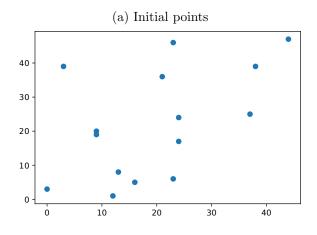
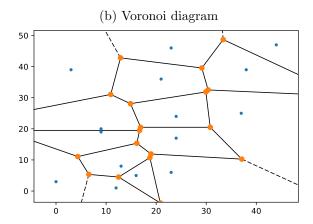
Tutorial: Voronoï Diagrams and Delaunay Triangulation

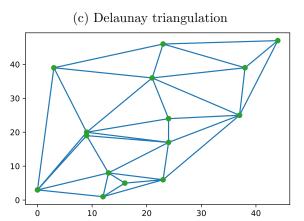
This tutorial aims to spatially characterize a spatial point pattern by using some tools of computational geometry: the Voronoi diagram, the Delaunay triangulation and the Minimum Spanning Tree (MST), illustrated in Fig.1.

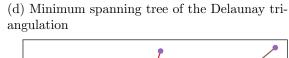
For biomedical issues, this point pattern analysis can help the biologists to classify different populations of cells.

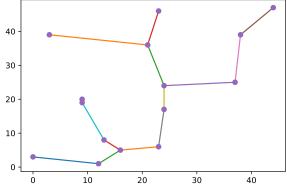
Figure 1: Random point pattern and some geometrical structures used to characterize it.











Voronoi and Delaunay 1

A voronoi diagram, in 2D, is defined as a partition of the plane into cells R_k according to a distance function d and a set of seeds (germs) P_k .

$$R_k = \{x \in X \mid d(x, P_k) \le d(x, P_j) \text{ for all } j \ne k\}$$

The Delaunay graph is the dual graph that links the germs of the neighborhing Voronoi cells.

1.1 Random tesselation

Follow these instructions to generate a random tesselation:



- 1. Generate a random point process.
- 2. Determine the Delaunay triangulation.
- 3. Determine the Voronoi diagram.



Use the MATLAB® functions delaunavTriangulation and voronoiDiagram.



Use the python functions Delaunay and Voronoi from scipy. spatial.

Characterization of the Voronoi diagram 1.2

This basic approach characterizes the set of the cells. With the help of the Voronoi diagram, it is possible to make the two following measurements, Area Disorder (AD) and Round Factor Homogeneity (RFH), defined by:

$$AD = 1 - \frac{1}{1 + \frac{\sigma(A)}{\mu(A)}}$$

$$RFH = 1 - \frac{\sigma(RF)}{\mu(RF)}$$
(2)

$$RFH = 1 - \frac{\sigma(RF)}{\mu(RF)} \tag{2}$$

where A and RF are calculated on the regions R_k of the Voronoi diagram. μ and σ are the mean and standard deviation of the areas of the Voronoi cells. The circularity (RF) of a polygon can be defined as the ratio between its area and the area of the disk of an equivalent perimeter.



• Code these measurements with the following prototypes:



```
\begin{array}{l} \textbf{function} \  \  \, ad = AD(V,\ R) \\ 2\ \% \  \  \, computes\  \, AD\  \, (\, area\  \, disorder\,)\  \, parameters \\ \%\  \, V\colon \  \, Vertices\  \, of\  \, the\  \, Voronoi\  \, diagram \\ 4\ \%\  \, R\colon \  \, Regions\  \, of\  \, the\  \, Voronoi\  \, diagram \\ \end{array}
```



```
1 def AD(vor):
```

takes a voronoi diagram to compute area disorder

In order to evaluate the area of each Voronoi cell, transform each cell to a polygon.

• Represent the couple (ad, rfh) in a graph, which gives a characterization of the Voronoi diagram.



See polyarea for evaluating the area of a polygon.



See shapely geometry. Polygon for evaluating the area of a polygon.

1.3 Characterization of the Delaunay graph

If L denotes the set of the edge lengths of the Delaunay triangulation, the mean and the standard deviation of L can also give informations on the graph.



• Compute and display in a graph the point of coordinates $(\mu(L), \sigma(L))$, with μ representing the mean and σ the standard deviation.

2 Minimum spanning tree

Definition from Wikipedia: a minimum spanning tree (MST) or minimum weight spanning tree is a subset of the edges of a connected, edge-weighted undirected graph that connects all the vertices together, without any cycles and with the minimum possible total edge weight. That is, it is a spanning tree whose sum of edge weights is as small as possible.

One of the methods to compute the MST is the Kruskal algorithm.



It is implemented in Matlab via the function minspantree (introduced in MATLAB® 2015b) or graphminspantree.

?

- Compute the MST.
- Compute $(\mu(L^*), \sigma(L^*))$ where L^* denotes the set of the edge lengths of the MST.

3 Characterization of various point patterns



- 1. Generate n condition Poisson point processes of 100 points each. For each realization, calculate the parameters (AD, RFH), $(\mu(L), \sigma(L))$ and $(\mu(L^*), \sigma(L^*))$. Display these n points in a 2D diagram in order to analyze the robustness of the quantification.
- 2. Generate 3 different point processes with regular, uniform and Gaussian dispersion. Display the different diagrams. Which one is the most discriminant?