Lecture 6

Optimal Estimation Theory and Its Applications

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Outline

- Bayesian estimate
- Minimum Mean Square Error estimate

Example3.4:

Further Consideration

If Fish 1 is sorted as Fish 2, the faced quality problem is "sell seconds at best quality prices". It is much severe with the cost being C1.

If Fish 2 is sorted as Fish 1, the faced problem is economic loss with the cost being C2.

In general, C1>C2

Requirement

Please design a fish sorting system to minimize the total sorting cost.

Suppose $Z = Z_{BE}$ is the classification threshold, i.e.,

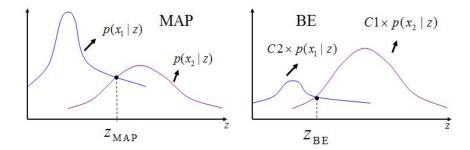
If $z < Z_{\rm BE}$, then Fish 1;Fish 2 otherwise.

The total cost is

$$F(Z_{\text{BE}}) = \int_{\mathbf{z} \ge Z_{\text{BE}}} C2 \times p(x_1|z)p(z)dz + \int_{\mathbf{z} < Z_{\text{BE}}} C1 \times p(x_2|z)p(z)dz$$

To minimize the total cost, Z_{BE} should satisfy

$$C2 \times p(X = x_1|z = Z_{BE}) = C1 \times p(X = x_2|z = Z_{BE})$$



 $Z_{\rm BE}{<}Z_{\rm MAP}$ means that the proposed estimate more prefers to Fish 1, compared with the MAP estimate.

Consider the vector to be estimated X, its measurement Z, the estimate $\hat{X}(Z)$ and the estimate error $\tilde{X}=X-\hat{X}(Z)$

Construct a scalar function!

$$L(\tilde{X}) = L\left[X - \hat{X}(Z)\right] \ge 0$$

L is called as the loss function, and its expectation

$$B(\tilde{X}) = E[L(\tilde{X})] = \iint L[x - \hat{X}(z)]p(x, z)dxdz$$

is called as the Bayesian risk. The Bayesian estimate aims at minimizing the Bayesian risk.

$$L = \left\{ \begin{array}{ll} C2 & \text{if} & z>Z_{BE} \\ C1 & \text{otherwise} \end{array} \right. \text{ in the fish sorting example considered the cost}$$

If X belongs to the \mathbb{R}^n space, the Bayesian cost is always defined satisfying

$$\begin{cases} 1.L(X) = 0, & \text{if} \quad X = 0\\ 2.L(X_2) \ge L(X_1), & \text{if} \quad \|X_2\| \ge \|X_1\|\\ 3.L(X) = L(-X) \end{cases}$$

L is a convex function L(X) is nonnegative.

If $L\left(\tilde{X}\right)=\tilde{X}^T\tilde{X}=\left(X-\hat{X}\right)^T\left(X-\hat{X}\right)$, the Bayesian estimate is the minimum-mean-square- error estimate.

lf

$$L\left[X - \hat{X}(Z)\right] = \begin{cases} 0 & \text{if } \left\|X - \hat{X}(Z)\right\| < \frac{\varepsilon}{2} \\ \frac{1}{\varepsilon} & \text{if } \left\|X - \hat{X}(Z)\right\| \ge \frac{\varepsilon}{2} \end{cases}$$

then we have the following Bayesian risk.

$$\begin{split} B\left(\tilde{X}\right) &= E\left\{L\left[X - \hat{X}\left(Z\right)\right]\right\} = \int_{-\infty}^{+\infty} \int\limits_{\left\|X - \hat{X}\right\| \geq \frac{\varepsilon}{2}} \frac{1}{\varepsilon} p\left(x|z\right) dx p\left(z\right) dz \\ &= \int_{-\infty}^{+\infty} \frac{1}{\varepsilon} \left[1 - \int\limits_{\left\|X - \hat{X}\right\| < \frac{\varepsilon}{2}} p\left(x|z\right) dx\right] p\left(z\right) dz \end{split}$$

$$\int\limits_{\|X\|\geq\frac{\varepsilon}{2}}p\left(x|z\right)dx+\int\limits_{\|X\|<\frac{\varepsilon}{2}}p\left(x|z\right)dx=1$$

suppose $\hat{X}_{B}\left(Z\right)$ is the Bayesian estimate, i.e.,

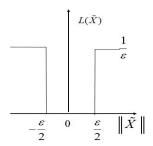
$$\hat{X}_B(Z) = \arg\min_{\hat{X}} B(\hat{X})$$

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$$\Leftrightarrow C_B(Z) = \arg\max_{\hat{X}} \int_{\|X - \hat{X}\| < \frac{\varepsilon}{2}} \frac{1}{\varepsilon} p(x|z) dx$$

As ε approaches zero, we have

$$\hat{X}_B(Z) = \arg \max_{x} p(x|z) \qquad \leftarrow \mathsf{MAP} \text{ estimate}$$



Sometimes also called as Minimum Variance estimation

The estimate is the optimal in the sense for any a function of the measurement $Z, \hat{X}(Z)$, the following inequality holds

$$E\left\{\left[X - \hat{X}_{\mathrm{MMSE}}(Z)\right]^{T} \left[X - \hat{X}_{\mathrm{MMSE}}(Z)\right]\right\} \leq E\left\{\left[X - \hat{X}(Z)\right]^{T} \left[X - \hat{X}(Z)\right]\right\}$$

or the following matrix inequality holds

$$E\left\{\left[X - \hat{X}_{\text{MV}}(Z)\right]\left[X - \hat{X}_{\text{MV}}(Z)\right]^{T}\right\} \leq E\left\{\left[X - \hat{X}(Z)\right]\left[X - \hat{X}(Z)\right]^{T}\right\}$$

On one hand, we have

$$\begin{split} &E\left\{\left[X-\hat{X}_{\mathrm{MV}}(Z)\right]\left[X-\hat{X}_{\mathrm{MV}}(Z)\right]^{T}\right\} \leq E\left\{\left[X-\hat{X}(Z)\right]\left[X-\hat{X}(Z)\right]^{T}\right\} \\ &\Rightarrow \operatorname{trace}\left\{E\left\{\left[X-\hat{X}_{\mathrm{MV}}(Z)\right]\left[X-\hat{X}_{\mathrm{MV}}(Z)\right]^{T}\right\}\right\} \leq \operatorname{trace}\left\{E\left\{\left[X-\hat{X}(Z)\right]\left[X-\hat{X}(Z)\right]^{T}\right\}\right\} \\ &\Rightarrow \operatorname{trace}\left\{E\left\{\left[X-\hat{X}_{\mathrm{MV}}(Z)\right]^{T}\left[X-\hat{X}_{\mathrm{MV}}(Z)\right]\right\}\right\} \leq \operatorname{trace}\left\{E\left\{\left[X-\hat{X}(Z)\right]^{T}\left[X-\hat{X}(Z)\right]\right\}\right\} \\ &\Rightarrow E\left\{\left[X-\hat{X}_{\mathrm{MV}}(Z)\right]^{T}\left[X-\hat{X}_{\mathrm{MV}}(Z)\right]\right\} \leq E\left\{\left[X-\hat{X}(Z)\right]^{T}\left[X-\hat{X}(Z)\right]\right\} \end{split}$$

Conclusion: the MV estimate is the MMSE estimate.

trace{AB}=trace{BA}

On the other hand, we have For any a estimate $\hat{X}(Z)$, its covariance matrix is

$$E(\tilde{X}\tilde{X}^T) = E\left[(X - \hat{X})(X - \hat{X})^T \right]$$

$$= \iint (x - \hat{X})(x - \hat{X})^T p(x, z) dx dz$$

$$\hat{X}(z) \text{ is the function of } z, \text{ instead of } x.$$

$$= \int_{-\infty}^{+\infty} p(z) \int_{-\infty}^{+\infty} \left[x - E(x|z) + \underline{E(x|z) - \hat{X}} \right] \times \left[x - E(x|z) + \underline{E(x|z) - \hat{X}} \right]^T p(x|z) dx dz$$

Notice
$$\int_{-\infty}^{+\infty} \frac{\left[E(x|Z) - \hat{X}\right]}{\left[E(x|Z) - \hat{X}\right]} \left[x - E(x|Z)\right]^T p(x|z) dx = 0$$
 $\int_{-\infty}^{+\infty} p(x|z) dz = 1$

$$\begin{split} &= \int_{-\infty}^{+\infty} \left\{ \operatorname{var}(x|z) + \left[E(x|z) - \hat{X} \right] \left[E(x|z) - \hat{X} \right]^T \right\} p(z) dz \\ &\geq \int_{-\infty}^{+\infty} \left\{ \operatorname{var}(x|z) \right\} p(z) dz = var(\hat{X}_{\text{MMSE}}) \end{split}$$

For any a estimate \hat{X} , we have $var(\hat{X}_{\text{MMSE}}) \leq var(\hat{X})$.

Conclusion: the MMSE estimate is the MV estimate.

according to definition

$$E\left\{ \left[X - \hat{X} \right]^T \left[X - \hat{X} \right] \right\}$$

$$= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \left[x - \hat{X} \right]^T \left[x - \hat{X} \right] p(x, z) dx dz$$

$$= \int_{-\infty}^{+\infty} p(z) \left\{ \int_{-\infty}^{+\infty} \left[x - \hat{X}(z) \right]^T \left[x - \hat{X}(z) \right] p(x|z) dx \right\} dz$$

 $p(z) \geq 0$. The MMSE estimate requires that for each Z = z, g(z) should be minimized.

$$\begin{aligned} & \frac{\partial g(\hat{X})}{\partial \hat{X}} \Big|_{\hat{X} = \hat{X}_{\text{MMSE}}} = 0 \\ &= -2 \int_{-\infty}^{+\infty} \left[x - \hat{X}(Z) \right] p(x|z) dx \Big|_{\hat{X} = \hat{X}_{\text{MMSE}}} = 0 \\ &\Rightarrow \hat{X}_{\text{MMSE}} = \int_{-\infty}^{+\infty} x p(x|z) dx = E(X|Z) \end{aligned}$$

The MMSE estimate is also called the conditional expectation.

Question: is the MMSE estimate is linear estimate?

Performance Analysis

(1) Unbiased analysis

$$E\left[\hat{X}_{MS}\right] = E\left[E(X|Z)\right]$$

$$= \int_{-\infty}^{+\infty} \left[\int_{-\infty}^{+\infty} x p(x|z) dx \right] p(z) dz$$

$$= \int_{-\infty}^{+\infty} x \left[\int_{-\infty}^{+\infty} p(x,z) dz \right] dx$$

$$= \int_{-\infty}^{+\infty} x p(x) dx = E(X)$$

Performance Analysis

(2) Covariance analysis

$$\begin{aligned} & \operatorname{var}(\hat{X}_{\operatorname{MMSE}}) = E(\tilde{X}_{\operatorname{MMSE}} \tilde{X}_{\operatorname{MMSE}}^T) \\ &= \iint \left[x - \hat{X}_{\operatorname{MMSE}} \right] \left[x - \hat{X}_{\operatorname{MMSE}} \right]^T p(x, z) dx dz \\ &= \int_{-\infty}^{+\infty} \left\{ \int_{-\infty}^{+\infty} \left[x - E(x \mid z) \right] \left[x - E(x \mid z) \right]^T p(x \mid z) dx \right\} p(z) dz \\ &= \int_{-\infty}^{+\infty} \overline{\operatorname{var}(x \mid z) p(z) dz} \end{aligned}$$

Consider the case that the measurement is not available, but the a priori statistics about X is known. How to choose a constant as the MMSE?

$$J=E\left\{\left(X-\hat{X}\right)^{T}\left(X-\hat{X}\right)\right\} = E\left\{X^{T}X\right\} - \hat{X}^{T}EX - (EX)^{T}\hat{X} + E\left\{\hat{X}^{T}\hat{X}\right\}$$

$$= E\left\{X^{T}X\right\} - 2\hat{X}^{T}EX + E\left\{\hat{X}^{T}\hat{X}\right\}$$

$$\frac{\partial J}{\partial \hat{X}} = -2EX - 2\hat{X} \Rightarrow \hat{X}_{MS} = EX$$

$$\hat{X}^{T}EX = E\left(X\hat{X}\right)^{T}$$

And they are scalar and thus equal each other.

Conclusion: without the measurement, the mean of X is its MMSE estimate.

Example3.5: Let unknown X be distributed uniformly according to

$$f_X(x) = \begin{cases} 1, & 0 \le x \le 1\\ 0, & otherwise \end{cases}$$

Suppose a Z is measured, which is related to X by

$$Z = \ln\left(\frac{1}{X}\right) + V$$

where V is noise with exponential distribution

$$f_V(v) = \begin{cases} e^{-v}, & v \ge 0\\ 0, & v < 0 \end{cases}$$

and X and V are independent. Find the MS estimate.

Solution

$$f_{Z|X}(z|x) = f_V(z - \ln(\frac{1}{x}))$$

$$= \begin{cases} e^{-(z - \ln(1/x))} & z - \ln(\frac{1}{x}) \ge 0 \\ 0, & z - \ln(\frac{1}{x}) < 0 \end{cases} = \begin{cases} \frac{1}{x}e^{-z} & x \ge e^{-z} \\ 0, & x < e^{-z} \end{cases}$$

$$\hat{X}_{MS} = \frac{\int_{e^{-z}}^{1} e^{-z} dx}{\int_{e^{-z}}^{1} \frac{1}{x}e^{-z} dx} = \frac{xe^{-z}|_{e^{-z}}^{1}}{e^{-z} \ln x|_{e^{-z}}^{1}} = \frac{1 - e^{-z}}{z}$$