

# Assignment 1: Imitation Learning

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## 1 Behavioral Cloning (9.75 pt)

### 1.1 Part 2 (1.5 pt)

Rounded to two decimals.

Table 1: Report your result in this table.

Metric/Env	Ant-v2	Humanoid-v2	Walker2d-v2	Hopper-v2	HalfCheetah-v2
Mean	4713.65	10344.52	5566.85	3772.67	4205.78
Std.	12.20	20.98	9.24	1.95	83.04

### 1.2 Part 3 (5.25 pt)

Rounded to two decimals.

Hyperparameters remains the same for both environment: ep\_len: 1000, num\_agent\_train\_steps\_per\_iter: 1000, batch\_size: 1000, train\_batch\_size: 100, eval\_batch\_size: 5000, n\_layers: 2, hidden\_layer\_size: 64, learning\_rate: 5e-3.

Table 2: Fill your results in this table.

Env	Ant-v2		Humanoid-v2	
Metric	Mean	Std.	Mean	Std.
Expert	4713.65	12.20	10344.52	20.98
BC	4683.13	83.31	276.18	27.72

### 1.3 Part 4 (3 pt)

Rounded to two decimals.

I choose Humanoid-v2 environment as my experiment environment.

I modified three parameters, train\_batch\_size: 100 -> 500, n\_layers: 2 -> 5, size: 64 -> 128.

The rationale behind this is to use a deeper and wider neural network to boost the performance. We can see average, max, and min returns all improved. However, the drawback of a deeper network may cause overfitting. The effect of overfitting is shown as the increase in StdReturn.

Table 3: Report your result in this table.

Metric/Hyperparameters	Original	Tuned
AverageReturn	276.18	301.42
StdReturn	27.72	48.58
MaxReturn	375.52	456.49
MinReturn	189.61	237.89
AverageEpLen	51.93	56.06

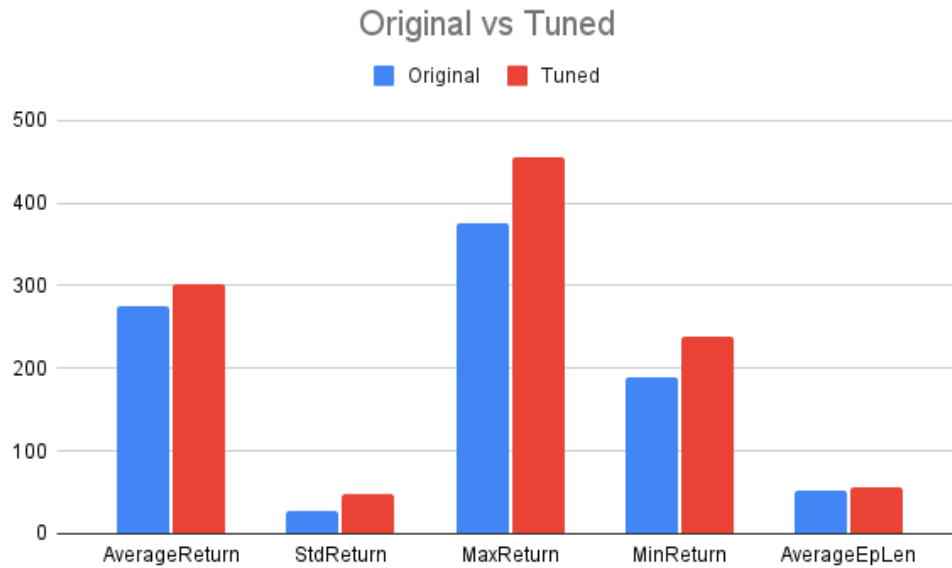


Figure 1: BC agent's performance varies with the value of `n_layers`, `train_batch_size`, and size parameters in Humanoid-v2 environment.

## 2 DAgger (5.25 pt)

### 2.1 Part 2 (5.25 pt)

For the Ant-v2 environment, I only trained the DAgger for 10 iters, and it's already at the same performance as the expert. However, for the Humanoid-v2 environment, I increased `n_layers` to 5, hidden neurons to size 128 to capture more features, increased iters to 100, and increased `train_batch_size` to 1000 to boost the efficiency in training.

Table 4: Fill your results in this table.

Env	Ant-v2		Humanoid-v2	
Metric	Mean	Std.	Mean	Std.
Expert	4713.65	12.20	10344.52	20.98
DAgger	4827.50	48.59	10506.08	48.08

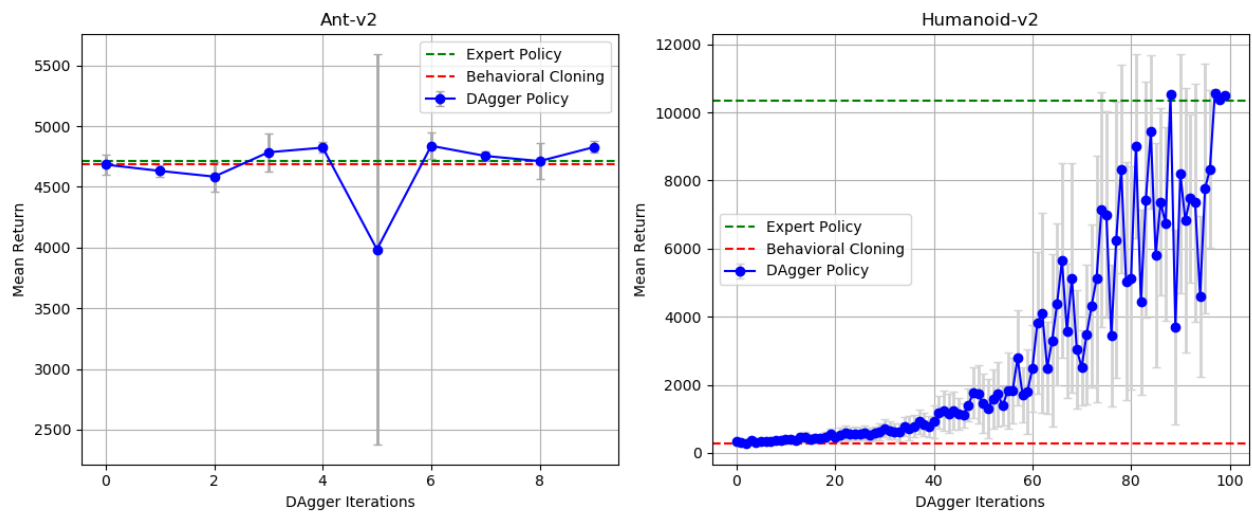


Figure 2: Learning curve, plotting the number of DAGger iterations vs. the policy's mean return, with error bars to show the standard deviation.