

1 Matlab correction

1.1 Shape contours

To generate a simple object, here is an example:

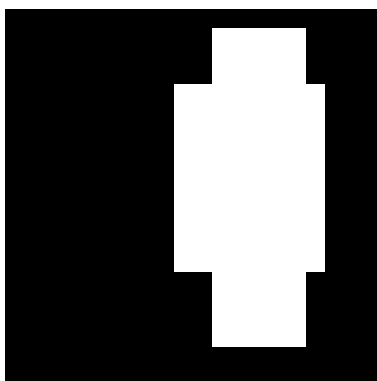


```
1 A=zeros(20,20);
  A(5:14,10:17)=1;A(2:18,12:16)=1;
```

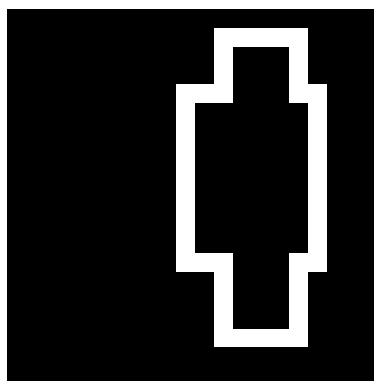
The contours are computed in 4- or 8-connectivity, see Fig.1.



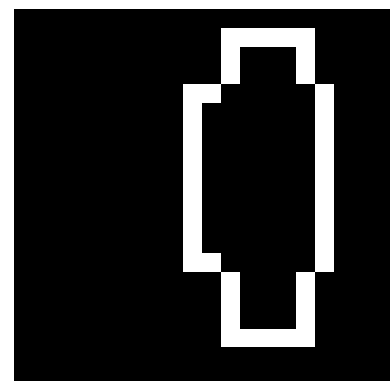
```
% compute the contours
2 contours8 = bwperim(A, 4);
  contours4 = bwperim(A, 8);
```



(a) Sample object.



(b) Contour in 4-connectivity.



(c) Contour in 8-connectivity.

Figure 1: Simple object and its contours in 4- or 8-connectivity.

1.2 Freeman chain code

1.2.1 First point of the shape



```
1 function [x,y]=firstPoint(A)
  % locates first non zero point of the contour A
3 [r,c]=find(A);
  x=r(1); y=c(1);
```

Command window

```
>>[r0 ,c0]=firstPoint (A)
```

2

```
r0 =
```

4

```
5
```

```
c0 =
```

6

```
10
```

1.2.2 Freeman chain code



```
function code=freeman(A,r0 ,c0 ,conn)
2 % freeman code of a contour.
  % A : contour
4 % r0 , c0 : coordinates of 1st point
  % conn: connectivity
6
  B=A;
8 stop=0; % stop condition
  point0=[r0 ,c0 ];
10 if (conn==8)
    lut=[1 2 3; 8 0 4; 7 6 5];
12 else
    lut=[0 2 0; 8 0 4; 0 6 0];
14 end

16 % be careful that these LUTs consider coordinates
  % from left to right , top to bottom
18 % 0
  % 0+----- y
20 % |
  % |
22 % |
  % x|
24 %
  lutx=[-1 -1 -1 0 1 1 1 0];
26 luty=[-1 0 1 1 1 0 -1 -1];
  lutcode=[3 2 1 0 7 6 5 4];
28
  nbrepoints=sum(B(:));
30 code=[];
  point=point0;
32
  for indice = 1:nbrepoints
34     B(point(1) ,point(2))=0;
    window=B(point(1)-1:point(1)+1,point(2)-1:point(2)+1);
36     window=window.*lut;
    index=max(window(:));
38     if (index==0) % no more points ? should link to first point
```



```

40     B(point0(1),point0(2))=1;
        window=B(point(1)-1:point(1)+1,point(2)-1:point(2)+1);
        window=window.*lut;
42     index=max(window(:));
        B(point0(1),point0(2))=0;
44     end

46     % compute coordinates of new point
        point=[point(1)+lutx(index),point(2)+luty(index)];
48
        % add code
50     code(indice) = lutcode(index);

52 end

```

Command window

```

z4= 6 6 6 6 6 6 6 6 6 0 0 6 6 6 6 0 0 0 0 2 2 2 2 0 2 2 2 2 2 2 2 2 2 4 2
    2 2 4 4 4 4 6 6 6 4 4
2
z8= 6 6 6 6 0 0 0 7 0 0 0 0 0 0 0 0 0 1 0 0 2 2 2 2 4 4 3 2 4 4 4 4 4 4 4
    4 4 6 5 4 4 4

```

1.3 Normalization

1.3.1 Differential code



```

1 function d=codediff(fcc,conn)
    % fcc : freeman chain code
3    % conn: connectivity
        sr=circshift(fcc,1);
5    d=fcc-sr;
        d = mod(d, conn);

```

1.3.2 Normalization



```

function code=freeman_normalization(fcc)
2 % find the lowest number constituted among all the cyclic translations of
    % fcc: freeman code
4 L = length(fcc);
    C = zeros(L);

```



```

6 for i=1:L
    C(i,:)=circshift(fcc , i);
8 end

10 % search for minimum number
    % evaluates the value of the number formed by the array , thus , use
        ↪ polyval
12 % in decimal basis for getting this number
    D= zeros(L, 1);
14 for i=1:L
    D(i) = polyval(C(i,:) , 10);
16 end

18 [~, ind]=min(D);
    code=C(ind(1) ,:);

```

The differential code is evaluated in d8, the normalization gives shapenumber8:



```

[r0 , c0]=firstPoint (A);
2 z8=freeman (contours8 , r0 , c0 , 8);
d8=codediff (z8 , 8);
4 shapenumber8=freeman_normalization (d8);

```

Command window

```

d8 = 2 0 0 0 2 0 0 7 1 0 0 0 0 0 0 0 0 1 7 0 2 0 0 0 2 0 7 7 2 0 0 0 0 0
    0 0 0 2 7 7 0 0
2 shapenumber8 = 0 0 0 0 0 0 0 0 1 7 0 2 0 0 0 2 0 7 7 2 0 0 0 0 0 0 0 0 2
    7 7 0 0 2 0 0 0 2 0 0 7 1

```

1.3.3 Validation

This validation shows the effect on a different starting point.



```

% check for another starting point
2 r0=9;c0=10;
z8=freeman (contours8 , r0 , c0 , 8);
4 d8=codediff (z8 , 8);
shapenumber8_startchanged=freeman_normalization (d8);
6 disp(' * validation test for starting point changed ')
if (shapenumber8-shapenumber8_startchanged)
8     disp(' error: different freeman code ')
else
10     disp(' OK: same freeman code ')

```



end

Another test is to verify the result after a rotation. To prevent discretization problems, we use 90 degrees and take the transpose of the matrix.



```

1 % check for rotation by 90 deg
  contours8rot=contours8';
3
  figure;imshow(contours8rot);
5
  [r0,c0]=firstPoint(contours8rot);
7 z8=freeman(contours8rot,r0,c0,8);
  d8=codediff(z8,8);
9 shapenumber8_rotated=freeman_normalization(d8);
  disp('* validation test after rotation')
11 if (shapenumber8-shapenumber8_rotated)
    disp(' error: different freeman code')
13 else
    disp(' OK: same freeman code')
15 end

```

The same code should be found:

Command window

```

1 * validation test for starting point changed
  OK: same freeman code
3 * validation test after rotation
  OK: same freeman code

```

1.4 Geometrical characterization

1.4.1 Perimeter for 8-connectivity

We first need to extract the codes in the diagonal directions and apply a $\sqrt{2}$ factor, then add the number of codes in vertical and horizontal directions.



```

  nb_diag=mod(z8, 2);
2 nb_diag=sum(nb_diag(:));
  nb = length(z8)-nb_diag;
4 perimeter = nb_diag * sqrt(2) + nb
  stats = regionprops(A,'Perimeter')

```

Command window

```
1 perimeter =  
    43.6569  
3 stats =  
    struct with fields:  
5     Perimeter: 41.5900
```

1.4.2 Area for 8-connectivity



```
1 area=0;  
  B=0;  
3 lutB=[0 1 1 1 0 -1 -1 -1];  
  for i=1:length(z8)  
5     lutArea=[-B -(B+0.5) 0 (B+0.5) B (B-0.5) 0 -(B-0.5)];  
     area=area+lutArea(z8(i)+1);  
7     B=B+lutB(z8(i)+1);  
  end  
9 disp(['Area by freeman code: ' num2str(area)]);  
  disp(['Number of pixels: ' num2str(sum(A(:)))])
```

Command window

```
Area by freeman code: 93  
2 Number of pixels: 115
```