STOR566: Introduction to Deep Learning

Lecture 10: LSTM and GRU

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Materials are from Deep Learning (UCLA)

Problems of Classical RNN

Hard to capture long-term dependencies

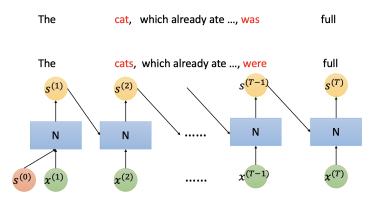
Problems of Classical RNN

Hard to capture long-term dependencies

The	cat, which already ate, was	full
The	cats, which already ate, were	full

Problems of Classical RNN

Hard to capture long-term dependencies



Hard to solve (vanishing gradient problem)

•
$$\mathbf{w}^t = \mathbf{w}^{t-1} - \alpha \times \nabla f(\mathbf{w}^{t-1})$$

Hard to solve (vanishing gradient problem)

$$\bullet \ \mathbf{w}^t = \mathbf{w}^{t-1} - \alpha \times \nabla f(\mathbf{w}^{t-1})$$

$$\bullet \left(\begin{array}{c} 0.499999 \\ 2.100001 \end{array} \right) = \left(\begin{array}{c} 0.5 \\ 2.1 \end{array} \right) - 0.01 \times \left(\begin{array}{c} 0.0001 \\ -0.0001 \end{array} \right)$$

Hard to solve (vanishing gradient problem)

$$s_t = \sigma(W_1 x_t + W_2 s_{t-1}), \quad o_t = V s_t$$

Let $W = [W_1, W_2]$, the gradient:

$$\frac{\partial L}{\partial W} = \sum_{t=1}^{I} \frac{\partial L_t}{\partial W}
\frac{\partial L_t}{\partial W} = \frac{\partial L_t}{\partial o_t} \frac{\partial o_t}{\partial s_t} \left(\Pi_{k=2}^t \sigma'(W_1 x_k + W_2 s_{k-1}) W_2 \right) \frac{\partial s_1}{\partial W}$$

Hard to solve (vanishing gradient problem)

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Let $W = [W_1, W_2]$, the gradient:

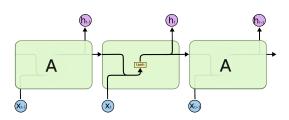
$$\frac{\partial L}{\partial W} = \sum_{t=1}^{T} \frac{\partial L_t}{\partial W}
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- Solution:
 - LSTM (Long Short Term Memory networks)
 - GRU (Gated Recurrent Unit)
 - . . .

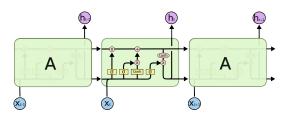
LSTM

LSTM

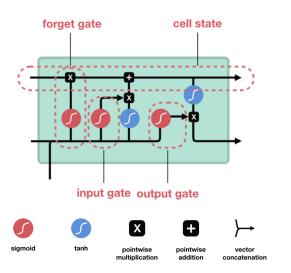
• RNN:



• LSTM:



LSTM Cell



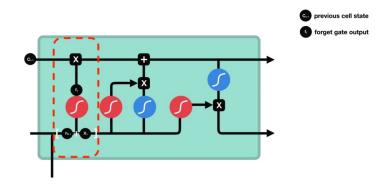
Cell State and Hidden State

The two hidden states $\mathbf{h}^{(t)}$ and $\mathbf{c}^{(t)}$ are calculated by:

$$egin{aligned} oldsymbol{c}^{(t)} &= oldsymbol{f}^{(t)} \circ oldsymbol{c}^{(t-1)} + oldsymbol{i}^{(t)} \circ oldsymbol{z}^{(t)}, \ oldsymbol{h}^{(t)} &= oldsymbol{o}^{(t)} \circ anh(oldsymbol{c}^{(t)}), \end{aligned}$$

- ullet Cell state: $oldsymbol{c}^{(t)}$, "memory" of the network
- $m{\bullet}$ Hidden state: $m{h}^{(t)}$, information on previous inputs
- o: point-wise multiplication

Forget Gate

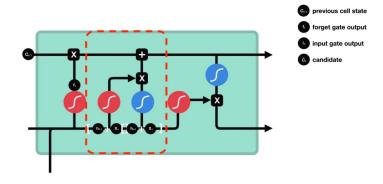


- $m{\bullet}$ Compute forget gate output: $m{f}^{(t)} = \sigma_g(m{W}_{1f}m{x}^{(t)} + m{W}_{2f}m{h}^{(t-1)} + m{b}_f)$
- Forget previous information: $f^{(t)} \circ c^{(t-1)}$
- ullet σ_g : sigmoid activation

Cell State

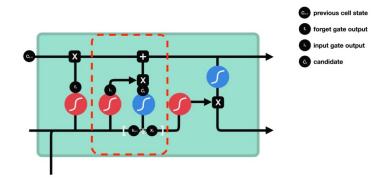
$$oldsymbol{c}^{(t)} = \underbrace{oldsymbol{f}^{(t)} \circ oldsymbol{c}^{(t-1)}}_{ extit{forget gate}} + \underbrace{oldsymbol{i}^{(t)} \circ oldsymbol{z}^{(t)}}_{ extit{input gate}},$$

Input Gate



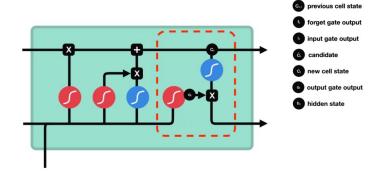
• Determine what to keep: $\mathbf{i}^{(t)} = \sigma_g(\mathbf{W}_{1i}\mathbf{x}^{(t)} + \mathbf{W}_{2i}\mathbf{h}^{(t-1)} + \mathbf{b}_i)$

Input Gate



- Determine what to keep: $\boldsymbol{i}^{(t)} = \sigma_g(\boldsymbol{W}_{1i}\boldsymbol{x}^{(t)} + \boldsymbol{W}_{2i}\boldsymbol{h}^{(t-1)} + \boldsymbol{b}_i)$
- ullet Compute tanh output: $oldsymbol{z}^{(t)} = anh(oldsymbol{W}_{1z}oldsymbol{x}^{(t)} + oldsymbol{W}_{2z}oldsymbol{h}^{(t-1)} + oldsymbol{b}_z)$

Output Gate



- Decide what to pass into next hidden state:
 - $oldsymbol{o}^{(t)} = \sigma_g(oldsymbol{W}_{1o}oldsymbol{x}^{(t)} + oldsymbol{W}_{2o}oldsymbol{h}^{(t-1)} + oldsymbol{b}_o)$
- $\bullet \ \pmb{h}^{(t)} = \pmb{o}^{(t)} \circ \tanh(\pmb{c}^{(t)})$

Gradient Vanishing

• Gradient:

$$\frac{\partial \ell^{(T)}}{\partial \boldsymbol{W}} = \frac{\partial \ell^{(T)}}{\partial \boldsymbol{h}^{(T)}} \frac{\partial \boldsymbol{h}^{(T)}}{\partial \boldsymbol{c}^{(T)}} \left(\prod_{j=t+1}^{T} \frac{\partial \boldsymbol{c}^{(j)}}{\partial \boldsymbol{c}^{(j-1)}} \right) \frac{\partial \boldsymbol{c}^{(t)}}{\partial \boldsymbol{W}}$$

Gradient Vanishing

• Gradient:

$$\frac{\partial \ell^{(T)}}{\partial \boldsymbol{W}} = \frac{\partial \ell^{(T)}}{\partial \boldsymbol{h}^{(T)}} \frac{\partial \boldsymbol{h}^{(T)}}{\partial \boldsymbol{c}^{(T)}} \left(\prod_{j=t+1}^{T} \frac{\partial \boldsymbol{c}^{(j)}}{\partial \boldsymbol{c}^{(j-1)}} \right) \frac{\partial \boldsymbol{c}^{(t)}}{\partial \boldsymbol{W}}$$

•
$$c^{(j)} = f^{(j)} \circ c^{(j-1)} + i^{(j)} \circ z^{(j)}$$

Gradient Vanishing

• Gradient:

$$\frac{\partial \ell^{(T)}}{\partial \boldsymbol{W}} = \frac{\partial \ell^{(T)}}{\partial \boldsymbol{h}^{(T)}} \frac{\partial \boldsymbol{h}^{(T)}}{\partial \boldsymbol{c}^{(T)}} \left(\prod_{j=t+1}^{T} \frac{\partial \boldsymbol{c}^{(j)}}{\partial \boldsymbol{c}^{(j-1)}} \right) \frac{\partial \boldsymbol{c}^{(t)}}{\partial \boldsymbol{W}}$$

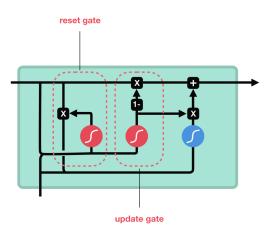
•
$$c^{(j)} = f^{(j)} \circ c^{(j-1)} + i^{(j)} \circ z^{(j)}$$

•
$$\frac{\partial \boldsymbol{c}^{(j)}}{\partial \boldsymbol{c}^{(j-1)}} = \boldsymbol{c}^{(j-1)} \times \frac{\partial \boldsymbol{f}^{(j)}}{\partial \boldsymbol{c}^{(j-1)}} + \boldsymbol{f}^{(j)} + \boldsymbol{z}^{(j)} \times \frac{\partial \boldsymbol{i}^{(j)}}{\partial \boldsymbol{c}^{(j-1)}} + \boldsymbol{i}^{(j)} \times \frac{\partial \boldsymbol{z}^{(j)}}{\partial \boldsymbol{c}^{(j-1)}}$$

The summation prevents gradient vanishing.

Gated Recurrent Unit

GRU Cell



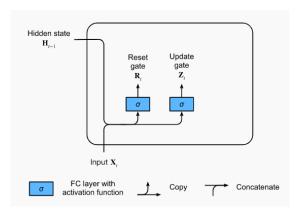
 $picture\ from\ https://towardsdatascience.com/illustrated-guide-to-lstms-and-gru-s-a-step-by-step-explanation-44e9eb85bf21$

Reset Gate and Update Gate

Reset gate $\mathbf{r}^{(t)}$ and Update gate $\mathbf{z}^{(t)}$ are calculated by:

$$\mathbf{r}^{(t)} = \sigma_g(\mathbf{W}_{1r}\mathbf{x}^{(t)} + \mathbf{W}_{2r}\mathbf{h}^{(t-1)} + \mathbf{b}_r),$$

$$\mathbf{z}^{(t)} = \sigma_g(\mathbf{W}_{1z}\mathbf{x}^{(t)} + \mathbf{W}_{2z}\mathbf{h}^{(t-1)} + \mathbf{b}_z),$$

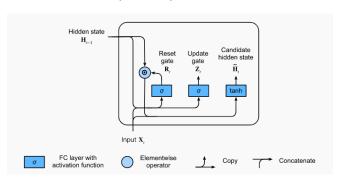


Candidate Hidden State

Candidate hidden state $\tilde{\mathbf{h}}^{(t)}$:

$$ilde{m{h}}^t = anh(m{W}_{1h}m{x}^{(t)} + m{W}_{2h}(m{r}^{(t)} \circ m{h}^{(t-1)}) + m{b}_h)$$

ullet Determine what to be kept from previous hidden state: $oldsymbol{r}^{(t)} \circ oldsymbol{h}^{(t-1)}$

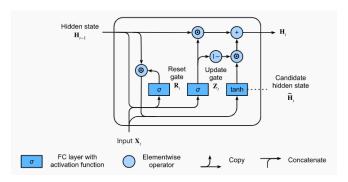


Final Hidden State

Hidden state $h^{(t)}$:

$$\mathbf{h}^{(t)} = \mathbf{z}^{(t)} \circ \mathbf{h}^{(t-1)} + (1 - \mathbf{z}^{(t)}) \circ \tilde{\mathbf{h}}^{(t)}$$

- Keep info from previous hidden state: $\mathbf{z}^{(t)} \circ \mathbf{h}^{(t-1)}$
- Get info from current state: $(1 \mathbf{z}^{(t)}) \circ \tilde{\mathbf{h}}^{(t)}$



Conclusions

- Gradient Vanishing
- LSTM
- GRU

Questions?