```
bls = 51794/57600d & b2s = 0d & b3s = 7571d/16695d & b4s = 393d/640d
b5s = -92097d/339200d & b6s = 187d/2100d & b7s = 1d/40d
b1d = b1-b1s & b2d = b2-b2s & b3d = b3-b3s & b4d = b4-b4s & b5d = b5-b5s & b6d = b6-b6s
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    The radiation pressure function only looks to see if the packet is in the
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   * xyz_to_magcoords and ionization_rate now determine whether the packet is shadowed by planets and moons. rk_5 is consistent with changes in those
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        a31 = 3d/40d & a32 = 9d/40d a41 a41 = 32d/9d a41 = 44d/45d & a42 = -56d/15d & a43 = 32d/9d a51 = 19372d/6561d & a52 = -25360d/2187d & a53 = 64448d/6561d & a54 = -212d/729d a51 = 19372d/6561d & a62 = -355d/33d & a63 = 46732d/5247d & a64 = 49d/176d
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         b1 = 35d/384d & b2 = 0d & b3 = 500d/1113d & b4 = 125d/192d & b5 = -2187d/6784d b6 = 11d/84d & b7 = 0d
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           ;; RK coefficients c2 = 0.2d & c3 = 0.3d & c4 = 0.8d & c5 = 8./9.d & c6 = 1d & c7 = 1d
                                                                                                                              This does a 5th order RK step and computes the error estimate
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 planet shadow. Adding fix to check for moon shadow also
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     9q
=
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                a76
                                                                                                                                                                                                                                                                                                                                                                                                                                                                   * cleaning up a bit and checking the error estimate
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  = b5 &
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     * Updating for new structure architecture
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             a71 = b1 & a72 = b2 & a73 = b3 & a74 = b4 & a75
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         pro rk_5, loc, h, input, which, delta
                                                                                                                                                                ;; See Numerical Recipes, ch 17.2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                a65 = -5103d/18656d
                                                                                                                                                                                                                                                                                                                                = -f * ioniz
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    hh = h # [1., 1., 1.]
hh2 = h^{2} # [1., 1.,
                                                                                                                                                                                                                                                                                                                                                                                                                                 ;; * 3.1: 4/27/2011
                                                                                                                                                                                                                                                                                                                                                                                                    ;; Version History
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      ;; * 2.1: 4/26/10
                                                                                                                                                                                                                                 ;; For each step:
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                3.0: 7/21/10
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  ;; * 2.2: 4/26/10
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              routines
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               common constants
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            = b7-b7s
                                                                                                                                                                                                                                                                                                 f_v = a
f_f = -f
                                                                                                                                                                                                                                                                   f_x = v
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             a21 = 0.2d
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            b7d
```

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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            loc4 = {t: ptr_new(*loc.t - c4*h), $
    x: ptr_new(*loc.x + a41*k1x + a42*k2x + a43*k3x),
    v: ptr_new(*loc.v + a41*k1v + a42*k2v + a43*k3v),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   step 3
loc3 = {t: ptr_new(*loc.t - c3*h), $
    x: ptr_new(*loc.x + a31*k1x + a32*k2x), $
    v: ptr_new(*loc.v + a31*k1v + a32*k2v), $
    frac: ptr_new(*loc.frac + a31*k1f + a32*k2f)}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                               ioniz2 = ionization_rate(loc2, input, magcoord)
a2 = accel(loc2, input, magcoord, which)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    magcoord = xyz_to_magcoord(loc3, input)
ioniz3 = ionization_rate(loc3, input, magcoord)
                                                                  ioniz1 = ionization_rate(loc, input, magcoord)
                                                                                                                                                                                                                                                                                         frac: ptr_new(*loc.frac+a21*klf)}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       a3 = accel(loc3, input, magcoord, which)
                                                                                                                                                                                                                                                                                                                                                                                                                                                          magcoord = xyz_to_magcoord(loc2, input)
                                                                                              al = accel(loc, input, magcoord, which)
                                             magcoord = xyz_to_magcoord(loc, input)
                                                                                                                                                                                                                                                                                                                                                         x: ptr_new(*loc.x+a21*k1x), $
                                                                                                                                                                                                                                                                                                                                                                                    v: ptr_new(*loc.v+a21*klv),
                                                                                                                                                                                                                                                                                                                                 loc2 = {t: ptr_new(*loc.t-c2*h), $
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               k3v = hh**a3.dvdt
k3f = -h**loc3.frac*ioniz3
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  k2v = hh**a2.dvdt
k2f = -h**loc2.frac*ioniz2
                                                                                                                                                                                   klv = hh**al.dvdt
klf = -h**loc.frac*ioniz1
;; Step 1
;; k1 = h*f(x_n,y_n)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   \log 2 = 0 \& a2 = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               10c3 = 0 & a3 = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               k2x = hh^**loc2.v
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           k3x = hh^**loc3.v
                                                                                                                                                                  k1x = hh^**loc.v
                                                                                                                     magcoord = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 magcoord = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              magcoord = 0
                                                                                                                                                                                                                                                                                                              ;; Step 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         ;; Step 4
                                                                                                                                                                                                                                          a1 = 0
```

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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            loc7 = {t: ptr_new(*loc.t - c7*h), $
x: ptr_new(*loc.x + a71*k1x + a72*k2x + a73*k3x + a74*k4x + a75*k5x + a76*k6x),
v: ptr_new(*loc.v + a71*k1v + a72*k2v + a73*k3v + a74*k4v + a75*k5v + a76*k6v),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            loc6 = {t: ptr_new(*loc.t - c6*h), $
x: ptr_new(*loc.x + a61*klx + a62*k2x + a63*k3x + a64*k4x + a65*k5x), $
v: ptr_new(*loc.v + a61*klv + a62*k2v + a63*k3v + a64*k4v + a65*k5v), $
frac: ptr_new(*loc.frac + a61*klf + a62*k2f + a63*k3f + a64*k4f + a65*k5f)}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            frac: ptr_new(*loc.frac + a51*klf + a52*k2f + a53*k3f + a54*k4f)}
                                                                                                                                                                                                                                                                                                                                                                                                                                             loc5 = {t: ptr_new(*loc.t - c5*h), $
    x: ptr_new(*loc.x + a51*k1x + a52*k2x + a53*k3x + a54*k4x), $
    v: ptr_new(*loc.v + a51*k1v + a52*k2v + a53*k3v + a54*k4v), $
frac: ptr_new(*loc.frac + a41*k1f + a42*k2f + a43*k3f)}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            ioniz5 = ionization_rate(loc5, input, magcoord)
a5 = accel(loc5, input, magcoord, which)
                                                                                            ioniz4 = ionization_rate(loc4, input, magcoord)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           ioniz6 = ionization_rate(loc6, input, magcoord)
                                                                                                                                                                                                                                                                                                                                                                                        a6 = accel(loc6, input, magcoord, which)
                                                                                                                               a4 = accel(loc4, input, magcoord, which)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             magcoord = xyz_to_magcoord(loc5, input)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               magcoord = xyz_to_magcoord(loc6, input)
                                                              magcoord = xyz_to_magcoord(loc4, input)
                                                                                                                                                                                                                                                                                      k4f = -h**loc4.frac*ioniz4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   k5f = -h**loc5.frac*ioniz5
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     k6f = -h**loc6.frac*ioniz6
                                                                                                                                                                                                                                                        k4v = hh^**a4.dvdt
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     k5v = hh^**a5.dvdt
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    loc5 = 0 & a5 = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      k6v = hh**a6.dvdt
                                                                                                                                                                                                                                                                                                                         loc4 = 0 & a4 = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     loc6 = 0 & a6 = 0
                                                                                                                                                                                                                          k4x = hh^**loc4.v
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         k5x = hh^**loc5.v
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        k6x = hh^**loc6.v
                                                                                                                                                             magcoord = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             magcoord = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            magcoord = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     ;; Step 6
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  ;; Step 7
```

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frac: ptr_new(*loc.frac + a71*k1f + a72*k2f + a73*k3f + a74*k4f + a75*k5f
a76*k6f)}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 deltax = abs(bld*klx + b2d*k2x + b3d*k3x + b4d*k4x + b5d*k5x + b6d*k6x + b7d*k7x) deltav = abs(bld*klv + b2d*k2v + b3d*k3v + b4d*k4v + b5d*k5v + b6d*k6v + b7d*k7v) deltaf = abs(bld*klf + b2d*k2f + b3d*k3f + b4d*k4f + b5d*k5f + b6d*k6f + b7d*k7f)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              *loc.frac = *loc.frac + b1*k1f + b2*k2f + b3*k3f + b4*k4f + b5*k5f + b6*k6f
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        *loc.t = *loc.t - h
*loc.x = *loc.x + b1*k1x + b2*k2x + b3*k3x + b4*k4x + b5*k5x + b6*k6x
*loc.v = *loc.v + b1*k1v + b2*k2v + b3*k3v + b4*k4v + b5*k5v + b6*k6v
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          delta = {x:ptr_new(deltax), v:ptr_new(deltav), frac:ptr_new(deltaf)}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                ptr_free, loc7.t, loc7.x, loc7.v, loc7.frac, a7.dvdt
                                                                                                                                                                   ioniz7 = ionization_rate(loc7, input, magcoord)
a7 = accel(loc7, input, magcoord, which)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         magcoord = xyz_to_magcoord(loc7, input)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             ;; Step 8 -- Estimate the error
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         ;; Step 7 -- Compute the result
                                                                                                                                                                                                                                                        destroy_structure, magcoord
                                                                                                                                                                                                                                                                                                                                                                     k7v = hh**a7.dvdt
k7f = -h**loc7.frac*ioniz7
```