

Batch Multi-Fidelity Active Learning with Budget Constraints

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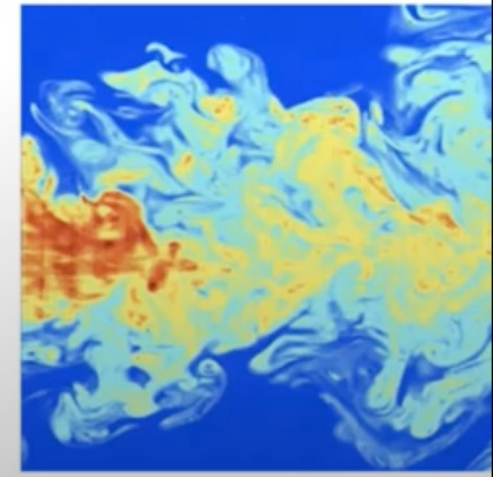
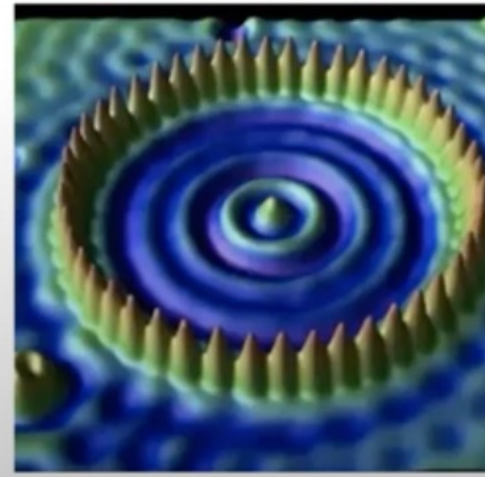
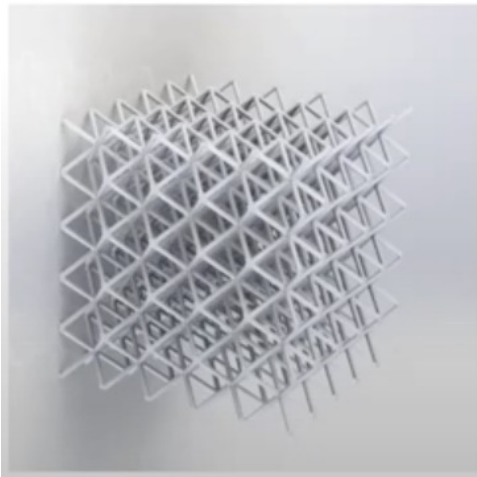
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Partial Differential Equations

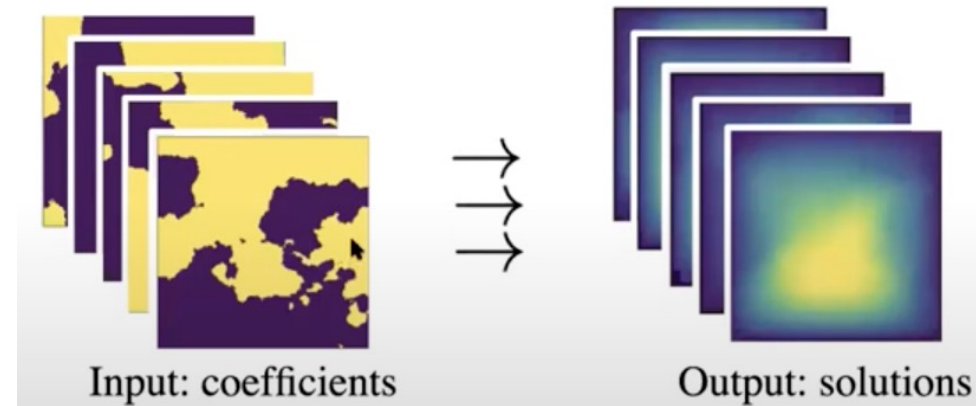
- PDE as the foundation for scientific computing
- Challenges:
 - Identify the governing model for complex systems
 - Efficiently solving large-scale non-linear systems of equations



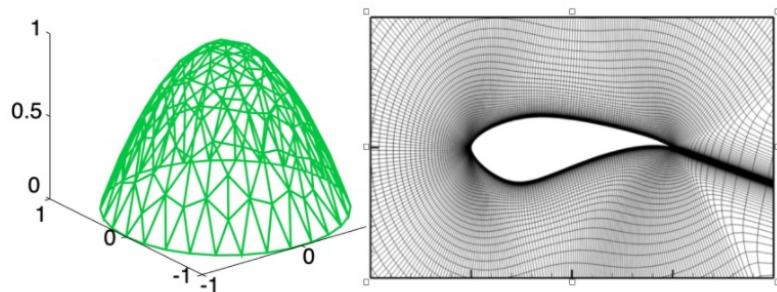


PDE Solutions: *Solve* vs. *Learn*

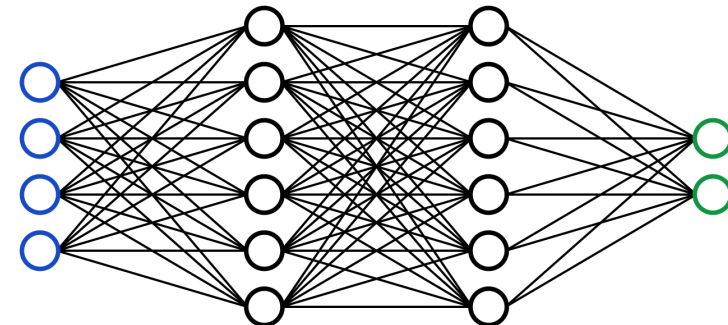
- Solving complicated PDEs:
 - Numerical solvers
 - Solve one instance
 - Data-driven solvers
 - Learn a family of solutions
 - Slow to train; fast to evaluate



Zongyi Li et al. 2020



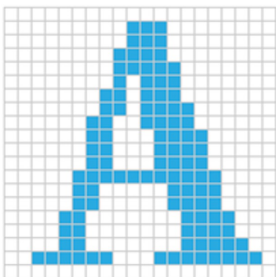
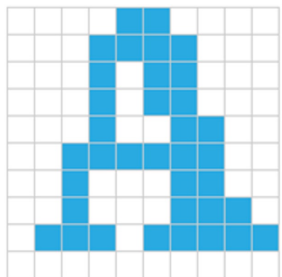
VS.





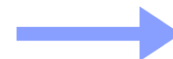
Multi-fidelity Active Learning

- Multi-fidelity Evaluations
 - *Low-fidelity solutions*: cheap to acquire but inaccurate
 - *High-fidelity solutions*: accurate but expensive to acquire
- Active Learning: Training examples are expensive

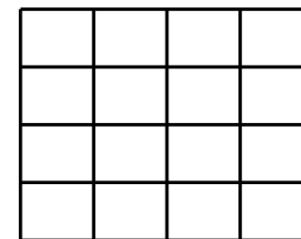


PDE parameters: ν
 $u_t + uu_x - \nu \cdot u_{xx} = 0$

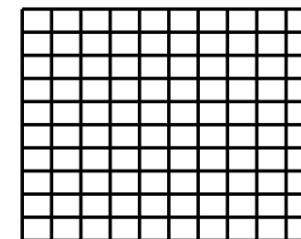
multi-fidelity surrogate to predict solution fields



PDE solvers



low-fidelity, cheap to solve

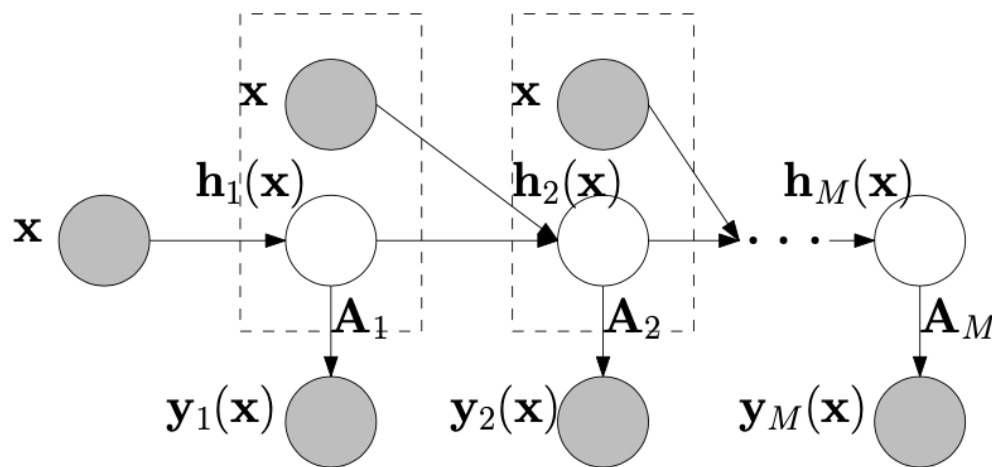


high-fidelity, costly to solve



Deep Multi-Fidelity Active Learning

- DMFAL (Li et al. 2022)



Concatenate inputs

Low-rank outputs

$$\xi_m = [\mathbf{x}; \mathbf{h}_{m-1}(\mathbf{x})], \quad \mathbf{h}_m(\mathbf{x}) = \mathbf{W}_m \rho_{\theta_m}(\xi_m)$$

$$\mathbf{y}_m(\mathbf{x}) = \mathbf{A}_m \mathbf{h}_m(\mathbf{x}) + \epsilon_m,$$

Outputs in solution space

MF Modeling

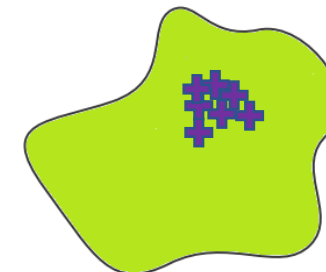
Jointly determines the query point and fidelity level

$$a(\mathbf{x}, m) = \frac{1}{\lambda_m} \mathbb{I}(\mathbf{y}_m(\mathbf{x}), \mathbf{y}_M(\mathbf{x}) | \mathcal{D})$$

$$= \frac{1}{\lambda_m} (\mathbb{H}(\mathbf{y}_m | \mathcal{D}) + \mathbb{H}(\mathbf{y}_M | \mathcal{D}) - \mathbb{H}(\mathbf{y}_m, \mathbf{y}_M | \mathcal{D}))$$

MF Acquisition

Ignoring the correlations between the successive queries

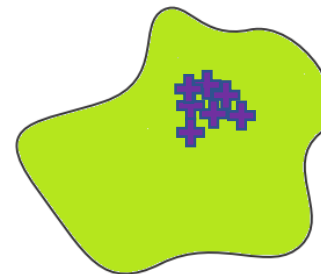
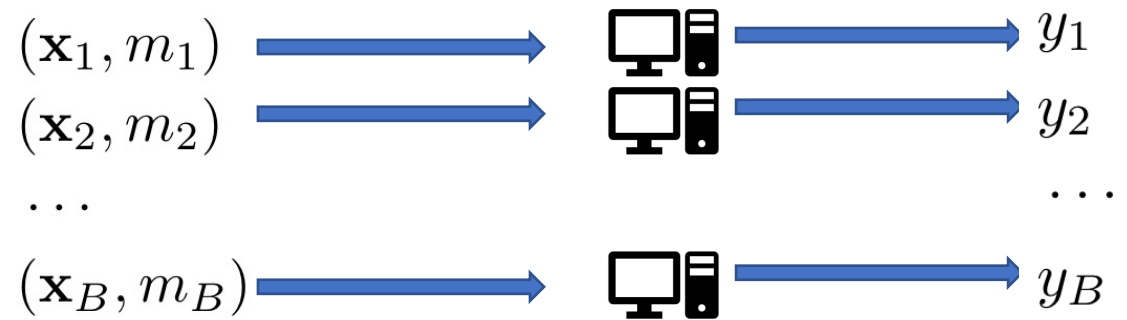




Our Contribution

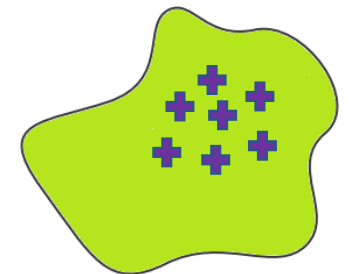
- A **batch** multi-fidelity active learning approach for high-dimensional outputs
- Consider **budget** constraints in query samples
- A proved efficient **greedy** algorithms that nearly **$1-1/e$ optimality**

Why batch matters?



Sequential strategy

vs.



Batch strategy



Novel Batch Acquisition

- Acquisition over the distribution over the input space:

$$a_s(m, \mathbf{x}) = \mathbb{E}_{p(\mathbf{x}')} [\mathbb{I}(\mathbf{y}_m(\mathbf{x}), \mathbf{y}_M(\mathbf{x}') | \mathcal{D})]$$

- Consider the batch budget

$$a_{\text{batch}}(\mathcal{M}, \mathcal{X}) = \mathbb{E}_{p(\mathbf{x}')} [\mathbb{I}(\{\mathbf{y}_{m_j}(\mathbf{x}_j)\}_{j=1}^n, \mathbf{y}_M(\mathbf{x}') | \mathcal{D})], \quad \text{s.t.} \quad \sum_{j=1}^n \lambda_{m_j} \leq B$$

$$\mathcal{M} = \{m_1, \dots, m_n\}, \mathcal{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$$

- Monte-Carlo approximation of target acquisition

$$\hat{a}_{\text{batch}}(\mathcal{M}, \mathcal{X}) = \frac{1}{A} \sum_{l=1}^A \mathbb{I}(\{\mathbf{y}_{m_j}(\mathbf{x}_j)\}_{j=1}^n, \mathbf{y}_M(\mathbf{x}'_l) | \mathcal{D})$$

Incurs combinatorial search over multiple fidelities



Weighted Greedy Optimization

- A weighed incremental version of acquisition

$$\hat{a}_{k+1}(\mathbf{x}, m) = \frac{1}{A} \sum_{l=1}^A \frac{\mathbb{I}(\mathcal{Y}_k \cup \{\mathbf{y}_m(\mathbf{x})\}, \mathbf{y}_M(\mathbf{x}'_l) | \mathcal{D}) - \mathbb{I}(\mathcal{Y}_k, \mathbf{y}_M(\mathbf{x}'_l) | \mathcal{D})}{\lambda_m}$$
$$\text{s.t. } \lambda_m + \sum_{\hat{m} \in \mathcal{M}_k} \lambda_{\hat{m}} \leq B,$$

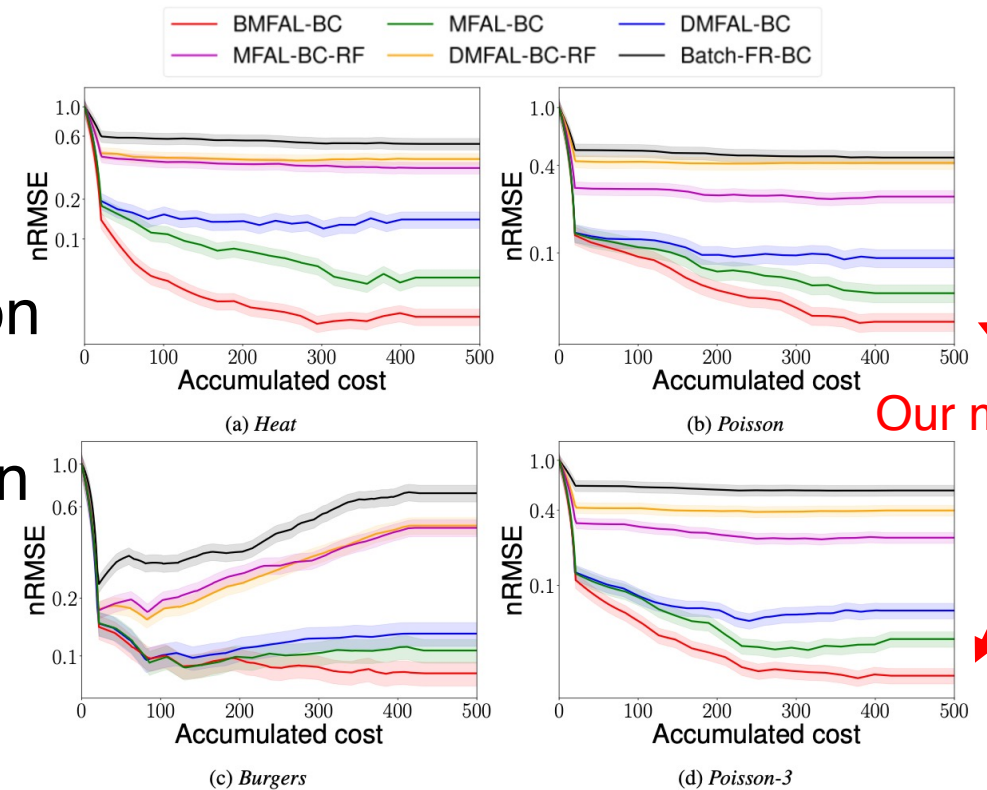
$(1 - 1/e)$ -approximation of the optimal

Proved



Experiment: Solving PDEs

- **BMFAL-BC**: our weighted greedy strategy
- **DMFAL-BC**: DMFAL with original acquisition
- **MFAL-BC**: DMFAL with modified acquisition
- **DMFAL-BC-RF**: DMFAL with original acquisition but random fidelity selection
- **MFAL-BC-RF**: DMFAL with modified acquisition but random fidelity selection
- **Batch-RF-BC**: Pure random selections of fidelities and query inputs



For all compared methods, the surrogate is updated in a batch fashion until the budgets are exhausted.



Experiment: Varying Budgets

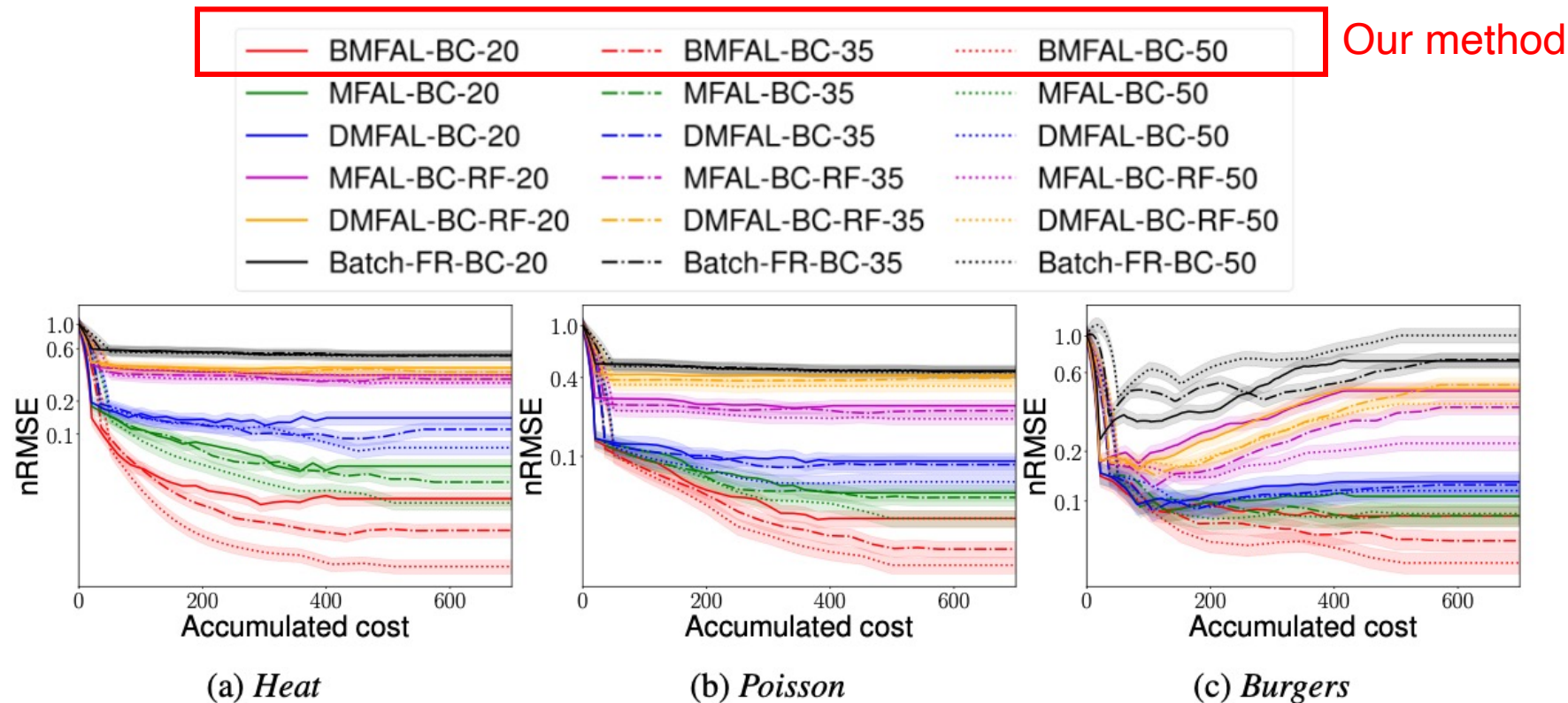


Figure 4: nRMSE vs. the accumulated cost under different budgets per batch: $B \in \{20, 35, 50\}$.

Welcome to our poster!

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