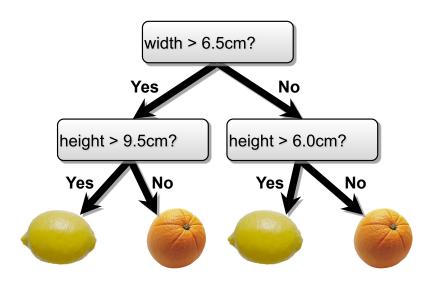
CSC 411: Introduction to Machine Learning Lecture 3: Decision Trees

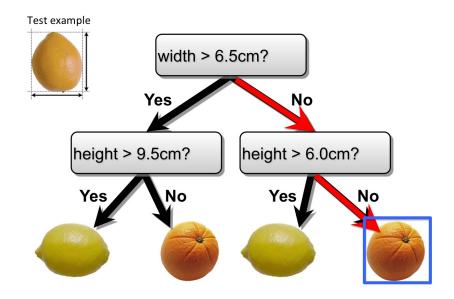
Mengye Ren and Matthew MacKay

University of Toronto

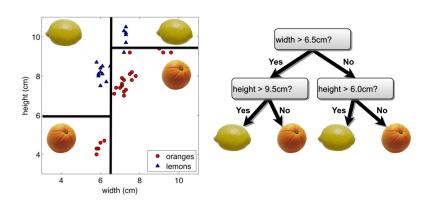
Today

- Simple but powerful learning algorithm
- One of the most widely used learning algorithms in Kaggle competitions
- Lets us introduce ensembles (Lectures 4–5), a key idea in ML more broadly
- Useful information theoretic concepts (entropy, mutual information, etc.)





 Decision trees make predictions by recursively splitting on different attributes according to a tree structure.



Example with Discrete Inputs

• What if the attributes are discrete?

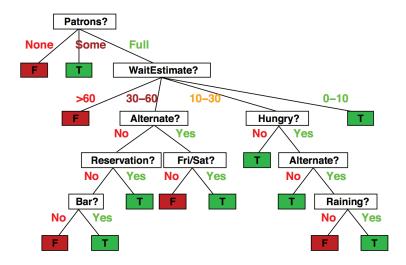
Example					Input	Attribu	ites				Goal
	Alt	Bar	Fri	Hun	Pat	Price	Rain	Res	Type	Est	WillWait
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\mathbf{x}_7	No	Yes	No	No	None	\$	Yes	No	Burger	0–10	$y_7 = No$
\mathbf{x}_8	No	No	No	Yes	Some	\$\$	Yes	Yes	Thai	0–10	$y_8 = \textit{Yes}$
\mathbf{x}_9	No	Yes	Yes	No	Full	\$	Yes	No	Burger	>60	$y_9 = No$
\mathbf{x}_{10}	Yes	Yes	Yes	Yes	Full	\$\$\$	No	Yes	Italian	10-30	$y_{10} = \mathit{No}$
\mathbf{x}_{11}	No	No	No	No	None	\$	No	No	Thai	0–10	$y_{11} = No$
\mathbf{x}_{12}	Yes	Yes	Yes	Yes	Full	\$	No	No	Burger	30–60	$y_{12} = \textit{Yes}$

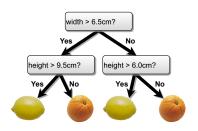
1.	Alternate: whether there is a suitable alternative restaurant nearby.
2.	Bar: whether the restaurant has a comfortable bar area to wait in.
3.	Fri/Sat: true on Fridays and Saturdays.
4.	Hungry: whether we are hungry.
5.	Patrons: how many people are in the restaurant (values are None, Some, and Full).
6.	Price: the restaurant's price range (\$, \$\$, \$\$\$).
7.	Raining: whether it is raining outside.
8.	Reservation: whether we made a reservation.
9.	Type: the kind of restaurant (French, Italian, Thai or Burger).
10.	WaitEstimate: the wait estimated by the host (0-10 minutes, 10-30, 30-60, >60).

Attributes:

Decision Tree: Example with Discrete Inputs

• The tree to decide whether to wait (T) or not (F)

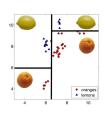




- Internal nodes test attributes
- Branching is determined by attribute value
- Leaf nodes are outputs (predictions)

Decision Tree: Classification and Regression

- Each path from root to a leaf defines a region R_m of input space
- Let $\{(x^{(m_1)}, t^{(m_1)}), \dots, (x^{(m_k)}, t^{(m_k)})\}$ be the training examples that fall into R_m



Classification tree:

- discrete output
- ▶ leaf value y^m typically set to the most common value in $\{t^{(m_1)}, \dots, t^{(m_k)}\}$

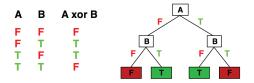
• Regression tree:

- continuous output
- ▶ leaf value y^m typically set to the mean value in $\{t^{(m_1)}, \dots, t^{(m_k)}\}$

Note: We will focus on classification

Expressiveness

- Discrete-input, discrete-output case:
 - Decision trees can express any function of the input attributes
 - ightharpoonup E.g., for Boolean functions, truth table row ightarrow path to leaf:



- Continuous-input, continuous-output case:
 - Can approximate any function arbitrarily closely
- Trivially, there is a consistent decision tree for any training set w/ one path to leaf for each example (unless f nondeterministic in x) but it probably won't generalize to new examples

[Slide credit: S. Russell]

How do we Learn a DecisionTree?

• How do we construct a useful decision tree?

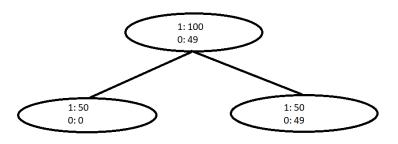
Learning Decision Trees

Learning the simplest (smallest) decision tree is an NP complete problem [if you are interested, check: Hyafil & Rivest'76]

- Resort to a greedy heuristic:
 - Start from an empty decision tree
 - ► Split on the "best" attribute
 - Recurse
- Which attribute is the "best"?
 - Choose based on accuracy?

Choosing a Good Split

• Why isn't accuracy a good measure?



- Is this split good? Zero accuracy gain.
- Instead, we will use techniques from information theory

Idea: Use counts at leaves to define probability distributions, so we can measure uncertainty

Choosing a Good Split

- Which attribute is better to split on, X_1 or X_2 ?
 - Deterministic: good (all are true or false; just one class in the leaf)
 - Uniform distribution: bad (all classes in leaf equally probable)
 - ▶ What about distributons in between?

Note: Let's take a slight detour and remember concepts from information theory

[Slide credit: D. Sontag]

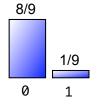
We Flip Two Different Coins

```
Sequence 1:
000100000000000100...?
Sequence 2:
010101110100110101...?
    16
                          10
                      8
              versus
     0
```

Quantifying Uncertainty

Entropy is a measure of expected "surprise":

$$H(X) = -\sum_{x \in X} p(x) \log_2 p(x)$$



4/9

$$-\frac{8}{9}\log_2\frac{8}{9} - \frac{1}{9}\log_2\frac{1}{9} \approx \frac{1}{2}$$

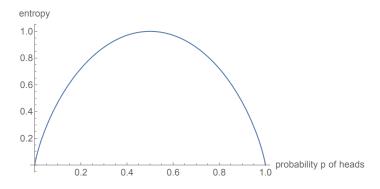
$$-\frac{4}{9}\log_2\frac{4}{9} - \frac{5}{9}\log_2\frac{5}{9} \approx 0.99$$

5/9

- Measures the information content of each observation
- Unit = bits
- A fair coin flip has 1 bit of entropy

Quantifying Uncertainty

$$H(X) = -\sum_{x \in X} p(x) \log_2 p(x)$$



Entropy

• "High Entropy":

- Variable has a uniform like distribution
- ▶ Flat histogram
- Values sampled from it are less predictable

"Low Entropy"

- Distribution of variable has many peaks and valleys
- Histogram has many lows and highs
- Values sampled from it are more predictable

[Slide credit: Vibhav Gogate]

Entropy of a Joint Distribution

• Example: $X = \{\text{Raining, Not raining}\}, Y = \{\text{Cloudy, Not cloudy}\}$

	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

$$H(X,Y) = -\sum_{x \in X} \sum_{y \in Y} p(x,y) \log_2 p(x,y)$$

$$= -\frac{24}{100} \log_2 \frac{24}{100} - \frac{1}{100} \log_2 \frac{1}{100} - \frac{25}{100} \log_2 \frac{25}{100} - \frac{50}{100} \log_2 \frac{50}{100}$$

$$\approx 1.56 \text{bits}$$

Specific Conditional Entropy

• Example: $X = \{\text{Raining, Not raining}\}, Y = \{\text{Cloudy, Not cloudy}\}$

	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

• What is the entropy of cloudiness Y, given that it is raining?

$$H(Y|X = x) = -\sum_{y \in Y} p(y|x) \log_2 p(y|x)$$
$$= -\frac{24}{25} \log_2 \frac{24}{25} - \frac{1}{25} \log_2 \frac{1}{25}$$
$$\approx 0.24 \text{bits}$$

• We used: $p(y|x) = \frac{p(x,y)}{p(x)}$, and $p(x) = \sum_{y} p(x,y)$ (sum in a row)

Conditional Entropy

	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

• The expected conditional entropy:

$$H(Y|X) = \sum_{x \in X} p(x)H(Y|X = x)$$
$$= -\sum_{x \in X} \sum_{y \in Y} p(x,y)\log_2 p(y|x)$$

Conditional Entropy

• Example: $X = \{\text{Raining, Not raining}\}, Y = \{\text{Cloudy, Not cloudy}\}$

	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

• What is the entropy of cloudiness, given the knowledge of whether or not it is raining?

$$H(Y|X) = \sum_{x \in X} p(x)H(Y|X = x)$$

$$= \frac{1}{4}H(\text{cloudy}|\text{is raining}) + \frac{3}{4}H(\text{cloudy}|\text{not raining})$$

$$\approx 0.75 \text{ bits}$$

Conditional Entropy

- Some useful properties:
 - ▶ *H* is always non-negative
 - ► Chain rule: H(X, Y) = H(X|Y) + H(Y) = H(Y|X) + H(X)
 - ▶ If X and Y independent, then X doesn't tell us anything about Y: H(Y|X) = H(Y)
 - ▶ But Y tells us everything about Y: H(Y|Y) = 0
 - ▶ By knowing X, we can only decrease uncertainty about Y: $H(Y|X) \le H(Y)$

Information Gain

	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

• How much information about cloudiness do we get by discovering whether it is raining?

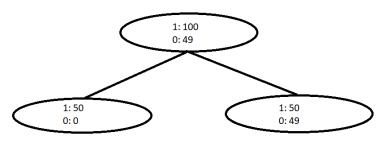
$$IG(Y|X) = H(Y) - H(Y|X)$$

 $\approx 0.25 \text{ bits}$

- This is called the information gain in Y due to X, or the mutual information of Y and X
- If X is completely uninformative about Y: IG(Y|X) = 0
- If X is completely informative about Y: IG(Y|X) = H(Y)

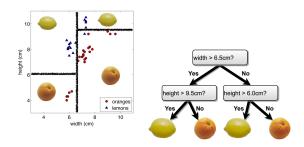
Revisiting Our Original Example

- Information gain measures the informativeness of a variable, which is exactly what we desire in a decision tree attribute!
- What is the information gain of this split?



- Root entropy: $H(Y) = -\frac{49}{149} \log_2(\frac{49}{149}) \frac{100}{149} \log_2(\frac{100}{149}) \approx 0.91$
- Leafs entropy: H(Y|left) = 0, $H(Y|right) \approx 1$.
- $IG(split) \approx 0.91 (\frac{1}{3} \cdot 0 + \frac{2}{3} \cdot 1) \approx 0.24 > 0$

Constructing Decision Trees



- At each level, one must choose:
 - 1. Which variable to split.
 - 2. Possibly where to split it.
- Choose them based on how much information we would gain from the decision! (choose attribute that gives the textbfest gain)

Decision Tree Construction Algorithm

- Simple, greedy, recursive approach, builds up tree node-by-node
- 1. pick an attribute to split at a non-terminal node
- 2. split examples into groups based on attribute value
- 3. for each group:
 - ▶ if no examples return majority from parent
 - else if all examples in same class return class
 - else loop to step 1

Back to Our Example

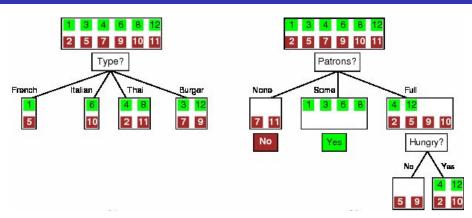
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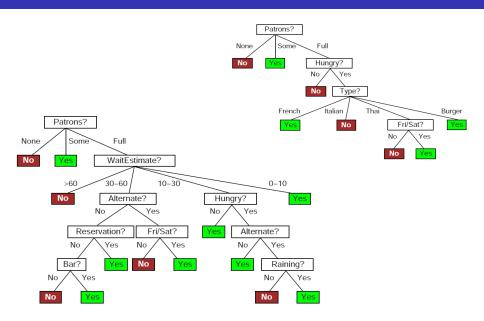
[from: Russell & Norvig]

Attribute Selection



$$\begin{split} \textit{IG(Y)} &= \textit{H(Y)} - \textit{H(Y|X)} \\ \textit{IG(type)} &= 1 - \left[\frac{2}{12} \textit{H(Y|Fr.)} + \frac{2}{12} \textit{H(Y|It.)} + \frac{4}{12} \textit{H(Y|Thai)} + \frac{4}{12} \textit{H(Y|Bur.)} \right] = 0 \\ \textit{IG(Patrons)} &= 1 - \left[\frac{2}{12} \textit{H(0,1)} + \frac{4}{12} \textit{H(1,0)} + \frac{6}{12} \textit{H(\frac{2}{6},\frac{4}{6})} \right] \approx 0.541 \end{split}$$

Which Tree is Better?



What Makes a Good Tree?

- Not too small: need to handle important but possibly subtle distinctions in data
- Not too big:
 - Computational efficiency (avoid redundant, spurious attributes)
 - Avoid over-fitting training examples
 - Human interpretability
- "Occam's Razor": find the simplest hypothesis that fits the observations
 - Useful principle, but hard to formalize (how to define simplicity?)
 - See Domingos, 1999, "The role of Occam's razor in knowledge discovery"
- We desire small trees with informative nodes near the root.

Decision Tree Miscellany

- Problems:
 - You have exponentially less data at lower levels
 - ▶ Too big of a tree can overfit the data
 - Greedy algorithms don't necessarily yield the global optimum
- Handling continuous attributes
 - ▶ Split based on a threshold, chosen to maximize information gain
- Decision trees can also be used for regression on real-valued outputs. Choose splits to minimize squared error, rather than maximize information gain.

Comparison to k-NN

Advantages of decision trees over KNN

- Good when there are lots of attributes, but only a few are important
- Good with discrete attributes
- Easily deals with missing values (just treat as another value)
- Robust to scale of inputs
- Fast at test time
- More interpretable

Comparison to k-NN

Advantages of KNN over decision trees

- Few hyperparameters
- Able to handle attributes/features that interact in complex ways (e.g. pixels)
- Can incorporate interesting distance measures (e.g. shape contexts)
- Typically make better predictions in practice
 - ► As we'll see next lecture, ensembles of decision trees are much stronger. But they lose many of the advantages listed above.