1 Matlab correction

1.1 Simulation of a 2-D Boolean model

The process for simulating the proposed Boolean model of 2-D disks consists in four steps:

- generate the random number of points (by using the intensity parameter of the Poisson distribution).
 - In order to avoid edge effects, one consider a larger window than the observation window to generate the disks. Indeed, a germ outside the observation window can generate a disk that intersects the observation window.
- generate the random locations of the germs (random coordinates from a uniform distribution)
- generate the random size of the disks (random radius from a probability distribution)
- generate the union of disks (by using the dilation of the germs with a disk of the corresponding radius as structuring element)

Here is the global function for generating such a Boolean model as a binary image:

```
1 function Z = Boolean Model (Wsize, Gamma, Radius Param)
 % Generates a boolean model of disks in 2D
3 % The number of disks is chosen according to a Poisson law of parameter
 % lambda = Gamma*areaW, where areaW is the area of the window defined by
_{5} % Wsize.
7 % Parameters:
 \% Wsize: size of the window (2x1 array)
9 % Gamma: Parameter to get the density for the Poisson law
 % RadiusParam: [min, max] valus of radii
11 % returns: boolean array of size Wsize(1)xWsize(2)
13 edgeEffect = 2*max(RadiusParam) + 100;
  WsizeExtended = [Wsize(1) + 2*edgeEffect, Wsize(2) + 2*edgeEffect];
15 % nb of points
  nf = WsizeExtended(1);
nc = WsizeExtended(2);
 areaW = nf*nc;
19 nbPoints = poissrnd(Gamma*areaW);
 % germs
x = randi(nf, nbPoints);
 y = randi(nc, nbPoints);
23 % grains
  r = randi(RadiusParam, nbPoints);
Z = false(nf,nc);
27 % union of grains
  [X, Y] = meshgrid(1:nf, 1:nc);
_{29} for i = 1:nbPoints
```

```
Z = Z | ((X-x(i)).^2+(Y-y(i)).^2)<= r(i)^2;

and end Z = Z(edgeEffect+1:edgeEffect+Wsize(1),edgeEffect+1:edgeEffect+Wsize(2));
```

When executing this function with the following parameters:

We get a realization of this Boolean model as a binary image in Fig.1.

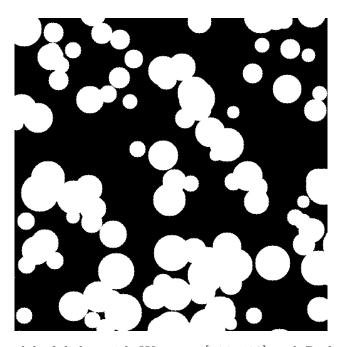


Figure 1: Boolean model of disks, with Wsize = [500, 500] and RadiusParam = [10, 30].

1.2 Geometrical characterization of a 2-D Boolean model

We can use the following function to compute the Minkowski functionals of the Boolean model (see the tutorial on Integral Geometry):

```
function [Area, Perimeter, EulerNb4, EulerNb8] = MinkowskiFunctionals(X)
 % Neighborhood configuration
_{4} F = [0 \ 0 \ 0; \ 0 \ 1 \ 4; \ 0 \ 2 \ 8];
 XF = conv2(double(X), F, 'same');
_{6} h = hist(XF(:), 16);
 %bar (0:15,h);
 % Computation of the functionals
f_{\text{intra}} = [0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1];
  e_{intra} = [0 \ 2 \ 1 \ 2 \ 1 \ 2 \ 2 \ 2 \ 0 \ 2 \ 1 \ 2 \ 1 \ 2 \ 2 \ 2];
EulerNb8 = sum(h.*v_intra - h.*e_intra + h.*f_intra);
e_{inter} = [0 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0 \ 2 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0 \ 2];
v_{inter} = [0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1];
  EulerNb4 = sum(h.*v_inter - h.*e_inter + h.*f_inter);
18 Area = sum(h.*f_intra);
  Perimeter = sum(-4*h.*f_intra + 2*h.*e_intra);
```

So we can estimate the Minkowski densites on different realizations of the Boolean model:

```
1 % use of the Tutorial "Integral Geometry"
% computation of the Minkowski densities on different realizations
3 nbRealizations = 100;
W = zeros(nbRealizations ,3);
5 areaWsize = Wsize(1)*Wsize(2);
for i = 1:nbRealizations
7 [Z] = BooleanModel(Wsize, Gamma, RadiusParam);
    [area, per, ~, chi8] = MinkowskiFunctionals(Z);
9 W(i,:) = [area, per/2, chi8*pi]/areaWsize;
    clear area per chi4 chi8;
11 end
```

Therefater, we can compare the estimated Minkowski mean densities of the Boolean model with the theoretical ones (by using the known parameters of the different probability distributions of this Boolean model):

```
1 % mean densisties (estimated)
W = mean(W,1);
3
% mean densities (theoretical) by using Miles formulas
5 rMean = (RadiusParam(1)+RadiusParam(2))/2;
AreaMean = pi*rMean^2;
7 PerMean = 2*pi*rMean;
```

```
WX = Gamma * [AreaMean, PerMean/2, pi];

W.th(1) = 1 - exp(-WX(1));

W.th(2) = exp(-WX(1)) * WX(2);

W.th(3) = exp(-WX(1)) * (WX(3)-WX(2)^2);

% comparison
error_W0 = abs(W(1)-W.th(1))/W.th(1)
error_W1 = abs(W(2)-W.th(2))/W.th(2)
error_W2 = abs(W(3)-W.th(3))/W.th(3)
```

Here are the results for 100 specific realizations:

```
Command window

errorW0 = 0.0701
errorW1 = 0.2437
errorW2 = 0.4396
```

The errors can be large due to the biais estimation of the Minkowski densities within an observation window (specifically for the perimeter and the Euler number). But you can use unbiased estimators which can be found in the literature.

Note that the Miles formulas can be inverted to estimate the Minkowski functionals of the typocal grain from the Minkowski mean densities of the Boolean model.