STOR566: Introduction to Deep Learning

Lecture 6: Neural Networks

Yao Li UNC Chapel Hill

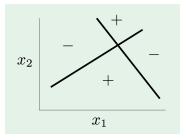
Sep 10, 2024

Materials are from Learning from data (Caltech) and Deep Learning (UCLA)

Neural Networks

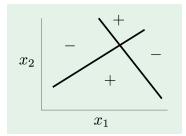
Another way to introduce nonlinearity

• How to generate this nonlinear hypothesis?

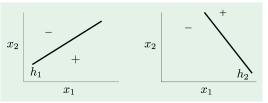


Another way to introduce nonlinearity

• How to generate this nonlinear hypothesis?



Combining multiple linear hyperplanes to construct nonlinear hypothesis

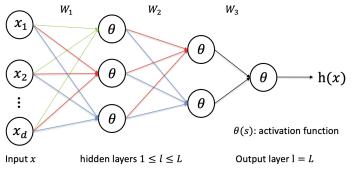


Neural Network

- Input layer: *d* neurons (input features)
- Neurons from layer 1 to L: Linear combination of previous layers + activation function

$$\theta(\mathbf{w}^T \mathbf{x}), \quad \theta$$
: activation function

• Final layer: one neuron \Rightarrow prediction by sign(h(x))



Activation Function

Sigmoid

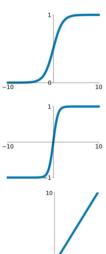
$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

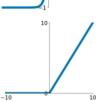
tanh

tanh(x)

ReLU

 $\max(0, x)$





Formal Definitions

```
Weight: w_{ij}^{(I)} \begin{cases} 1 \leq I \leq L & \text{: layers} \\ 0 \leq i \leq d^{(I-1)} & \text{: inputs} \\ 1 \leq j \leq d^{(I)} & \text{: outputs} \end{cases}
```

bias: $b_j^{(I)}$: added to the j-th neuron in the I-th layer

Formal Definitions

Weight:
$$w_{ij}^{(l)}$$

$$\begin{cases} 1 \leq l \leq L & : \text{layers} \\ 0 \leq i \leq d^{(l-1)} & : \text{inputs} \\ 1 \leq j \leq d^{(l)} & : \text{outputs} \end{cases}$$

bias: $b_j^{(I)}$: added to the j-th neuron in the I-th layer

j-th neuron in the *l*-the layer:

$$x_j^{(l)} = \theta(s_j^{(l)}) = \theta(\sum_{i=0}^{d^{(l-1)}} w_{ij}^{(l)} x_i^{(l-1)} + b_j^{(l)})$$

Formal Definitions

Weight:
$$w_{ij}^{(l)}$$

$$\begin{cases} 1 \leq l \leq L & : \text{layers} \\ 0 \leq i \leq d^{(l-1)} & : \text{inputs} \\ 1 \leq j \leq d^{(l)} & : \text{outputs} \end{cases}$$

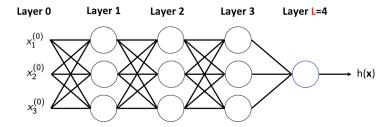
bias: $b_j^{(I)}$: added to the j-th neuron in the I-th layer

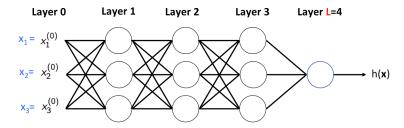
j-th neuron in the *l*-the layer:

$$x_j^{(I)} = \theta(s_j^{(I)}) = \theta(\sum_{i=0}^{d^{(I-1)}} w_{ij}^{(I)} x_i^{(I-1)} + b_j^{(I)})$$

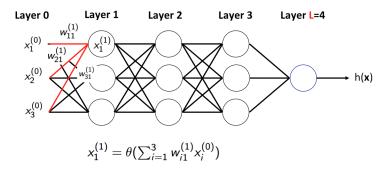
Output:

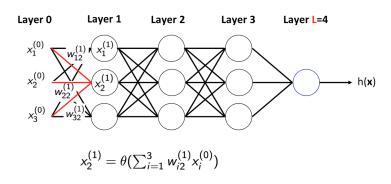
$$h(\boldsymbol{x}) = x_1^{(L)}$$

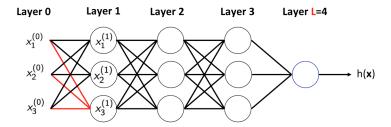


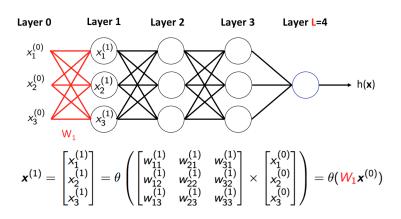


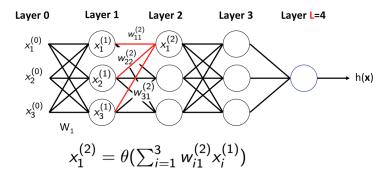
features for one data point $\mathbf{x} = [x_1, x_2, x_3]$

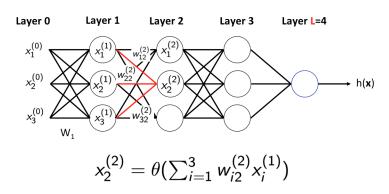


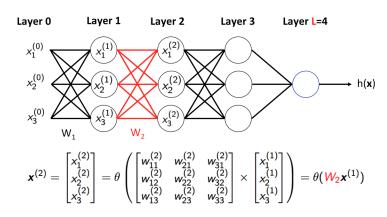


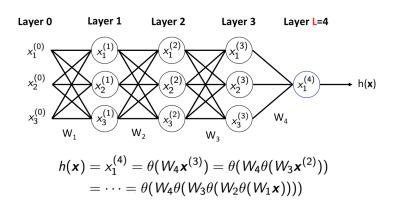


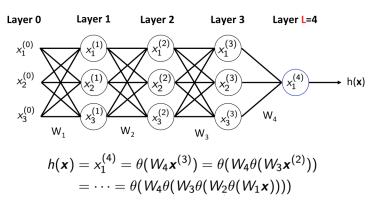






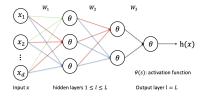






With the bias term: $h(\mathbf{x}) = \theta(W_4\theta(W_3\theta(W_2\theta(W_1\mathbf{x} + \mathbf{b}_1) + \mathbf{b}_2) + \mathbf{b}_3) + \mathbf{b}_4)$

Example: Forward Pass Computation



- Input data: $\mathbf{x} = (1.5, -1.0, 1.3)^T$
- Activation: ReLU $(\theta(x) = \max(0, x))$
- Weights:

$$W_1 = \begin{pmatrix} 0.3 & 0.4 & 0.2 \\ 0.3 & 0.5 & 0.2 \\ 0.8 & 1.0 & -1.0 \end{pmatrix}, W_2 = \begin{pmatrix} 0 & -1.2 & 0.5 \\ 0.9 & 1.0 & 0 \end{pmatrix}$$

$$W_3 = (-1.0, 1.0)$$

- Please compute h(x).
- Reminder: $h(\mathbf{x}) = \theta(W_3\theta(W_2\theta(W_1\mathbf{x})))$

Training

- Weights $W = \{W_1, \cdots, W_L\}$ and bias $\{\boldsymbol{b}_1, \cdots, \boldsymbol{b}_L\}$ determine $h(\boldsymbol{x})$
- Learning the weights: solve ERM with SGD.
- Loss on example (x_n, y_n) is

$$e(h(\boldsymbol{x}_n),y_n)=e(W)$$

Training

- Weights $W = \{W_1, \dots, W_L\}$ and bias $\{\boldsymbol{b}_1, \dots, \boldsymbol{b}_L\}$ determine $h(\boldsymbol{x})$
- Learning the weights: solve ERM with SGD.
- Loss on example (x_n, y_n) is

$$e(h(\boldsymbol{x}_n),y_n)=e(W)$$

• To implement SGD, we need the gradient

$$\nabla e(W): \{ \frac{\partial e(W)}{\partial w_{ij}^{(I)}} \} \text{ for all } i, j, I$$

(for simplicity we ignore bias in the derivations)

Review the Notations

Weight:
$$w_{ij}^{(l)}$$

$$\begin{cases} 1 \leq l \leq L & : \text{layers} \\ 0 \leq i \leq d^{(l-1)} & : \text{inputs} \\ 1 \leq j \leq d^{(l)} & : \text{outputs} \end{cases}$$

bias: $b_j^{(I)}$: added to the *j*-th neuron in the *I*-th layer

j-th neuron in the *l*-the layer:

$$x_j^{(I)} = \theta(s_j^{(I)}) = \theta(\sum_{i=0}^{d^{(I-1)}} w_{ij}^{(I)} x_i^{(I-1)} + b_j^{(I)})$$

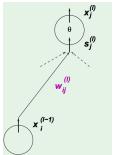
Output:

$$h(\mathbf{x}) = x_1^{(L)}$$

Computing Gradient $\frac{\partial e(W)}{\partial w_{ii}^{(l)}}$

• Use chain rule:

$$\frac{\partial e(W)}{\partial w_{ij}^{(I)}} = \frac{\partial e(W)}{\partial s_j^{(I)}} \times \frac{\partial s_j^{(I)}}{\partial w_{ij}^{(I)}}$$



$$s_j^{(I)} = \sum_{i=1}^d x_i^{(I-1)} w_{ij}^{(I)}$$

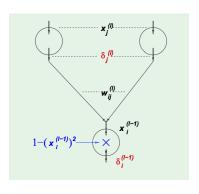
$$\begin{split} s_j^{(I)} &= \sum_{i=1}^d x_i^{(I-1)} w_{ij}^{(I)} \\ \bullet & \text{We have } \frac{\partial s_j^{(I)}}{\partial w_{ii}^{(I)}} = x_i^{(I-1)} \end{split}$$

Computing Gradient $\frac{\partial e(W)}{\partial w_{ii}^{(I)}}$

• Define
$$\delta_j^{(I)} := \frac{\partial e(W)}{\partial s_i^{(I)}}$$

• Compute by layer-by-layer:

$$\begin{split} \delta_{i}^{(l-1)} &= \frac{\partial e(W)}{\partial s_{i}^{(l-1)}} \\ &= \sum_{j=1}^{d} \frac{\partial e(W)}{\partial s_{j}^{(l)}} \times \frac{\partial s_{j}^{(l)}}{\partial x_{i}^{(l-1)}} \times \frac{\partial x_{i}^{(l-1)}}{\partial s_{i}^{l-1}} \\ &= \sum_{i=1}^{d} \delta_{j}^{(l)} \times w_{ij}^{(l)} \times \theta'(s_{i}^{(l-1)}), \end{split}$$



where $\theta'(s) = 1 - \theta^2(s)$ for tanh

•
$$\delta_i^{(l-1)} = (1 - (x_i^{(l-1)})^2) \sum_{j=1}^d w_{ij}^{(l)} \delta_j^{(l)}$$

Final layer

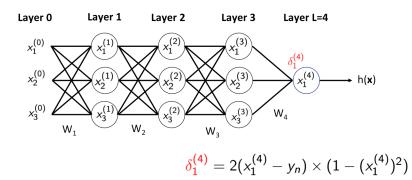
(Assume square loss)

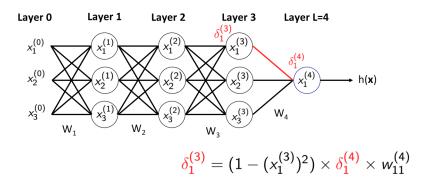
•
$$e(W) = (x_1^{(L)} - y_n)^2$$

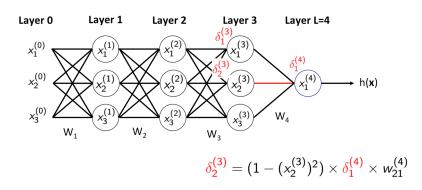
 $x_1^{(L)} = \theta(s_1^{(L)})$

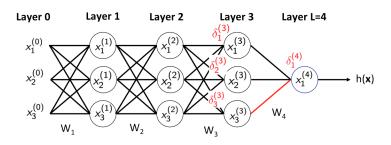
So,

$$\begin{split} \delta_{1}^{(L)} &= \frac{\partial e(W)}{\partial s_{1}^{(L)}} \\ &= \frac{\partial e(W)}{\partial x_{1}^{(L)}} \times \frac{\partial x_{1}^{(L)}}{\partial s_{1}^{(L)}} \\ &= 2(x_{1}^{(L)} - y_{n}) \times \theta'(s_{1}^{(L)}) \end{split}$$

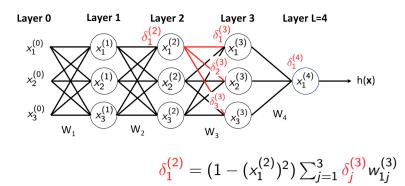


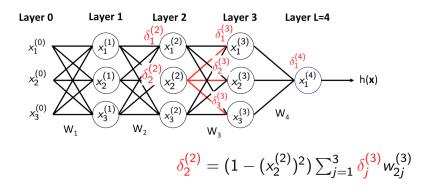


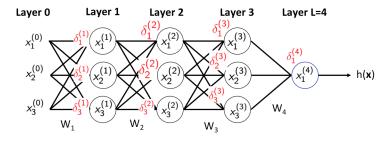




$$\delta_3^{(3)} = (1 - (x_3^{(3)})^2) \times \delta_1^{(4)} \times w_{31}^{(4)}$$



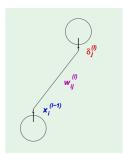




Backpropagation

SGD for neural networks

- Initialize all weights $w_{ij}^{(I)}$ at random
- For iter = $0, 1, 2, \cdots$
 - Forward: Compute all $x_j^{(l)}$ from input to output
 - Backward: Compute all $\delta_i^{(l)}$ from output to input
 - Update all the weights $w_{ij}^{(l)} \leftarrow w_{ij}^{(l)} \eta x_i^{(l-1)} \delta_j^{(l)}$



Backpropagation

- Just an automatic way to apply chain rule to compute gradient
- Auto-differentiation (AD) as long as we define derivative for each basic function, we can use AD to compute any of their compositions
- Implemented in most deep learning packages (e.g., pytorch, tensorflow)

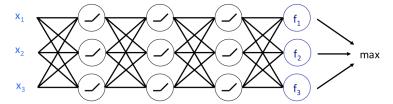
Backpropagation

- Just an automatic way to apply chain rule to compute gradient
- Auto-differentiation (AD) as long as we define derivative for each basic function, we can use AD to compute any of their compositions
- Implemented in most deep learning packages (e.g., pytorch, tensorflow)
- Auto-differentiation needs to store all the intermediate nodes of each sample
 - \Rightarrow Memory cost
 - ⇒ This poses a constraint on the batch size

Multiclass Classification

- K classes: K neurons in the final layer
- Output of each f_i is the score of class iTaking arg $\max_i f_i(x)$ as the prediction

features for one data point $\mathbf{x} = [x_1, x_2, x_3]$



Multiclass loss

• Softmax function: transform output to probability:

$$[f_1,\cdots,f_K] \rightarrow [p_i,\cdots,p_K]$$

where
$$p_i = rac{\mathrm{e}^{f_i}}{\sum_{j=1}^K \mathrm{e}^{f_j}}$$

• Cross-entropy loss:

$$L = -\sum_{i=1}^{K} y_i \log(p_i)$$

where y_i is the i-th label

Conclusions

- Neural network
- Forward propagation
- Back-propagation for computing gradient

Questions?