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Code for Project 2(Here just give the code for using triangle element, the code of using rectangle
element is similar)
function [ ErrorMax,Error2 ] = Project Parabolic2d Triangle( n,dt,T )
N=n+1;h=1/n;
xe=linspace(0,1,N);ye=xe;
b=[1,-2];F=zeros(N*N,1);
nn=zeros(N*N,1);%to record for each node, how many elements of the coefficient matrix are
not zero
for k=1:N*N
            i=mod(k-1,N)+1; j=floor((k-1)/N)+1;
            if(i\sim=1 \&\& i\sim=N \&\& j\sim=1 \&\& j\sim=N)
                        nn(k)=7;
%
                                    A(k,k)=4;A(k,k+1)=-1;A(k,k-1)=-1;A(k,k+N)=-1;A(k,k-N)=-1;
                                     B(k,k)=0.5*h*h;B(k,k+1)=h*h/12;B(k,k-1)=h*h/12;B(k,k+N)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/12;B(k,k-1)=h*h/
N)=h*h/12;B(k,k-N-1)=h*h/12;B(k,k+N+1)=h*h/12;
                                    C(k,k)=0; C(k,k+1)=h/3; C(k,k-1)=-h/3; C(k,k+N)=-h/6; C(k,k-N)=h/6; C(k,k-N-1)=-h/6; C(k,k-N-1
h/6; C(k,k+N+1)=h/6;
                                    D(k,k)=0;D(k,k+1)=-h/6;D(k,k-1)=h/6;D(k,k+N)=h/3;D(k,k-N)=-h/3;D(k,k-N-1)=-h/6;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k,k)=0;D(k
h/6;D(k,k+N+1)=h/6;
                        F(k) = f Parabolic(xe(i)+0.5*h,ye(j),dt)+f Parabolic(xe(i)+0.5*h,ye(j)+0.5*h,dt)
  +f Parabolic(xe(i),ye(j)+0.5*h,dt)+f Parabolic(xe(i)-0.5*h,ye(j),dt)+f Parabolic(xe(i)-0.5*h,ye(j)-
0.5*h,dt)+f Parabolic(xe(i),ye(j)-0.5*h,dt);
                       F(k)=h*h*F(k)/6; %To calculate the RHS integration
            else
                        nn(k)=1;
%
                                    B(k,k)=1;%to use the Dirichlet boundary condition at any time t
            end
end
pnn=zeros(N*N,1);pnn(1)=1;%to record the first position in coefficient matrix for each grid
ii=zeros(sum(nn),1);%to construct the sparse matrix in matlab
jj=zeros(sum(nn),1);%to construct the sparse matrix in matlab
value A=zeros(sum(nn),1); %to construct the sparse matrix A in matlab
value B=zeros(sum(nn),1);%to construct the sparse matrix A in matlab
value C=zeros(sum(nn),1);%to construct the sparse matrix A in matlab
value D=zeros(sum(nn),1);%to construct the sparse matrix A in matlab
for k=2:N*N
            pnn(k)=nn(k-1)+pnn(k-1);
end
for k=1:N*N
            if(nn(k)==1)
                       ii(pnn(k))=k;jj(pnn(k))=k;value\ B(pnn(k))=1;
                       for i=pnn(k):(pnn(k+1)-1)
                                   ii(i)=k;
                       end
                       jj(pnn(k))=k-N-1; jj(pnn(k)+1)=k-N; jj(pnn(k)+2)=k-1; jj(pnn(k)+3)=k; jj(pnn(k)+4)=k+1;
                       jj(pnn(k)+5)=k+N; jj(pnn(k)+6)=k+N+1;
                       value A(pnn(k))=0; value A(pnn(k)+1)=-1; value A(pnn(k)+2)=-1; value A(pnn(k)+2)=-1
  +3)=4; value A(pnn(k)+4)=-1;
                       value A(pnn(k)+5)=-1; value A(pnn(k)+6)=0;
                        value B(pnn(k))=h*h/12; value B(pnn(k)+1)=h*h/12; val
  +2)=h*h/12;value B(pnn(k)+3)=h*h/2;value B(pnn(k)+4)=h*h/12;
                       value B(pnn(k)+5)=h*h/12; value B(pnn(k)+6)=h*h/12;
                       value C(pnn(k))=-h/6; value C(pnn(k)+1)=h/6; value C(pnn(k)+2)=-h/3; value C(pnn(k)+2)=-
  +3)=0; value C(pnn(k)+4)=h/3;
                       value C(pnn(k)+5)=-h/6; value C(pnn(k)+6)=h/6;
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value D(pnn(k))=-h/6; value D(pnn(k)+1)=-h/3; value D(pnn(k)+2)=h/6; value D(pnn(k)+2)=h
+3)=0;value D(pnn(k)+4)=-h/6;
          value D(pnn(k)+5)=h/3; value D(pnn(k)+6)=h/6;
     end
end
A=sparse(ii,jj,value A,N*N,N*N);
B=sparse(ii,jj,value B,N*N,N*N);
C=sparse(ii,jj,value C,N*N,N*N);
D=sparse(ii,jj,value_D,N*N,N*N);
bb=zeros(N*N,1);%the source terms
for k=1:N*N
     i=mod(k-1,N)+1; j=floor((k-1)/N)+1;
     if(i\sim=1 \&\& i\sim=N \&\& i\sim=1 \&\& i\sim=N)
         bb(k)=u0 Parabolic(xe(i)+0.5*h,ye(j))+u0 Parabolic(xe(i)+0.5*h,ye(j)+0.5*h)
+u0 Parabolic(xe(i),ye(j)+0.5*h)+u0 Parabolic(xe(i)-0.5*h,ye(j))+u0 Parabolic(xe(i)-0.5*h,ye(j)-
0.5*h)+u0 Parabolic(xe(i),ye(j)-0.5*h);
         bb(k)=h*h*bb(k)/6;%To calculate the RHS integration
          bb(k)=u_Parabolic(xe(i),ye(j),0);
     end
u0=B\b;%u {h}^{0} is taken to be the interpolation of u {0}
E1=B+A*dt;%use (3.69) to calculate u1
E=B+2*dt*A/3;%use (3.68);E(k,k) need to equals B(k,k)=1
bb=dt*F+B*u0-dt*b(1)*C*u0-dt*b(2)*D*u0;%use to calculate u1
for k=1:N*N
     i=mod(k-1,N)+1; i=floor((k-1)/N)+1;
     if(i==1 || i==N || i==1 || i==N)
          bb(k)=u Parabolic( xe(i),ye(j),dt );
     end
end
u1=E1\b;
while((iter-1)*dt<T) %Pay attention to iter! If use 'iter*dt<T', just calculate to T-dt, not T!
     F=zeros(N*N,1);
     for k=1:N*N
         i=mod(k-1,N)+1; j=floor((k-1)/N)+1;
         if(i\sim=1 \&\& i\sim=N \&\& j\sim=1 \&\& j\sim=N)
          F(k)=f Parabolic(xe(i)+0.5*h,ye(j),dt*iter)+f Parabolic(xe(i)+0.5*h,ye(j)+0.5*h,dt*iter)
+f Parabolic(xe(i),ye(j)+0.5*h,dt*iter)+f Parabolic(xe(i)-0.5*h,ye(j),dt*iter)+f Parabolic(xe(i)-
0.5*h, ve(i)-0.5*h, dt*iter)+f Parabolic(xe(i), ve(i)-0.5*h, dt*iter);
         F(k)=h*h*F(k)/6; %To calculate the RHS integration
         end
     end
     bb=2*dt*F+4*B*u1-B*u0-2*dt*b(1)*C*(2*u1-u0)-2*dt*b(2)*D*(2*u1-u0);
     bb=bb/3:
     for k=1:N*N
         i=mod(k-1,N)+1; j=floor((k-1)/N)+1;
         if(i==1 || i==N || j==1 || j==N)
               bb(k)=u_Parabolic( xe(i),ye(j),dt*iter );
         end
     end
     u2=E\b;
     u0=u1;u1=u2;
     iter=iter+1;
end
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u exact=zeros(N*N,1);
for k=1:N*N
                 i=mod(k-1,N)+1; j=floor((k-1)/N)+1;
                  u exact(k)=u Parabolic( xe(i),ye(j),dt*(iter-1) );
end
 ErrorMax=norm(u2-u_exact,inf);
 Error2=norm(u2-u_exact,2)*h;
function u = u Parabolic( x,y,t )
u = cos(t).*cos(\overline{6}*x).*sin(6*y).*exp(x-y);
function u = u0 Parabolic( x,y )
u = \cos(6*x).*\sin(6*y).*\exp(x-y);
function f = f_Parabolic( x,y,t )
 diff(\cos(t)*\cos(6*x)*\sin(6*y)*\exp(x-y),t,1)+diff(\cos(t)*\cos(6*x)*\sin(6*y)*\exp(x-y),x,1)-diff(\cos(t)*\cos(6*x)*\sin(6*y)*\exp(x-y),x,1)-diff(\cos(t)*\cos(6*x)*\sin(6*y)*\exp(x-y),x,1)-diff(\cos(t)*\cos(6*x)*\sin(6*y)*\exp(x-y),x,1)-diff(\cos(t)*\cos(6*x)*\sin(6*y)*\exp(x-y),x,1)-diff(\cos(t)*\cos(6*x)*\sin(6*y)*\exp(x-y),x,1)-diff(\cos(t)*\cos(6*x)*\sin(6*y)*\exp(x-y),x,1)-diff(\cos(t)*\cos(6*x)*\sin(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x)*\sin(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x)*\sin(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(\cos(t)*\cos(6*x))*exp(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-y),x,1)-diff(x-x),x,1)-di
 2*diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,1)-(diff(cos(t)*cos(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6*x)*sin(6
y),x,2)+diff(cos(t)*cos(6*x)*sin(6*y)*exp(x-y),y,2))
 f=73*cos(6*x).*sin(6*y).*exp(x - y).*cos(t) - cos(6*x).*sin(6*y).*exp(x - y).*sin(t) +
 6*sin(6*x).*sin(6*y).*exp(x - y).*cos(t);
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