## The MOSTLEE Model

## A Model Of Sources, Transport, Loss, and Emission in Exospheres

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## $1 \checkmark AtomicData/get gvalue 3.1.pro$

## Summary

Creates a g-value structure using saved atomic data.

## **Calling Procedure**

```
gval = get_gvalue, atom, a, path=path
```

#### Inputs

- 1 atom = species being modeled
- 2 a = heliocentric distance
- 3 path = path where g-values are saved (optional)

## **Outputs**

Function returns a structure with the fields:

- species = same as the atom input
- a = same as the input. Units: AU.
- wavelength = pointer to an array of length nlam with wavelengths of resonance transitions. Units: Å.
- v = pointer to an array of length *nvel* with the radial velocities at which the g-value was calculated Units:  $km cm^{-2} s^{-1}$ .
- g = pointer to an array of size  $nvel \times nlam$  with g-values as function of radial velocity for each resonant transition scaled to distance a. Units: photons s<sup>-1</sup>.
- radaccel = pointer to an array of size nvel with the radiation acceleration at each wavelength. See radiation pressure and Figure 1. Units: km s<sup>-1</sup>.
- If the species is not found, a warning is printed and the g-value is set to 0.

#### Model Procedures Called

None.

#### Notes

- 1 The g-values are saved in \$BASEPATH/Work/AtomicData/g-values/'
- 2 The structure saved in the g-value files are created with set\_up\_gvals.
- 3 See Table 1 for list of species that have g-values implemented in the code.
- 4 Figure ?? shows g-value at 1 AU as function of radial velocity for each species listed in Table 1.

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Species	Wavelengths (Å)	Reference
С	1560, 1657	Killen et al. (2009)
$Ca^{+}$	3934, 3969	Killen et al. (2009)
Ca	2722, 4227, 4567	Killen et al. (2009)
Η	1215	Killen et al. (2009)
Не	584	Killen et al. (2009)
K	4045	Killen et al. (2009)
$\mathrm{Mg}^{+}$	2083, 2796	Killen et al. (2009)
Mg	2026, 2852,	Killen et al. (2009)
Mn	2795, 2799, 2802	XXXXX
Na	3303, 5891, 5897	Killen et al. (2009)
O	1303	Killen et al. (2009)
ОН	3081, 3092	Killen et al. (2009)
S	1807, 1820	Killen et al. (2009)
Ti	3187, 3193, 3204, 3342, 3371, 3371, 3636, 3644	XXXXX

Table 1: Available g-values

## $2 \sqrt{\text{Data/SystemConstants}}$ 2.0.pro

## Summary

Creates the SystemConsts and DipoleConsts structures from data stored in the !consts system variables.

#### **Calling Procedure**

SystemConstants, planet, SystemConsts, DipoleConsts

## Inputs

• planet: String containing planet name. For purposes of the model, *planet* is defined as the center of the modeled system. Therefore, "sun" and "pluto" are valid planets.

## **Outputs**

- SystemConsts: Structure containing the planetary system constants The fields in the structure are given in Table 4. The values for each object are given in Table 6.
- DipoleConsts: Structure containing the planetary dipole constants The fields in the structure are given in Table 5. The values for each object are given in Table 6.

#### Model Procedures Called

None.

#### **Notes**

- 1 The values used in this routine are saved in the files Data/PhysicalData/PlanetaryConstants.dat and Data/PhsyicalData/DipoleConstants.dat.
- 2 Data taken from NASA Solar System Dynamics and Wikipedia: Sun.

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## 3 √Display/determine image rotation 4.0.pro

## Summary

Computes the rotation matrix for an image given a sub-observer longitude, sub-observer latitude, and north pole rotation angle, or a time and observer location.

#### **Calling Procedure**

M = determine\_image\_rotation, input, format

#### Inputs

- 1 input = input structure
- 2 format = format structure

#### Outputs

Returns the rotation matrix from model coordinates to the observer's viewpoint.

#### Model Procedures Called

- 1 relative\_position
- 2 utc2et
- 3 rotationmatrix
- 4 rotation

#### **Notes**

- 1 There are two ways to specify the observing geometry:
  - 1.1 Sub-Observer point:
    - format.geometry.SubObsLongitude: radians dawnward of sub-solar point
    - format.geometry.SubObsLatitude: radians northward of sub-solar point
    - format.geometry.PolarAngle: north pole rotation angle radians counter-clockwise (?) from north.
  - 1.2 Time and Observer location:
    - format.geometry.time: string time in ISOC format (YYYY-MM-DDTHH:MM:SS.S or YYY-DOYTHH:MM:SS.S)
    - format.geometry.observer: NAIF observer location (e.g., 'Earth', 'MESSENGER')
- 2 The rotation matrix is determined by the rotation angle  $(\theta)$  of the sun direction  $(\hat{\mathbf{x}}_{\odot})$  to the observer direction  $(\hat{\mathbf{x}}_{obs})$  around the axis perpendicular to both vectors  $(\hat{\mathbf{a}})$ :

$$\hat{\mathbf{a}} = \hat{\mathbf{x}}_{\odot} \times \hat{\mathbf{x}}_{obs} \tag{1}$$

$$\cos\theta = \hat{\mathbf{x}}_{\odot} \cdot \hat{\mathbf{x}}_{obs} \tag{2}$$

$$M = \begin{pmatrix} a_x^2 + (1 - a_x)^2 \cos \theta & a_x a_y (1 - \cos \theta) - a_z \sin \theta & a_x a_z (1 - \cos \theta) + a_y \sin \theta \\ a_x a_y (1 - \cos \theta) + a_z \sin \theta & a_y^2 + (1 - a_y^2) \cos \theta & a_y a_z (1 - \cos \theta) - a_x \sin \theta (3) \\ a_x a_z (1 - \cos \theta) - a_y \sin \theta & a_y a_z (1 - \cos \theta) + a_x \sin \theta & a_z^2 + (1 - a_z^2) \cos \theta \end{pmatrix}$$

3 If specifying Sub-Observer point, then:

$$\hat{\mathbf{x}}_{\odot} = (0, -1, 0) \tag{4}$$

$$\hat{\mathbf{x}}_{obs} = (\sin \lambda \cos \mu, -\cos \lambda \cos \mu, \sin \mu) \tag{5}$$

where  $\lambda = input.geometry.SubObsLongitude$  and  $\mu = input.geometry.SubObsLatitude$ 

- 4 If specifying Time and Observer location, then  $\hat{\mathbf{x}}_{\odot}$  and  $\hat{\mathbf{x}}_{obs}$  are determined with relative\_position using SPICE.
- 5 If format.geometry.PolarAngle  $\neq$  0, then a rotation is taken around the new y-axis.

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## 21 $\sqrt{\text{Forces/accel } 3.1.pro}$

## **Summary**

Computes the acceleration on a packet due to the specified forces. Possible forces are gravity, radiation pressure, and Lorentz (not working).

## **Calling Procedure**

a = accel(loc, input, magcood, which)

## Inputs

- $1 \log = \text{packet location structure}$
- 2 input = input structure
- 3 magcoords = magnetic coordinate structure (which includes out of shadow). See xyz to magcoord.
- 4 which = array specifying which objects are included in the calculation

## Outputs

Function returns a structure with field dvdt, which is an  $n \times 3$  array with  $a_x, a_y, a_z$  in units of R<sub>plan</sub> s<sup>-2</sup>.

#### Model Procedures Called

- 1 gravity
- 2 radiation pressure
- 3 Lorentz

#### **Notes**

1 Total acceleration:

$$\mathbf{a} = \mathbf{a}_{grav} + \mathbf{a}_{radpres} + \mathbf{a}_{lor} \tag{6}$$

- 2 The input structure fields input.Forces.gravity, input.Forces.radpres, and input.Forces.Lorentz are used to specify which forces are included in the calculations.
- 3 The Lorentz force, which only affects ions, does not currently work properly.

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## 22 $\sqrt{\text{Forces/gravity}}$ 3.1.pro

## Summary

Computes acceleration due to gravity from each object.

#### **Calling Procedure**

agrav = gravity(loc, input)

#### Inputs

- $1 \log = \text{packet location structure}$
- 2 input = input structure

## **Outputs**

Function returns acceleration due to gravity as a  $n \times 3$  array with  $a_x, a_y, a_z$  in units of R<sub>plan</sub> s<sup>-2</sup>.

## Model Procedures Called

1 locmoon: gives the location of each object as viewed by each packet.

### **Notes**

1 Gravity computed by:

$$\mathbf{a} = \sum_{i=0}^{nobj} \frac{GM}{r_i^2} \hat{\mathbf{r}}_{i} \tag{7}$$

$$r_i = \sqrt{(x-x_i)^2 + (y-y_i)^2 + (z-z_i)^2}$$
 (8)

which is given in component form by:

$$a_x = \sum_{i=0}^{nobj} \frac{GM_i(x - x_i)}{r_i^3} \tag{9}$$

$$a_y = \sum_{i=0}^{nobj} \frac{GM_i(y-y_i)}{r_i^3} \tag{10}$$

$$a_z = \sum_{i=0}^{nobj} \frac{GM_i(z-z_i)}{r_i^3} \tag{11}$$

(12)

where the coordinates of each object (planet and satellites) are  $\mathbf{r_i} = (x_i, y_i, z_i)$  are computed by locmoon,  $GM_i$  are stored in the SystemConsts variable, and the sum is only performed for objects which input.geometry.include = 1.

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${\bf 23  Forces/lorentz\_2.0}$	.pro
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## 24 √Forces/radiation pressure 3.1.pro

## Summary

Returns the radiation acceleration as function of radial velocity.

#### **Calling Procedure**

radiation\_pressure, loc, out\_of\_shadow

#### Inputs

- $1 \log = \text{packet location structure}$
- 2 out\_of\_shadow = boolean array specifying whether each packet is in the planet's shadow. Does not currently compute satellite shadow

#### **Outputs**

Function returns acceleration due to radiation pressure as a  $n \times 3$  array with  $a_x, a_y, a_z$  in units of  $R_{\text{plan}}$  s<sup>-2</sup>.

#### Model Procedures Called

None.

#### **Notes**

1 The radiation pressure is computed by:

$$\mathbf{a}_{rad}(v_r) = \sum_{i} \frac{hg(v_r)}{m\lambda_i} \hat{y} \tag{13}$$

where  $h = 6.6260690 \times 10^{-27}$  erg s<sup>-1</sup> is Planck's constant, g is the g-value as a function of radial velocity relative to the sun  $v_r$ , m is the atomic mass, and  $\lambda_i$  is each resonant transition for the species in question.

- 2 The radiation acceleration is actually calculated by the function get\_gvalue and stored in the stuff structure in modeldriver (in the fields stuff.radpres\_v and stuff.radpres\_const). This is done to speed things up.
- 3  $\mathbf{a}_{rad}$  is directed entirely in the  $+\hat{y}$  direction. I currently assume the planets' equatorial (rotational) planes are not tilted relative to their orbital planes.
- 4 Similarly,  $v_{rad}$  is the velocity in the  $\hat{y}$  direction (which is computed relative to the planet) + stuff.vrplanet. stuff.vrplanet is computed by planet\_dist and saved into the stuff structure in modeldriver.
- 5 Because the radiation acceleration is computed at discrete values by get\_gvalue, the radiation acceleration for each packet is computed by linear interpolation between values.
- 6 If  $v_r$  is outside the velocity range in  $stuff.radpres_v$ , then  $v_r$  is assumed to be either the maximum or minimum value of  $stuff.radpres_v$ , as appropriate.
- 7  $\mathbf{a_{rad}} = 0$  in the shadow of a planet or satellite.
- 8 See Table 1 for list of species that have g-values implemented in the code.
- 9 Figure 1 shows radiation acceleration as function of radial velocity at 1 AU for each species listed in Table 1.

## Things to do

- 1 Does not currently compute shadowing for satellites. If radiation pressure is turned on for a system with multiple objects, program will stop.
- 2 The radiation acceleration for K is wrong because I do not have the g-values for the strongest lines.

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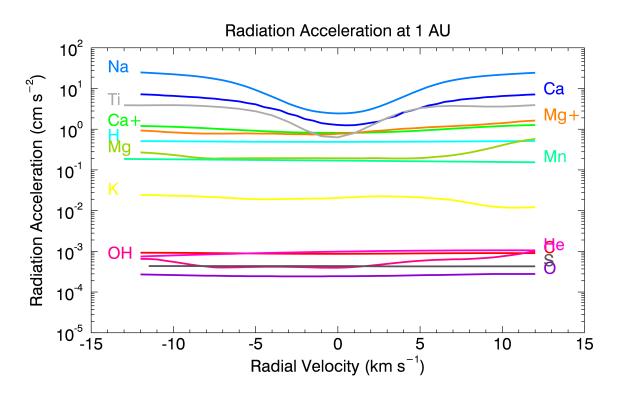


Figure 1: Radiation acceleration as function of velocity for species with available g-values.

${\bf 25}  {\bf Integrator/driver\_3.2.pro}$
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## 26 Integrator/rk5 3.3.pro

## **Summary**

Computes a Runge-Kutta step and estimates the error.

## **Calling Procedure**

Inputs

## **Outputs**

#### Model Procedures Called

#### **Notes**

- 1 Based on Numerical Recipies, 3rd Edition, Ch. 17.2
- 2 The general form of a fifth-order Runge-Kutta formula is (NR, p. 912):

$$k_1 = hf(x_n, y_n) (14)$$

$$k_2 = hf(x_n + c_2h, y_n + a_{21}k_1) (15)$$

$$k_3 = hf(x_n + c_3h, y_n + a_{31}k_1 + a_{32}k_2) (16)$$

$$k_4 = hf(x_n + c_4h, y_n + a_{41}k_1 + a_{42}k_2 + a_{43}k_3)$$

$$\tag{17}$$

$$k_5 = hf(x_n + c_5h, y_n + a_{51}k_1 + a_{52}k_2 + a_{53}k_3 + a_{54}k_4)$$
(18)

$$k_6 = hf(x_n + c_6h, y_n + a_{61}k_1 + a_{62}k_3 + a_{63}k_3 + a_{64}k_4 + a_{65}k_5)$$

$$\tag{19}$$

$$y_{n+1} = y_n + b_1 k_1 + b_2 k_2 + b_3 k_3 + b_4 k_4 + b_5 k_5 + b_6 k_6 \tag{20}$$

- 3 The coefficients are given in Table 2
- 4  $(x_n, y_n)$  are the values at the beginning of the interval.  $(x_{n+1}, y_{n+1})$  are the values at the end. Actually, there are 7 equations for each  $y_n$  corresponding to the 7 output values.

Table 2: 5th Order Runge-Kutta Coefficeints

5 Solving this set of differential equations:

$$\frac{dx}{dt} = v_x \tag{21}$$

$$\frac{dy}{dt} = v_y \tag{22}$$

$$\frac{dz}{dt} = v_z \tag{23}$$

$$\frac{dv_x}{dt} = F_x(x, y, z, v_x, v_y, v_z) \tag{24}$$

$$\frac{dy}{dt} = v_x \tag{21}$$

$$\frac{dy}{dt} = v_y \tag{22}$$

$$\frac{dz}{dt} = v_z \tag{23}$$

$$\frac{dv_x}{dt} = F_x(x, y, z, v_x, v_y, v_z) \tag{24}$$

$$\frac{dv_y}{dt} = F_y(x, y, z, v_x, v_y, v_z) \tag{25}$$

$$\frac{dv_z}{dt} = F_z(x, y, z, v_x, v_y, v_z) \tag{26}$$

$$f = f_0 e^{-\nu(x, y, z, v_x, v_y, v_z)t} \tag{27}$$

$$\frac{dv_z}{dt} = F_z(x, y, z, v_x, v_y, v_z) \tag{26}$$

$$f = f_0 e^{-\nu(x, y, z, v_x, v_y, v_z)t} (27)$$

27 Lifetimes/JupiterPlasma_3.1.pro
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${\bf 33  Model IO/Benna Precipitation Filename\_1.0.pro}$
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# $34 \sqrt{\text{ModelIO}/\text{MercuryModelEndTime}}$ 1.0.pro

### **Summary**

Computes the appropriate value of *input.options.endtime* for a Mercury model run as a function of true anomaly angle. The appropriate value is set at  $4\times$  the photoionization lifetime.

#### **Calling Procedure**

endtime = MercuryModelEndTime(atoms, taa)

#### Inputs

- 1 atoms = species to look at
- 2 taa = true anomaly angle in radians

#### **Outputs**

Function returns  $4\times$  the photoionization lifetime of each species at the requested true anomaly angles.

#### Model Procedures Called

- 1 planet dist: determines Mercury's distance from the sun as function of true anomaly.
- 2 search atomicdata [not in the manual yet]

#### **Notes**

None.

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# $44 \quad \sqrt{\text{ModelIO/print\_inputs}\_3.1.pro}$

# **Summary**

Prints the contents of an input structure to the screen.

#### **Calling Procedure**

print\_inputs, input, printarr=printarr

# Inputs

1 input: either an input structure or the name on an inputfile

# Outputs

1 printarr: contains a strarr with each of the input fields

#### Model Procedures Called

1 inputs\_restore

#### Notes

None.

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9 December 2011.

45 SourceDistributions/PSD_distribution_1.1.pro
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46 SourceDistributions/SO2exosphere_distribution_3.2.pro
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# 47 SourceDistributions/SourceFlux\_1.0.pro Summary Calling Procedure Inputs Outputs Model Procedures Called Notes This Page Last Updated

48 SourceDistributions/SourceRate_1.0.pro
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$49  Source Distributions/add\_perturbation\_2.2.pro$
Summary
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# 50 SourceDistributions/angular distribution 3.1.pro

#### Summary

Determines the initial angular distribution for packets.

#### **Calling Procedure**

angular\_distribution, input, output, npack, seed

#### Inputs

- 1 input = input structure
- 2 output = output structure with  $output.vx\theta$ =initial speed distribution.
- 3 npack = number of packets
- 4 seed = seed for random number generator

#### Outputs

1 output = output structure with output.vx0, output.vy0, and output.vz0 defined in units of  $R_{plan}$  s<sup>-1</sup>

#### Model Procedures Called

- 1 random\_nr
- $2 \text{ RandomDeviates\_1d}$

#### **Notes**

- 1 First step: randomly choose altitude  $(\theta)$  and azimuth  $(\phi)$  angles.
  - 1.1 Altitude is measured from surface tangent ( $\theta = 0$ ) to surface normal ( $\theta = \pi/2$ ).
  - 1.2 The zero point for azimuth angle is not clear to me. It is possible to limit the azimuth angle, but I'm not sure exactly how the zero point is defined at each point on the surface. It is better to use the default  $(0 \le \phi \le 2\pi)$ .
  - 1.3 Three options for angulardist.type: radial, isotropic, costheta
  - 1.4 Radial ejection
    - 1.4.1  $\theta = \pi/2$  for all packets
    - 1.4.2  $\phi = 0$  for all packets (azimuth angle is technically undefined for normal ejection.
  - 1.5 Isotropic ejection
    - 1.5.1 Azimuth angles are evenly distributed from  $0 \to 2\pi$ .
    - 1.5.2  $\sin \theta$  is evenly distributed between  $0 \to 1$  for distributions that start at the surface  $(2\pi \text{ ejection into outward-facing hemisphere})$  or  $-1 \to 1$  for ejection into  $4\pi \text{ str.}$
  - 1.6 costheta ejection
    - 1.6.1 Azimuth angles are evenly distributed from  $0 \to 2\pi$ .
    - $1.6.2 \ f(\sin \theta) = \sin^n \theta$

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20 January 2012

$51  Source Distributions/charge\_exchange\_perturbation\_2.0.p$	ro
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52 SourceDistributions/exosphere_distribution_3.0.pro
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53 SourceDistributions/show_veldist_1.0.pro			
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# 54 ✓ Source Distributions/source distribution 3.3.pro

#### Summary

Determines the initial positions and velocities for each packet. This is a driver program which calls the procuedures to determine initial spatial, speed, and angular distributions of packets.

#### **Calling Procedure**

source\_distribution, input, npack, seed, output=output

#### Inputs

- 1 input: input structure
- 2 npack: number of packets in the output
- 3 seed: seed for random number generator (optional)

#### Outputs

1 output: an output structure (see below)

#### Model Procedures Called

- 1 random nr
- 2 surface distribution
- 3 torus distribution
- 4 exosphere distribution
- 5 SO2exosphere distribution
- 6 PSD distribution
- 7 speed distribution
- 8 angular distribution
- 9 add perturbation
- 10 locmoon

#### Notes

Procuedure used:

- 1 Create the output structure (see Table 3 for description of fields). This just sets up the structure put does not put any values into the fields.
- 2 output.f0 = 1 for all packets initially.
- 3 Set the output time:
  - If input.options.at\_once = 1, then output.time is set to input.options.endtime for all packets.
  - If input.options.at\_once = 0, then output.time is set to a random value between 0 and input.options.endtime.
- 4 Set the initial locations for packets. Possible distributions allowed in input.SpatailDist.type are:
  - *surface*: starts all packets at a sphere located at input.geometry.startpoint's surface or a uniform exobase. See surface distribution
  - torus: starts all packets in a uniform torus around input.geometry.startpoint. See torus\_distribution

- exosphere: starts all the packets in an exosphere over the surface of input.geometry.startpoint See exosphere distribution
- SO2 exosphere: Uses Vincent Dol's exospheric source model. See SO2 exosphere distribution
- *PSD distribution*: Approximation to the ion-enhanced PSD distribution described by Burger et al. (2010). See PSD\_distribution

These routines set output.x0, output.y0, and output.z0 in a coordinate system centered on input.geometry.startpoint. A transformation to the input.geometry.planet-cenetered coordinate system is made later, if necessary.

- 5 Set the initial speed distribution. See speed\_distribution. This routine sets the initial speed (and possibly the components of the speed) in units of R<sub>plan</sub> s<sup>-1</sup>. Satellite orbital velocity is not included yet.
- 6 Set the angular disitribution, if necessary. See angular\_distribution. This routine sets output.vx0, output.vx0, and output.vz0 (if it has not already been done) in a coordinate system centered on input.geometry.startpoint. A transformation to the input.geometry.planet-centered coordinate system is made later, if necessary.
- 7 Add a perturbation to the intial velocities, if requested. See add perturbation.
- 8 Make the conversion from the input.geometry.startpoint-centered system to the input.geometry.planet-centered system if necessary.
  - 8.1 Move the packets out to their starting distance and rescale from R<sub>st.pt.</sub> to R<sub>plan</sub>:

$$x = x_0 \times \text{SystemConsts.radius}$$
 (28)

$$y = y_0 \times SystemConsts.radius + SystemConsts.a$$
 (29)

$$z = z_0 \times \text{SystemConsts.radius}$$
 (30)

This places each packet at the satellite's orbital distance at orbital phase  $= 0^{\circ}$  (local midnight).

8.2 Add in the orbital velocity, if input.options.motion=1:

$$v_x = vx_0 \tag{31}$$

$$v_y = vy_0 - \text{SystemConsts.orbvel}$$
 (32)

$$v_z = vz_0 \tag{33}$$

For a packet at orbital phase =  $0^{\circ}$ , the direction of orbital motion is in the  $-\hat{y}$  direction.

- 8.3 Determine output.phi0, the orbital phase of the satellite at the start time of each packet (output.time seconds ago). See locmoon.
- 8.4 Rotate the packets to the proper location in planet-centered coordinates:

$$output.x = x\cos\phi_0 - y\sin\phi_0 \tag{34}$$

$$output.y = x \sin \phi_0 + y \cos \phi_0 \tag{35}$$

$$output.z = z (36)$$

$$output.vx = v_x \cos \phi_0 - v_y \sin \phi_0 \tag{37}$$

$$output.vy = v_x \sin \phi_0 + v_y \cos \phi_0 \tag{38}$$

$$output.vz = v_z \tag{39}$$

- 9 output.x0, etc., are in startpoint-centered coordinates. These are not used in any of the model computations.
- 10 output.x, etc., are in planet-centered coordinates. These are used in all of the model computations.

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55 SourceDistributions/speed_distribution_3.3.pr	O
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56	${\bf Source Distributions/speed\_}$	$_{ m dists}_{ m }$	$_{2}.1.\mathrm{pro}$
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# ${\bf 57 \quad Source Distributions/surface\_distribution \quad 3.2.pro}$

#### Summary

Distribute packets about a sphere with radius r = input.SpatialDist.exobase

#### **Calling Procedure**

surface\_distribution, input, output, npack, seed

#### Inputs

- 1 input: input structure
- 2 output: output structure defined in source distribution (Table 3)
- 3 npack: number of packets in the output
- 4 seed: seed for random number generator (optional)

#### **Outputs**

1 output: output.x0, output.y0, and output.z0 fields are populated.

#### Model Procedures Called

- 1 RandomDeviates 2d
- 2 random nr

#### Notes

There are several ways to use this option:

- 1 Use a predefined map file:
  - 1.1 The following lines must be included in the *input* file.

```
SpatialDist.type = surface
SpatialDist.use_map = 1
SpatialDist.mapfile = path_to_mapfile
```

1.2 mapfile is an IDL savefile with a variable called sourcemap which is a structure defined by:

```
sourcemap = {longitude:ptr_new(longitude), latitude:ptr_new(latitude), $
    map:ptr_new(map)}
```

where:

- longitude is an array of longitude ( $\lambda$ ) values in radians. See Section ?? for definition of longitude. The acceptable range of values is  $0 \le \lambda \le 2\pi$ . I generally set this to: longitude = fltarr(361)\*!dtor}
- latitude is an array of latitude  $(\mu)$  values in radians. The acceptable range of values is  $-\pi/2 \le \mu \le \pi/2$ . I generally set this to latitude = fltarr(181)\*!dtor !pi/2.
- map is an array of size  $(n_{\lambda}, n_{\mu})$  containing the relative source flux (particles per unit area) as a function of  $\lambda$  and  $\mu$ . This does not need to be absolute flux since it is normalized to the total number of packets ejected.
- 2 Uniform ejection within a specified range
  - 2.1 The following lines must be included in the input file:

```
SpatialDist.type = surface
```

SpatialDist.use\_map = 0

The following lines are optional:

SpatialDist.longitude0 = minlong

SpatialDist.longitude1 = maxlong

SpatialDist.latitude0 = minlat

SpatialDist.latitude1 = maxlat

- 2.2 minlong  $(\lambda_{min})$  and maxlong  $(\lambda_{max})$  are the minimum and maximum longitude values with  $0 \le \lambda_{min}, \lambda_{max} \le 2\pi$ .
  - If  $\lambda_{min} < \lambda_{max}$ , then packets are randomly distributed with  $\lambda_{min} \leq \lambda < \lambda_{max}$  (Figure 2a).
  - If  $\lambda_{min} > \lambda_{max}$ , then packets are randomly distributed with  $\lambda_{max} \leq \lambda < \lambda_{max} + 2\pi$  (Figure 2b).
  - If  $\lambda_{min} = \lambda_{max}$  then all packets are set to  $\lambda = \lambda_{min}$ .
- 2.3 minlat  $(\mu_{min})$  and maxlat  $(\mu_{max})$  are the minimum and maximum values of latitude with  $\pi/2 \le \mu_{min} \le \mu_{max} \le \pi/2$ .
- 2.4 Default values:

$$\begin{array}{rcl} \lambda_{min} & = & 0 \\ \lambda_{max} & = & 2\pi \\ \mu_{min} & = & -\pi/2 \\ \mu_{max} & = & \pi/2 \end{array}$$

- 3 Choosing random values:
  - 3.1 Longitude values are evenly distributed between  $\lambda_{min}$  and  $\lambda_{max}$ , so we can choose values with:

$$\lambda = \lambda_{min} + (\lambda_{max} - \lambda_{min})R \tag{40}$$

where R is a random deviate from a uniform distribution with  $0 \le R < 1$ .

3.2 Latitude values are not evenly distributed; however,  $\sin \mu$  are, so we can choose values with:

$$\sin \mu = \sin \mu_{min} + (\sin \mu_{max} - \sin \mu_{min})R \tag{41}$$

where R is a random number as above and  $-1 \le \sin \mu < 1$ .

- 4 If input.geometry.StartPoint = input.geometry.planet then:
  - local noon:  $\lambda = 0^{\circ}, (x, y, z) = (0, -1, 0)$
  - local dusk:  $\lambda = 90^{\circ}, (x, y, z) = (1, 0, 0)$
  - local midnight:  $\lambda = 180^{\circ}$ , (x, y, z) = (0, 1, 0)
  - local dawn:  $\lambda = 270^{\circ}, (x, y, z) = (-1, 0, 0)$

$$x_0 = r_0 \sin \lambda \cos \mu \tag{42}$$

$$y_0 = -r_0 \cos \lambda \sin \mu \tag{43}$$

$$z_0 = r_0 \sin \mu \tag{44}$$

where  $r_0 = input.SpatialDist.exobase$ 

- 5 If input.geometry.StartPoint ≠ input.geometry.planet then:
  - sub-planet:  $\lambda = 0^{\circ}, (x, y, z) = (0, -1, 0)$
  - leading side:  $\lambda = 90^{\circ}, (x, y, z) = (1, 0, 0)$

- $\begin{array}{l} \bullet \ \ {\rm anti-planet:} \ \lambda = 180^{\circ}, \ (x,y,z) = (0,1,0) \\ \bullet \ \ {\rm trailing \ side:} \ \lambda = 270^{\circ}, \ (x,y,z) = (-1,0,0) \\ \end{array}$

$$x_0 = -r_0 \sin \lambda \cos \mu \tag{45}$$

$$y_0 = -r_0 \cos \lambda \cos \mu \tag{46}$$

$$z_0 = r_0 \sin \mu \tag{47}$$

21 December 2011.

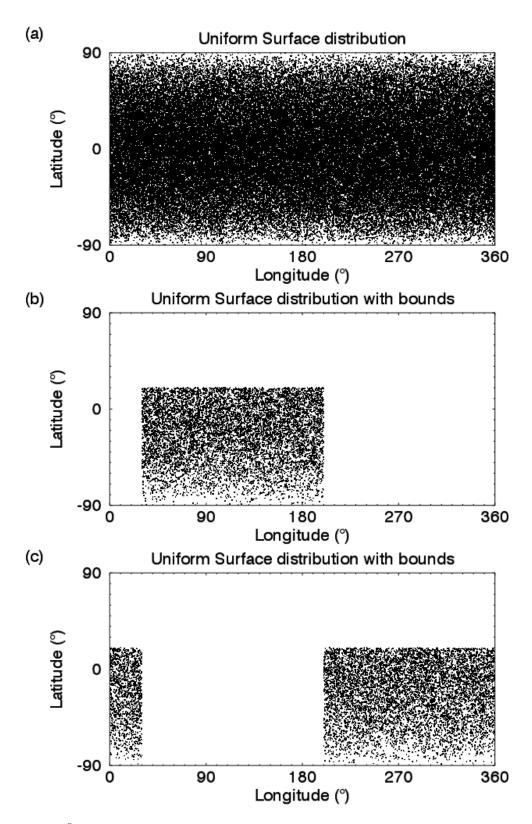


Figure 2: (a)  $10^5$  packets randomly distributed in longitude and latitude over a surface. (b)  $10^4$  packets randomly distributed over a surface with  $\lambda_{min} = 30^\circ$ ,  $\lambda_{max} = 200^\circ$ ,  $\mu_{min} = -90^\circ$ , and  $\mu_{max} = 20^\circ$ . (c)  $10^4$  packets randomly distributed over a surface with  $\lambda_{min} = 200^\circ$ ,  $\lambda_{max} = 30^\circ$ ,  $\mu_{min} = -90^\circ$ , and  $\mu_{max} = 20^\circ$ .

58 SourceDistributions/surface_temperature_3.0.pro
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59 SourceDistributions/torus_distribution_2.0.pro
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60 loc\_operations\_3.0.pro
Summary
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## $61 \sqrt{\text{locmoon}} 1.0.\text{pro}$

#### **Summary**

Calculates the coordinates of each moon given a "final" orbital longitude and a time difference. Determines where a moon was *time* seconds ago.

#### **Calling Procedure**

locmoon, time, theta0, radius, orbrate, x=x, y=y, z=z, ang=ang

#### Inputs

- time: time before moon was at theta0 (seconds)
- theta0: final orbital longitude of each moon (radians). Corresponds to the position at time=0.
- radius: orbital radius of each moon (R<sub>plan</sub>)
- orbrate: angular speed of each moon (radians/sec)

### Outputs

- x: x-position of each moon relative to the planet *time* seconds it was before it was at *theta0* (R<sub>plan</sub>)
- y: y-position of each moon relative to the planet time seconds it was before it was at theta0 (R<sub>plan</sub>)
- z: z-position of each moon relative to the planet time seconds it was before it was at theta0 (R<sub>plan</sub>)
- ang: orbital longitude time seconds ago (radians)

#### Model Procedures Called

None.

#### **Notes**

- time and theta0 are arrays of length npackets. radius and orbrate are arrays with length nobj (number of objects in the system which are included in the model run).
- The outputs are arrays of size (npackets x nobj) which give the location (in model coordinates) of each satellite as seen by each packet.
- $z \equiv 0 \rightarrow I$  have assumed satellites orbit in the planetary equatorial planes.
- Equations used:

$$\theta = -tR + \theta_0 \tag{48}$$

$$x = -r\sin\theta \tag{49}$$

$$y = r\cos\theta \tag{50}$$

where  $\theta$  is ang, t is time, R is orbrate  $\theta_0$  is theta0, and r is radius.

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## $62 \quad \sqrt{\bmod el\_common\_blocks\_3.0.pro}$

## Summary

Initializes the common blocks used in the model

### **Calling Procedure**

model\_common\_blocks

#### Inputs

None.

## Outputs

None.

#### Model Procedures Called

None.

#### **Notes**

Three common blocks are defined:

- 1 constants
  - SystemConsts: See Table 4
  - DipoleConsts: See Table 5
  - stuff: See modeldriver
- 2 ratecoefs
  - kappa: See modeldriver
- 3 plasma
  - plasma: See modeldriver
  - plasmahot: See modeldriver

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63 model\_findpackets\_4.0.pro
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64 modeldriver\_3.9.pro

Summary

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65	$model streamlines B\_$	$\_3.0.\mathrm{pro}$					
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$66 \mod \text{elstreamlines}$	$\_3.0.$ pro						
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$67  modstream A\_3.0.pro$
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$68 \mod \text{streamB} \_ 3.0. \text{pro}$							
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## 69 √planet dist 2.0.pro

#### Summary

Calculates the distance and radial velocity of a planet relative to the sun as a function of true anomaly angle.

#### **Calling Procedure**

planet\_dist, taa, SystemConsts, distance=distance, velocity=velocity

#### Inputs

- 1 taa: array containing true anomaly angles in radians
- 2 SystemConsts: a SystemConstants structure.

#### **Outputs**

- 1 distance: distance of the planet from the sun. Units: AU
- 2 velocity: radial velocity (dr/dt) of the planet from the sun. Units: km s<sup>-1</sup>.

#### Model Procedures Called

None.

#### **Notes**

- 1 The radial velocity is only computed for Mercury and Pluto. Otherwise, it is assumed to be 0. This is to avoid having to model a specific true anomaly for Jupiter and Saturn where dr/dt is small.
- 2 Equations:

$$r = \frac{a(1+\epsilon)}{1+\epsilon\cos\phi} \tag{51}$$

$$v_r = \frac{dr}{dt} \tag{52}$$

where a is the semi-major axis,  $\epsilon$  is the orbital eccentricity, and  $\phi$  is the true anomaly angle. While computing r is straight forward, computing  $v_r$  is not as that requires knowing how  $\phi$  varies with time.

- 3 Procedure used (from wikipedia):
  - 3.1 The mean anomaly is given by:

$$M = \frac{2\pi t}{P} \tag{53}$$

where P is the orbital period and t is time (t/P) is the orbital phase

3.2 The *eccentric anomaly* is the angle from perihelion to the center of the ellipse to the planet:

$$M = E - \epsilon \sin E \tag{54}$$

where E, the eccentric anomaly, is determined numerically.

3.3 The true anomaly angle is given by:

$$\tan(\phi/2) = \sqrt{\frac{1+\epsilon}{1-\epsilon}} \tan(E/2) \tag{55}$$

which can easily be inverted to compute  $\phi$ .

3.4 To get  $\phi(t)$ , I compute  $\phi$  at 1000 points discrete points along the orbit and numerically compute the derivative dr/dt. This gives  $\phi$ , r, and dr/dt as functions of time (converting from orbital phase to time units using Kepler's Third Law,  $P^2 = a^3$ , to get the orbital period). I compute r and drdt at the requested true anomalies by linear interpolation.

#### This Page Last Updated

12 December 2011

# References

Burger et al. 2010.

Killen et al. 2009.

Field	Data Type	$\mathbf{Unit}$	Description
x0	pointer to dblarr	R <sub>obj</sub>	initial x position
у0	pointer to dblarr	$R_{obj}$	initial y position
z0	pointer to dblarr	$R_{obj}$	initial $z$ position
fO	pointer to dblarr	_	initial fractional content
vx0	pointer to dblarr	$R_{\rm plan}~{ m s}^{-1}$	initial $v_x$
vy0	pointer to dblarr	$R_{\rm plan}~{\rm s}^{-1}$	initial $v_y$
vz0	pointer to dblarr	$R_{\rm plan}~{\rm s}^{-1}$	initial $v_z$
phi0	pointer to dblarr	radians	initial orbital phase (local time)
totalsource	double	$R_{obj}$	total of f0
time	pointer to dblarr	$\sec$	integration time for each packet
x	pointer to dblarr	$R_{plan}$	final $x$ position
У	pointer to dblarr	$R_{plan}$	final $y$ position
z	pointer to dblarr	$R_{plan}$	final $z$ position
frac	pointer to dblarr	_	final fractional content
VX	pointer to dblarr	$R_{\rm plan}~{\rm s}^{-1}$	final $v_x$
vy	pointer to dblarr	$R_{\rm plan}~{\rm s}^{-1}$	final $v_y$
VZ	pointer to dblarr	$R_{\rm plan} \ s^{-1}$	final $v_z$
lossfrac	pointer to dblarr	_	fraction lost to ionization
hitfrac	pointer to dblarr	_	fraction hitting objects
ringfrac	pointer to dblarr	_	fraction hitting Saturn's rings
leftfrac	pointer to dblarr	_	fraction escaping beyond input.options.outeredge
deposition	structure	_	map of surface deposition (Table ??)
loss_info	structure	_	ionization and dissociation reactions used (Table ??)
sourcefile	pointer to strarr	_	origin of this output file

Table 3: output fields.

$\mathbf{Field}$	Data Type	${f Unit}$	Description
Planet	string	_	Planet name
rPlan	double	$\mathrm{km}$	Planetary radius
aPlan	double	AU	Planetary semi-major axis
epsPlan	double	_	Planetary eccentricity
Objects	pointer to strarr	_	Object (planet and satellite) names (1)
GM	pointer to dblarr	$R_{\rm plan}^3 \ {\rm s}^{-2}$	Gravitational constant $\times$ Planetary mass $(1,2)$
radius	pointer to dblarr	$R_{plan}$	Radius of each object relative to planetary radius (1)
a	pointer to dblarr	$R_{plan}$	semi-major axis of each object relative to plantary radius (1)
eps	pointer to dblarr	_	eccentricity of each object (1)
orbvel	pointer to dblarr	${\rm km~s^{-1}}$	orbital velocity of satellites (2)
period	pointer to dblarr	$\mathbf{s}$	orbital period of satellites (1)
orbrate	pointer to dblarr	$s^{-1}$	orbital frequency of satellites (= $2\pi/\text{period}$ ) (1)

Table 4: SystemConsts fields. Notes: (1) The length of these arrays is (number of satellites) + 1. The first element refers to the planet and is 0, except for radius (where it is 1). (2)  $G = 6.67428 \times 10^{-8} \text{ cm}^{-3} \text{ s}^{-2} \text{ g}^{-1}$ 

$\mathbf{Field}$	Data Type	$\mathbf{Unit}$	Description
strength	double	$G R_{plan}^{3}$	Dipole field strength
tilt	double	radians	Dipole tilt
lam3	double	radians	Longitude of tilt
offset	double	$R_{plan}$	Dipole offset
offlong	double	radians	Longitude of offset
offlat	double	radians	Latitude of offset
period	double	hours	Dipole period
magrat	double	$hours^{-1}$	Dipole rotation frequency $(2\pi/\text{period})$

Table 5: DipoleConsts fields.

Object	orbits	radius	mass	a	$\epsilon$	rot period	orb period
Sun	_	$6.955 \times 10^{5}$	$1.9891 \times 10^{30}$	0	0	601.2	0.
Mercury	Sun	2439.7	$0.330104 \times 10^{24}$	0.387098	0.205630	1407.51	87.97
Venus	Sun	6051.8	$4.86732 \times 10^{24}$	0.723	0.0068	5832.45	244.70
Earth	$\operatorname{Sun}$	6378.14	$5.97219 \times 10^{24}$	1.0	0.0167	23.93	365.25
Mars	Sun	3396.2	$0.641693 \times 10^{24}$	1.524	0.0934	24.62	687.02
Jupiter	$\operatorname{Sun}$	71492.	$1898.13 \times 10^{24}$	5.203	0.0483	9.9250	4333.
Saturn	$\operatorname{Sun}$	60268.	$568.319 \times 10^{24}$	9.529	0.0560	10.7625	10743.
Uranus	Sun	25559.	$86.8103 \times 10^{24}$	19.19	0.0461	17.24	30700.
Neptune	Sun	24764.	$102.410 \times 10^{24}$	30.09	0.0097	16.11	60280.
Pluto	$\operatorname{Sun}$	1151.	$0.01309 \times 10^{24}$	39.24	0.2482	153.29	90130.
Moon	Earth	1737.10	7.3477e22	384400	0.554	655.728	27.322
Io	Jupiter	1821.6	8.9319e22	421800.	0.0041	42.456	1.769
Europa	Jupiter	1560.8	4.8e22	671100.	0.0094	85.224	3.551
Ganymede	Jupiter	2163.2	1.4819e23	1070400.	0.0013	171.72	7.155
Callisto	Jupiter	2410.3	1.0759e23	1882700.	0.0074	400.56	16.69
Mimas	Saturn	198.2	0.4e20	185539.	0.0196	22.608	0.942
Enceladus	Saturn	252.1	1.1e20	238037.	0.0047	31.344	1.370
Tethys	Saturn	533.0	6.2e20	294672.	0.0001	45.312	1.888
Dione	Saturn	561.7	11e20	377415.	0.0022	65.688	2.737
Rhea	Saturn	764.3	23e20	527068.	0.0010	108.432	4.518
Titan	Saturn	2575.5	1350e20	1221865.	0.0288	478.800	15.95
Hyperion	Saturn	135.0	5.58e18	1500934.	0.0232	510.720	21.28
Iapetus	Saturn	735.6	18e20	3560851.	0.0293	1903.92	79.33
Phoebe	Saturn	106.6	8.292e18	12947913.	0.1634	13207.2	550.30
Charon	Pluto	593.	1.62e21	19600.	0.	153.294	6.38725
Nix	Pluto	68.	2e18	48708.	0.	596.544	24.856
Hydra	Pluto	84.	2e18	64749.	0.	916.944	38.206

Table 6: Solar System Parameters