Tutorial: Morphological skeletonization

Note

This tutorial aims to skeletonize objects with specific tools from mathematical morphology (thinning, maximum ball...).

The different processes will be applied on the following image:



1 Hit-or-miss transform

The hit-or-miss transformation enables specific pixel configurations to be detected. Based on a pair of disjoint structuring elements $T = (T^1, T^2)$, this transformation is defined as:

$$\eta_T(X) = \{x, T_x^1 \subseteq X, T_x^2 \subseteq X^c\}$$
 (1)

$$= \epsilon_{T^1}(X) \cap \epsilon_{T^2}(X^c) \tag{2}$$

where $\epsilon_B(X)$ denotes the erosion of X using the structuring element B.

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- 1. Implement the hit-or-miss transform.
- 2. Test this operator with the following pair of disjoint structuring elements:

where the points with +1 (resp. -1) belong to T^1 (resp. T^2).

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2 Thinning and thickening

Using the hit-or-miss transform, it is possible to make a thinning or thickening of a binary object in the following way:

$$\theta_T(X) = X \backslash \eta_T(X) \tag{3}$$

$$\chi_T(X) = X \cup \eta_T(X^c) \tag{4}$$

These two operators are dual in the sense that $\theta_T(X) = (\chi_T(X^c))^c$.



- 1. Implement these two transformations.
- 2. Test these operators with the previous pair of structuring elements.

3 Topological skeleton

By using the two following pairs of structuring elements with their rotations (90°) in an iterative way (8 configurations are thus defined), the thinning process converges to a resulting object which is homothetic (topologically equivalent) to the initial object.

+1	+1	+1
0	+1	0
-1	-1	-1

0	+1	0
+1	+1	-1
0	-1	-1



- 1. Implement this transformation (the convergence has to be satisfied).
- 2. Test this operator and comment.

4 Morphological skeleton

A ball $B_n(x)$ with center x and radius n is maximum with respect to the set X if there exists neither indice k nor centre y such that:

$$B_n(x) \subseteq B_k(y) \subseteq X$$

In this way, the morphological skeleton of a set X is constituted by all the centers of maximum balls. Mathematically, it is defined as:

$$S(X) = \bigcup_{r} \epsilon_{B_r(0)}(X) \backslash \gamma_{B_1(0)}(\epsilon_{B_r(0)}(X))$$
(5)

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- 1. Implement this transformation.
- 2. Test this operator and compare it with the topological skeleton.