$

$$\langle x_N, t_N | x_1, t_1 \rangle = \int_{x_1}^{x_N} \mathcal{D}[x(t)] \exp \left[i \int_{t_1}^{t_N} dt \frac{L(x, \dot{x})}{\hbar} \right]$$

传播子

$$K(\mathbf{x}'', t; \mathbf{x}', t_0) = \sum_{\mathbf{a}'} \langle \mathbf{x}'' | \mathbf{a}' \rangle \langle \mathbf{a}' | \mathbf{x}' \rangle \exp \left[\frac{-i E_{\mathbf{a}'} (t - t_0)}{\hbar} \right]$$

$$K(\mathbf{x}'', t; \mathbf{x}', t_0) = \langle \mathbf{x}'' | \exp \left[\frac{-i H (t - t_0)}{\hbar} \right] | \mathbf{x}' \rangle = \langle \mathbf{x}'', t | \mathbf{x}', t_0 \rangle$$

跃迁振幅

从 (a, t_a) 移动到 (b, t_b) 的概率幅

$$P_{b \leftarrow a} = |K(b, a)|^2$$

系起来。但首先回忆一下，波函数作为固定的位置左矢 $\langle \mathbf{x}' |$ 与运动的态右矢 $|\mathbf{a}, t_0; t\rangle$ 的内积，还可以看作是随时间“相反”运动的海森伯绘景的位置左矢 $\langle \mathbf{x}', t |$ 与海森伯绘景中时间固定的态右矢 $|\mathbf{a}, t_0\rangle$ 的内积。同样地，传播子也可以写为

值 \mathbf{x}' 的粒子将在稍后的 t 时刻在 \mathbf{x}'' 处被发现的概率振幅。粗略地讲， $\langle \mathbf{x}'', t | \mathbf{x}', t_0 \rangle$ 是粒子从时空点 (\mathbf{x}', t_0) 到另一个时空点 (\mathbf{x}'', t) 的振幅，因此，术语跃迁振幅对于这个表示式是

积分算子 $\mathcal{D}[x(t)]$ 给出该积分的测度（事实上是给出了该积分具体的形式）：

$$\int_{x_1}^{x_N} \mathcal{D}[x(t)] \equiv \lim_{N \rightarrow \infty} \left(\frac{m}{2\pi i \hbar \Delta t} \right)^{(N-1)/2} \int dx_{N-1} \int dx_{N-2} \cdots \int dx_2$$

路径积分表述与Schrodinger方程给出等价的时间演化：

$$\psi(x_2, t_2) = \int dx_1 K(x_2, t_2; x_1, t_1) \psi(x_1, t_1)$$

$$\psi(x_2, t + \epsilon) = \int d\eta \frac{1}{A} e^{\frac{im\eta^2}{2\hbar\epsilon}} e^{-\frac{i}{\hbar}\epsilon V(x_2 + \frac{\eta}{2}, t)} \psi(x_2 + \eta, t)$$

小时间变化，换元 $x_1 = x_2 + \eta$

$$\begin{aligned} \psi(x_2, t) + \epsilon \frac{\partial \psi(x_2, t)}{\partial t} &= \frac{[1 - \frac{i\epsilon}{\hbar} V(x_2, t)] \psi(x_2, t)}{A} \int d\eta e^{\frac{im\eta^2}{2\hbar\epsilon}} \\ &+ \frac{[1 - \frac{i\epsilon}{\hbar} V(x_2, t)]}{A} \frac{\partial \psi(x_2, t)}{\partial x_2} \int d\eta e^{\frac{im\eta^2}{2\hbar\epsilon}} \eta \\ &+ \frac{[1 - \frac{i\epsilon}{\hbar} V(x_2, t)]}{A} \frac{\partial^2 \psi(x_2, t)}{\partial x_2^2} \int d\eta e^{\frac{im\eta^2}{2\hbar\epsilon}} \frac{\eta^2}{2} \end{aligned}$$

$$A = \sqrt{\frac{2\pi i \hbar \epsilon}{m}}$$

$$\int d\eta e^{\frac{im\eta^2}{2\hbar\epsilon}} \eta = 0$$

$$\int d\eta e^{\frac{im\eta^2}{2\hbar\epsilon}} \frac{\eta^2}{2} = \frac{i\hbar\epsilon}{2m}$$



$$i\hbar \frac{\partial \psi(x, t)}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi(x, t)}{\partial x^2} + V(x, t) \psi(x, t)$$

实际上路径积分中的传播子就是坐标表象下的时间演化算符

$$\frac{\partial K(x_2, t_2; x_1, t_1)}{\partial t_2} = -\frac{\hbar^2}{2m} \frac{\partial^2 K(x_2, t_2; x_1, t_1)}{\partial x_2^2} + V(x_2, t_2) K(x_2, t_2; x_1, t_1)$$