请使用 Ubuntu 20.04 进行测试。

需要先安装 OpenCV 库。

```
sudo apt install libopencv-dev
sudo apt install libopencv-core4.2
sudo apt install libopencv-core-dev
```

然后加入 WEBOTS\_HOME 环境变量。可以加在 ~/.profile 中,然后 source ~/.profile 。也可以在一个终端中 export 后再编译控制器(不要重新用另一个终端)。

## 1 export WEBOTS\_HOME=/usr/local/webots

最后,controller 在 FinalProject/controllers 下, cd 到某个 controller 的目录下后, make clean && make 即可重新编译 controller。

```
Q lixk28@kbuntu ≥ ~/Introduction-to-Robotics/Project ≅ $\mathcal{V}$ main *1 !2 ?9
> cd FinalProject/controllers/my_controller1
) make clean && make
# updating my_controller1.d
# compiling my_controller1.cpp
my_controller1.cpp: In function 'bool needPlan(cv::Mat, std::vector<point>, point)':
my_controller1.cpp:249:21: warning: comparison of integer expressions of different signedness: 'int' and 'std::vector
 {aka 'long unsigned int'} [-Wsign-compare]
         for (int i = 0; i < path.size() - 1; i++)
 249 |
my_controller1.cpp: In function 'int main(int, char**)':
my_controller1.cpp:372:37: warning: comparison of integer expressions of different signedness: 'size_t' {aka 'long
int' [-Wsign-compare]
 372 |
             for (size_t i = outlierCnt; i < lidarRes - outlierCnt; ++i)</pre>
my_controller1.cpp:377:42: warning: comparison of integer expressions of different signedness: 'int' and 'size_t' {
nt'} [-Wsign-compare]
                for (int k = i - outlierCnt; k < i + outlierCnt; ++k)</pre>
my_controller1.cpp: In function 'std::vector<point> astar(int (*)[1002], std::vector<point>, point, point)':
my_controller1.cpp:138:15: warning: control reaches end of non-void function [-Wreturn-type]
 138 | vector<int> openSet;
# linking my_controller1
# copying my_controller1

    d lixk28@kbuntu ≈ ~/Introduction-to-Robotics/Project/FinalProject/controllers/my_controller1 ★ P main *1 !2 ?9
>
```