## 1 Python correction

## 1.1 White noise

The white noise is generated with the following code.

```
 \begin{array}{c} \label{eq:continuous_problem} \\ \mbox{W = np.random.randn } (N, N) \ ; \end{array}
```

## 1.2 Gaussian Random Field

The Gaussian function that will serve as a covariance function is generated via the given code. Pay attention to the discretization grid: the FFT implies that functions are periodic, and in order to do that, the discretization must be set between [-N/2:N/2].

The Gaussian Random Field can be generated via the formula already presented (see Fig.1).

```
def grf2D(N, sigma):
     # Discrete space
     x = np.arange(-N/2, N/2);
      [X, Y] = np.meshgrid(x, x);
     # Covariance function
     C = np.exp(-1/2 * ((X/ sigma / np.sqrt(2)) **2+(Y/sigma / np.sqrt(2)) **
         \hookrightarrow 2);
     Cmat = np.fft.fftshift (C);
     # real positive part, then square root
     Cf = np.real(np.fft.fft2(Cmat));
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     Cf = np.sqrt (np.maximum (np.zeros (Cf.shape), Cf);
     # Complex white noise
     W = np.random.randn (N, N);
     A = Cf * np. fft. fft2 (W);
     G = np.real (np.fft.ifft2 (A));
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      return G;
```

## 1.3 Minkowski functionals

The Minkowski functionals are illustrated in Fig.2. The code follows.

The measures can be performed with the code from the tutorial about integral geometry.

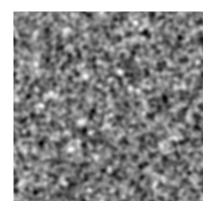


Figure 1: Gaussian Random Field, with  $\sigma=10$  (pixels) and  $N=2^{10}=1024$  pixels.

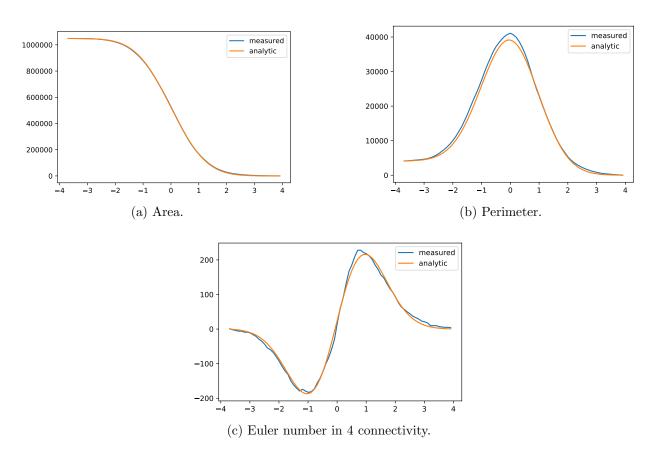


Figure 2: Illustration of the simulated and analytical values of the Minkowski functionals of the level sets of the Gaussian Random Field, for  $\sigma = 10$  and N = 1024.

```
def bwminko(X):
      # zero padding of input
      X = np.pad(X, ((1,1), (1,1)), mode='constant');
      # Neighborhood configuration
      F = np.array([[0, 0, 0], [0, 1, 4], [0, 2, 8]]);
      XF = signal.convolve2d(X,F,mode='same');
      edges = np.arange(0, 17, 1);
      h, edges = np. histogram (XF[:], bins=edges);
      f_{\text{-intra}} = [0, 1, 0, 1, 0, 1, 0, 1, 0, 1, 0, 1, 0, 1, 0, 1];
      e_{intra} = [0, 2, 1, 2, 1, 2, 2, 2, 2, 0, 2, 1, 2, 1, 2, 2, 2];
      e_{inter} = [0,0,0,1,0,1,0,2,0,0,0,1,0,1,0,2];
      {\tt v\_inter} \; = \; [\, 0\;, 1\;, 0\;, 1\;, 0\;, 1\;, 0\;, 1\;, 0\;, 1\;, 0\;, 1\;, 0\;, 1\;, 0\;, 1\,]\,;
      EulerNb4 = np.sum(h*v_inter - h*e_inter + h*f_inter)
      Area = np.sum(h*f_intra)
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      Perimeter = np.sum(-4*h*f_intra + 2*h*e_intra)
      return Area, Perimeter, EulerNb4;
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```

Then, the measurements consists in taking all the level-sets and evaluating the properties from these binary sets. Notice that the perimeter is allways a difficult task and is not really precise.

```
def minkoMeasured(G, sigma, hmin, hmax):
    H = np.arange(hmin, hmax, .1);
    A = [];
    P = [];
    E = [];

    bar = progressbar.ProgressBar();
    for h in bar(H):
        levelset = G >= h;
        a, p, e = bwminko(levelset);
        A.append(a);
        P.append(p);
        E.append(e);
    return A, P, E;
```

The analytical values are simply evaluated with the formulas.

```
def minkoAnalytical(N, sigma, hmin, hmax):
       1 = 1/(2*sigma**2);
       # analytical values
       H = np.arange(hmin, hmax, .1);
       rho_0 = 1/2 * erfc(H / np.sqrt(2));
       Aa = N**2 * rho_0;
       {\rm Pa} \, = \, 4*{\rm N*rho\_0} \, \, + \, \, {\rm np.pi*N**2*rho\_1} \, ; \\
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       {\rm Ea} \ = \ {\rm r}\,{\rm h}\,{\rm o}_{-}0 \ + \ 2*{\rm N}*\,{\rm r}\,{\rm h}\,{\rm o}_{-}1 \ + \ {\rm N}**2*\,{\rm r}\,{\rm h}\,{\rm o}_{-}2 \ ;
       return Aa, Pa, Ea;
12
```