

# Prompting in Visual Generation

Ziwei Liu

Nanyang Technological University



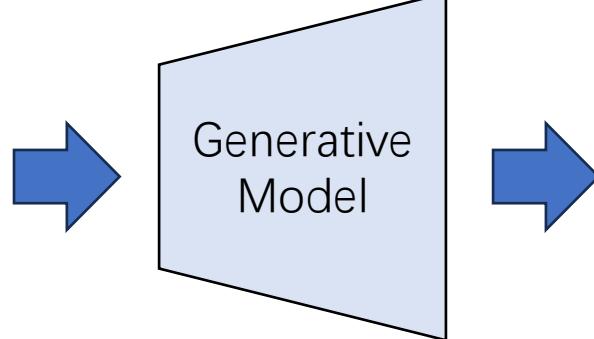
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# Prompting in Generation



Image Prompt



*"A Corgi"*

Text Prompt



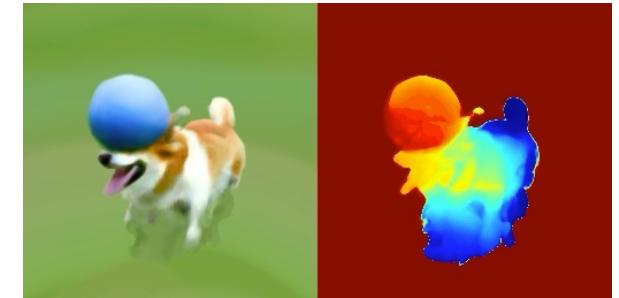
Image



Video



3D



4D Dynamic Scene





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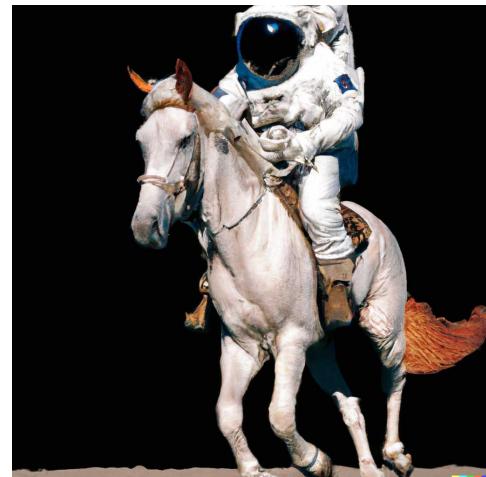
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# Text to Image Generation

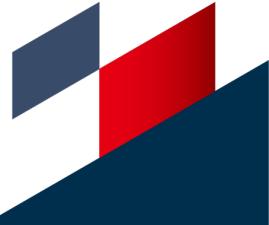


# Text to Image Generation

- Prompt: An astronaut riding a horse in photorealistic style.

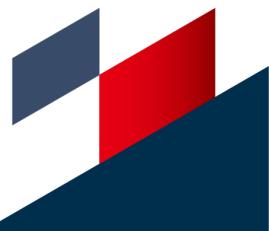


Source: <https://openai.com/dall-e-2>

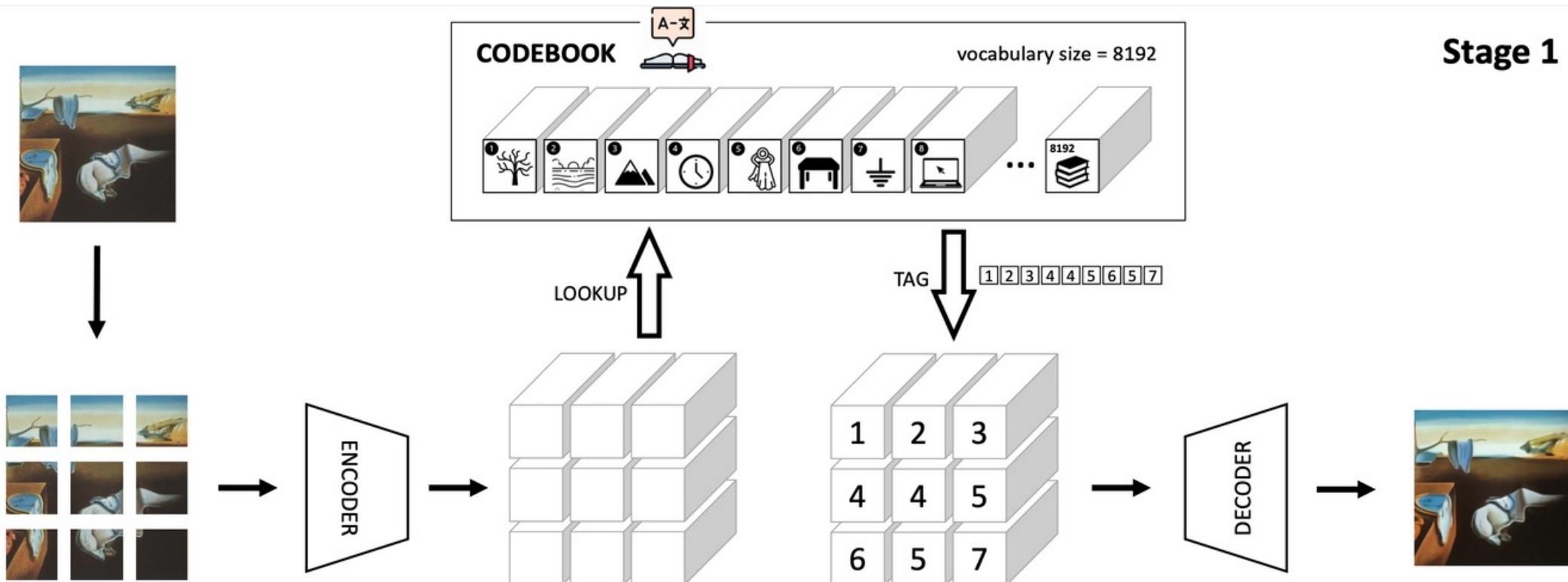


# Text to Image Generation

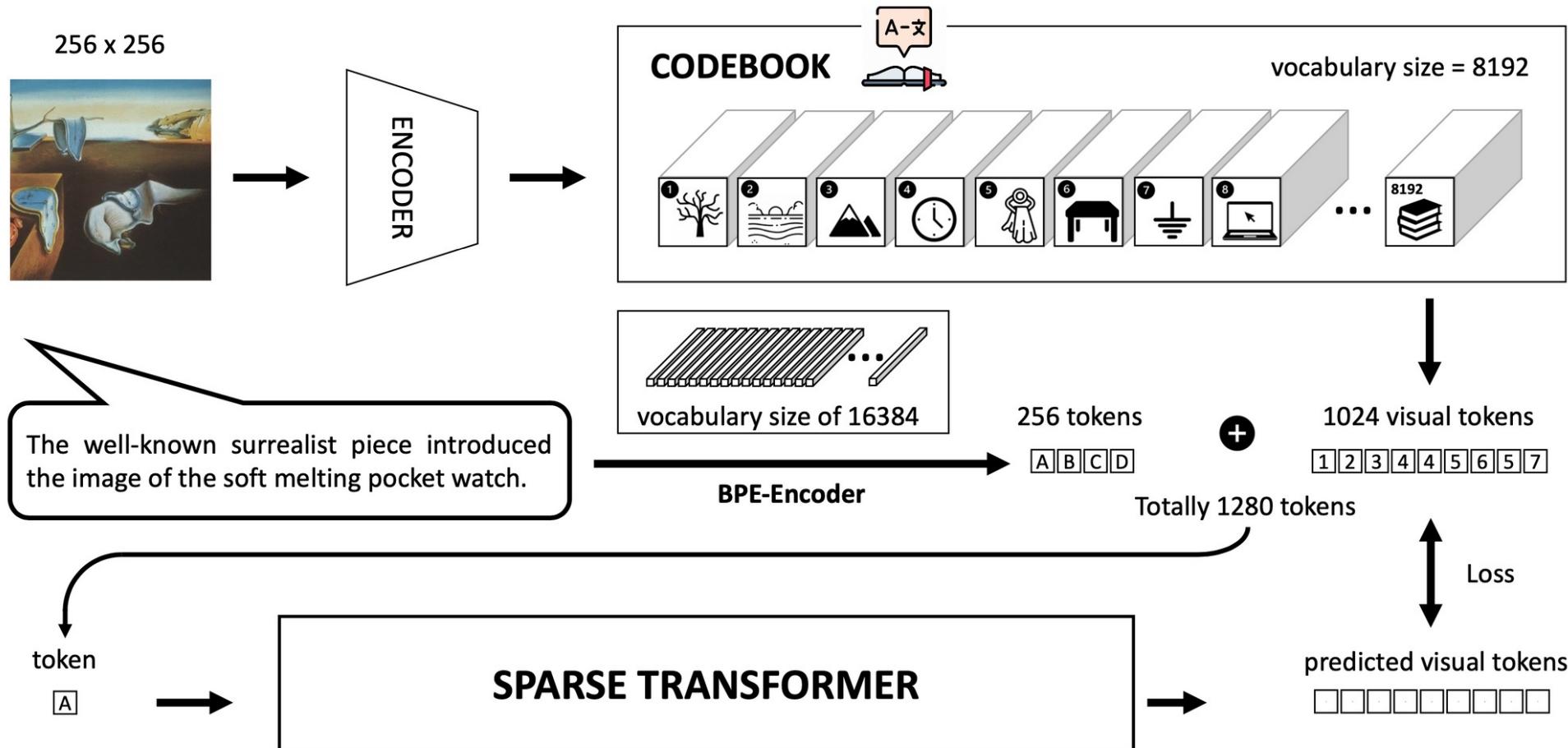
- VQGAN-based Methods
  - DALLE
- Diffusion-based Methods
  - GLIDE, DALEE2, Stable Diffusion
- GAN-based Methods
  - GigaGAN
- Generation on Specialized data
  - Text2Human



- Stage 1: Learning the Visual Codebook



- Stage 2: Learning the Prior



# GLIDE

- Diffusion Models

- Markov chain of latent variables by progressively adding Gaussian noise to samples

$$q(x_t|x_{t-1}) := \mathcal{N}(x_t; \sqrt{\alpha_t}x_{t-1}, (1 - \alpha_t)\mathbf{I})$$

- Learn a model to approximate the true posterior

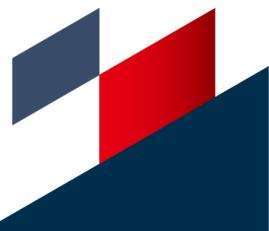
$$p_\theta(x_{t-1}|x_t) := \mathcal{N}(\mu_\theta(x_t), \Sigma_\theta(x_t))$$

- The model is trained to predict the added noise

$$L_{\text{simple}} := E_{t \sim [1, T], x_0 \sim q(x_0), \epsilon \sim \mathcal{N}(0, \mathbf{I})} [\|\epsilon - \epsilon_\theta(x_t, t)\|^2]$$

- Guided Diffusion

$$\hat{\mu}_\theta(x_t|y) = \mu_\theta(x_t|y) + s \cdot \Sigma_\theta(x_t|y) \nabla_{x_t} \log p_\phi(y|x_t)$$



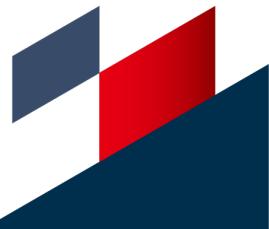
- Classifier-free guidance

$$\hat{\epsilon}_\theta(x_t|y) = \epsilon_\theta(x_t|\emptyset) + s \cdot (\epsilon_\theta(x_t|y) - \epsilon_\theta(x_t|\emptyset))$$

- CLIP Guidance

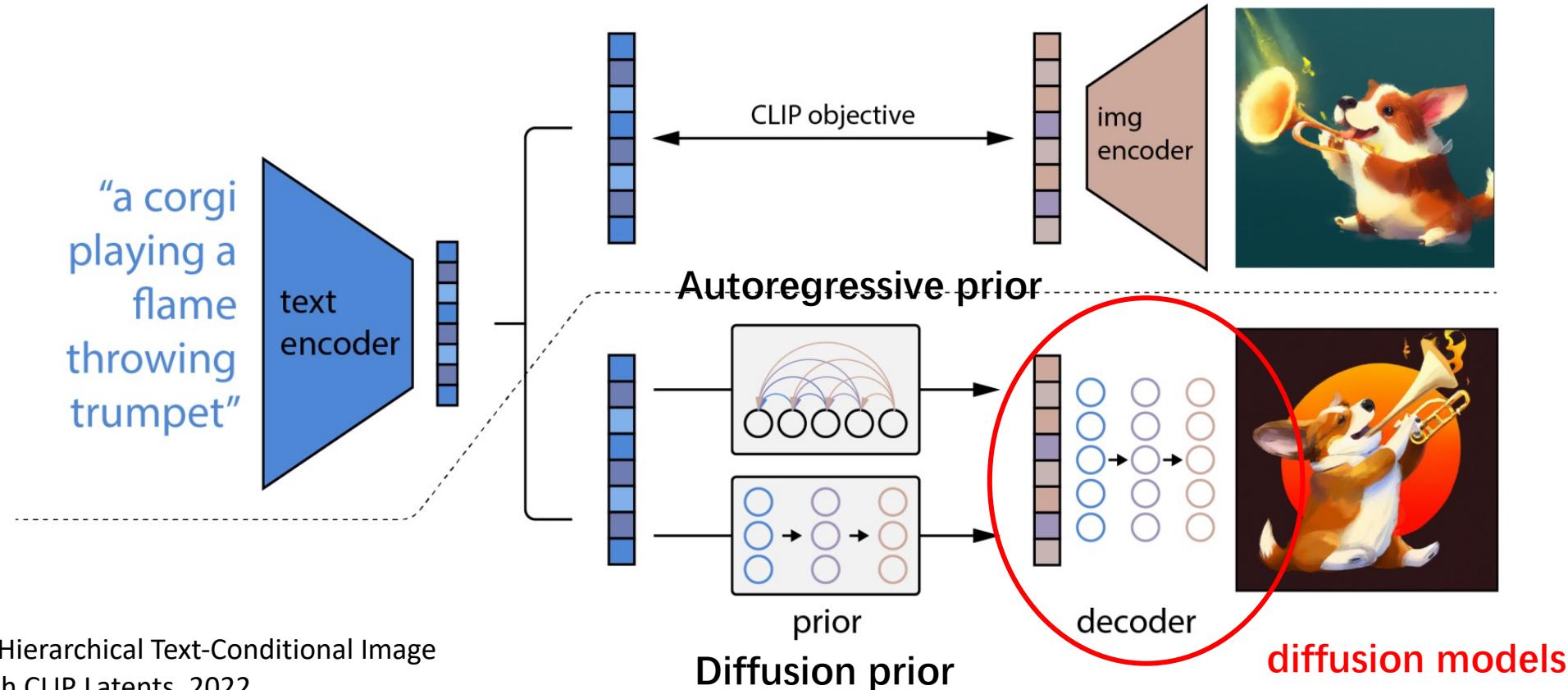
$$\hat{\mu}_\theta(x_t|c) = \mu_\theta(x_t|c) + s \cdot \Sigma_\theta(x_t|c) \nabla_{x_t} (f(x_t) \cdot g(c))$$

- Conclusion: Classifier-free guidance is preferred by human evaluators for both photorealism and caption similarity



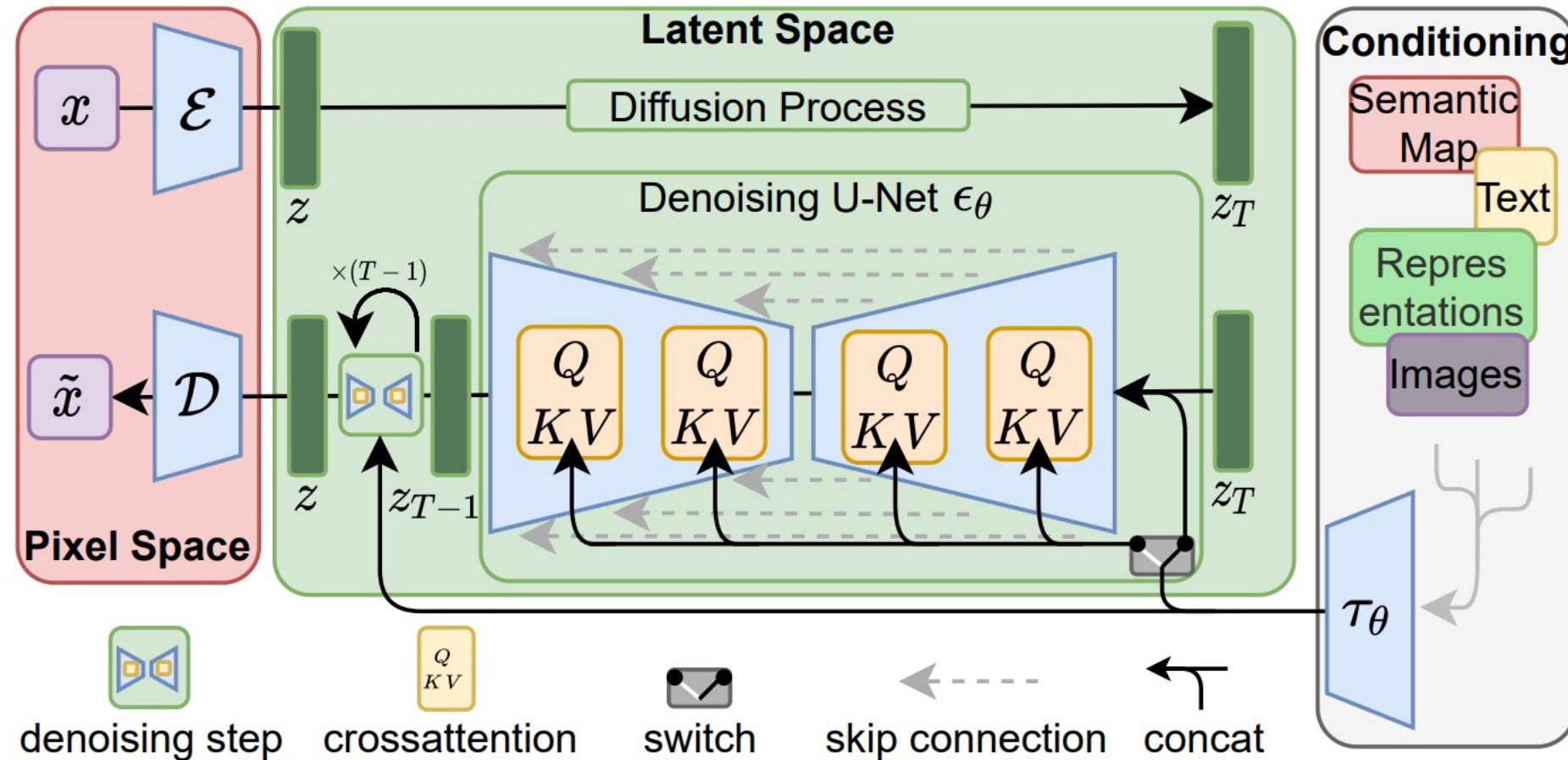
# DALLE2

- Two key components:
  - Prior: produces CLIP Image Embeddings conditioned on captions
  - Decoder: produces images conditioned on CLIP Image Embeddings

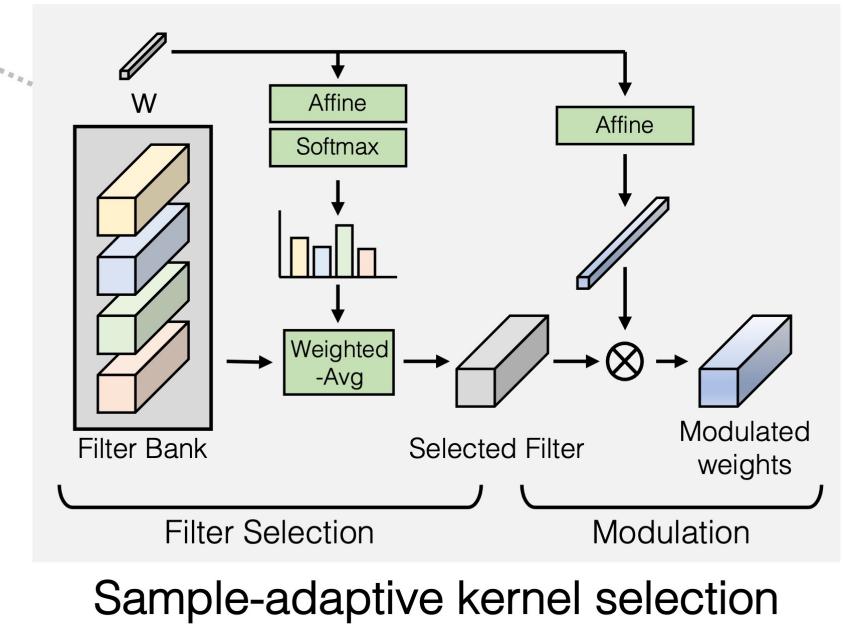
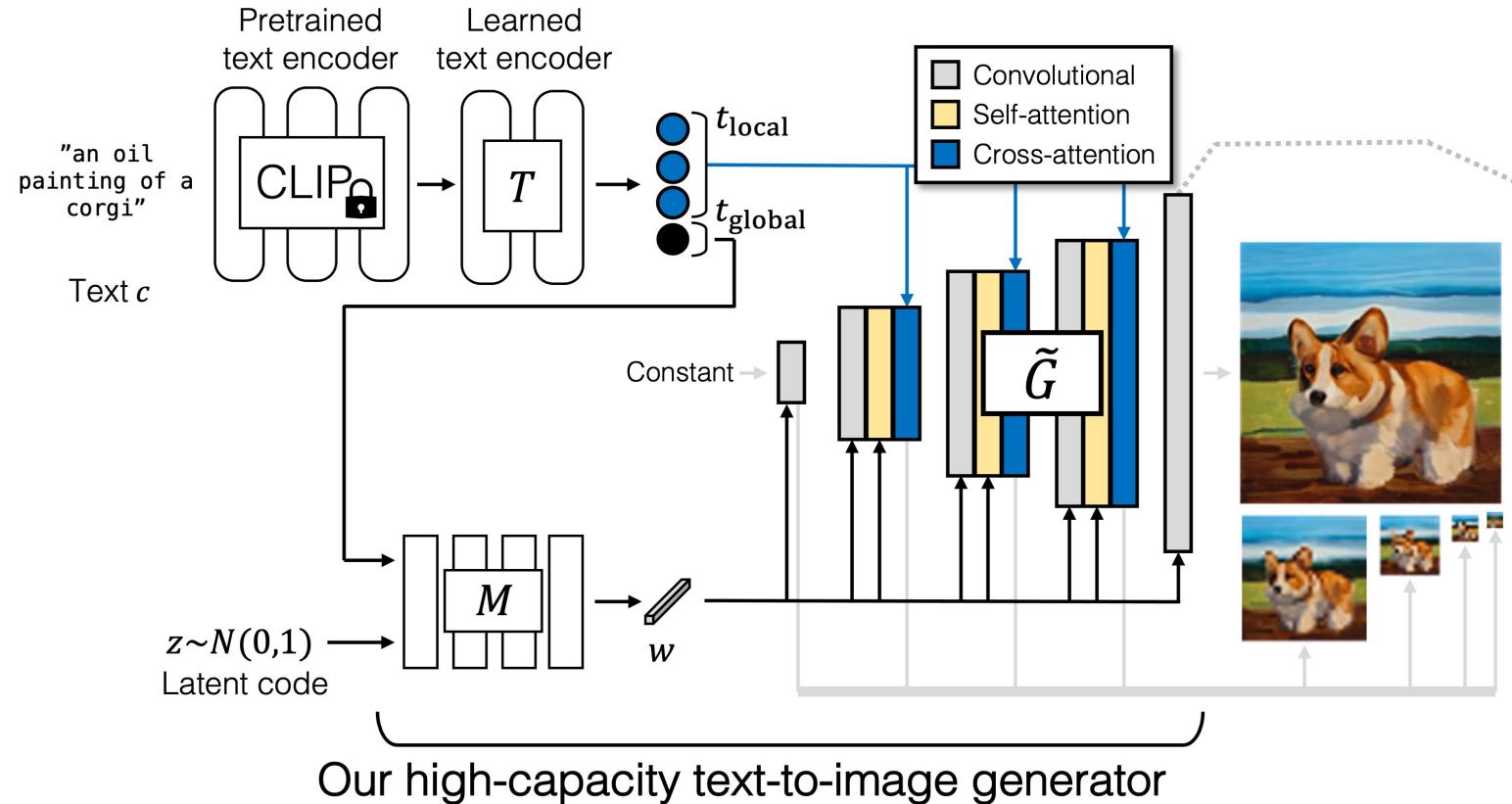


# Stable Diffusion

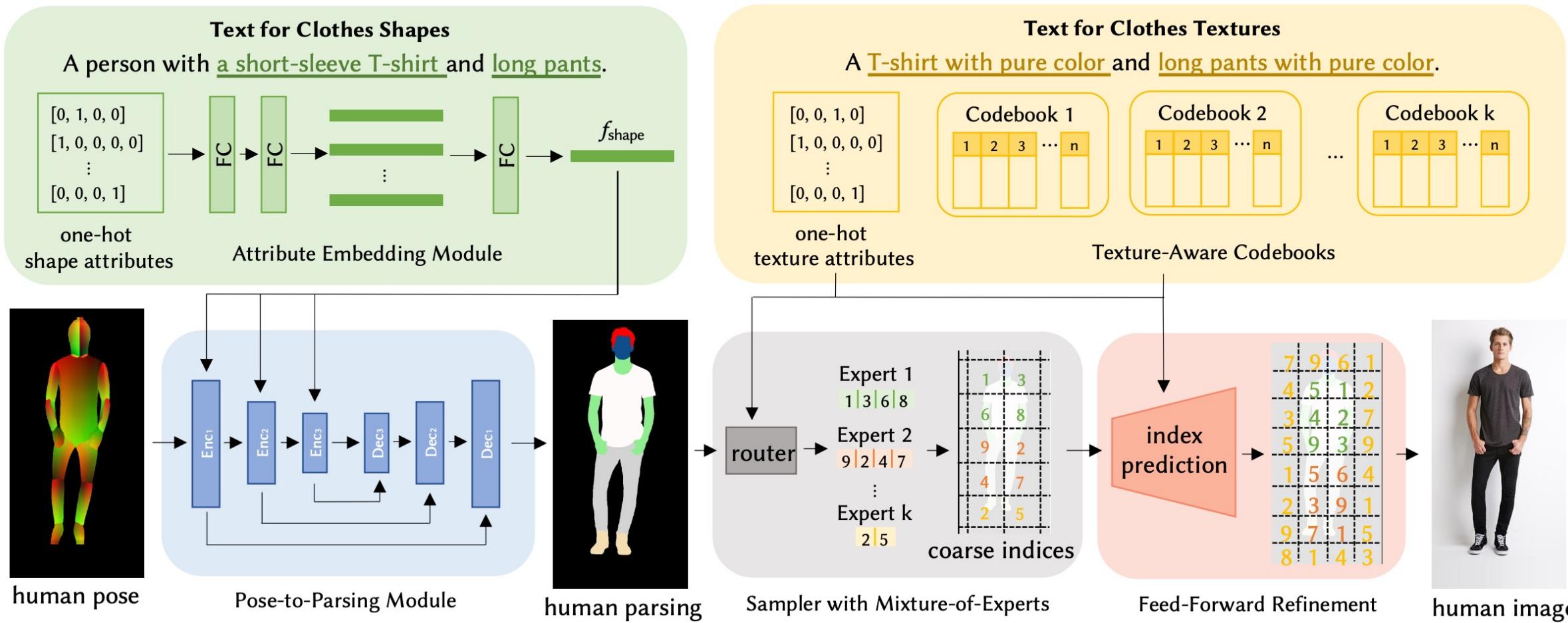
- Encode the images into the latent space



# GigaGAN

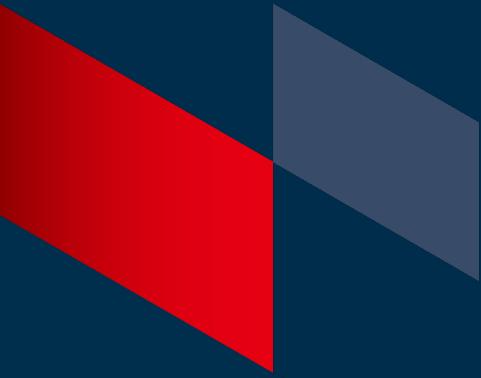


# Text2Human





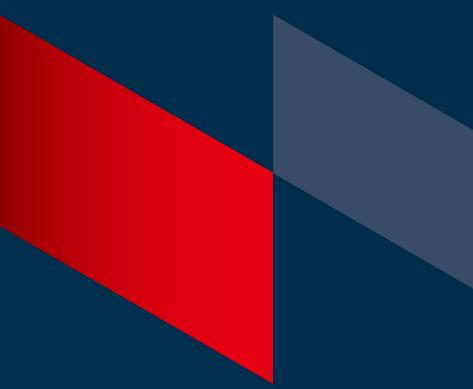
# Image Prompt



- Prompting for Appearance Generation
  - Optimization-Based
    - Textual Inversion
    - DreamBooth
  - Encoder-Based
    - Tuning Encoder
    - ELITE
    - Taming Encoder
- Prompting for Relation Generation
  - ReVersion



# Image Prompt



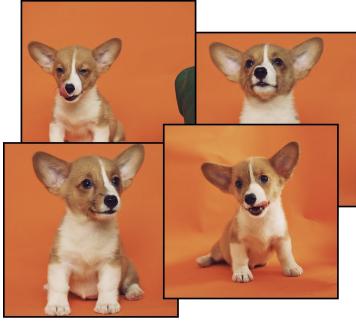
- Prompting for Appearance Generation
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- Prompting for Relation Generation
  - ReVersion

# Textual Inversion



- Task: prompting for appearance generation (personalized generation)
- Method: optimize a text token:  $v_* = \arg \min_v \mathbb{E}_{z \sim \mathcal{E}(x), y, \epsilon \sim \mathcal{N}(0, 1), t} [\|\epsilon - \epsilon_\theta(z_t, t, c_\theta(y))\|_2^2]$

# DreamBooth



Input images



in the Acropolis



swimming      sleeping



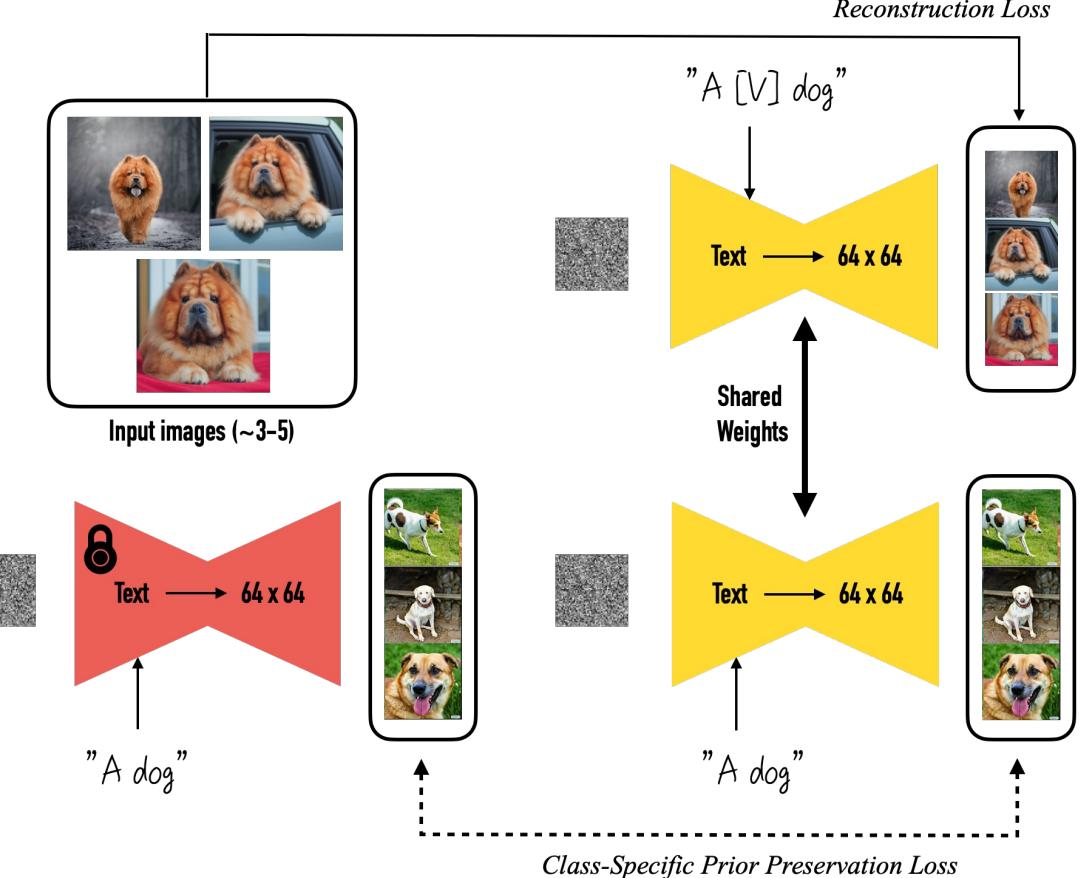
Input images



worn by a bear



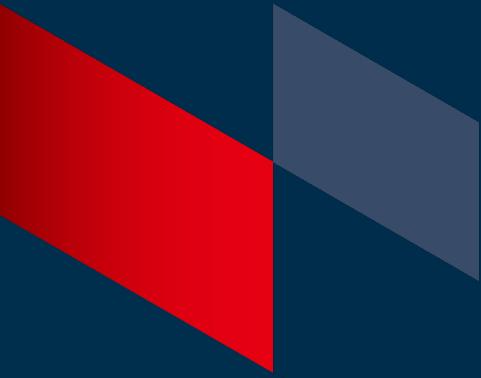
in the jungle      on red fabric  
at Mt. Fuji      on top of snow



- Task: prompting for appearance generation (personalized generation)
- Method: fine-tune to obtain a personalized text-to-image model

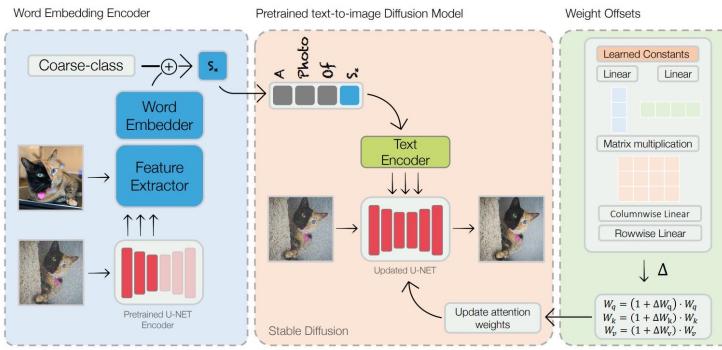


# Image Prompt



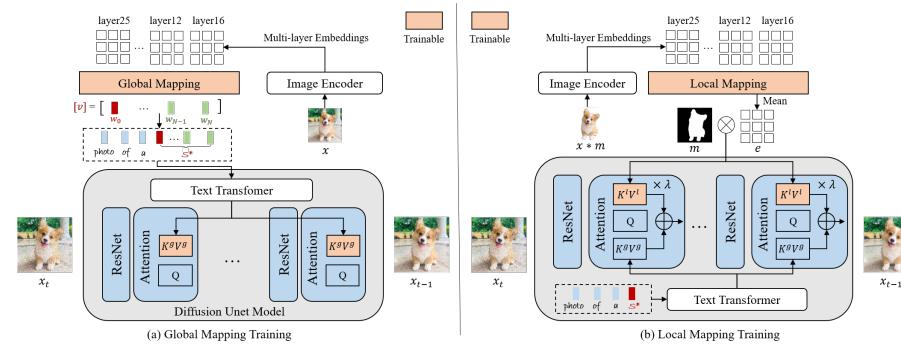
- **Prompting for Appearance Generation**
  - Optimization-Based
    - Textual Inversion
    - DreamBooth
  - Encoder-Based
    - Tuning Encoder
    - ELITE
    - Taming Encoder
- **Prompting for Relation Generation**
  - ReVersion

# Encoder-Based

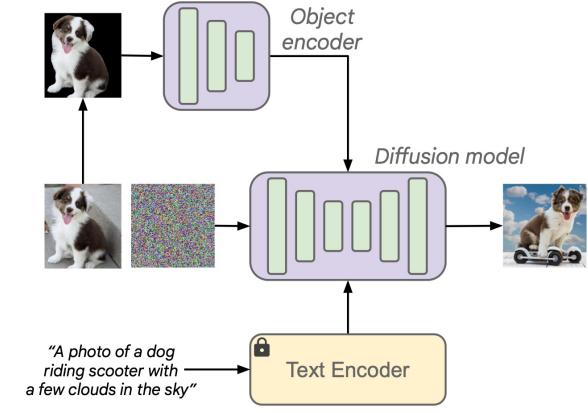


*Tuning Encoder*

- Fast: a few optimization steps
- Memory Efficient
- One-Shot



*ELITE*



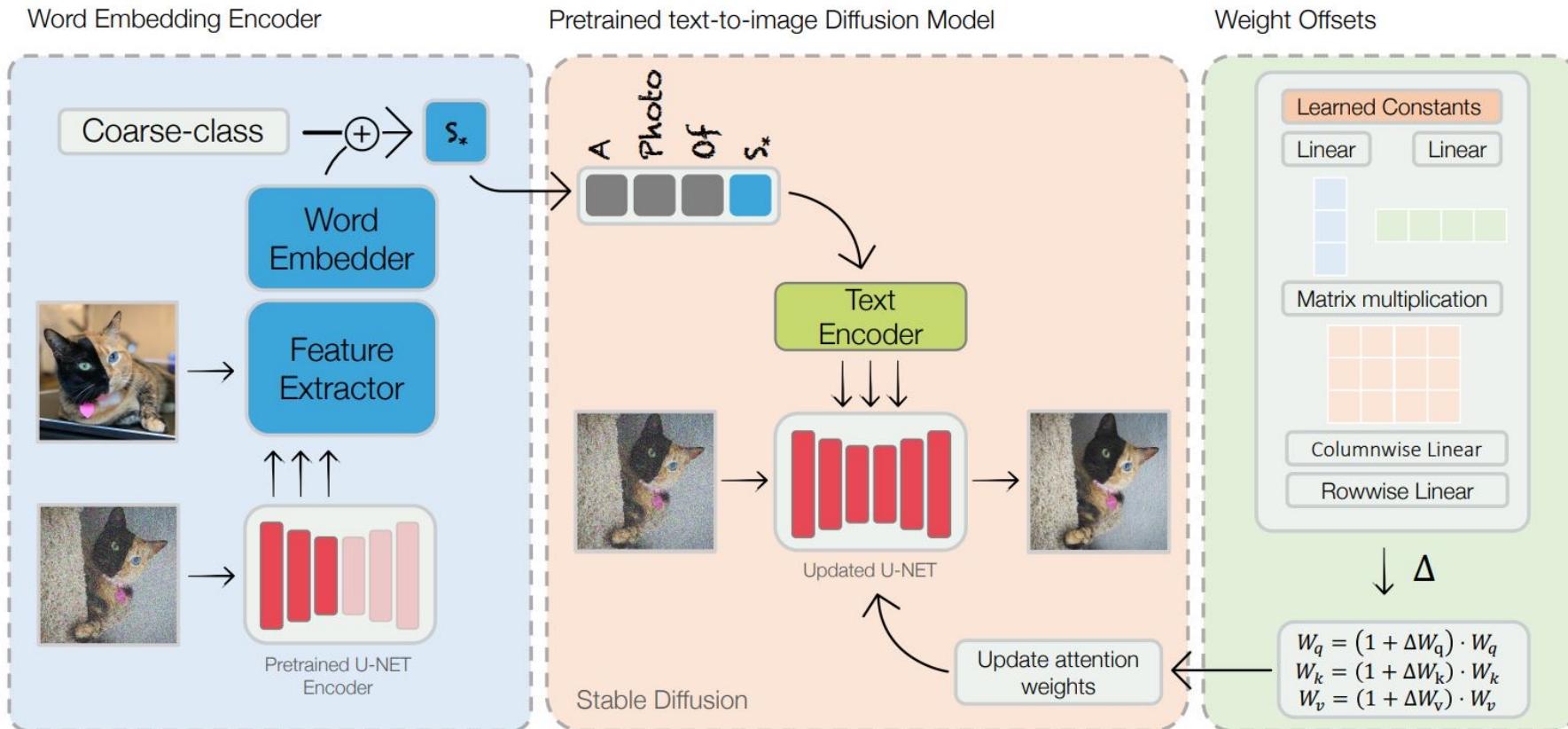
*Taming Encoder*

Encoder-based Domain Tuning for Fast Personalization of Text-to-Image Models (2023)

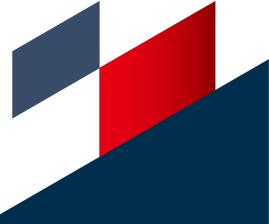
ELITE: Encoding Visual Concepts into Textual Embeddings for Customized Text-to-Image Generation (2023)

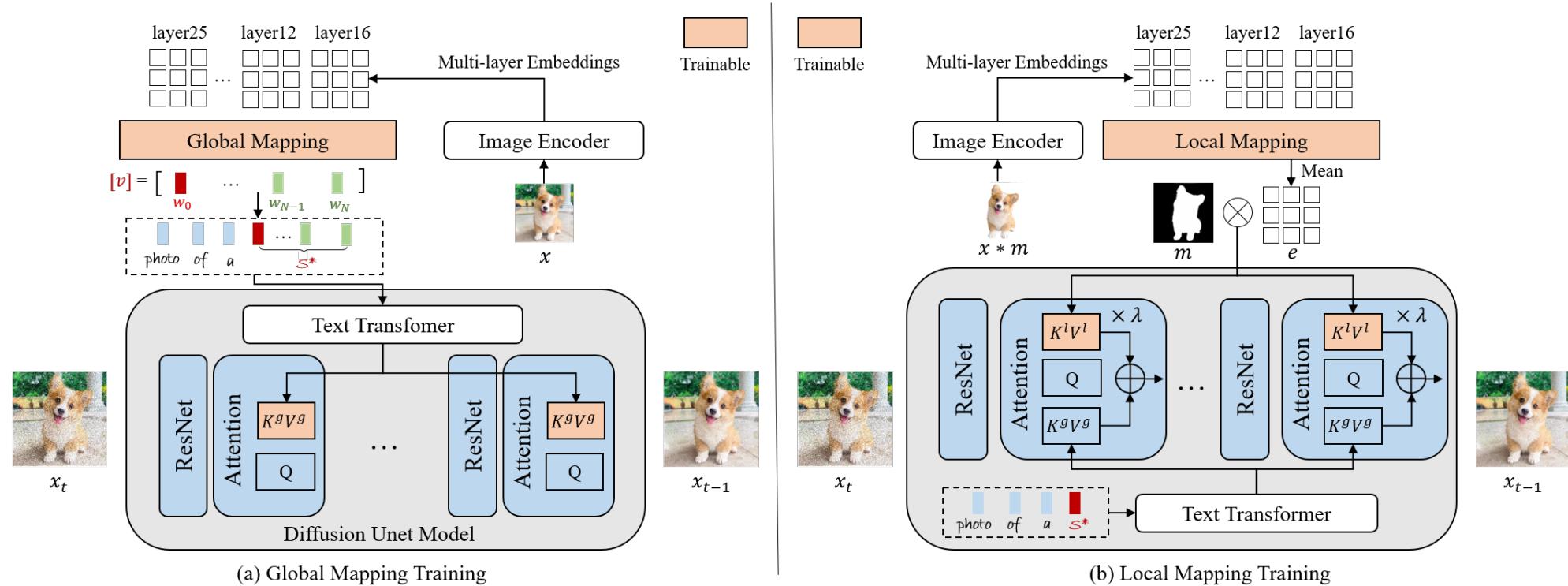
Taming encoder for zero fine-tuning image customization with text-to-image diffusion models (2023)

# Tuning Encoder



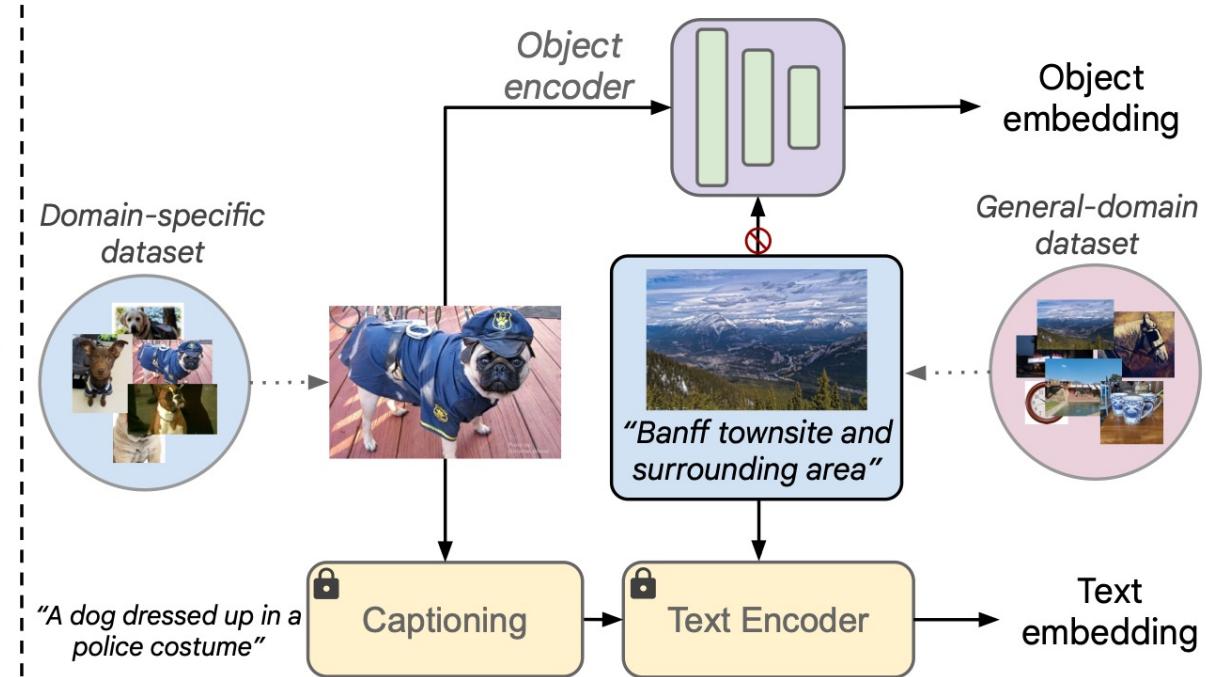
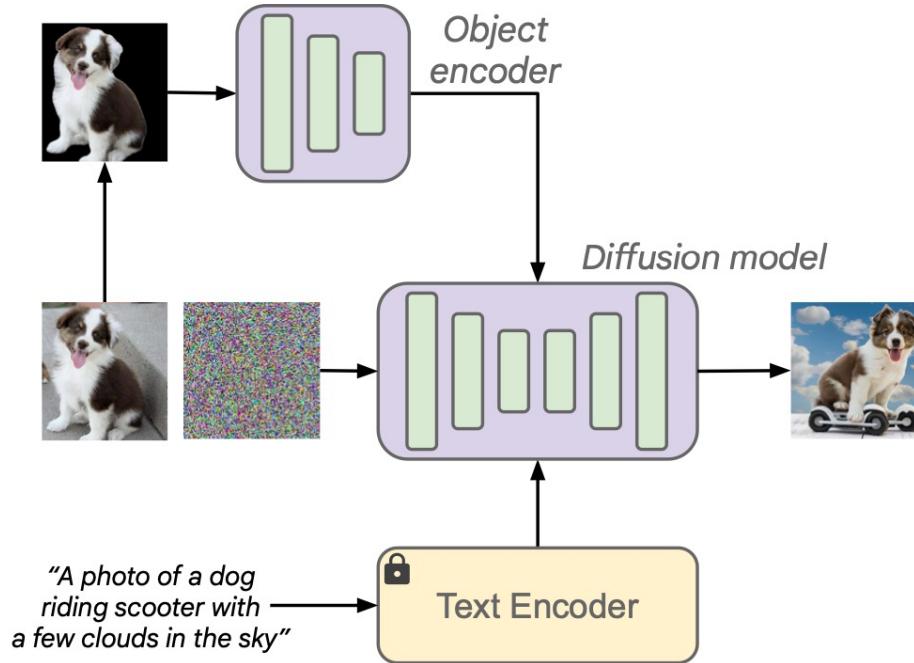
- Domain-Specific Encoder
- Weight Offsets



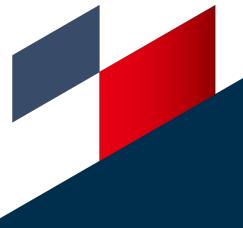


- Global Mapping Network – Text Embeddings
- Local Mapping Network – Details

# Taming Encoder

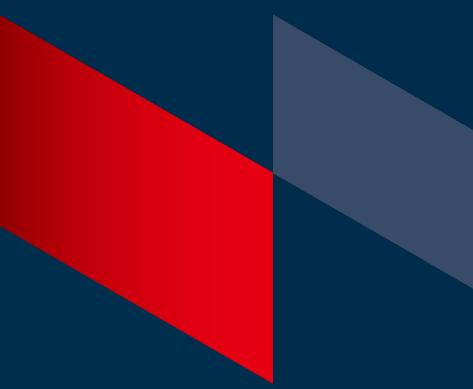


- Background Removal + Encoder
- Triplet Preparation Scheme





# Image Prompt



- Prompting for Appearance Generation
  - Optimization-Based
    - Textual Inversion
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  - Encoder-Based
    - Tuning Encoder
    - ELITE
    - Taming Encoder
- Prompting for Relation Generation
  - ReVersion

# ReVersion

## *Input*

### *Exemplar Images*



## *Output*

### *Relation Prompt*

$\langle R \rangle$

*represent the co-existing  
relation in exemplar images*

## *Application*

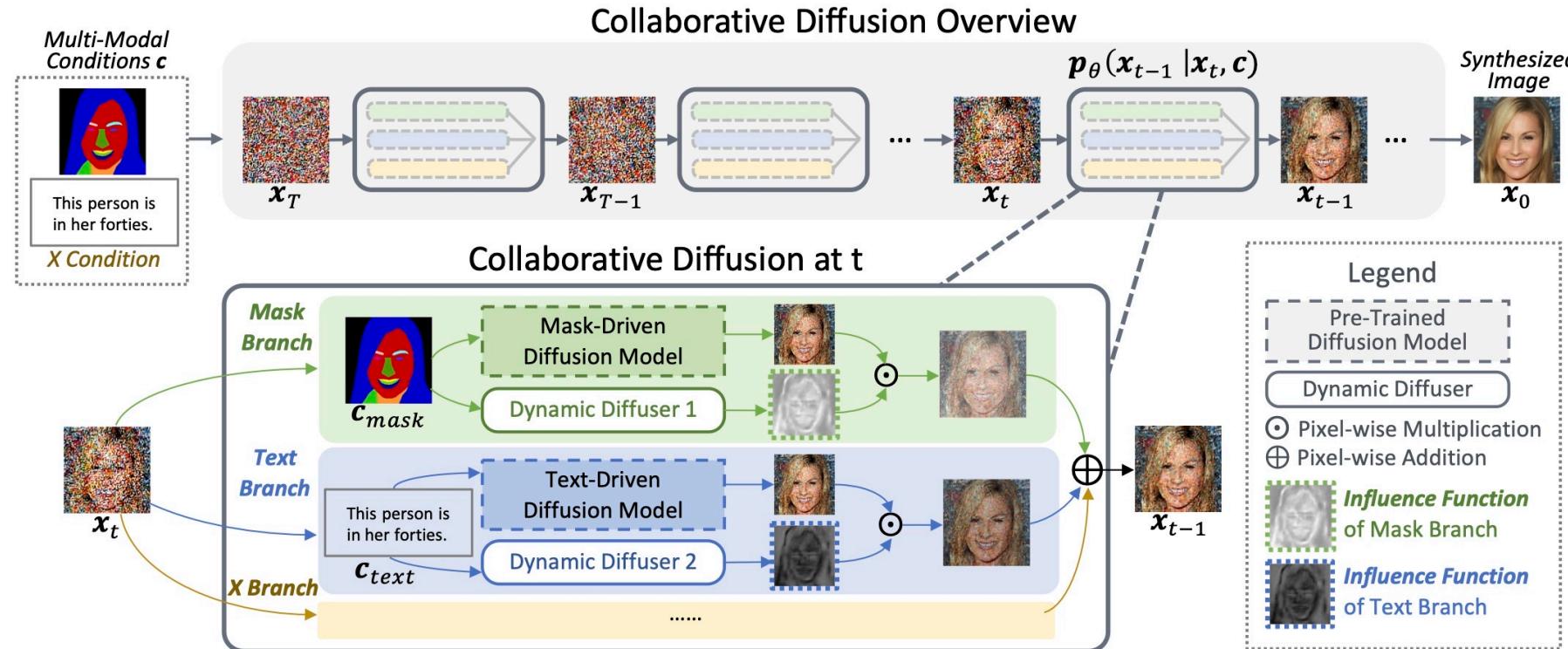
### *Relation-Specific Text-to-Image Synthesis*



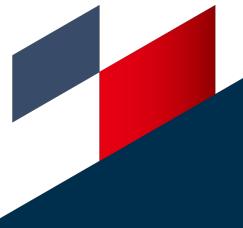
“Synthesize  $\langle R \rangle$  *basket*”

“vegetable **is contained inside** paperBag”

# Collaborative Diffusion



- Use model collaboration to simultaneously accept different types of prompt: linguistic, visual





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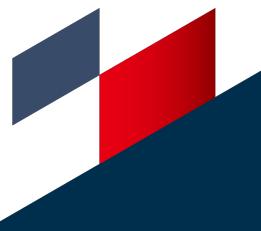
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# Text to Video Generation



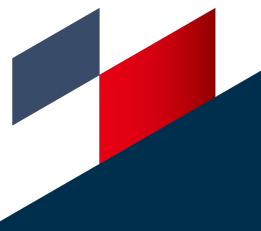
# Text to Video Generation

- Auto-regressive methods
  - VideoGPT
  - TATS
  - Phenaki
- Diffusion models
  - Imagen Video
  - Gen1
  - Text2Performer



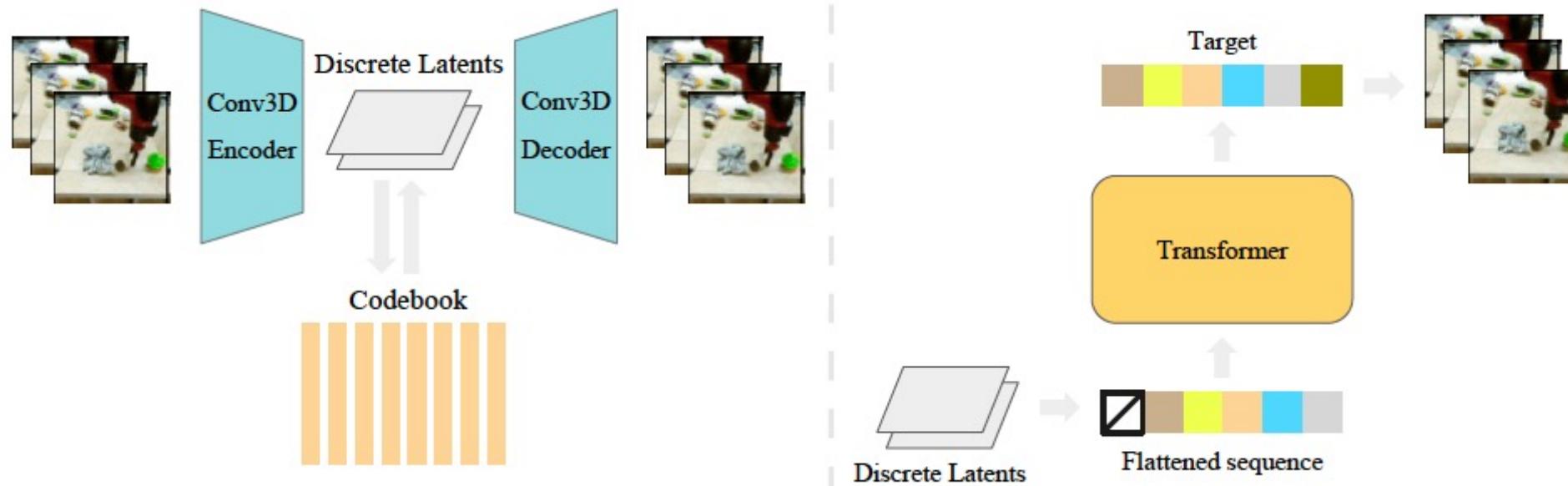
# Text to Video Generation

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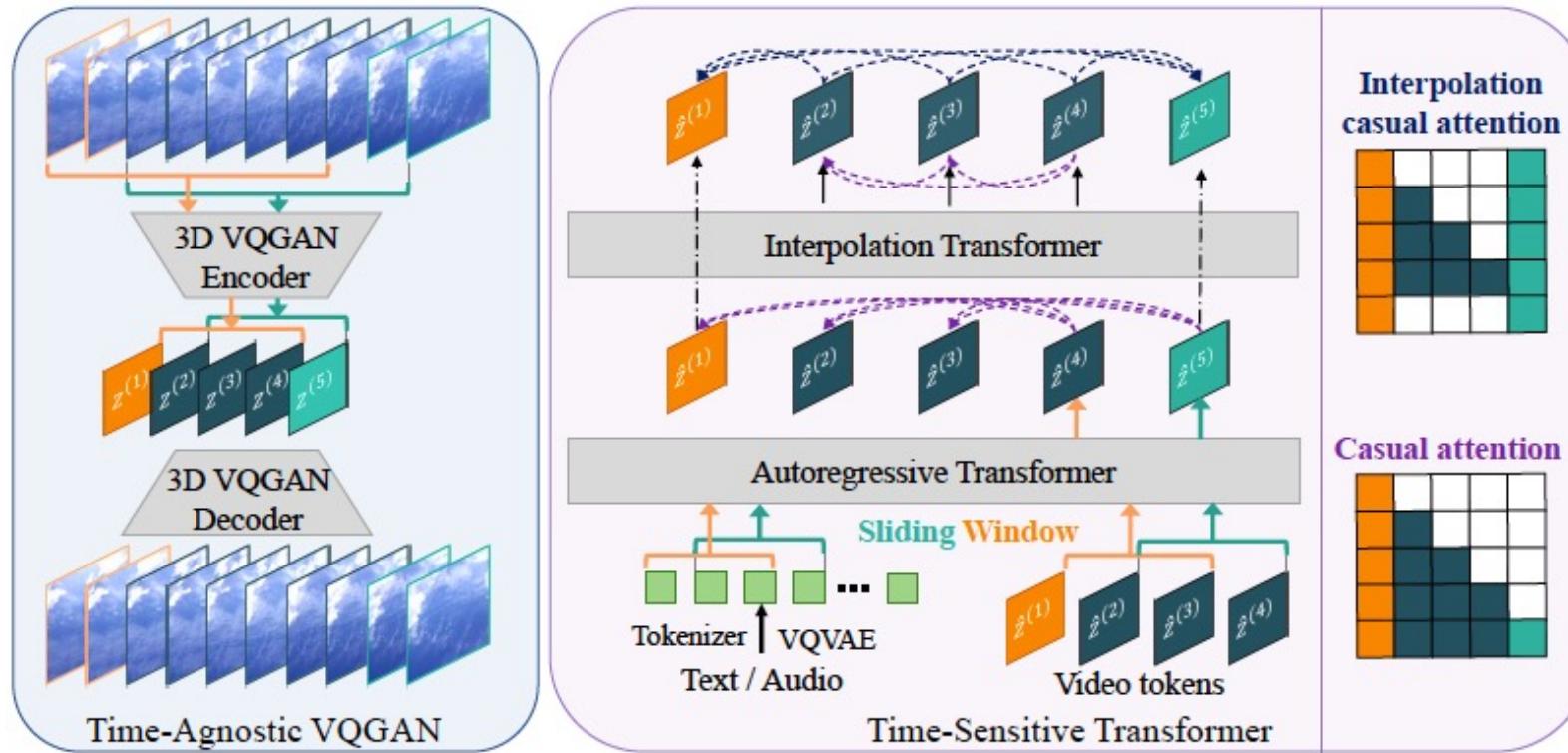
# T2V: VideoGPT

- VQGAN: learn a set of discrete latent codes from raw pixels of the video frames.
- Transformer: learn a prior over the VQ-VAE latent codes.



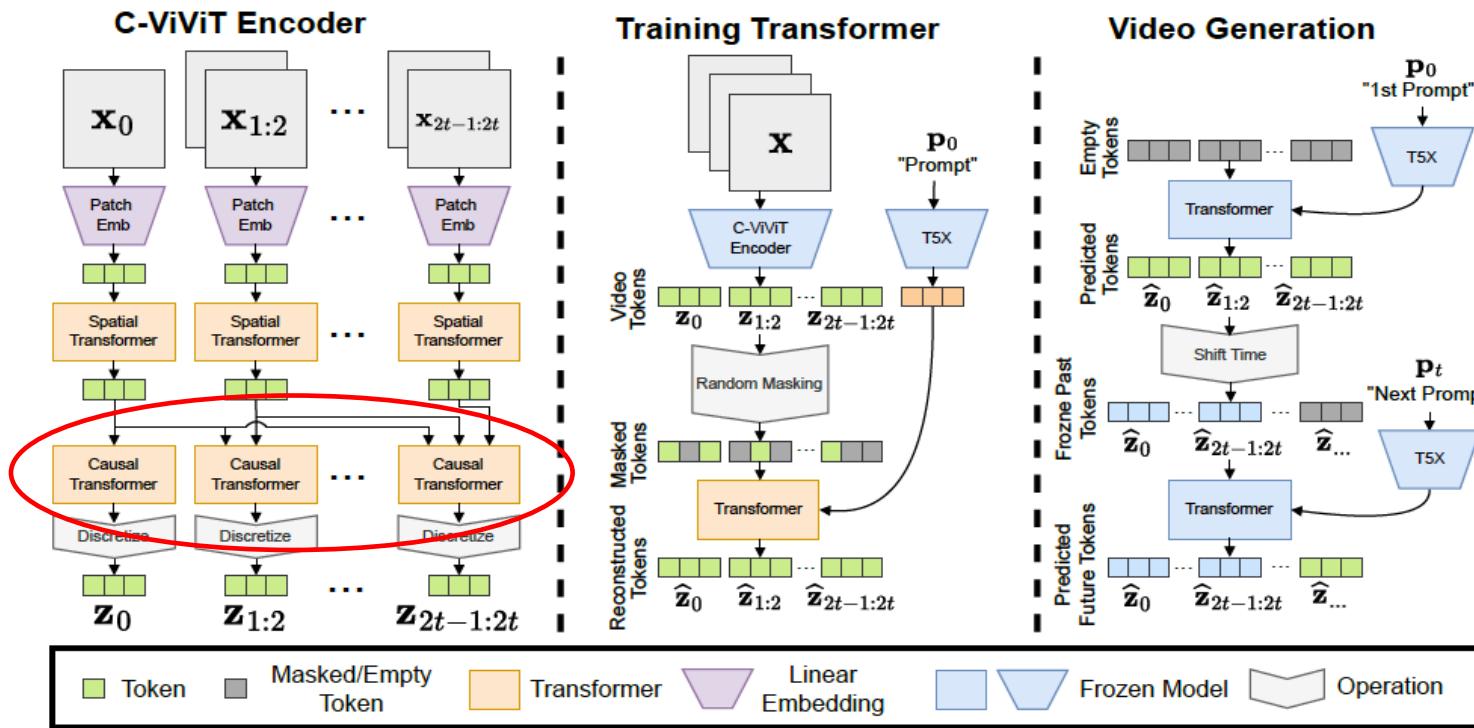
# T2V: TATS

- 3D VQGAN: replacing 2D convolution operations with 3D convolutions for modeling videos.
- Transformer: the hierarchical transformer can model longer time dependence and delay the quality degradation.



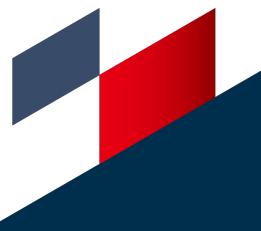
# T2V: Phenaki

- Encoder-decoder model: compress videos to discrete embeddings.
  - Causal attention makes the C-ViViT encoder autoregressive and enables it to handle a variable number of input frames.
- Transformer model: translate text embeddings to video tokens.



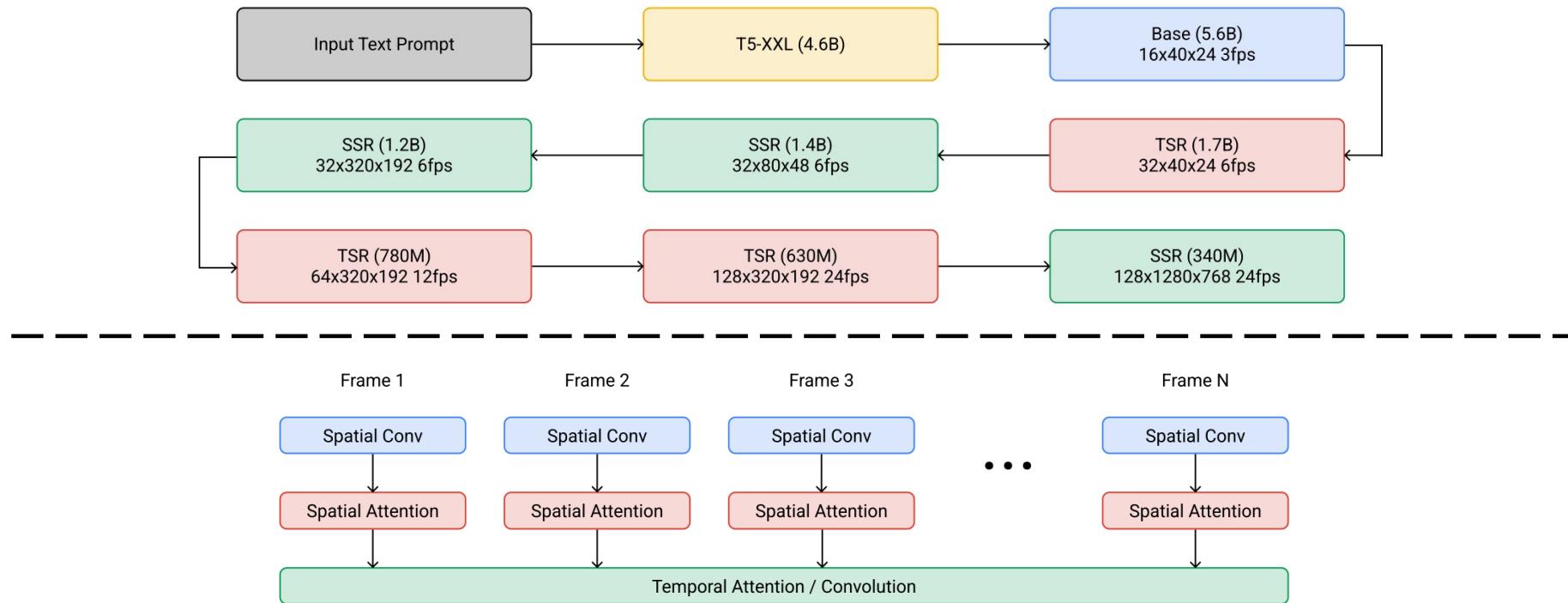
# Text to Video Generation

- Auto-regressive methods
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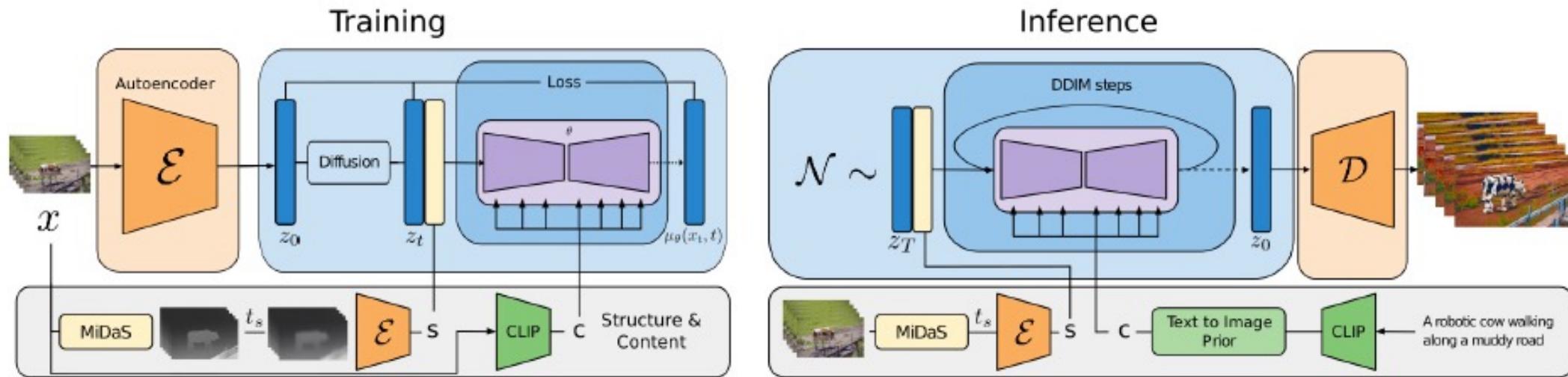
# T2V: Imagen video

- Cascaded Diffusion Models.
  - 1 frozen text encoder, 1 base video diffusion model, 3 SSR (spatial super-resolution), and 3 TSR (temporal superresolution) models – for a total of 7 video diffusion models

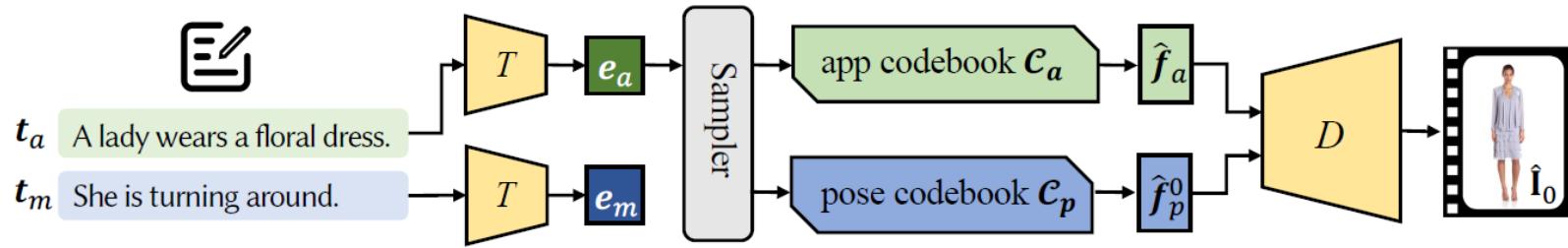


# T2V: Gen1

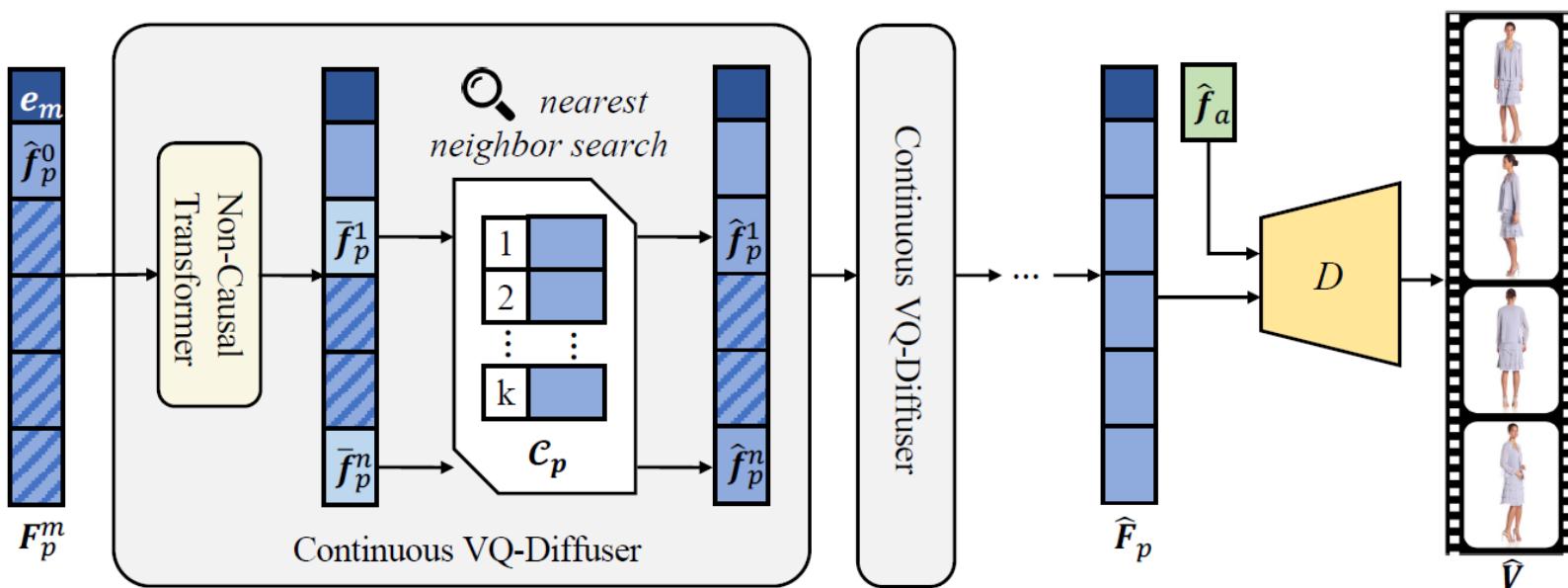
- Diffusion model: introduce temporal layers into a pre-trained image latent diffusion model
- Structure representation: utilize depth maps to provide control over structure and content fidelity.
- Content Representation: utilize CLIP to produce image (training) or text (inference) embeddings.



# T2V: Text2Performer



(b) Motion Sampling with Continuous VQ-Diffuser



## Legend

	Text
	Text encoder
	VQ-VAE Decoder
	Sampler
	Text embedding
	Continuous embedding
	Masked continuous embedding
	Codebook
	Appearance-related
	Motion-related



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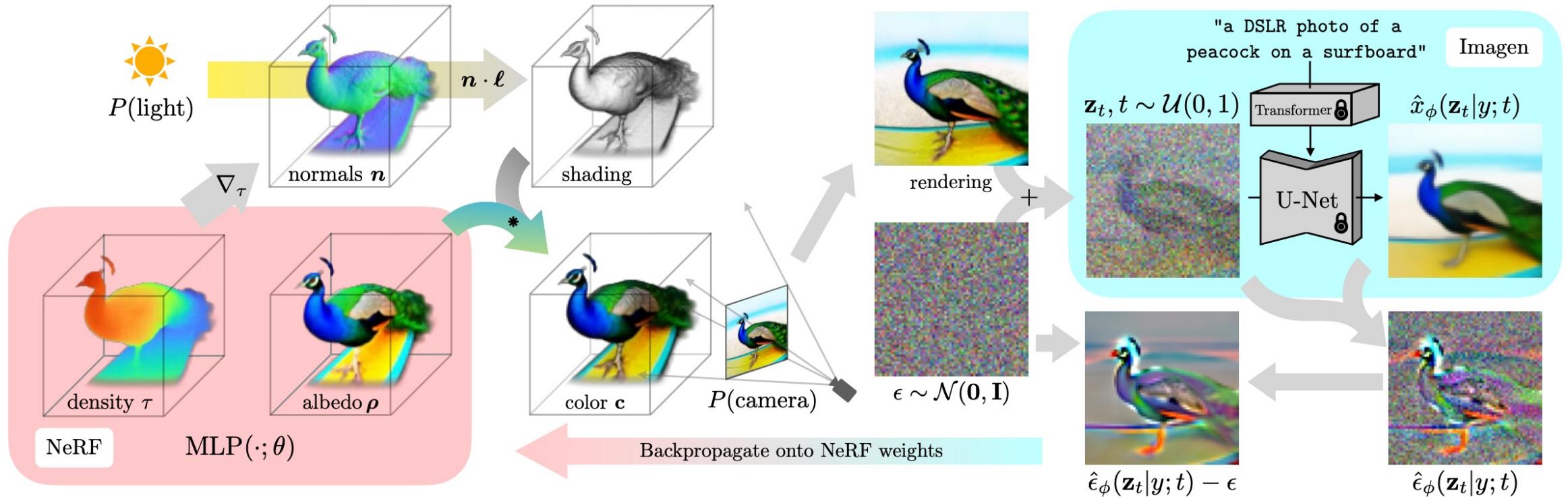
# Text to 3D Generation



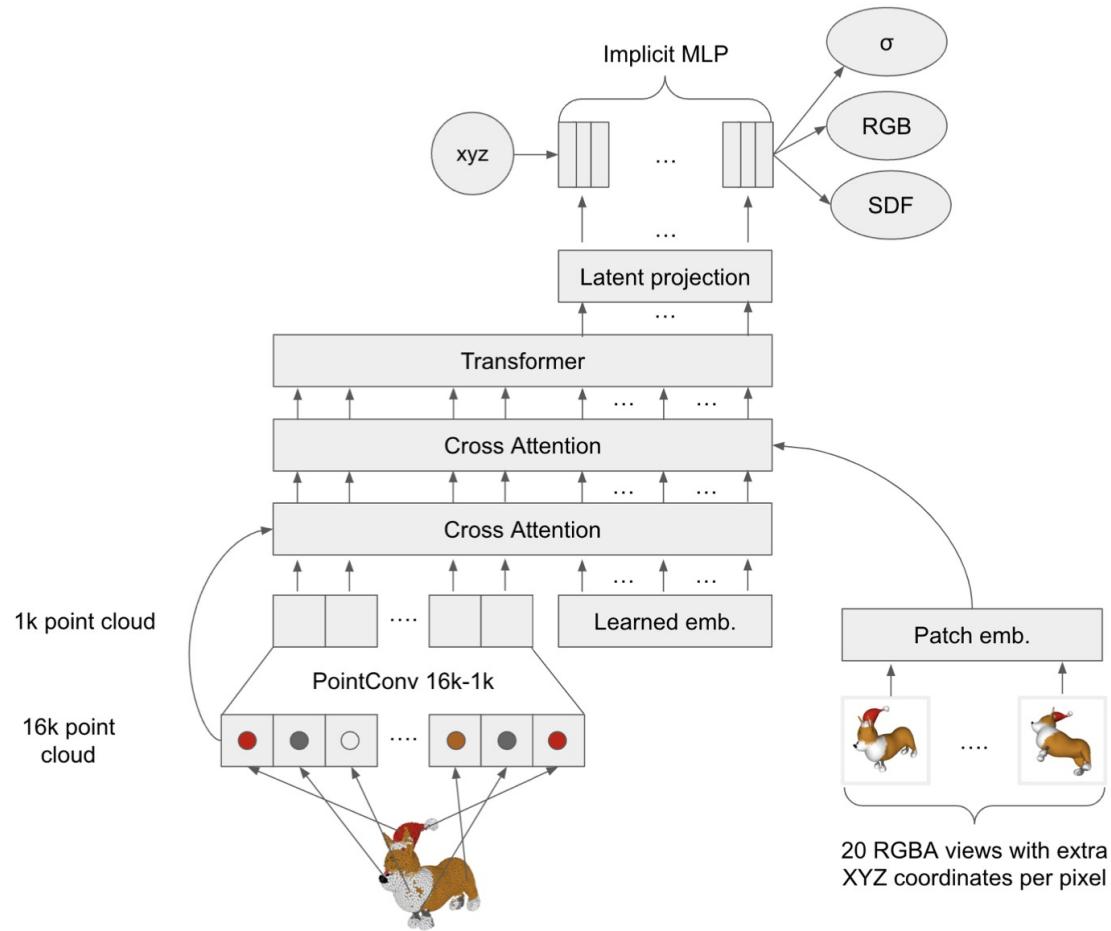
# Overview

	Object	Human	Scene												
Leveraging 2D Prior from pretrained text-2D models	DreamFusion 	AvatarCLIP 	Text2Room 												
Supervised Training from text-3D paired data	Shap-E  <table border="1"><tbody><tr><td></td><td></td><td></td></tr><tr><td>A chair that looks like an avocado</td><td>An airplane that looks like a banana</td><td>A spaceship</td></tr><tr><td></td><td></td><td></td></tr><tr><td>A birthday cupcake</td><td>A chair that looks like a tree</td><td>A green boot</td></tr></tbody></table>				A chair that looks like an avocado	An airplane that looks like a banana	A spaceship				A birthday cupcake	A chair that looks like a tree	A green boot	Rodin 	Text2Light 
A chair that looks like an avocado	An airplane that looks like a banana	A spaceship													
A birthday cupcake	A chair that looks like a tree	A green boot													

# DreamFusion

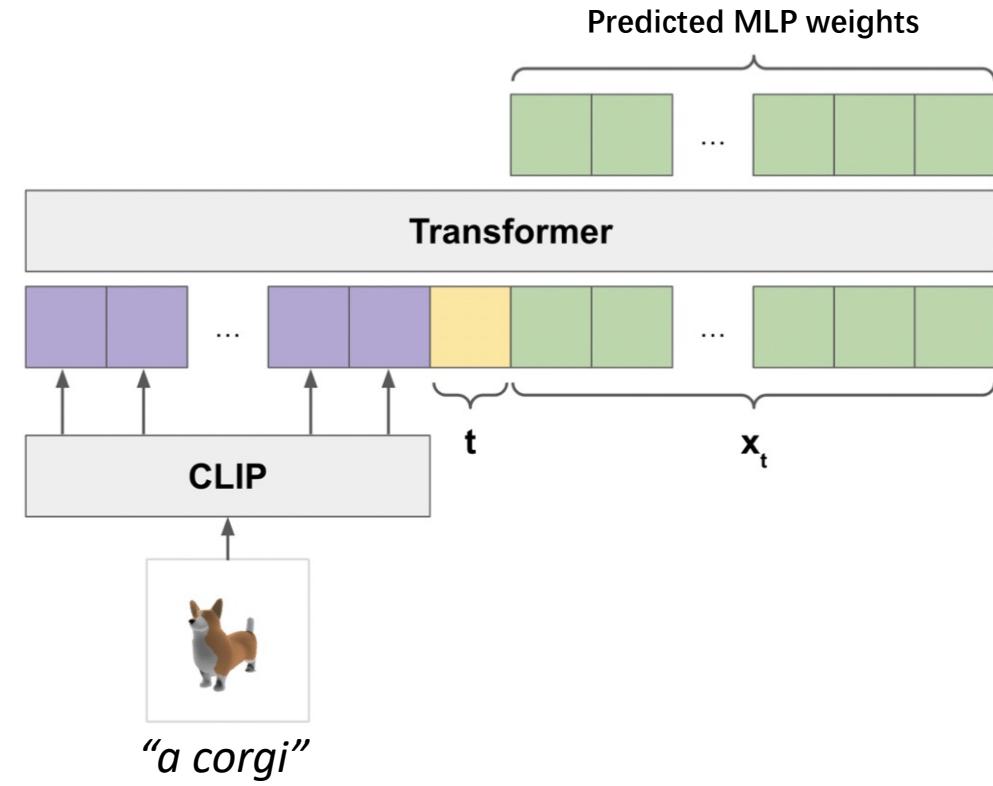


# Shap-E

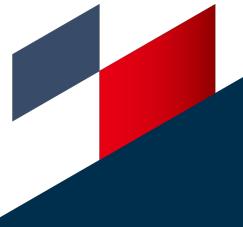


Step 1: Encode 3D Objects into Latent Space

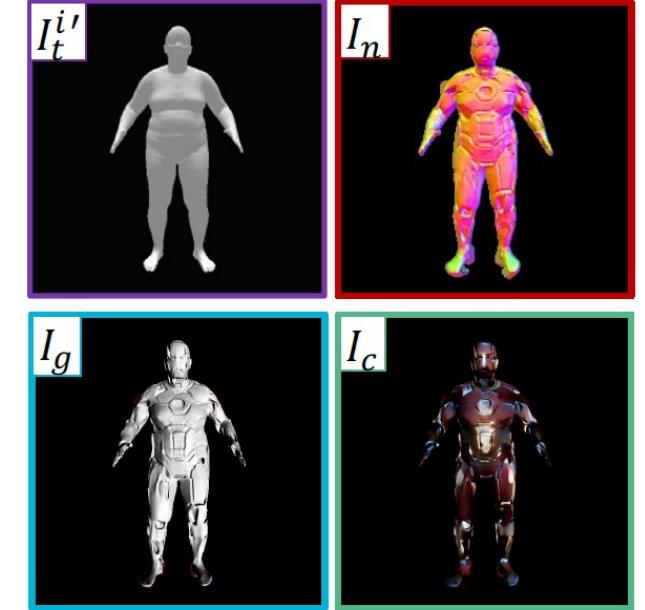
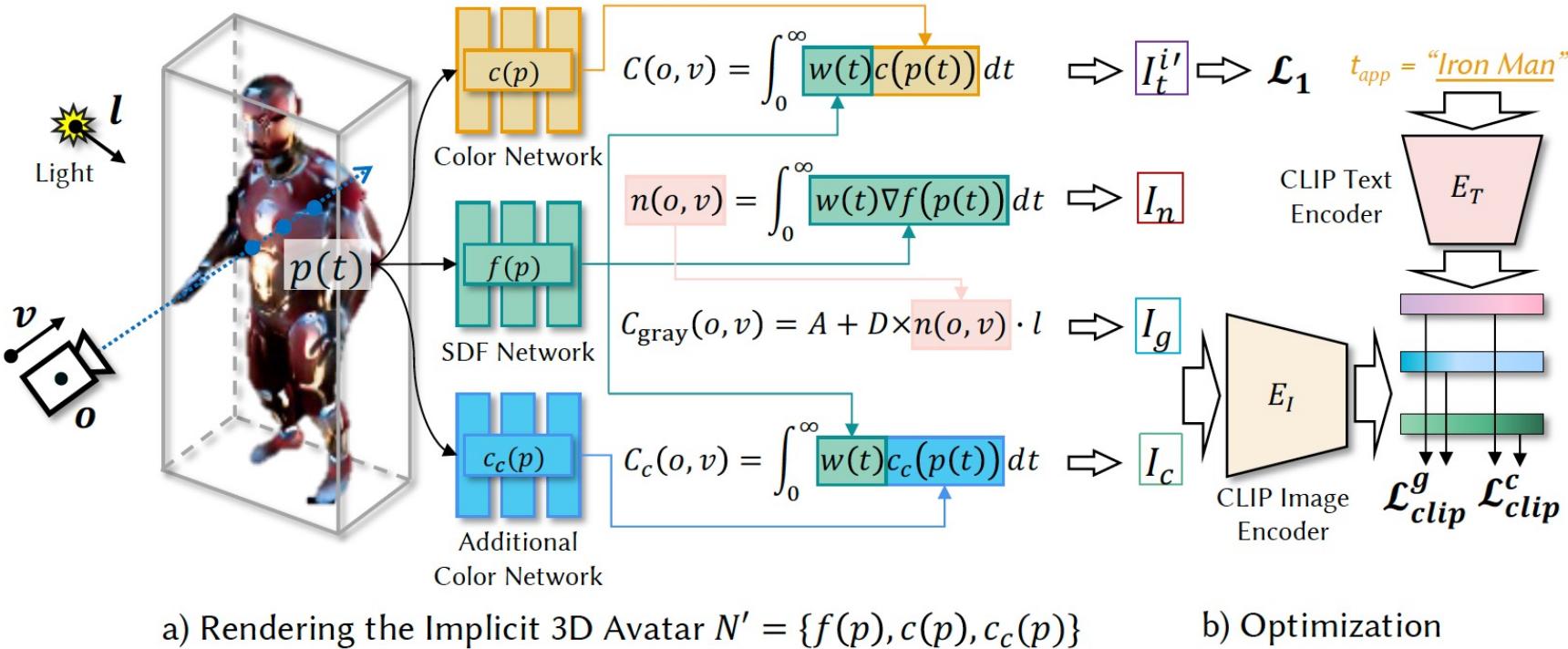
Shap-E: Generating Conditional 3D Implicit Functions



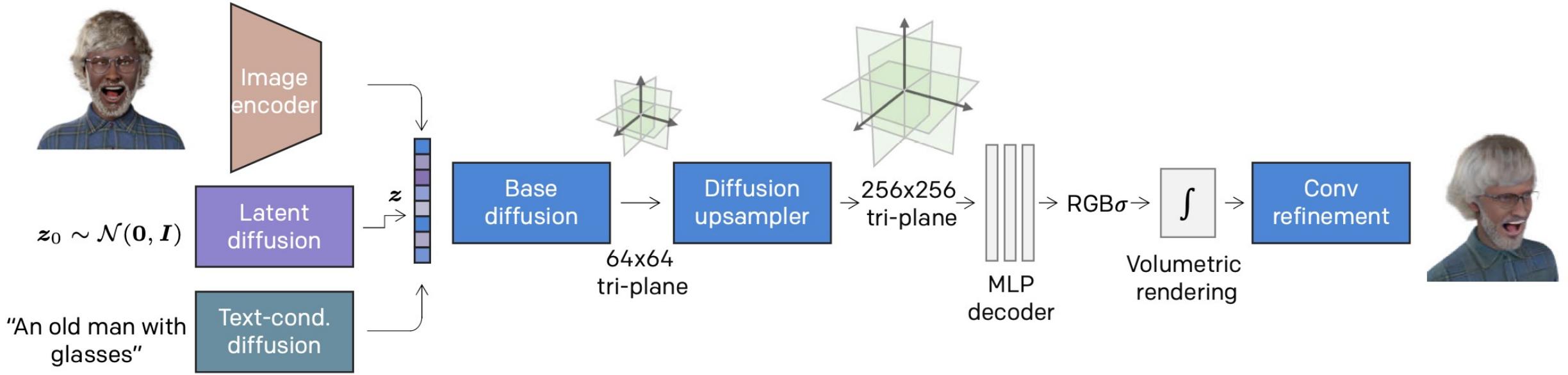
Step 2: Latent Diffusion



# AvatarCLIP



# Rodin



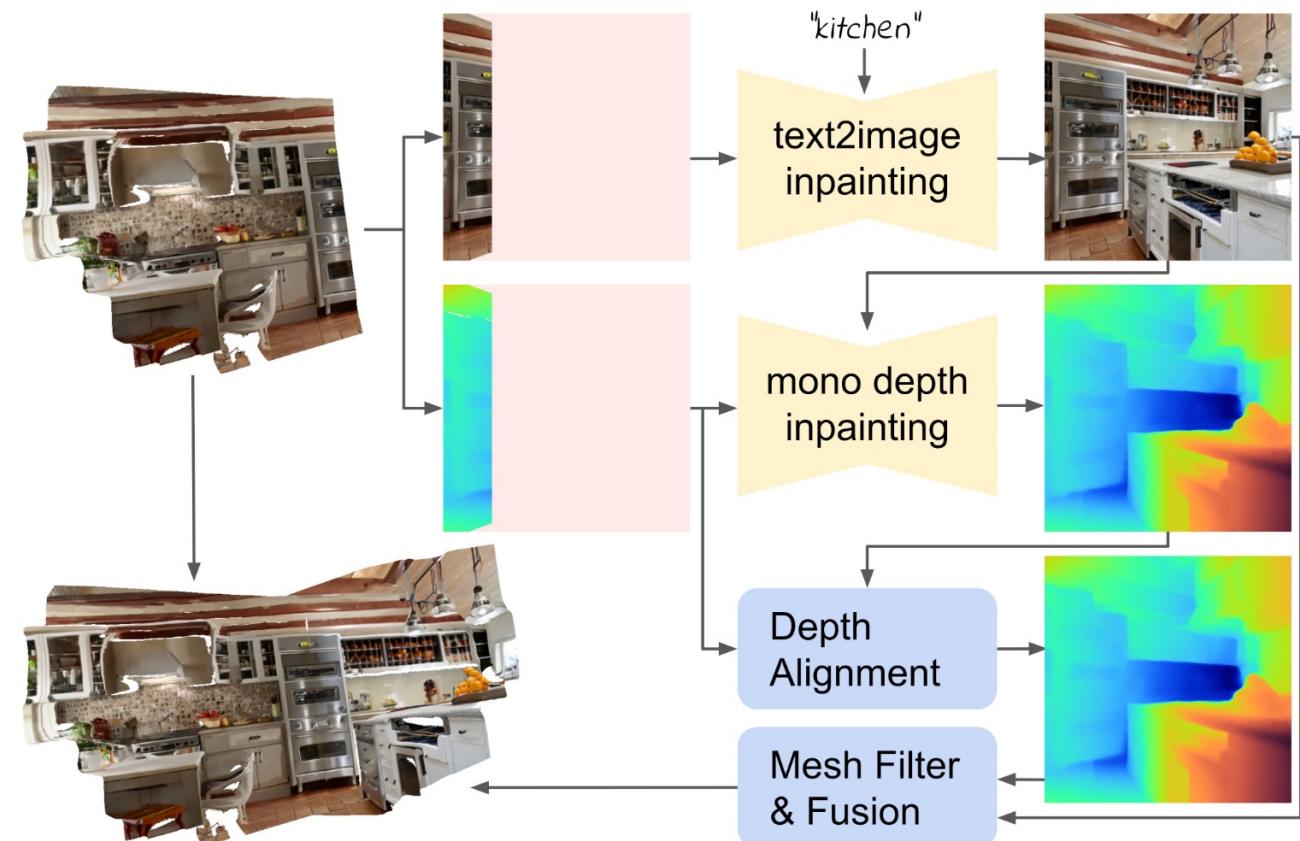
# Text2Room: Extracting Textured 3D Meshes from 2D Text-to-Image Models



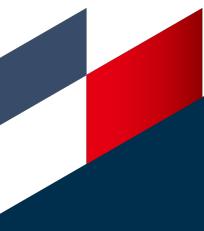
"Editorial Style Photo, Rustic Farmhouse, Living Room, Stone Fireplace, Wood, Leather, Wool"



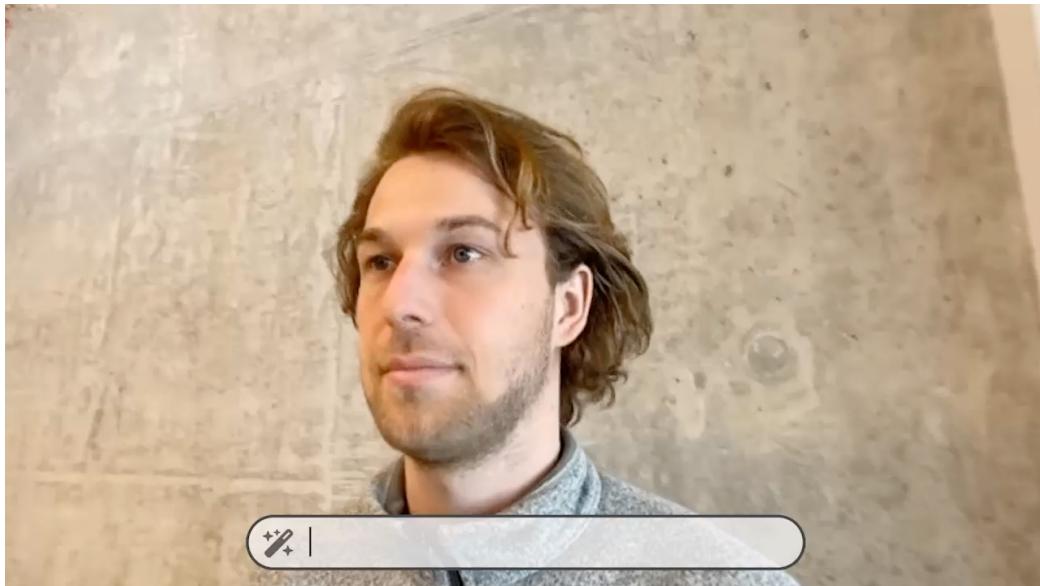
"A living room with a lit furnace, couch, and cozy curtains, bright lamps that make the room look well-lit."



Text Prompts -> 3D Scenes  
**Optimization based**



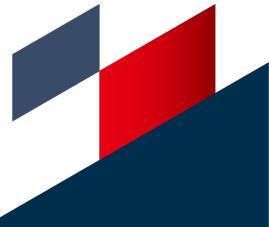
# Instruct-NeRF2NeRF: Editing 3D Scenes with Instructions



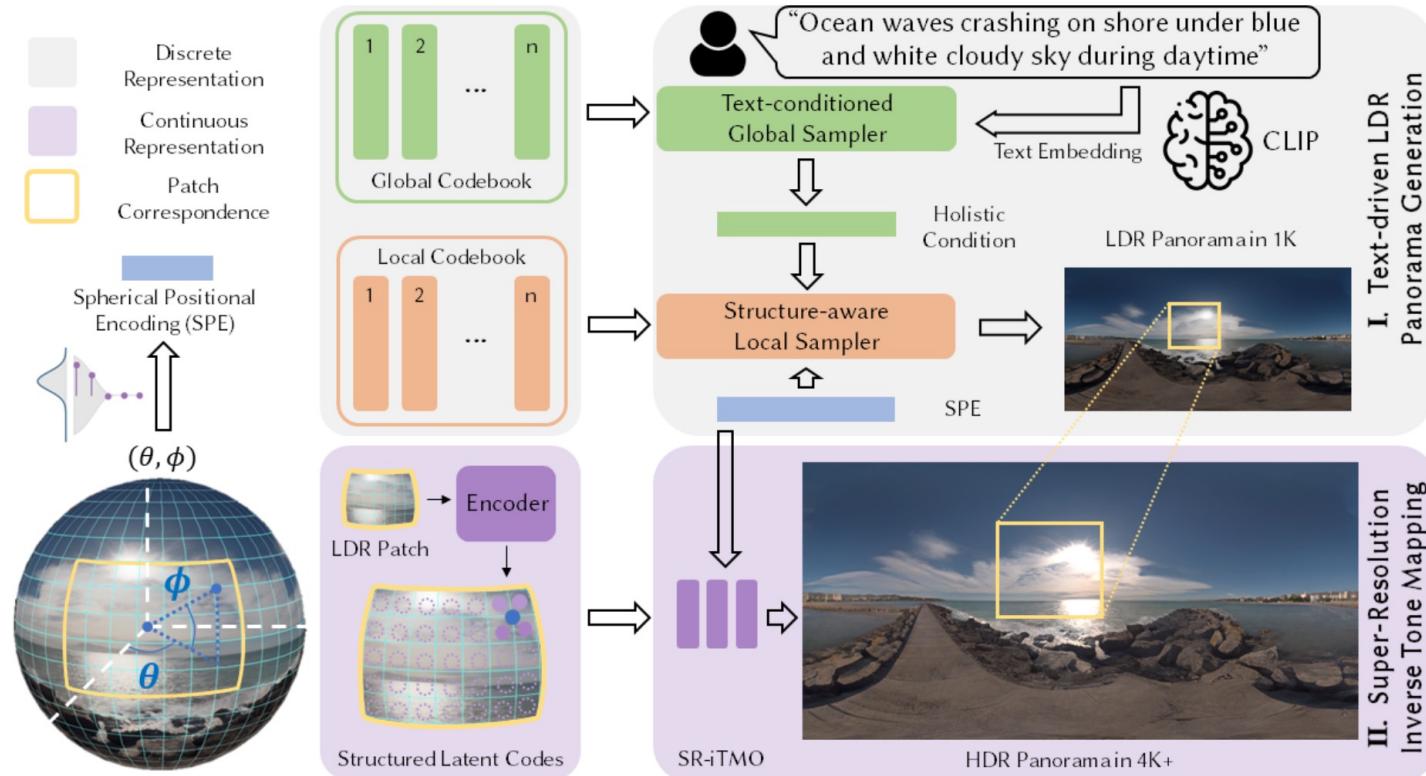
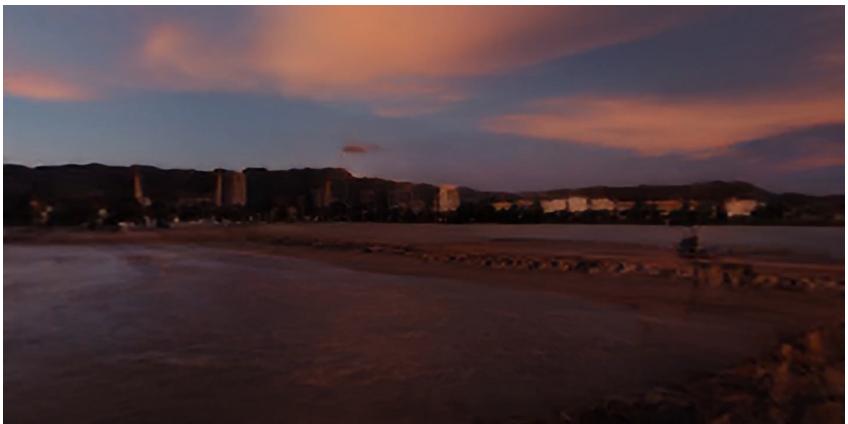
Edit 3D Scenes via Instructions



Text Prompts + Instruction Tuning -> 3D Scenes  
**Optimization based**



# Text2Light: Zero-shot Text-driven HDR Panorama Generation

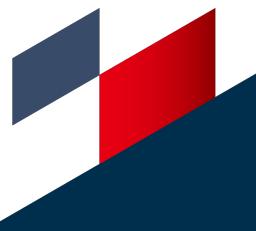


Text Prompts -> Panoramic 3D Scenes  
Feed Forward Generation



# Future work

- Faster Generation:
  - Per-scene-optimization is time consuming.
- Higher Quality:
  - The resolution is limited by the resolution of 2D model.
  - Super high guidance weight leads to over-saturation, over-smoothing results.
- More Efficient 3D Representation
  - Directly learning from 3D data is expensive.





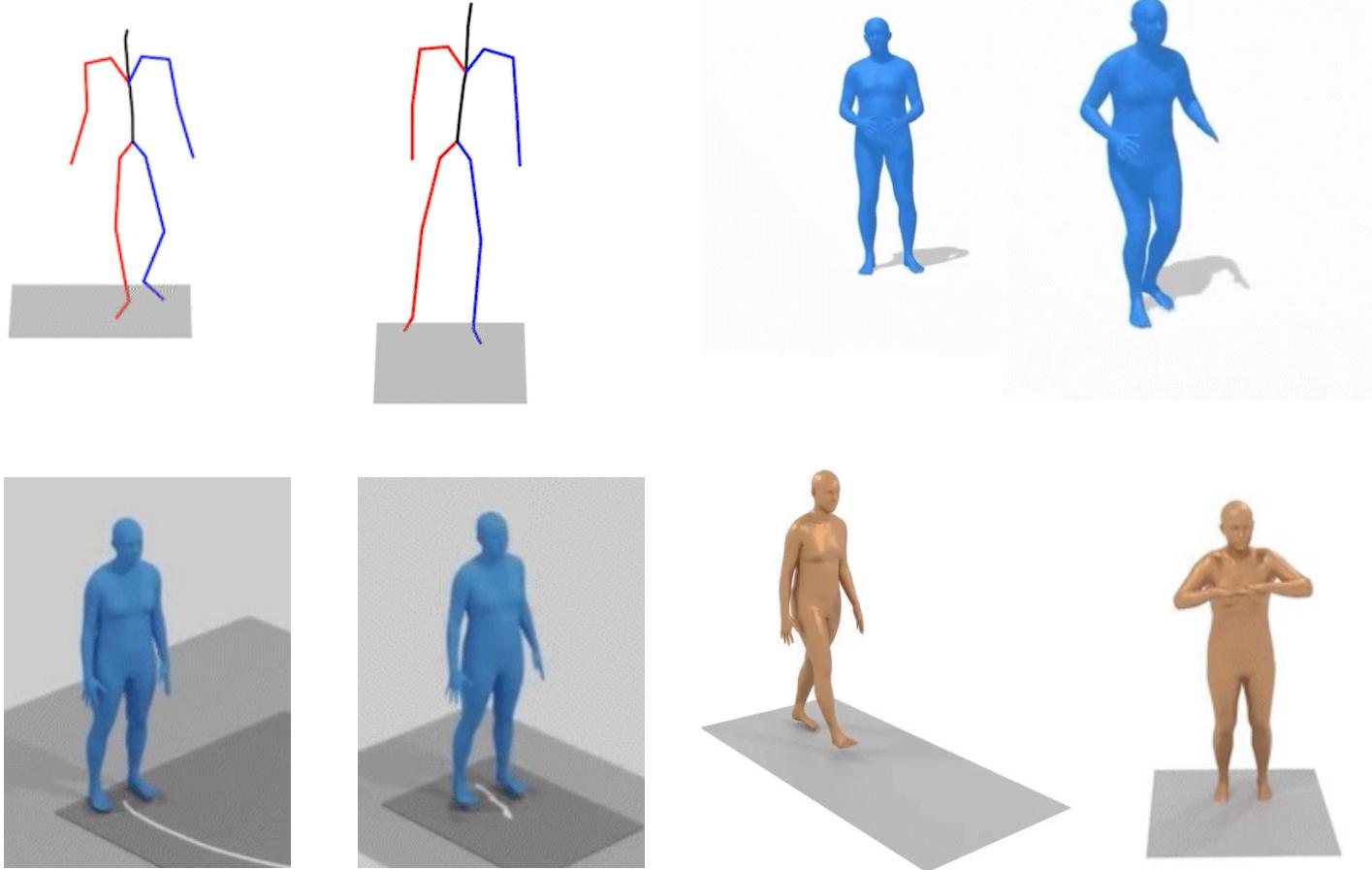
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# Text to 4D Generation



# Text-to-4D Generation

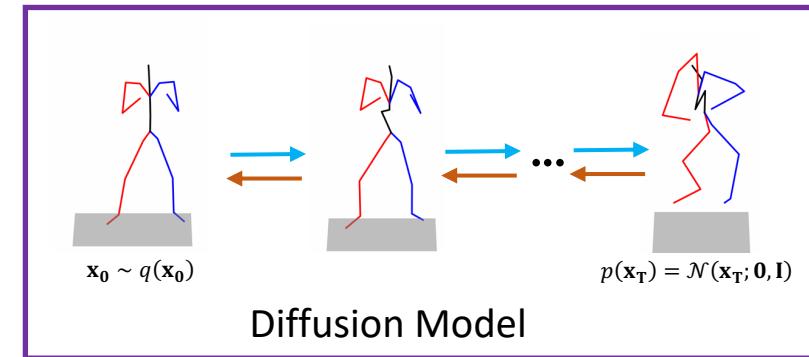
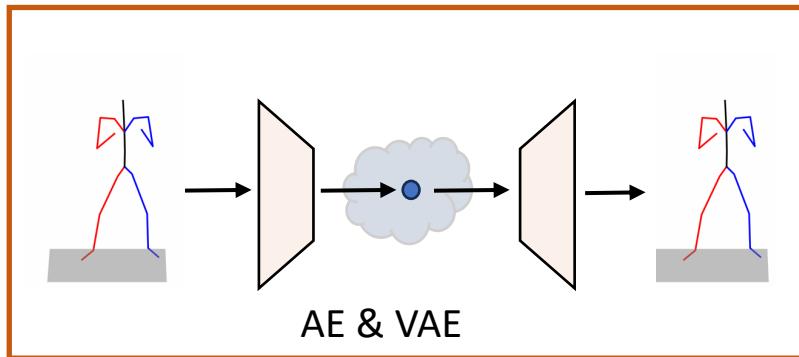
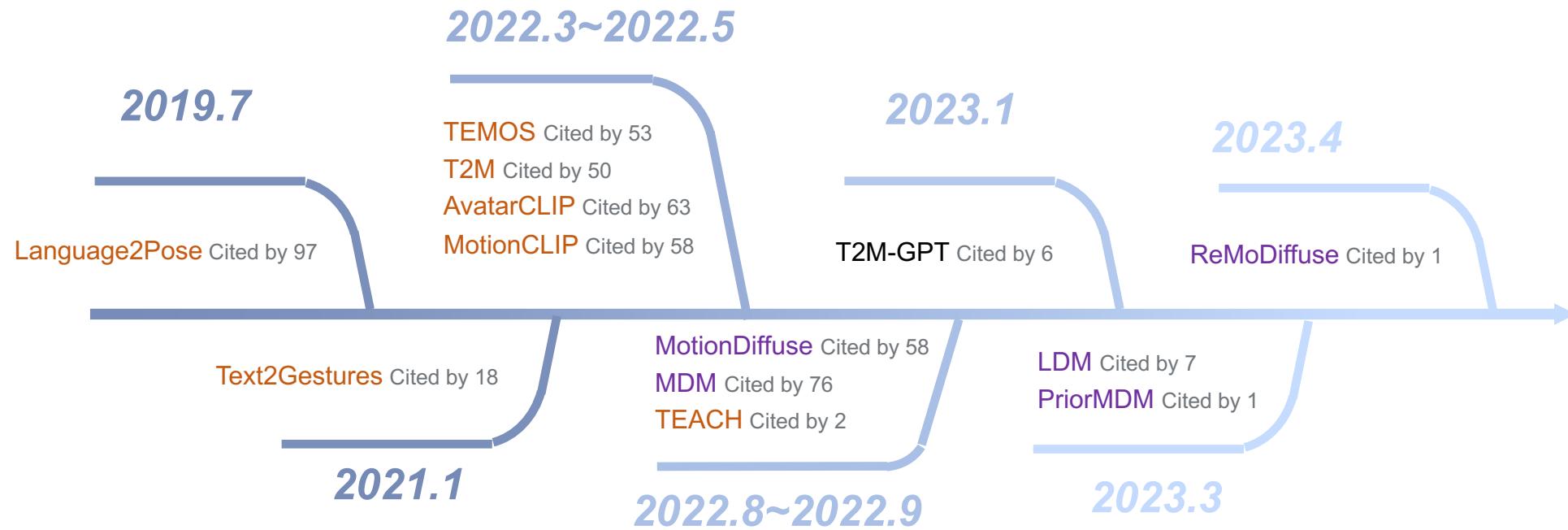


Motion generation

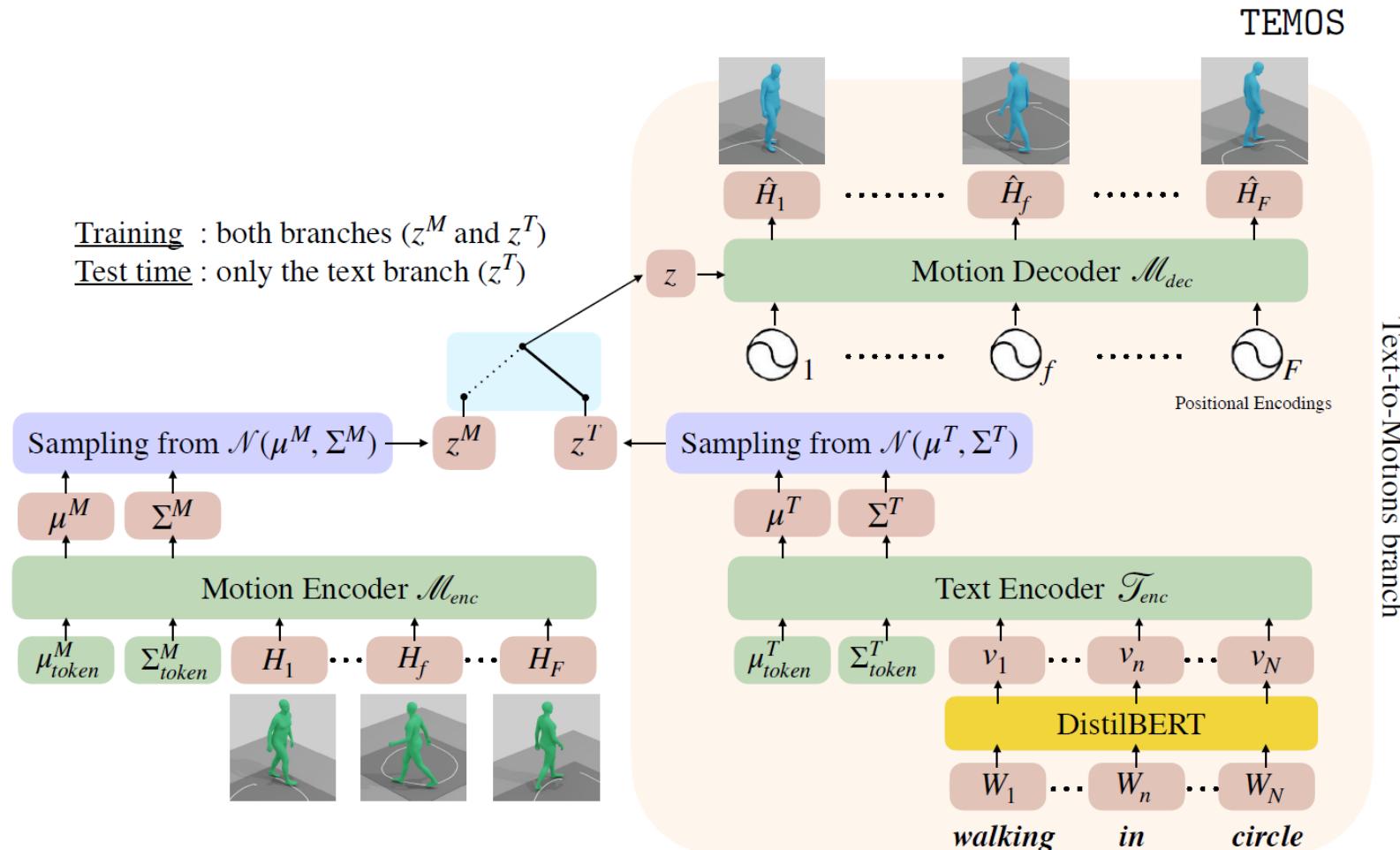


4D scene generation

# Human Motion Generation

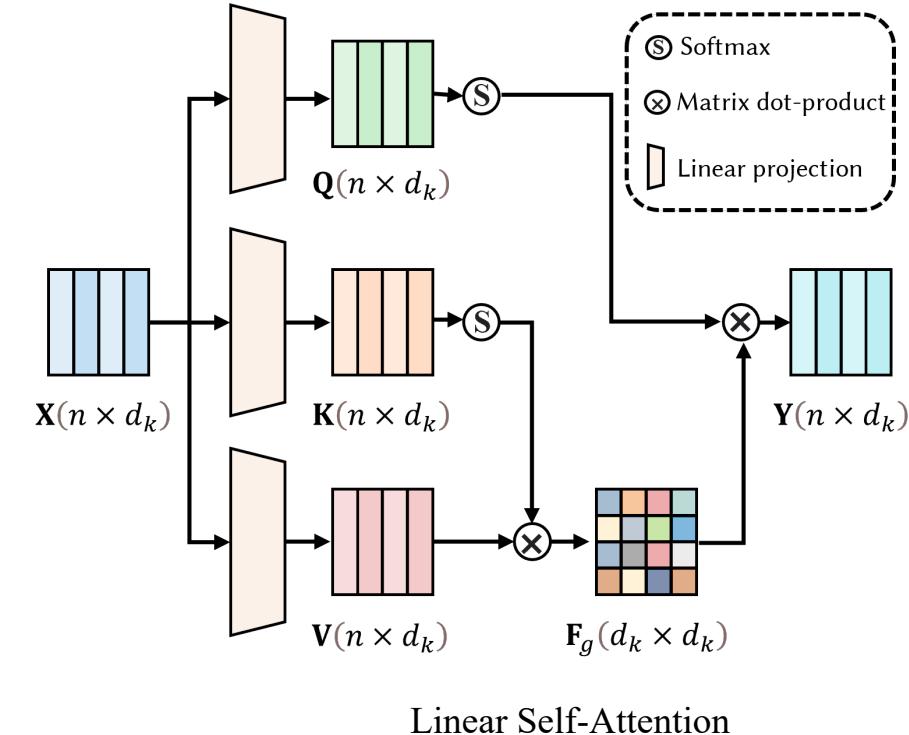
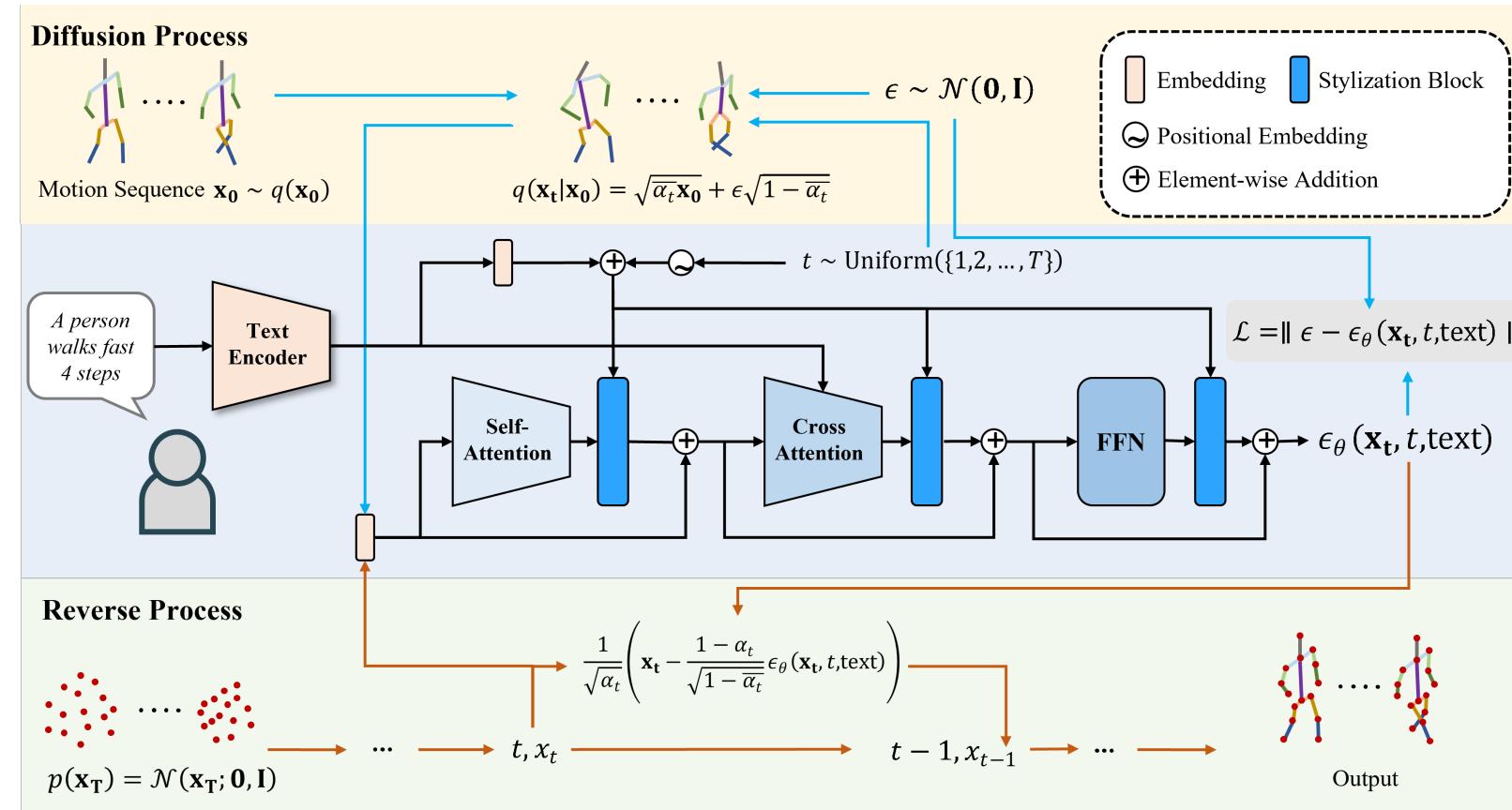


# TEMOS

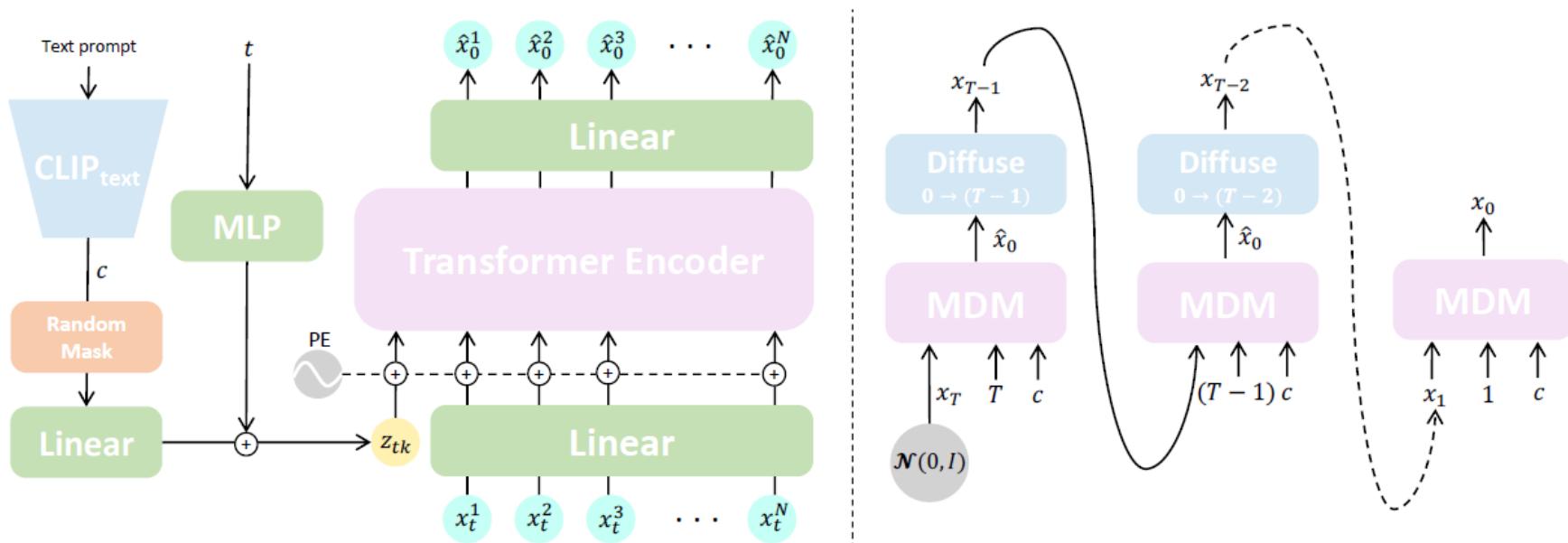


$$\mathcal{L} = L_1(H, \hat{H}^M) + L_1(H, \hat{H}^T) + KL(\phi^T, \phi^M) + KL(\phi^M, \phi^T) + KL(\phi^T, \psi) + KL(\phi^M, \psi)$$

# MotionDiffuse



# MDM



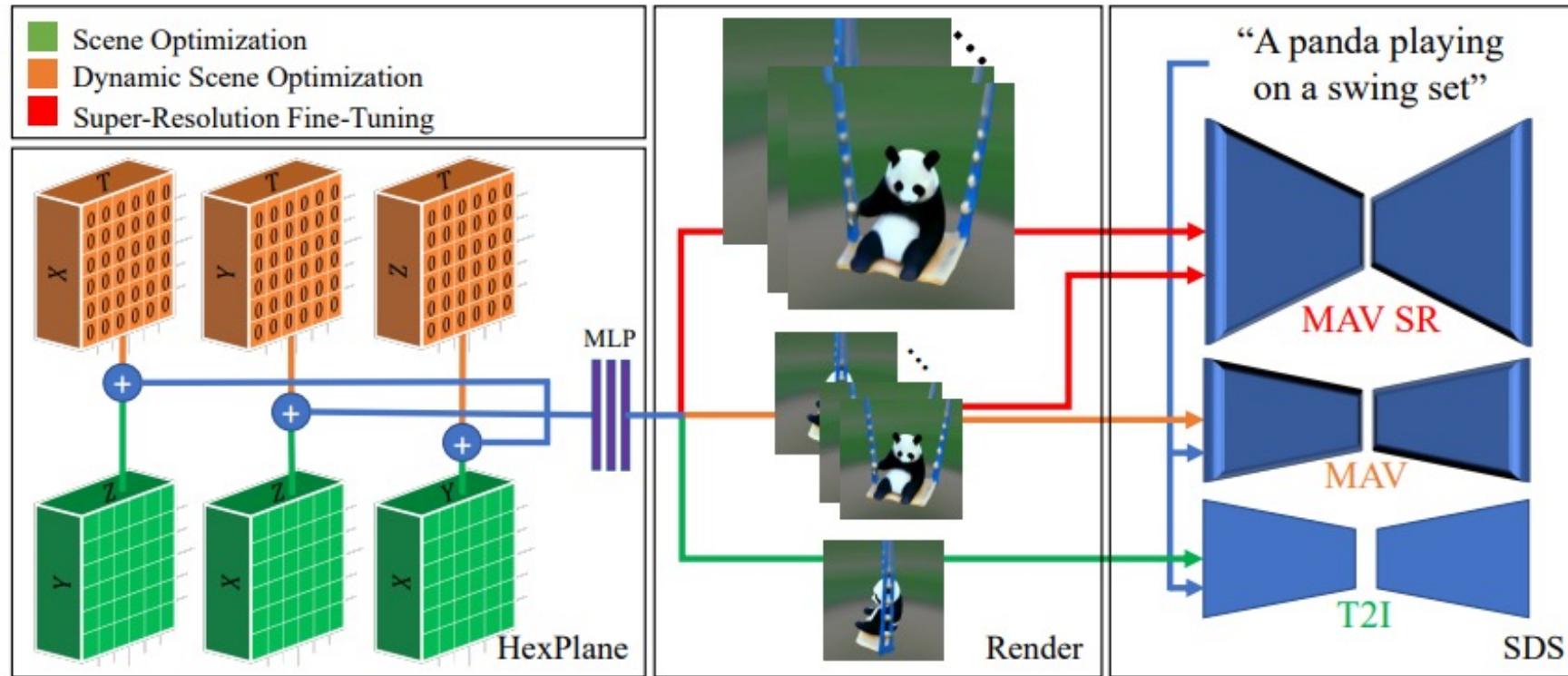
$$\mathcal{L}_{\text{pos}} = \frac{1}{N} \sum_{i=1}^N \|FK(x_0^i) - FK(\hat{x}_0^i)\|_2^2$$

## Geometric Loss

$$\mathcal{L}_{\text{foot}} = \frac{1}{N-1} \sum_{i=1}^{N-1} \|(FK(\hat{x}_0^{i+1}) - FK(\hat{x}_0^i)) \cdot f_i\|_2^2$$

$$\mathcal{L}_{\text{vel}} = \frac{1}{N-1} \sum_{i=1}^{N-1} \|(x_0^{i+1} - x_0^i) - (\hat{x}_0^{i+1} - \hat{x}_0^i)\|_2^2$$

# 4D Scene Generation – MAV3D



**4D Scene Representation**

$$[P_{xy}^{XYR_1} + P_{zt}^{ZTR_1}; P_{xz}^{XZR_2} + P_{yt}^{YTR_2}; P_{yz}^{YZR_3} + P_{yz}^{XTR_3}]$$

**Dynamic Scene Optimization**

$$\nabla_{\theta} \mathcal{L}_{SDS-T} = E_{\sigma, \epsilon} \left[ w(\sigma) (\hat{\epsilon}(V_{(\bar{\theta}, \sigma, \epsilon)} | y, \sigma) - \epsilon) \frac{\partial V_{\theta}}{\partial \theta} \right].$$

# Future Direction

- 1. More Customized Generation**
- 2. More Dynamic Modeling**
- 3. More Fine-Grained Alignment**

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