

1.1.3

$$Av = \lambda v$$

$$(1) v^T A v = v^T \lambda v = \lambda v^T v = \lambda v^2 \quad \forall v \neq 0$$

$$\lambda_i(A) > 0 \Rightarrow \lambda v^2 > 0 \Rightarrow \text{from (1)} v^T A v > 0 \quad \forall v \neq 0$$

$$v^T A v > 0 \Rightarrow \text{from (1)} \lambda v^2 > 0 \Rightarrow \lambda_i(A) > 0 \quad \forall v \neq 0$$

1.2.1

Prove that:

1. The mean of $\mathcal{Z} = \{z_i\}_{i=1}^N$ is zero, that is, $\mu_z = \frac{1}{N} \sum_{i=1}^N z_i = 0$.
2. The covariance of \mathcal{Z} is diagonal, that is Σ_z is diagonal.
3. $\|x_i - x_j\|_2 = \|z_i - z_j\|_2$ for all i and j .

#1.

$$\frac{1}{N} \sum_{i=1}^N z_i = 0 = \frac{1}{N} \sum_{i=1}^N U^T (x_i - \mu_x) = \frac{1}{N} U^T \sum_{i=1}^N (x_i - \mu_x) = 0$$

$$\sum_{i=1}^N (x_i - \mu_x) = 0$$

#2.

$$\Sigma_z = \mathbb{E}(Z Z^T) = \mathbb{E}((U^T (x_i - \mu_i))(U^T (x_i - \mu_i))^T) = \mathbb{E}(Z Z^T) = \mathbb{E}((U^T (x_i - \mu_i))(x_i - \mu_i)^T U) = \mathbb{E}(Z Z^T) = U^T \mathbb{E}((x_i - \mu_i)(x_i - \mu_i)^T) U$$

$$= U^T \Sigma_x U = U^T U \Lambda U^T U = \Lambda$$

Λ is diagonal and $\Sigma_z = \Lambda \Rightarrow \Sigma_z$ is diagonal

#3.

$$\|z_i - z_j\|_2 = \|U^T (x_i - \mu_x) - U^T (x_j - \mu_x)\|_2 = \|(U^T x_i - U^T \mu_x - U^T x_j + U^T \mu_x)\|_2 = \|(U^T x_i - U^T x_j)\|_2 = \|x_i - x_j\|_2$$

1.2.7

We'll use the hint and plug $M = BC$ into the equivalent unconstrained problem while:

$$M \in \mathbb{R}^{D \times N} \text{ with rank}(M) = d$$

$$(a) B \in \mathbb{R}^{D \times d}$$

$$(b) C \in \mathbb{R}^{d \times N}$$

$$\text{So, } \min_{M \in \mathbb{R}^{D \times N}} \|A - M\|_F^2 = \min_{M \in \mathbb{R}^{D \times N}} \|A - BC\|_F^2$$

Now, as we learnt in class, since a solution is up to some matrix Y :

$$BC = BYY^{-1}C$$

so we add orthogonality constraint as follow:

$$\begin{cases} \min_{B_d \in \mathbb{R}^{d \times d}, C \in \mathbb{R}^{d \times N}} \|A - B_d C\|_F^2 \\ \text{s.t. } B_d^T B_d = I_d \end{cases}$$

we assume that is B sem-orthogonal matrix

So now we want to find the optimal C as a function of A and B . We'll calculate the gradient:

$$\nabla_C \|A - B_d C\|_F^2 = 0$$

$$-2B_d^T (A - B_d C) = 0$$

$$B_d^T A - \underbrace{B_d^T B_d}_{=I_d} C = 0$$

$$C = B_d^T A$$

and in truncated form we'll define $B = B_d^T$ and $C^T = C$ and get: $A = B \Sigma C^T$

$$B = ?$$

$$+1$$

$$B = ? \quad (+1)$$

$$M = ?$$

2.1.3

Show that if k can be written as an inner product, that is

$$k(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle$$

for some ϕ , then, the matrix defined by:

$$K_x[i, j] = k(x_i, x_j)$$

is an SPSP matrix, namely, $K_x \geq 0$

$K_x[i, j] = k(x_i, x_j)$ is SPSP matrix because K_x is symmetric $K_x[i, j] = k(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \langle \phi(x_j), \phi(x_i) \rangle = k(x_j, x_i) = K_x[j, i]$

we will show that each $K_x[i, j] \geq 0$

$K_x[i, j] = k(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi^T \phi \geq 0 \Rightarrow K_x[i, j]$ is SPSP matrix

2.1.5

$$k(x_i, x_j) := \langle \phi(x_i), \phi(x_j) \rangle$$

for some ϕ .

• Let:

$$\tilde{k}(x_i, x_j) := \langle \phi(x_i) - \mu_\phi, \phi(x_j) - \mu_\phi \rangle$$

be the centered version, where:

$$\mu_\phi = \frac{1}{N} \sum_{i=1}^N \phi(x_i)$$

$$\begin{aligned} \tilde{k}(x_i, x_j) &:= \langle \phi(x_i) - \mu_\phi, \phi(x_j) - \mu_\phi \rangle = \langle \phi(x_i), \phi(x_j) \rangle - \langle \phi(x_i), \mu_\phi \rangle - \langle \phi(x_j), \mu_\phi \rangle + \langle \mu_\phi, \mu_\phi \rangle = k(x_i, x_j) \\ &- \langle \phi(x_i), \frac{1}{N} \sum_{j=1}^N \phi(x_j) \rangle - \langle \phi(x_j), \frac{1}{N} \sum_{i=1}^N \phi(x_i) \rangle + \langle \frac{1}{N} \sum_{i=1}^N \phi(x_i), \frac{1}{N} \sum_{j=1}^N \phi(x_j) \rangle = k(x_i, x_j) - \frac{1}{N} \sum_{j=1}^N \langle \phi(x_i), \phi(x_j) \rangle - \frac{1}{N} \\ &\sum_{i=1}^N \langle \phi(x_j), \phi(x_i) \rangle + \frac{1}{N^2} \sum_{j=1}^N \sum_{i=1}^N \langle \phi(x_i), \phi(x_j) \rangle = k(x_i, x_j) - \frac{1}{N} \sum_{j=1}^N k(x_i, x_j) - \frac{1}{N} \sum_{i=1}^N k(x_i, x_j) + \frac{1}{N^2} \sum_{j=1}^N \sum_{i=1}^N k(x_i, x_j) \end{aligned}$$

2.1.6

DisProve

if every $K[i, j] = 3$ then the mean of the columns is 3 and the mean of the rows is 3 and after we subtract the mean we can see that not every $k[i, j] \leq 0$ and that why the matrix is not SPD matrix.

2.1.7

$$\phi = \phi(X)$$

$$K_x^* = \phi^T \phi$$

$$\widetilde{\Phi}^T \bar{\phi}^* \mapsto \bar{k}x = J(kx - \frac{1}{N} K_x \mathbf{1}_N)$$

$$Z = \Sigma_d^{-1} V_d^T \bar{\phi}^* \phi$$

2.1.8

We know that:

The training encoding $Z = \Sigma_d V_d^T$

The OOSE $Z^* = \Sigma_d^{-1} V_d^T \tilde{k}_x$

Where

$$\tilde{k}_x = V_d \Sigma_d^2 V_d^T$$

and

$$V^T V = I$$

Therefore:

X^* is a subset of X
 (-1)

$$\begin{aligned} Z^* &= \\ \Sigma_d^{-1} V_d^T \tilde{k}_x &= \\ \Sigma_d^{-1} V^T V \Sigma_d^2 V_d^T &= \\ \Sigma_d^{-1} \Sigma_d^2 V_d^T &= \\ \Sigma_d V_d^T &= Z \end{aligned}$$

```

24 def test_d_pca(d):
25
26     count = 0
27     for i in range(10):
28         x = mX[:, np.where(vY == i)[0]]
29         my_pca = PCA(d)
30         my_pca.fit(x)
31         mZ = my_pca.encode(x)
32         mHatX = my_pca.decode(mZ)
33         vIdx[i] = count
34         if i == 0:
35             result = mHatX
36         else:
37             result = np.column_stack((result, mHatX))
38         count += mHatX.shape[1]
39
40     plot_mX(result)
41
42     for d in range(20, 160, 20):
43
44         test_d_pca(d)
45
46     plt.tight_layout()
47     plt.show()
48
49     mX.shape, vY.shape
50

```

$(+8)$



```

1 import scipy.stats as st
2 from scipy.spatial.distance import cdist
3
4 def k_1(x1, x2):
5
6     return x1.T @ x2
7
8 def k_2(x1, x2):
9     p = 2
10    return np.power(1+ x1.T @ x2, p)
11
12 def k_3(x1, x2):
13
14    dist_matrix = cdist(x1.T, x2.T)
15    sigma = np.median(dist_matrix)
16    b = 2*sigma**2
17    return np.exp(-dist_matrix/b)

```

1. sigma must be a fixed value
2. dist_matrix**2

-2

a