

# Contents

<b>1</b>	<b>Building Mathematical Models</b>	<b>2</b>
1.1	a . . . . .	2
<b>2</b>	<b>Employ assumptions to simplify systems</b>	<b>5</b>
2.1	a . . . . .	5
2.2	b . . . . .	5
<b>3</b>	<b>Matrices and vectors</b>	<b>6</b>
3.1	a . . . . .	6
3.2	b . . . . .	6
3.3	c . . . . .	7
3.4	d . . . . .	7
<b>4</b>	<b>Complex numbers</b>	<b>8</b>
4.1	a . . . . .	8
4.2	b . . . . .	8
4.3	c . . . . .	8
4.4	d . . . . .	8

# 1 Building Mathematical Models

## 1.1 a

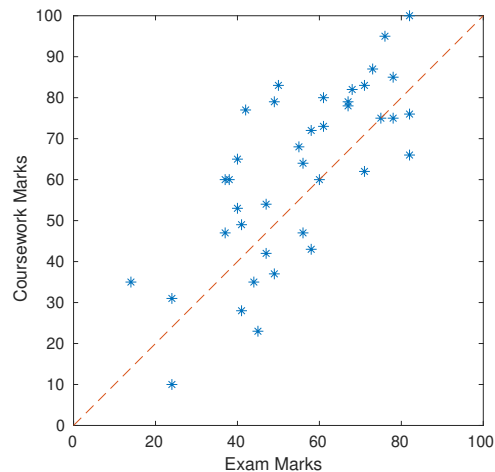


Figure 1: Coursework marks plotted against exam marks. Note the orange dashed line of symmetry

In Figure 1 the line of symmetry,  $x = y$ , was plotted. Because the data are reasonably spread around the line of symmetry, there is evidence for some proportionality between the two data sets.

Listing 1: Code for Topic 1. Question a.

```
1 data = readmatrix('MMA I CW I Dataset.xlsx');
2 courseworkMarks = data(:,1);
3 examMarks = data(:,2);
4 figure,plot(examMarks,courseworkMarks, '*');
5 xlabel('Exam Marks'); ylabel('Coursework Marks')
6 axis square; axis ([0 100 0 100])
7 hold on; plot(0:100,0:100, '—');
```

**b**

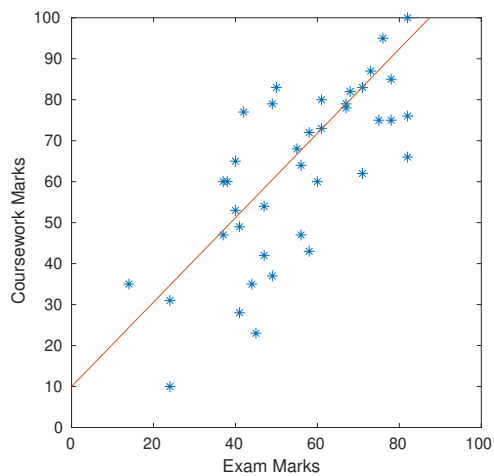


Figure 2: Coursework marks plotted against exam marks. Line of best fit estimated by eye

Given a line  $y = ax + b$ , the parameters were estimated as per below. This is represented in Figure 2.

$$\begin{aligned} a &= \frac{90 - 10}{78 - 0} = 1.03 \\ b &= 10 \end{aligned} \tag{1}$$

**c**

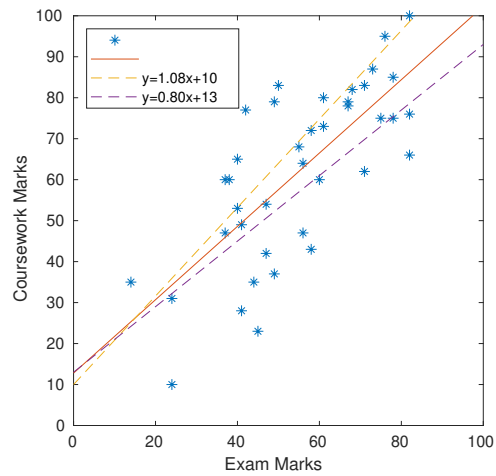


Figure 3: Coursework marks plotted against exam marks.

Therefore the uncertainty in the parameters is

*content...*

(2)

Listing 2: Code for Topic 1. Question c.

```
1 figure,plot(examMarks,courseworkMarks, '*');
2 xlabel('Exam Marks'); ylabel('Coursework Marks')
3 hold on;
4 axis square; axis ([0 100 0 100]);
5
6 p=polyfit(examMarks, courseworkMarks, 1); %Generate polynomial of best fit
7 xfit=0:100; yfit=polyval(p,xfit); %Line of best fit
8 plot(xfit,yfit)
9 plot(i,10+i.*1.08, '—'); %max slope
10 plot(i,13+i.*0.80, '—'); %min slope
11 legend(' ', ' ', 'y=1.08x+10', 'y=0.80x+13', 'Location', 'northwest')
12 hold off;
```

d

## 2 Employ assumptions to simplify systems

### 2.1 a

Length =  $L$ , Mass =  $M$ , Time =  $T$

- $[x] = L$
- $[m] = M$
- $\left[\frac{d^2x}{dt^2}\right] = \frac{L}{T^2}$
- $[k] = \frac{M}{T^2}$

### 2.2 b

$$\begin{aligned} A &\approx 10^{-3}; k \approx 10^3; m = 1; t = 10^{-3} \\ x(10^{-3}) &\approx 10^{-3} \cdot \cos\left(\cancel{10^{-3} \cdot \sqrt{10^3}}^1\right) \approx 10^{-3} \end{aligned} \tag{3}$$

## 3 Matrices and vectors

### 3.1 a

Listing 3: Code for Topic 3. Question a.

```
1 t=0:0.4:40
2 p=[20*sin(t); 20*cos(t); 10-(t./4).^2]
```

### 3.2 b

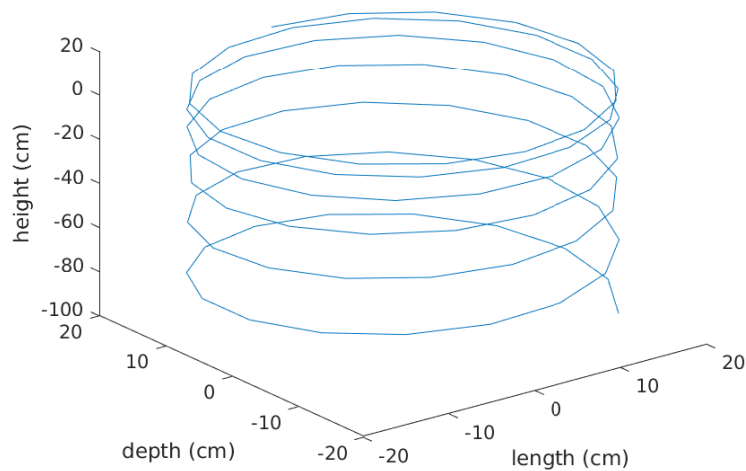


Figure 4:

Listing 4: Code for Topic 3. Question b.

```
1 plot3(p(1,:),p(2,:),p(3,:))
2 xlabel('length (cm)'),ylabel('depth (cm)'), zlabel('height (cm)')
```

### 3.3 c

Given that the speed is the modulus of velocity,

$$|\vec{v}(15)| = \left\| \begin{bmatrix} 20 \cos(15) \\ -20 \sin(15) \\ -\frac{2}{16}15 \end{bmatrix} \right\| = \left\| \begin{bmatrix} -15.1938 \\ -13.0058 \\ -1.8750 \end{bmatrix} \right\| = 20.0877 \quad (4)$$

### 3.4 d

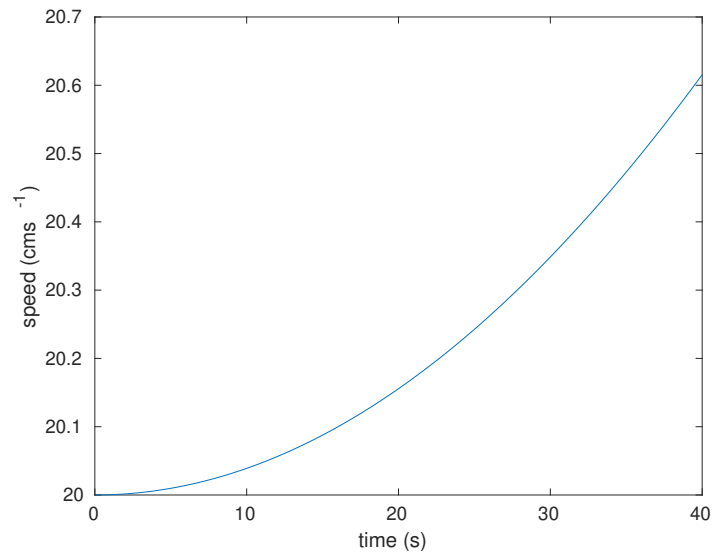


Figure 5:

Listing 5: Code for Topic 3. Question d.

```
1 v=[20*cos(t); -20*sin(t); -2.*t./16]
2 speed=sqrt(sum(v.^2))
3 plot(t,speed)
4 xlabel('time (s)'),ylabel('speed (cms^{-1})')
```

## 4 Complex numbers

4.1 a

4.2 b

4.3 c

4.4 d