

ASM Language



CSC 236

Precision vs. accuracy

Precision

- Number of digits in the calculation

Accuracy

- Is the result correct?

$$\begin{array}{r} 1.174567940325672 \\ + 2.348920178544532 \\ \hline 27.010203040599999 \end{array}$$

Precise but not accurate

Safeguard — anti-ballistic missile system

- Determines position of incoming missile
 - Emits a signal
 - Bounces off missile
 - Detect reflection
 - Measure time (t_{rt})
- Distance to missile
 - Distance = speed x time
 - Speed 186,000 miles/sec

Safeguard — anti-ballistic missile system

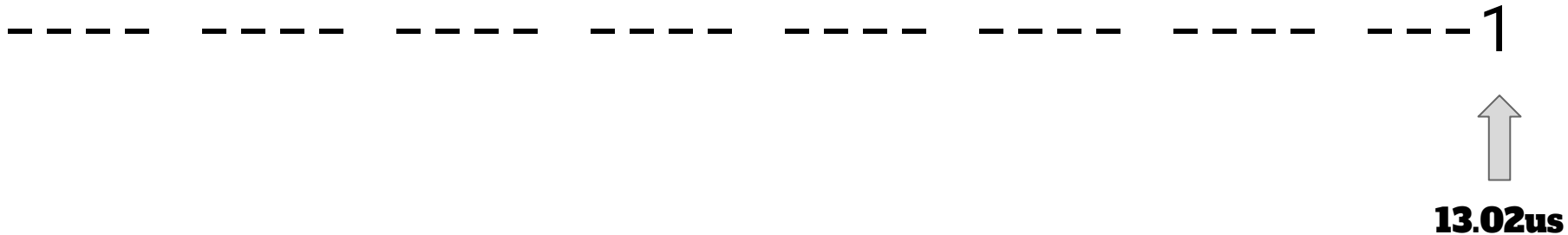
- Precision timer
 - 13.02 μ s
- Distance of 1 tick
 - 186,000 mile/s \times 13.02 μ s
 - 1.86×10^5 mile/s \times 1.302×10^{-5} s
 - \sim 2.42 mile
- Round trip
 - Smallest distance is \sim 1.21 miles
 - Eg, 10 ticks \Rightarrow missile is approx 12.1 miles away

Safeguard — anti-ballistic missile system

- Preliminary testing
 - 1,000+ mile radius
 - 3 orders of magnitude worse than expected
- Examined code
 - Software is usually the problem
 - 3 months ... no code errors
 - ?

Safeguard — anti-ballistic missile system

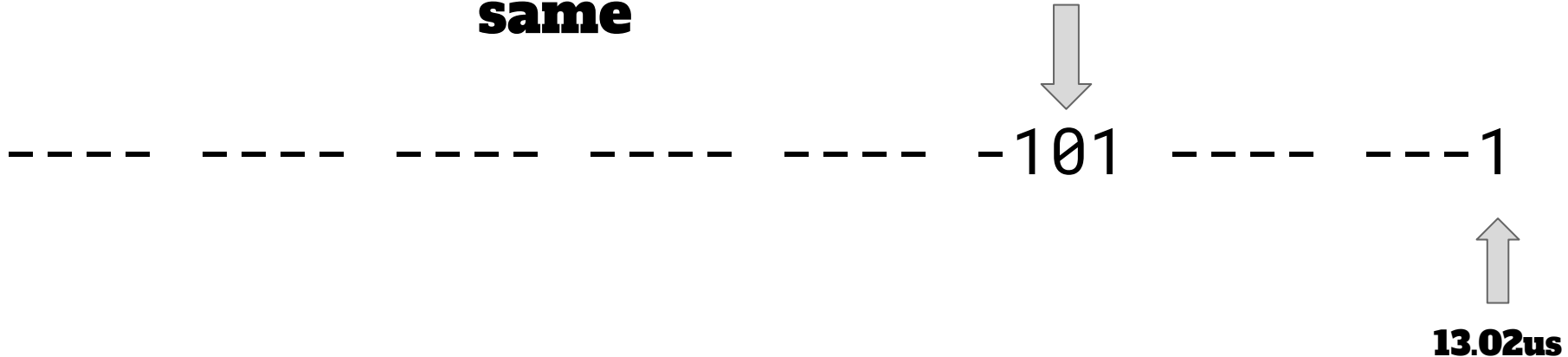
- Timer
 - 13.02 us precision
 - 32-bit counter



Safeguard — anti-ballistic missile system

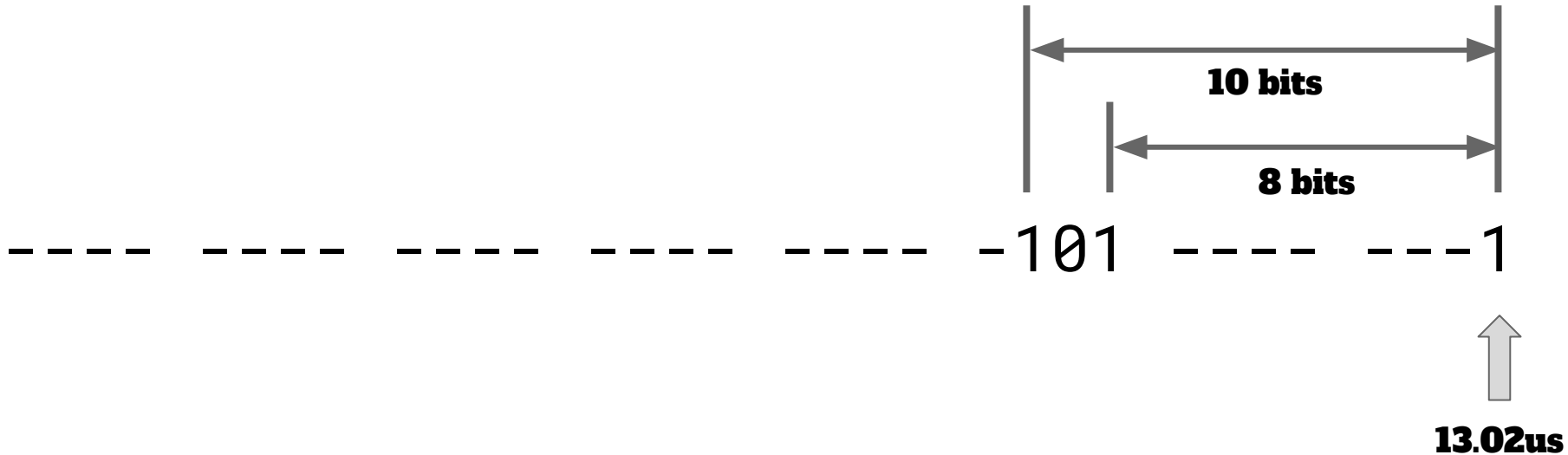
- Timer
 - 13.02 us precision
 - 32-bit counter

Discovered these bits always the same



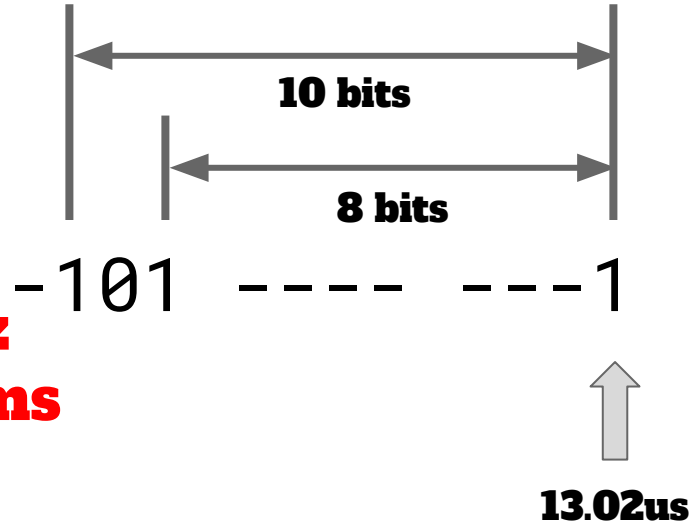
Safeguard — anti-ballistic missile system

- Timer
 - 13.02 us precision
 - 32-bit counter



Safeguard — anti-ballistic missile system

- Timer
 - 13.02 us precision
 - 32-bit counter
- Fixed bits
 - $13.02\mu\text{s} \times 2^8 = 3.3\text{ms}$
 - $13.02\mu\text{s} \times 2^{10} = 13.33\text{ms}$
 - Sum = 16.66ms



- **$1/16.66\text{ms} = 60 \text{ cycles/sec} = 60\text{Hz}$**
- **Timer was updated every 16.66ms**
- **Precision 13.02us**
- **Accuracy 16.66ms**

Calculate C = A+B

```
a    db    10    ;0A  
b    db    55    ;37  
c    db    00    ;00
```

```
mov    al,[a]        ; ax = --0A  
add    al,[b]        ; ax = --41  
mov    [c],al        ;  c = 41
```

**How does this
become a *program*?**

```

-----
Program: Hello (MASM version)

Function: Writes "Hello World" to the standard output device.
It is equivalent to the famous C++ program, hello world.

It uses 3 constant declarations to generate the message,
to show that dos writes data until it finds a '$'.

A single constant will also work, such as
msg db 'Hello World',13,10,'$'

In assembler you have as much flexibility as you want.

Owner: DAL

Date: Changes
01/26/01 original version
-----

```

```

-----
.model small ;64k code and 64k data
.8086 ;only allow 8086 instructions
.stack 256 ;reserve 256 bytes for the stack
-----

```

```

-----
;start the data segment
.data
msg db 'Hello World' ;the hello world message
eol db 13,10 ;cr/lf = \n in c++
term db '$' ;dos end of string
msglen dw term-msg+1 ;total length of the message
-----

```

```

-----
;start the code segment
.code
hello: ;
mov ax,@data ;establish addressability to the
mov ds,ax ;data segment for this program
; write out the message
mov dx,offset msg ;point to the message
mov ah,9 ;set the dos code to write a string
int 21h ;write the string
; terminate program execution
exit: ;
mov ax,4c00h ;set dos code to terminate program
int 21h ;return to dos
end hello ;end marks the end of the source code
;...and specifies where you want the
;...program to start execution
-----

```

- **Program has sections**
 - **Directives**
 - **Data**
 - **Code**

```

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term db '$'           ;dos end of string
;
msglen dw term-msg+1  ;total length of the message
;-----

```

```

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.code           ;start the code segment
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○ Directives

○ Data

○ Code

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msg db 'Hello World'      ;the hello world message
eol db 13,10               ;cr/lf = \n in c++
term db '$'               ;dos end of string
msglen dw term-msg+1      ;total length of the message
;-----

```

```

;-----
.code                      ;start the code segment
;-----
hello: mov ax,@data         ;establish addressability to the

```

```

;-----
.model    small    ;64k code and 64k data
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.stack    256      ;reserve 256 bytes for the stack
;-----

```

- **Directives**
 - **Flags for the assembler**
- **.model small**
 - **Limits segments to 64KB (8086)**
- **.8086**
 - **Only allow 8086 instructions**
- **.stack 256**
 - **Declare a stack size**
 - **256 B is big enough for this class**

```

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01/26/01 original version

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.8086 ;only allow 8086 instructions
.stack 256 ;reserve 256 bytes for the stack

```

- **Program has sections**
 - **Directives**
 - **Data**
 - **Code**

```

;-----
; .data ;start the data segment
;-----
msg db
eol db
term db
msglen dw
;-----

```

```

;-----
; .code
;-----
hello: mov     msg     db     'Hello World' ;the hello world message
      mov     eol     db     13,10        ;cr/lf (DOS line termination)
; write out the message
      mov     term    db     '$'          ;DOS end of string
      mov     msglen  dw     term-msg+1   ;total length of the message
      mov     int     int
; terminate program
exit:  mov     int     int
      end
;-----

```

- **Code segment**
 - **Begins with .code**

```

-----
Program:  Hello (MASM version)

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         It is equivalent to the famous C++ program, hello world.

         It uses 3 constant declarations to generate the message,
         to show that dos writes data until it finds a '$'.

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         msg  db  'Hello World',13,10,'$'

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msg       db      'Hello World' ;the hello world message
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term      db      '$'          ;dos end of string
;
msglen    dw      term-msg+1    ;total length of the message
;-----

```

```

;-----
;-----
.code     ;start the code segment
;-----
hello:
    mov     ax,@data          ;establish addressability to the
    mov     ds,ax             ;data segment for this program
;-----
; write out the message
;-----
    mov     dx,offset msg      ;point to the message
    mov     ah,9               ;set the dos code to write a string
    int     21h               ;write the string
;-----
; terminate program execution
;-----
exit:
    mov     ax,4c00h          ;set dos code to terminate program
    int     21h               ;return to dos
    end     hello             ;end marks the end of the source code
                                ;...and specifies where you want the
                                ;...program to start execution
;-----

```

```

;-----
;               .code               ;
;-----
hello:          ;
                mov     ax,@data     ;
                mov     ds,ax        ;
;-----
; write out the message
;-----
                mov     dx,offset msg
                mov     ah,9
                int     21h
;-----
; terminate program execution
;-----
exit:           mov     ax,4c00h     ;
                int     21h         ;
                end     hello       ;
;-----
;-----

```

Three parts

1. initialization

Remember:

- **DS & ES set by programmer**
- **Cannot move immediate into segment register**

Data segment register

- Not allowed
 - `mov ds, @data`
 - Cannot move immediate to segment register
- What is `@data`?
 - It is the location of the data segment
 - In memory — it is a memory label
- Consider
 - `val db 20h`
 - `val` is the name for a memory location
 - `20h` is the value you want to store there.

@data

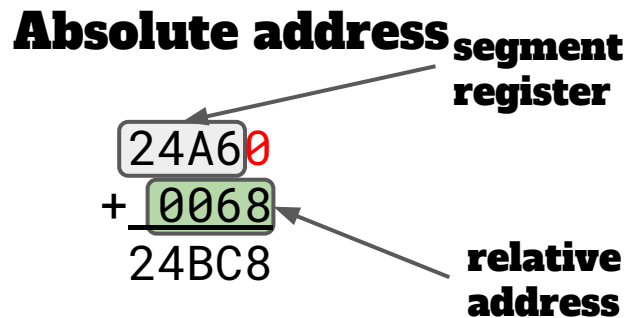
- What is “@data”
 - A built-in, implicit assembler variable
 - It denotes the beginning of the data segment
 - It is a memory reference, location
 - The assembler interprets this as an *immediate* value
- Why a name
 - Loader decides (not programmer)
 - Decision is made when DOS loads program into memory (not static)

mov ds, @data

- Why doesn't this work?
 - @data is an immediate value
- What about?
 - `val dw @data ; val = @data`
 - `mov ds, [val]`
- Why doesn't that work?

mov ds, @data

- Why doesn't this work?
 - @data is an immediate value
- What about?
 - `val dw @data ; val = @data`
 - `mov ds, [val]`
- Why doesn't that work?
 - How to reference val?
 - val is a relative offset
 - Must initialize the ds first



Three parts

1. initialization

```
;-----  
                .code                ;  
;-----  
hello:          ;  
    mov         ax,@data              ;  
    mov         ds,ax                 ;  
;-----  
; write out the message  
;-----  
    mov         dx,offset m  
    mov         ah,9  
    int         21h  
;-----  
; terminate program execution  
;-----  
exit:          ;  
    mov         ax,4c00h  
    int         21h  
    end        hello  
  
;-----
```

Remember:

- **DS & ES set by programmer**
- **Cannot move immediate into segment register**

If program does not have data, do you need to initialize ds?

Three parts

1. initialization

```
;-----  
                .code                ;  
;-----  
hello:          ;  
                mov     ax,@data      ;  
                mov     ds,ax         ;  
;-----  
; write out the message  
;-----  
                mov     dx,offset m  
                mov     ah,9  
                int     21h  
;-----  
; terminate program execution  
;-----  
exit:           ;  
                mov     ax,4c00h  
                int     21h  
                end     hello  
;-----
```

Remember:

- **DS & ES set by programmer**
- **Cannot move immediate into segment register**

If program does not have data, do you need to initialize ds?

No.

```

;-----
                .code                ;
;-----
hello:          ;
                mov     ax,@data      ;
                mov     ds,ax         ;
;-----
; write out the message
;-----
                mov     dx,offset msg ;
                mov     ah,9          ;
                int     21h           ;
;-----
; terminate program execution
;-----
exit:           ;
                mov     ax,4c00h      ;
                int     21h           ;
                end     hello         ;
;-----
;-----

```

Three parts

1. Initialization
2. Body

```

;-----
                .code                ;
;-----
hello:
    mov         ax,@data             ;
    mov         ds,ax               ;
;-----
; write out the message
;-----
    mov         dx,offset msg
    mov         ah,9
    int         21h
;-----
; terminate program execution
;-----
exit:
    mov         ax,4c00h
    int         21h
    end         hello
;-----

```

Three parts

1. Initialization
2. Body
3. Termination

- **int — “interrupt”**
 - **Generates a software interrupt**
 - **21h is caught by DOS**
- **int 21h — is a service call to DOS**
 - **ah — desired service**
- **4C**
 - **Terminate (al is the exit status)**
 - **Eg, exit(0)**


```

;-----
;               .code               ;
;-----
hello:          ;
               mov     ax,@data      ;
               mov     ds,ax         ;
;-----
; write out the message
;-----
               mov     dx,offset msg
               mov     ah,9
               int     21h
;-----
; terminate program execution
;-----
exit:
               mov     ax,4c00h
               int     21h
               end     hello
;-----
;-----

```

Three parts

1. Initialization
2. Body
3. Termination

- **End**

- **Last statement**
- **Mandatory**
- **Has to match start label**

Assembler keywords

- Reserved words
 - Cannot be used as labels or variable names
- Includes
 - Opcodes — add, mov, sub
 - Directives — end
- Full list on web page
 - See: “Reserved Words in MASM”

Data sizes

- Source and destination must be same size
- Suppose you want to add AX and DL
 - `add ax, dl`

Data sizes

- Source and destination must be same size
- Suppose you want to add AX and DL
 - `add ax, dl`

- In C:
 - `char a = 9;`
 - `short b = 10;`
 - `short c;`
 - `c = a + b;`

a is *implicitly* cast from char to short

Data sizes

- Source and destination must be same size
- Suppose you want to add AX and DL
 - `add ax, dl`
- In C:
 - Can do *explicit* cast
 - e.g., `long x = (long)c;`

Asm casting

- 4-bit to 8-bit

- Unsigned

- $1_{10} = 0001_2 = \underline{0000}0001_2$

- $10_{10} = 1010_2 = \underline{0000}1010_2$

- Extend with zeros

- Byte to word

- `mov al,[var]` ;ax = ?? 0A₁₆

- `mov ah,0` ;ax = 00 0A₁₆

It's convenient to be able to access ax as two bytes.

Asm casting

- 4-bit to 8-bit
- Signed
 - $+1_{10} = 0001_2 = \underline{0000}0001_2$
 - $-1_{10} = 1111_2 = \underline{????}1111_2$

Asm casting

- 4-bit to 8-bit
- Signed
 - $+1_{10} = 0001_2 = \underline{0000}0001_2$
 - $-1_{10} = 1111_2 = \underline{1111}1111_2$

Asm casting

- 4-bit to 8-bit
- Signed
 - $+1_{10} = 0001_2 = \underline{0000}0001_2$
 - $-1_{10} = 1111_2 = \underline{????}1111_2$
- For positive
 - Add zeros (same as unsigned)
- For negative
 - Add ones
- How do you know which?

Asm casting

- Byte to word
- Signed
 - $+1_{10} = 01_{16} = 0001_{16}$
 - $-1_{10} = FF_{16} = FFFF_{16}$
- For positive
 - Add zeroes (same as unsigned)
- For negative
 - Add ones
- How do you know which?

Asm casting

- Byte to word
- Signed
 - $+1_{10} = 01_{16} = 0001_{16}$
 - $-1_{10} = FF_{16} = FFFF_{16}$
- For positive
 - Add zeroes (same as unsigned)
- For negative
 - Add ones
- How do you know which?
 - `cbw` — convert byte to word

Asm casting

- Unsigned
 - Move 00_{16} into high-order byte
 - Works for any general-purpose register (ax, bx, cx, dx)
- Signed
 - Use `cbw`
 - ax & al are implicit source and destination
 - First: move byte into al
 - Then: call `cbw`
 - ax holds the sign-extended value of al

Unsigned conversion

a db 255 ; FF₁₆
b db 1 ; 01₁₆
c dw 0 ; 00 00₁₆

					FF	01	00	00							
--	--	--	--	--	----	----	----	----	--	--	--	--	--	--	--

Cannot convert a or b in memory

Unsigned conversion

```
a db 255 ; FF16
b db 1    ; 0116
c dw 0     ; 00 0016
```

```
mov al,[a] ;ax = __ FF
mov ah,0   ;ax = 00 FF
mov bl,[b] ;bx = __ 01
mov bh,0   ;bx = 00 01
add ax,bx  ;ax = 01 00
mov [c],ax
```

Unsigned conversion

```
a db 255 ; FF16  
b db 1    ; 0116  
c dw 256  ; 00 0116
```

```
mov al,[a] ;ax = __ FF  
mov ah,0   ;ax = 00 FF  
mov bl,[b] ;bx = __ 01  
mov bh,0   ;bx = 00 01  
add ax,bx  ;ax = 01 00  
mov [c],ax
```

Signed conversion

```
a db  -1    ; FF16  
b db   2    ; 0216  
c dw   0     ; 00 0016
```


Signed conversion

```
a db -1 ; FF16  
b db 2 ; 0216  
c dw 0 ; 00 0016
```

```
mov al,[a] ;ax = __ FF  
cbw ;ax = FF FF
```



sign-bit in al is 1
⇒ cbw extends with 1s

Signed conversion

```
a db -1 ; FF16  
b db 2 ; 0216  
c dw 0 ; 00 0016
```

```
mov al,[a] ;ax = __ FF  
cbw ;ax = FF FF  
mov [c],ax ;c = FF FF  
mov al,[b] ;ax = FF 02  
cbw ;ax = 00 02
```



sign-bit in al is 0
⇒ cbw extends with 0s

Signed conversion

```
a db  -1    ; FF16
b db   2     ; 0216
c dw   0     ; 00 0016
```

```
mov     al,[a]    ;ax = __ FF
cbw                     ;ax = FF FF
mov     [c],ax    ;c  = FF FF
mov     al,[b]    ;ax = FF 02
cbw                     ;ax = 00 02
add     [c],ax    ;c  = 00 01
```

Signed conversion

```
a db  -1    ; FF16
b db   2    ; 0216
c dw   1     ; 01 0016
```

```
mov     al,[a]    ;ax = __ FF
cbw                     ;ax = FF FF
mov     [c],ax    ;c  = FF FF
mov     al,[b]    ;ax = FF 02
cbw                     ;ax = 00 02
add     [c],ax    ;c  = 00 01
```

Some basic opcodes

- `inc dest` ;dest = dest + 1
- `dec dest` ;dest = dest - 1
- `neg dest` ;dest = 0 - dest = -dest
- `cwd` ;converts 16-bit signed value in ax
;to a 32-bit signed value in dx:ax

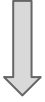
Increment

- `ADD SI, 1` ; $SI = SI + 1$
 - ASM LANG is **not** case sensitive
 - Increments the si register
 - Sets the condition codes: SF, ZF, OF, CF
- `inc si` ; $SI = SI + 1$
 - Increments the si register
 - Sets the condition codes: SF, ZF, OF
 - But not CF

Why not?

Suppose need to add column of numbers

current
column

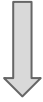


1	2	7
+3	9	5
<hr/>		

$i = 0$
 $TOP[i] + BOT[i]$

Suppose need to add column of numbers

current
column



$$\begin{array}{r} 1 \\ 1 \ 2 \ 7 \\ +3 \ 9 \ 5 \\ \hline 2 \end{array}$$

$$i = 0 \\ \text{TOP}[i] + \text{BOT}[i]$$

Suppose need to add column of numbers

current
column
↓
1
1 2 7
+3 9 5
—
2

i++
TOP[i] + BOT[i] + CARRY

Must be able to move index pointer without losing carry information

Moving the pointer with an inc or dec maintains the carry

Dest = source

This is legal:

```
add ax,ax    ;doubles ax
```

Immediate values

How you specify immediate data affects the readability of code

- `mov al, 65`
- `mov al, 41h`
- `mov al, 'A'`

Which is better?

Immediate values

How you specify immediate data affects the readability of code

- `mov al, 65`
- `mov al, 41h`
- `mov al, 'A'`

Which is better?

- Depends on how `al` is being used
- If as a char, last one is much more readable than the others

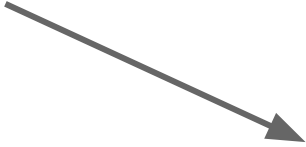
Compare

- `cmp dest, src` — Compare instruction
 - Compares two values
 - Signed or unsigned
 - No special hardware
 - Works by subtracting `src` from `dest`

Compare

`sub ax, bx`

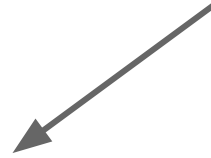
- Calc $ax - bx$
- Save result in `ax`
- Sets `CC`



$ax < bx$
 $ax = bx$
 $ax > bx$

`cmp ax, bx`

- Calc $ax - bx$
- Does not save result in `ax`
- Sets `CC`

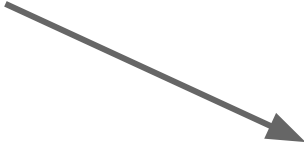


$result < 0$
 $result = 0$
 $result > 0$

Compare

`sub ax, bx`

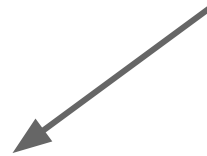
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- Calc $ax - bx$
- Does not save result in `ax`
- Sets CC



$result < 0$
 $result = 0$
 $result > 0$

Is this a signed or
an unsigned
comparison?

Depends on which
condition codes you
check.