Contents

1	Building Mathematical Models	2
	1.1 a	2
	1.2 b	3
	1.3 c	4
	1.4 d	5
	1.5 e	5
	1.6 f	5
2	Employ assumptions to simplify systems	6
	2.1 a	6
	2.2 b	6
3	Matrices and vectors	7
	3.1 a	7
	3.2 b	7
	3.3 c	8
	3.4 d	8
4	Complex numbers	9
	4.1 a	9
	4.2 b	9
	4.3 c	10
	4.4 d	10
		10

1 Building Mathematical Models

1.1 a

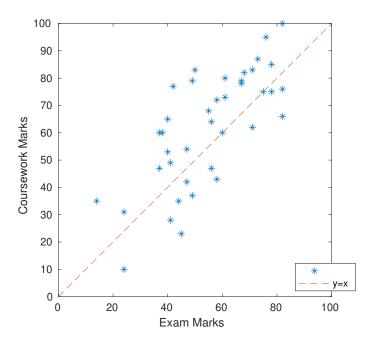


Figure 1: Coursework marks plotted against exam marks. Note the orange dashed line of symmetry

In Figure 1 the line of symmetry, x = y, was plotted. Because the data are reasonably spread around the line of symmetry, there is evidence for some proportionality between the two data sets.

Listing 1: Topic 1. Question a. Note all code per topic belongs to same file

```
figure,plot(examMarks,courseworkMarks, '*');

xlabel('Exam Marks'); ylabel('Coursework Marks')

axis square; axis ([0 100 0 100])

hold on; plot(0:100,0:100, '—'); hold off;

legend('', 'y=x', 'Location', 'best');

print('eps/topicl_a.eps','-depsc')
```

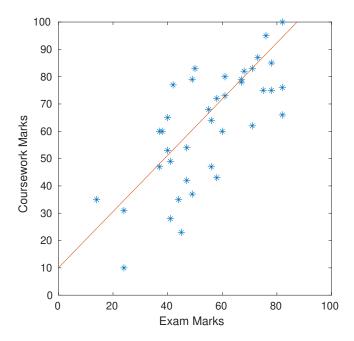


Figure 2: Coursework marks plotted against exam marks. Line of best fit estimated by eye Given a line y = ax + b, the parameters were estimated as per below. This is represented in Figure 2.

$$a = \frac{90 - 10}{78 - 0} = 1.03$$

$$b = 10$$
(1)

1.3 c

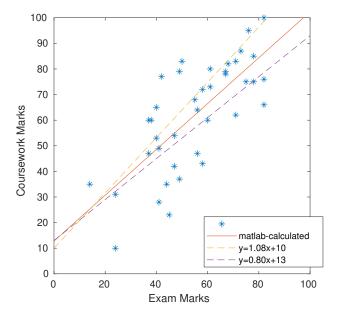


Figure 3: Coursework marks plotted against exam marks.

By comparing the maximum and minimum fits, we find the uncertainties on slope (Δa) and y-intercept (Δb) to be

$$Y_{\text{max}} = 1.08x + 10;$$
 $Y_{\text{min}} = 0.80x + 13$

$$\therefore \Delta a = \frac{1.08 - 0.80}{2} = 0.14;$$
 $\Delta b = 1.5$ (2)

Listing 2: Topic 1. Question c. Note all code per topic belongs to same file

```
figure,plot(examMarks,courseworkMarks, '*');
   xlabel('Exam Marks'); ylabel('Coursework Marks')
3
   hold on;
4
   axis square; axis ([0 100 0 100]);
   p=polyfit(examMarks, courseworkMarks, 1); %Generate polynomial of best fit
   xfit=0:100; yfit=polyval(p,xfit); %Line of best fit
6
7
   plot(xfit,yfit)
   plot(i,10+i.*1.08, '---'); %max slope
   plot(i,13+i.*0.80, '---'); %min slope
   legend('', 'matlab—calculated', 'y=1.08x+10', 'y=0.80x+13', 'Location', 'best')
10
   hold off;
11
```

1.4 d

The general trend is similar, but Matlab calculates a higher y-intercept (12.7990) and a lower slope (0.8950). This suggests that I overvalue the density of points towards the extremity of the graph, while the software appropriately looks at all points equally.

1.5 e

$$f(x) = 0.8950x + 12.7990$$

$$f(60) = 0.8950 \cdot 60 + 12.7990 = 66.499$$
 (3)

Predicted grade would be 66.

1.6 f

We could present a more quantitative marker of reliability by measuring the correlation coefficient, but it can also be done qualitatively. There is a general correlation between exam marks and coursework marks, but the scattering suggests this will be imperfect (have an R-coefficient less than 1). From the data we have students with coursework marks around 60% getting exam marks ranging from approximately 40% to 80%. This is a really large spread that covers failing and getting first-class, so while the correlation is there, and it is accurate, it is not precise enough.

2 Employ assumptions to simplify systems

2.1 a

Length = L, Mass = M, Time = T

- \bullet [x] = L
- [m] = M
- $\bullet \ \left[\frac{d^2x}{dt^2}\right] = \frac{L}{T^2}$
- $[k] = \frac{M}{T^2}$

$$A \approx 10^{-3}; k \approx 10^{3}; m = 1; t = 10^{-3}$$

$$x(10^{-3}) \approx 10^{-3} \cdot \cos\left(10^{-3} \cdot \sqrt{10^{3}}\right) \approx 10^{-3}$$
(4)

3 Matrices and vectors

3.1 a

Listing 3: Topic 3. Question a. Note all code per topic belongs to same file

```
t=0:0.4:40
p=[20*sin(t); 20*cos(t); 10-(t./4).^2]
```

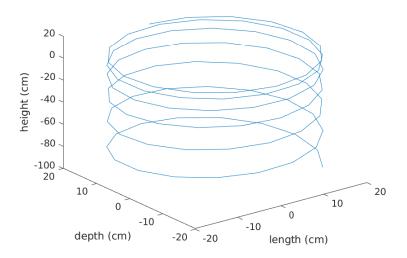


Figure 4: Particle position from t = 0s to t = 40s with 0.4 second intervals.

Listing 4: Code for Topic 3. Question b. Note all code per topic belongs to same file

```
plot3(p(1,:),p(2,:),p(3,:))
xlabel('length (cm)'),ylabel('depth (cm)'), zlabel('height (cm)')
```

3.3 c

Given that the speed is the modulus of velocity,

$$|\overrightarrow{v}(15)| = \begin{bmatrix} 20\cos(15) \\ -20\sin(15) \\ -\frac{2}{16}15 \end{bmatrix} = \begin{bmatrix} -15.1938 \\ -13.0058 \\ -1.8750 \end{bmatrix} = 20.0877 \text{ cms}^{-1}$$
 (5)

3.4 d

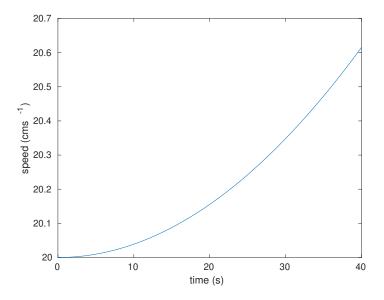


Figure 5: Particle speed varying with time.

Listing 5: Topic 3. Question d. Note all code per topic belongs to same file

```
v=[20*cos(t); -20*sin(t); -2.*t./16]
speed=sqrt(sum(v.^2))
plot(t,speed)
xlabel('time (s)'),ylabel('speed (cms^{-1})')
```

4 Complex numbers

4.1 a

Given that j^{α} is a positive imaginary number, we can conclude that its argument is $\frac{\pi}{2}$, that is

$$(re^{jx})^{\alpha} = r^{\alpha} (\cos(x\alpha) + j\sin(x\alpha))$$
 (De Moivre's theorem)
 $j^{\alpha} = r^{\alpha}e^{jx\alpha} \implies x = \frac{\pi}{2}; r = 1$ (6)

$$\therefore j^{\alpha} = e^{j\frac{\pi\alpha}{2}} = \cos\left(\frac{\alpha\pi}{2}\right) + j\sin\left(\frac{\alpha\pi}{2}\right)$$

$$Z = R_{\infty} + \frac{R_{0} - R_{\infty}}{1 + (j\omega\tau)^{\alpha}} = R_{\infty} + \frac{R_{0} - R_{\infty}}{1 + (\omega\tau)^{\alpha} \cdot j^{\alpha}}$$

$$= R_{\infty} + \frac{R_{0} - R_{\infty}}{1 + \theta^{\alpha}(c + js)} = R_{\infty} + \frac{R_{0} - R_{\infty}}{1 + \theta^{\alpha}c + \theta^{\alpha}js}$$

$$= R_{\infty} + \frac{R_{0} - R_{\infty}}{1 + \theta^{\alpha}c + \theta^{\alpha}js} \cdot \frac{1 + c\theta^{\alpha} - js\theta^{\alpha}}{1 + c\theta^{\alpha} - js\theta^{\alpha}}$$

$$= R_{\infty} + \frac{(R_{0} - R_{\infty})(1 + c\theta^{\alpha} - js\theta^{\alpha})}{1 + c\theta^{\alpha} + js\theta^{\alpha} + c\theta^{\alpha} + c^{2}\theta^{2\alpha} + cjs\theta^{2\alpha} - js\theta^{\alpha} - jse\theta^{2\alpha} - (js)^{2}\theta^{2\alpha}}$$

$$= R_{\infty} + \frac{(R_{0} - R_{\infty})(1 + c\theta^{\alpha} - js\theta^{\alpha})}{1 + 2c\theta^{\alpha} + \theta^{2\alpha}(c^{2} - j^{2}s^{2})}$$

$$= R_{\infty} + \frac{(R_{0} - R_{\infty})(1 + c\theta^{\alpha} - js\theta^{\alpha})}{1 + 2c\theta^{\alpha} + \theta^{2\alpha}(c^{2} + s^{2})^{-1}} \qquad \text{(from } \cos^{2}(x) + \sin^{2}(x) = 1)$$

$$\therefore Z = R_{\infty} + \frac{(R_{0} - R_{\infty})(1 + c\theta^{\alpha} - js\theta^{\alpha})}{1 + 2c\theta^{\alpha} + \theta^{2\alpha}(c^{2} + s^{2})^{-1}} \qquad \text{as required}$$

4.3 c

Given that
$$\Delta = R_0 - R_{\infty}$$
, and $q = 1 + 2c\theta^{\alpha} + \theta^{2\alpha}$,

$$Z = R_{\infty} + \Delta \frac{1 + c\theta^{\alpha} - js\theta^{\alpha}}{q}$$

$$Z = R_{\infty} + \frac{\Delta + \Delta c\theta^{\alpha}}{q} - j\frac{s\Delta\theta^{\alpha}}{q}$$

$$\Rightarrow |Z| = \sqrt{\left(R_{\infty} + \frac{\Delta + \Delta c\theta^{\alpha}}{q}\right)^{2} + \left(\frac{s\Delta\theta^{\alpha}}{q}\right)^{2}}$$

$$|Z| = \sqrt{R_{\infty}^{2} + \frac{2R_{\infty}\Delta + 2R_{\infty}\Delta c\theta^{\alpha}}{q} + \frac{\Delta^{2} + 2\Delta^{2}c\theta^{\alpha} + \Delta^{2}c^{2}\theta^{2\alpha}}{q^{2}} + \frac{(s\Delta\theta^{\alpha})^{2}}{q^{2}}}$$

$$[\text{note that } \theta^{2\alpha}\Delta^{2} \left(c^{2} + s^{2}\right) = \theta^{2\alpha}\Delta^{2}]$$

$$|Z| = \sqrt{R_{\infty}^{2} + \frac{2R_{\infty}\Delta + 2R_{\infty}\Delta c\theta^{\alpha}}{q} + \Delta^{2}\left(\frac{1 + 2c\theta^{\alpha} + \theta^{2\alpha}}{q^{2}}\right)^{\frac{1}{q}}}$$

$$|Z| = \sqrt{\frac{qR_{\infty}^{2} + 2R_{\infty}\Delta + 2R_{\infty}\Delta c\theta^{\alpha} + \Delta^{2}}{q}}$$

$$|Z| = \sqrt{\frac{qR_{\infty}^{2} + 2R_{\infty}\Delta + 2R_{\infty}\Delta c\theta^{\alpha} + \Delta^{2}}{q}}$$

$$|Z| = \sqrt{\frac{(1 + 2c\theta^{\alpha} + \theta^{2\alpha})R_{\infty}^{2} + 2R_{\infty}(R_{0} - R_{\infty}) + 2R_{\infty}(R_{0} - R_{\infty})c\theta^{\alpha} + (R_{0} - R_{\infty})^{2}}{1 + 2c\theta^{\alpha} + \theta^{2\alpha}}}$$

$$|Z| = \sqrt{\frac{R_{\infty}^{2} + 2c\theta^{\alpha}R_{\infty}^{2} + R_{\infty}^{2}\theta^{2\alpha} + 2R_{\infty}R_{0} - 2R_{\infty}^{2} + 2R_{\infty}R_{0}c\theta^{\alpha} - 2R_{\infty}^{2}c\theta^{\alpha} + R_{0}^{2} + R_{\infty}^{2} - 2R_{0}R_{\infty}}{1 + 2c\theta^{\alpha} + \theta^{2\alpha}}}$$

$$\therefore |Z| = \sqrt{\frac{R_{\infty}^2 \theta^{2\alpha} + 2cR_{\infty}R_0\theta^{\alpha} + R_0^2}{1 + 2c\theta^{\alpha} + \theta^{2\alpha}}} \quad \text{as required}$$

(8)

4.4 d

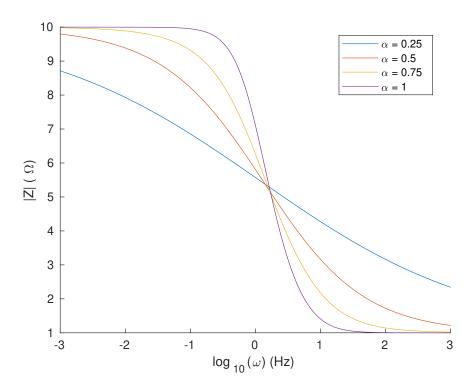


Figure 6: Magnitude of impedance plotted against angular frequency

Listing 6: Code for Topic 4. Question d.

```
R_{infty} = 1
 2
    R_0 = 10
 3
    tau = 1
 4
    omega=0.001:0.001:10<sup>3</sup>
 5
    theta = omega*tau
 6
 7
    figure, hold on;
 8
    for alpha = [0.25, 0.5, 0.75, 1]
 9
        c=cos(alpha*pi/2)
10
        modZ = sqrt(((R_infty)^2.*theta.^(2*alpha) + 2*c*R_0*R_infty.*theta.^alpha + (R_0)^2)./
             (1+2*c*theta.^alpha + theta.^(2.*alpha)) )
11
        plot(log10(omega), modZ);
12
    end
13
    xlabel('log_{10}(\omega) (Hz)'); ylabel('|Z| (\omega)')
    legend('\alpha = 0.25', '\alpha = 0.5', '\alpha = 0.75', '\alpha = 1', 'Location', 'best')
14
    print('eps/topic4_d.eps','-depsc')
```

4.5 e

We see variations of logistic curves, which is somewhat surprising, given that the equation for |Z| is quite different from the standard f(x), such that

$$f(x) = \frac{L}{1 + e^{-k(x - x_0)}} \tag{9}$$