

LI-YEN HUANG

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EDUCATION

National Taiwan University, Taipei, Taiwan

February 2014 – January 2016

Completed 18 credits towards a Master of Science in Mechanical Engineering (GPA: 4.22/4.30)

National Taiwan University, Taipei, Taiwan

September 2009 – January 2014

Bachelor of Science in Mechanical Engineering (GPA: 89.37/100)

Relevant courses: General Psychology, Social Psychology, Computer Programming, Engineering Graphics, Application of CAD System, Computer-aided Engineering Drawing, Mechanism Design

CONTINUING EDUCATION

Algorithms, Part I, Princeton University (Coursera)

Introduction to User Experience Principles and Processes, University of Michigan (Coursera)

Understanding User Needs, University of Michigan (Coursera)

Web Design for Everybody: Basics of Web Development & Coding, University of Michigan (Coursera)

WORK EXPERIENCE

Motion Planning Team, Syntec Technology Co., Ltd.

January 2021 – December 2021

Senior Research Developer

Hsinchu, Taiwan

- Communicated with product engineers and software architects and offered comprehensive solutions for both parties.
- Developed robust software for CNC machines with a minimum expected life cycle of 10+ years.
- Validated the core components of the software shared by a wide variety of manufacturing machines.

CAD/CAM Team, Syntec Technology Co., Ltd.

June 2019 – December 2020

Senior Product Engineer

Hsinchu, Taiwan

- Developed a turn-milling Computer-Aided Design and Manufacturing (CAD/CAM) system from the ground up.
- Designed a user flow to produce tool paths for turn-milling machines.
- Conducted an extensive user survey from potential customers to optimize the portfolio of the final product.
- Integrated a machining engine and 3D libraries with a user interface.

Laser Marking Team, Syntec Technology Co., Ltd.

May 2016 – May 2019

Product Engineer

Hsinchu, Taiwan

- Developed a new algorithm to eliminate the workspace limitations of a laser marking system.
- Designed a user interface on both PCs and embedded systems.
- Developed and maintained a laser marking CAD/CAM software.

RESEARCH EXPERIENCE

Robot Gripper Design

February 2014 – January 2016

Research Assistant

Taipei, Taiwan

- Researched robot grippers to install multiple sensors for bin picking.
- Improved a self-compliant robot gripper with tactile sensors to grasp different geometric objects.
- Designed and integrated a custom-made robot gripper with an off-the-shelf industrial robot arm.

Spring Balancing Mechanism Design

February 2013 – November 2013

Undergraduate Independent Researcher

Taipei, Taiwan

- Surveyed a self-balancing spring planar mechanical structure.
- Analyzed and optimized parameters for a self-balanced surgical inspection light.

Remote-controlled Ball-shooting Robot

February 2012 – June 2012

Course Project in Machine Design Theory

Taipei, Taiwan

- Designed and assembled a remote-controlled robot for a ball-shooting challenge in a complex environment.
- Produced technical drawings and built prototypes of different modules of the robot.

PUBLICATIONS

- L. Y. Huang (second author) et al, “A manipulator with a depth sensor and an underactuated and tactile gripper for identifying and grasping the objects in various shapes and sizes,” International Federation for the Promotion of Mechanism and Machine Science World Congress (IFToMM), Oct. 2015, Taipei, Taiwan.
- L. Y. Huang (second author) et al, “An underactuated and compliant gripper with multi-sensor feedback,” in Proc. The Chinese Society of Mechanical Engineers Annual Meeting, Dec. 2014, Taichung, Taiwan, 02295.
- L. Y. Huang (second author) et al, “Design and implementation of an underactuated and sensor-rich gripper,” in Proc. International Conference on Advanced Robotics and Intelligent Systems (ARIS), Jun. 2014, Taipei, Taiwan, pp29.

VOLUNTEER EXPERIENCE

- **Robot Summer Camp for Elementary School Students**, Syntec Technology Co., Ltd. August 2018
- **Summer Camp for Elementary School Students**, Taiwan Campus Crusade for Christ July 2011
- **Summer Camp for Elementary School Students**, Taiwan Campus Crusade for Christ July 2010

AWARDS

- **Academic Excellence Award * 3 (for top 5% students in class each semester)**
- **First Prize, Best Conference Paper Award, International Conference on Advanced Robotics and Intelligent Systems (ARIS), Jun. 2014, Taipei, Taiwan**

SKILLS

- **Applications:** Solidworks, AutoCAD, Siemens NX (UG), Microsoft Office
- **Programming Languages:** C#, C++, Python, JavaScript, HTML5, CSS3, MATLAB
- **Languages:** Mandarin Chinese: native speaker, English: proficient (TOEFL:106/120)