

Individual & Collective Intelligence

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Intelligence

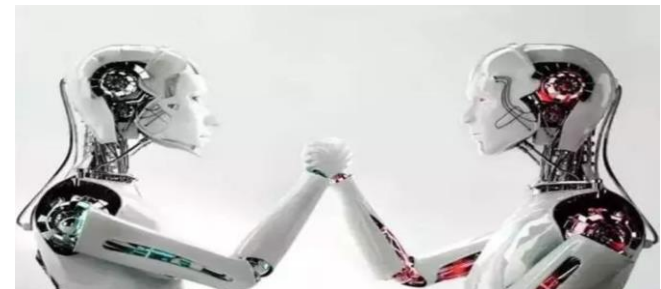
Individual Intelligence
Reinforcement Learning

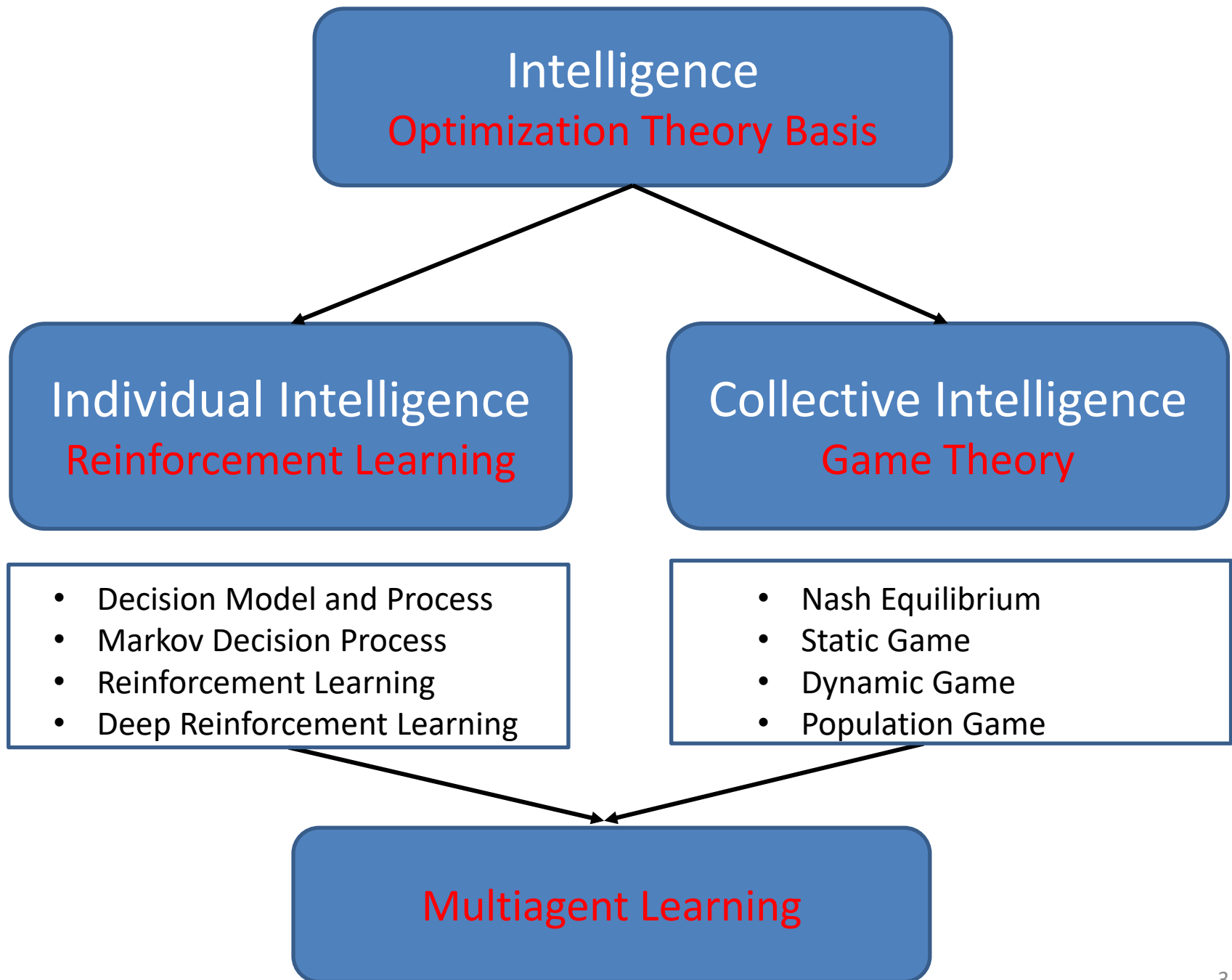
Collective Intelligence
Game Theory

AlphaGo



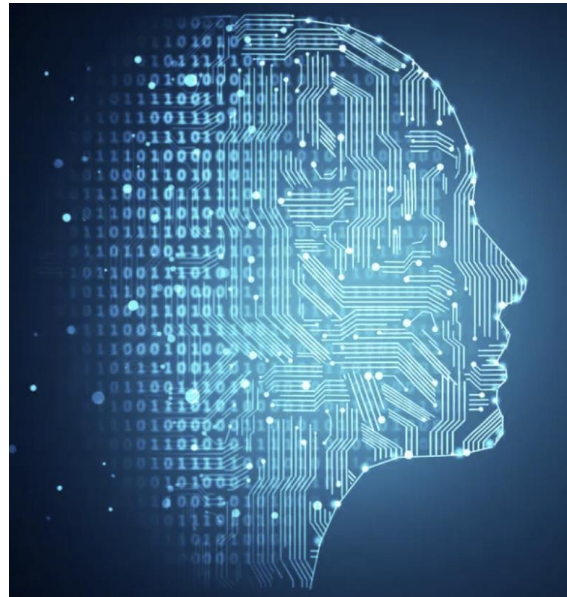
Pluribus





Individual Intelligence

A Brief Introduction to Reinforcement Learning



Fundamental challenge in artificial intelligence is learning to make good decisions under uncertainty



What is reinforcement learning?

A computational approach to learning whereby **an agent** tries to **maximize** the total amount of **reward** it receives while interacting with a complex and uncertain **environment**.



Supervised Learning

Data: (x, y)

x is data, y is label

Goal: Learn a *function* to map $x \rightarrow y$

Examples: Classification,
regression, object detection,
semantic segmentation, image
captioning, etc.



→ Cat

Classification

Supervised Learning: Image Classification

- Annotated images, data follows i.i.d distribution
- Learners are told what the labels are

Training annotated data

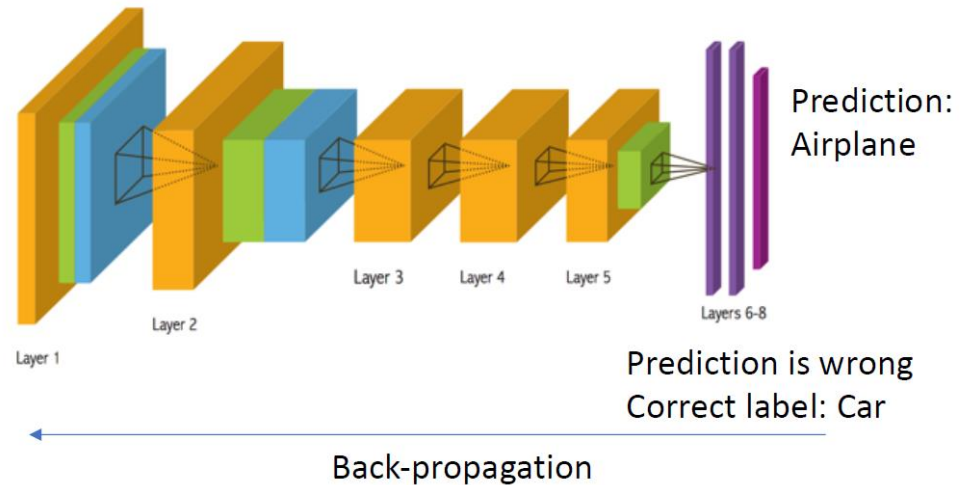
Car



Airplane



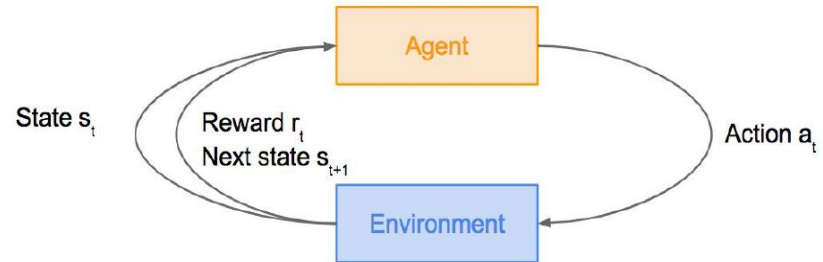
Chair



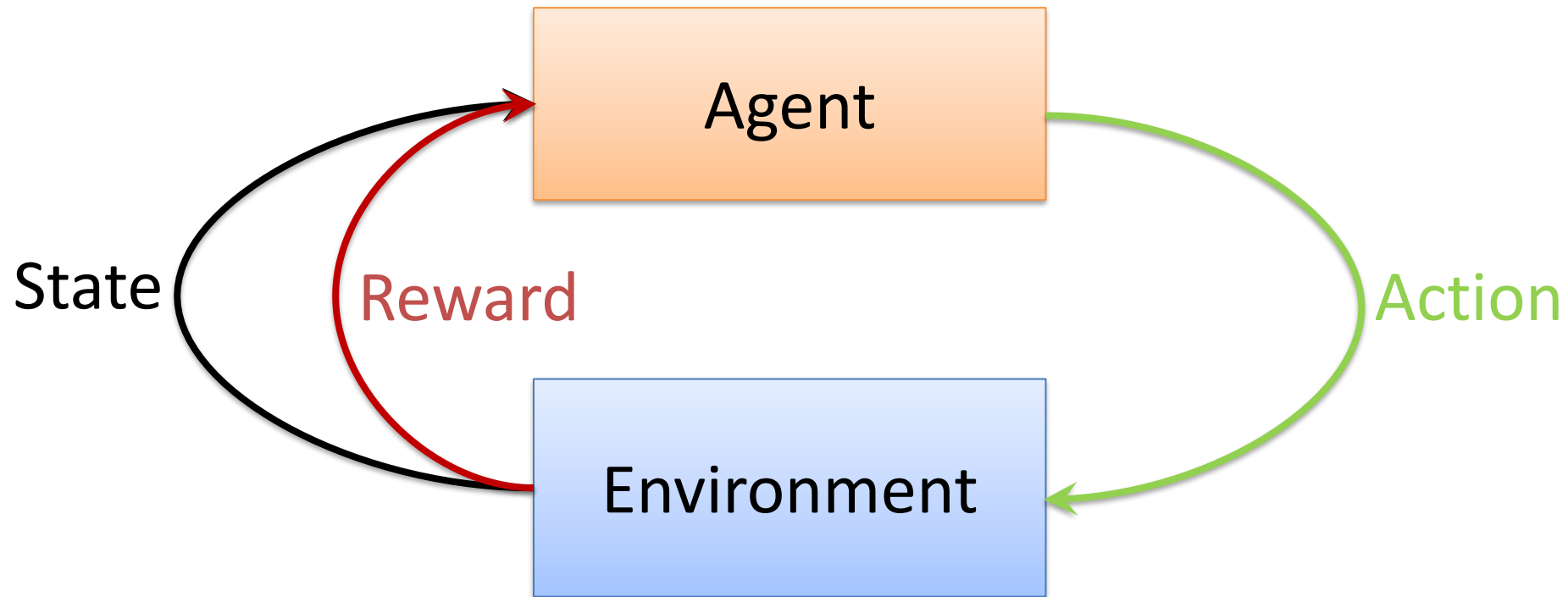
Reinforcement Learning

Problems involving an **agent** interacting with an **environment**, which provides numeric **reward** signals

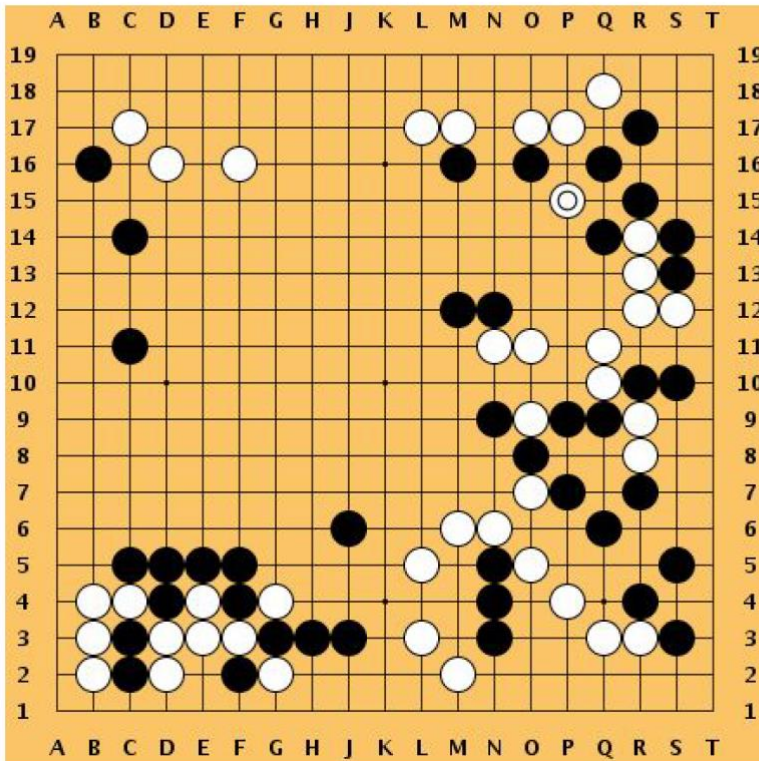
Goal: Learn how to take actions in order to maximize reward



Reinforcement Learning



Go



Objective: Win the game!

State: Position of all pieces

Action: Where to put the next piece down

Reward: 1 if win at the end of the game, 0 otherwise

Atari Games



Objective: Complete the game with the highest score

State: Raw pixel inputs of the game state

Action: Game controls e.g. Left, Right, Up, Down

Reward: Score increase/decrease at each time step

Difference between Reinforcement Learning and Supervised Learning

- Sequential data as input (not i.i.d)
- The learner is not told which actions to take, but instead must discover which actions yield the most reward by trying them.
- Trial-and-error exploration (balance between exploration and exploitation)
- There is no supervisor, only a reward signal, which could also be delayed

Big deal: Able to Achieve Superhuman Performance

- Upper bound for supervised learning is human-performance
- Upper bound for reinforcement learning?



Why Reinforcement Learning Works Now?

- Computation power: many GPUs to do trial-and-error rollout
- Acquire the high degree of proficiency in domains governed by simple and known rules; huge volume of data samples available
- End-to-end deep learning based training, features and policy are jointly optimized toward the end goal



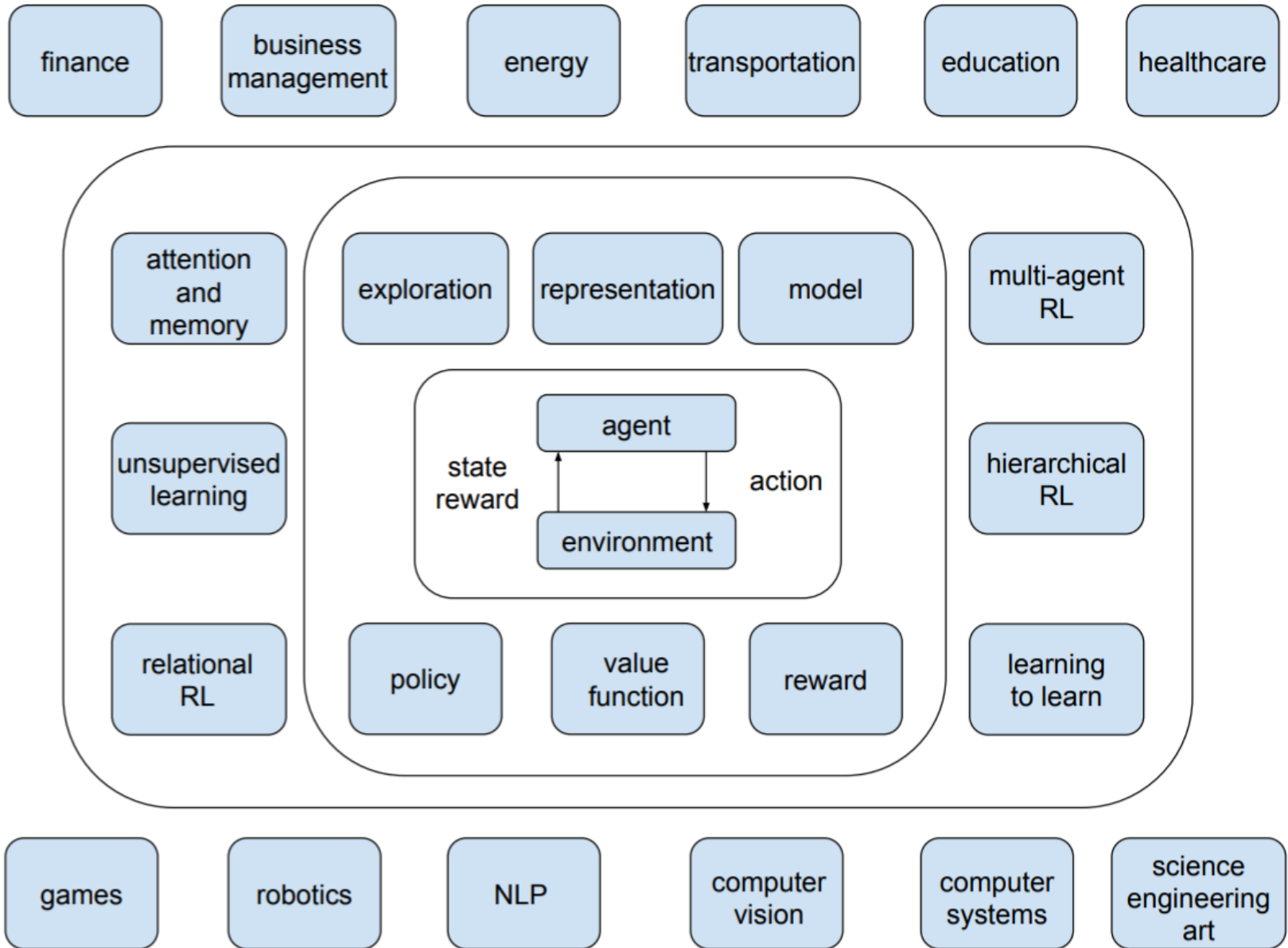
Game playing



Robotics



Beating best human player



Reinforcement Learning: Flappy Bird

```
q_network.py > trainNetwork

def bias_variable(shape):
    initial = tf.constant(0.01, shape = shape)
    return tf.Variable(initial)

def conv2d(x, W, stride):
    return tf.nn.conv2d(x, W, strides = [1, stride, 1, 1], padding = "SAME")

def max_pool_2x2(x):
    return tf.nn.max_pool(x, ksize = [1, 2, 1, 2], strides = [1, 2, 1, 2], padding = "SAME")

def createNetwork():
    # 设置初始权重
    W_conv1 = weight_variable([8, 8, 4, 32])
    b_conv1 = bias_variable([32])

    W_conv2 = weight_variable([4, 4, 32, 64])
    b_conv2 = bias_variable([64])

    W_conv3 = weight_variable([3, 3, 64, 64])
    b_conv3 = bias_variable([64])

    W_fc1 = weight_variable([1600, 512])
    b_fc1 = bias_variable([512])

    W_fc2 = weight_variable([512, ACTIONS])
    b_fc2 = bias_variable([ACTIONS])

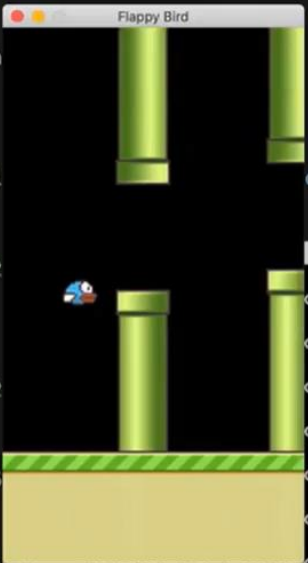
    x = tf.placeholder(tf.float32, [None, 1600])
    y_ = tf.placeholder(tf.float32, [None, ACTIONS])
    z = tf.nn.softmax(tf.matmul(x, W_fc2) + tf.matmul(b_fc2))

    # 训练网络
    cost = tf.nn.softmax_cross_entropy_with_logits(logits = tf.matmul(x, W_fc2) + tf.matmul(b_fc2), labels = y_)
    optimizer = tf.train.AdamOptimizer()
    train_op = optimizer.minimize(cost)

    # 保存模型
    saver = tf.train.Saver()
    saver.save(sess, "q_network.ckpt")

    # 加载模型
    saver.restore(sess, "q_network.ckpt")

    # 训练
    for i in range(10000):
        state = env.reset()
        done = False
        while not done:
            action = sess.run(z, {x: state})
            state, reward, done, _ = env.step(action)
            sess.run(train_op)
```

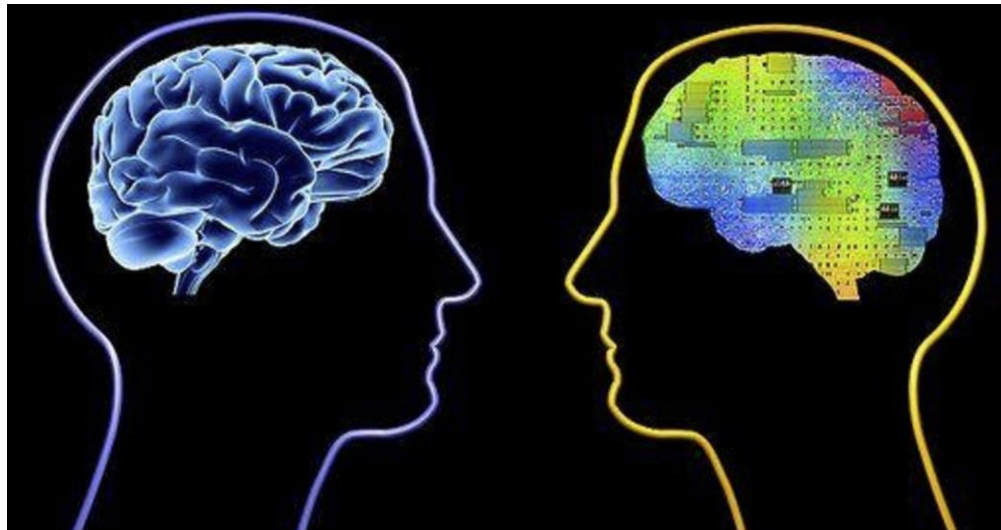


```
auto_bird -- python bird.q_network.py -- 80x24

observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX -1.
observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX 2.
observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX 9.
observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX 7.
observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX 8.
observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX 1.
observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX 1.
observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX 1.
observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX 1.
observe / EPSILON 0.0001 / ACTION 0 / REWARD 0.1 / Q_MAX 9.
TIMESTEP 650 / STATE 406398e-02
TIMESTEP 651 / STATE 037979e-02
TIMESTEP 652 / STATE 488752e-02
TIMESTEP 653 / STATE 630221e-02
134788e-03
```

Collective Intelligence

A Brief Introduction to Game Theory



Game Theory

Rational – user aims to optimize its own objective

Interaction – user needs to take others' decisions into account



“...Game Theory is designed to address situations in which the outcome of a person's decision depends not just on how they choose among several options, but also on the choices made by the people they are interacting with...” --David Easley and Jon Kleinberg

“... Game theory is the study of the ways in which strategic interactions among rational agents produce *outcomes* with respect to the *utilities* of those agents” --Stanford Encyclopedia of Philosophy

A Brief History

- 1944: Von Neumann and Oskar Morgenstern

Theory of Games and Economic Behavior

Two-player games



O. Morgenstern 1902-1977

- 1950: John Nash

Nash Equilibrium

Equilibrium points in n-player games



von Neumann 1903-1957

- After 1950s: widely used in economics, politics, biology...

Competition between firms

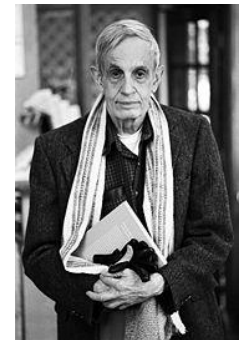
Auction design

Role of punishment in law enforcement

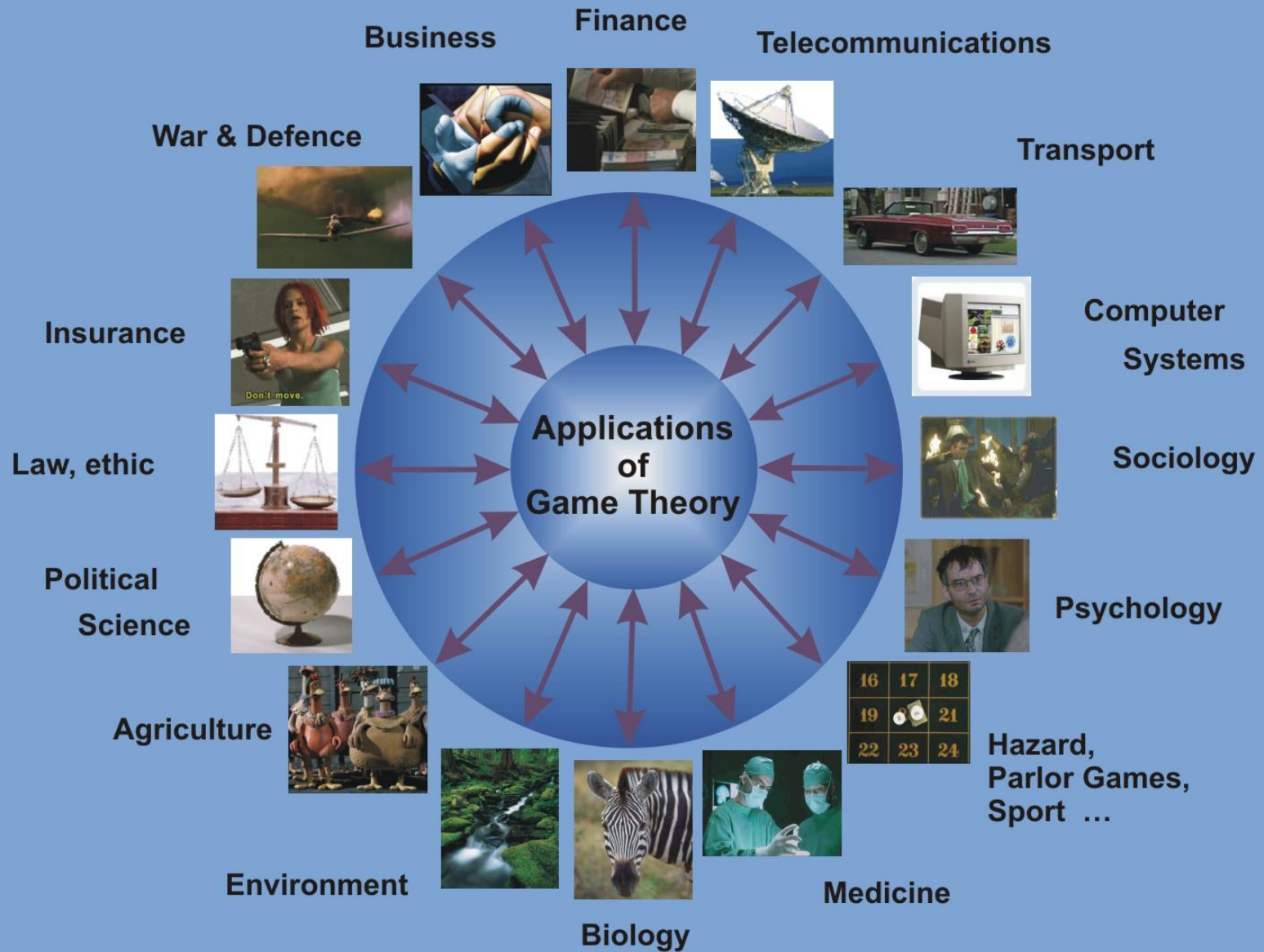
International policies

Evolution of species

Artificial Intelligence/machine learning

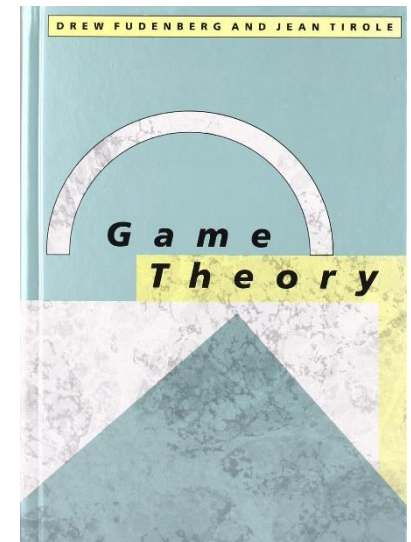
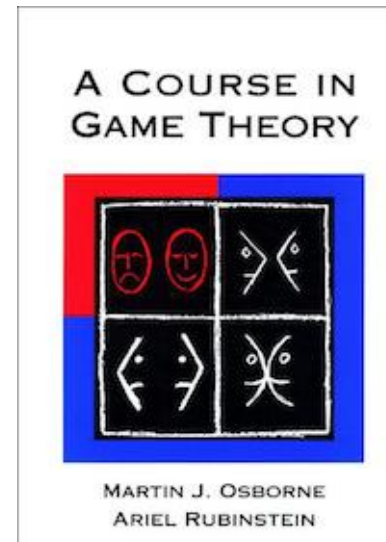


John Nash 1928-2015



Relevance to Computing Research

- Economic issues become increasingly important
 - Interactions with/between human users
e.g., data-driven pricing, resource allocation
(Urban/Amazon/DiDi/Taobao)
 - Independent service providers
e.g., bandwidth trading, peering agreements
- Tool for smart system design
 - Distributed Intelligent algorithms
 - Multi-objective optimization
 - Incentive compatible protocols



Game Theory Basics

- Strategic game form (P, S, U)
 - **Players** (P_1, \dots, P_N) : finite number of decision makers
 - **Strategy sets** (S_1, \dots, S_N) : player P_i has a nonempty set S_i of actions/strategies s_i
 - **Payoff function** $U_i(s_1, \dots, s_N)$: player's preference/individual utility
- Nash equilibrium (NE)
 - A strategy profile $(s_1^*, \dots, s_i^*, \dots, s_N^*)$ is a NE if for each player i
$$U_i(s_1^*, \dots, s_i^*, \dots, s_N^*) \geq U_i(s_1^*, \dots, s_i, \dots, s_N^*), \forall s_i \in S_i$$
 - No player has incentive to deviate (**stable system point**)
 - NE is a fixed point of the **best response** functions
$$s_i^* = \operatorname{argmax}_{s_i \in S_i} U_i(s_1^*, \dots, s_i, \dots, s_N^*), \forall i$$
- There is no universal rule for finding a Nash equilibrium!

Prisoner's Dilemma

- Two suspects are arrested
- The police lack sufficient evidence to convict the suspects, unless at least one confesses
- The police hold the suspects in two separate rooms, and tell each of them three possible consequences:
 - If both deny: 1 month in jail each
 - If both confess: 6 months in jail each
 - If one confesses and one denies:
 - The one confesses: walk away free of charge
 - The one denies: serve 12 months in jail

Prisoner's Dilemma

strategies

Player 2

Deny Confess

Player 1

Deny Confess

Deny	$-1, -1$	$-12, 0$
Confess	$0, -12$	$-6, -6$

payoffs

Prisoner's Dilemma

- Strictly dominated strategy

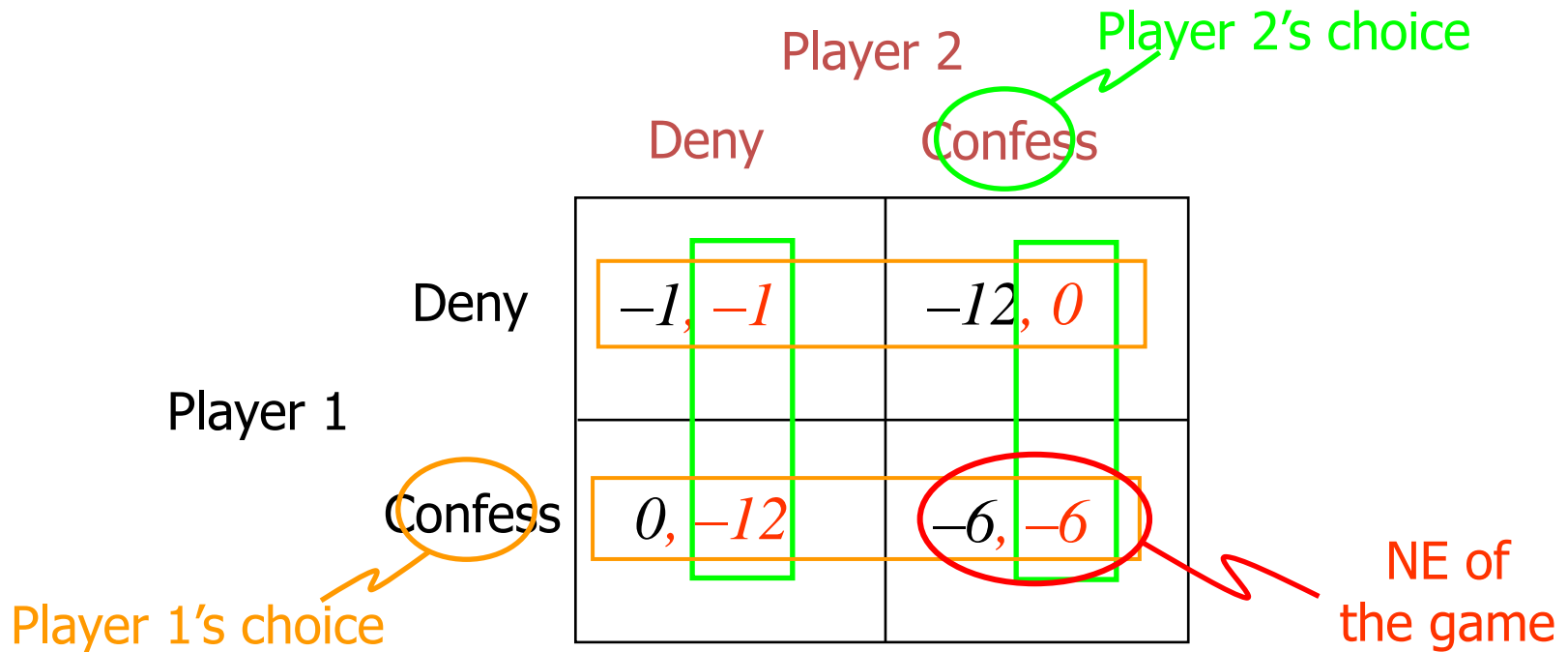
- Player i 's strategy s'_i is **strictly dominated** by player i 's strategy s_i if

$$U_i(s_i, s_{-i}) > U_i(s'_i, s_{-i}), \forall s_{-i}$$

where s_{-i} is the strategy profile of all the other players except player i

- No matter what other people do, by choosing s_i instead of s'_i , player i will always obtain a **better payoff**
- Key principle: **Never play a strictly dominated strategy**

Prisoner's Dilemma



A 2x2 payoff matrix for a Prisoner's Dilemma game. The rows represent Player 1's choices (Deny, Confess) and the columns represent Player 2's choices (Deny, Confess). The payoffs are shown in red text within the cells. Annotations include: a green circle around 'Confess' in the column header with an arrow pointing to it labeled 'Player 2's choice'; an orange circle around 'Confess' in the row header with an arrow pointing to it labeled 'Player 1's choice'; green vertical rectangles around the 'Confess' column; an orange rectangle around the 'Deny' row; and a red circle around the bottom-right cell (-6, -6) with an arrow pointing to it labeled 'NE of the game'.

		Player 2	
		Deny	Confess
Player 1	Deny	$-1, -1$	$-12, 0$
	Confess	$0, -12$	$-6, -6$

Deny is **strictly dominated** by Confess!

Finding Nash Equilibrium

- When there are no strictly dominated strategies, we can not easily “simplify” the game
- Nash equilibrium is a state of mutual best responses
- Key principle: derive the best responses

Stag Hunt

- Two hunters decide what to hunt independently
- Each one can hunt a stag (deer) or a hare
- Successful hunt of stag requires cooperation
- Successful hunt of hare can be done individually
- Simultaneous decisions without prior communications

Stag Hunt

		Player 2	
		Stag	Hare
Player 1	Stag	5 , 5	0 , 2
	Hare	2 , 0	2 , 2

There is no **strictly dominated** strategy

Find out a player's **best response** given the other player's choice

Stag Hunt

Given Player 2 chooses Stag

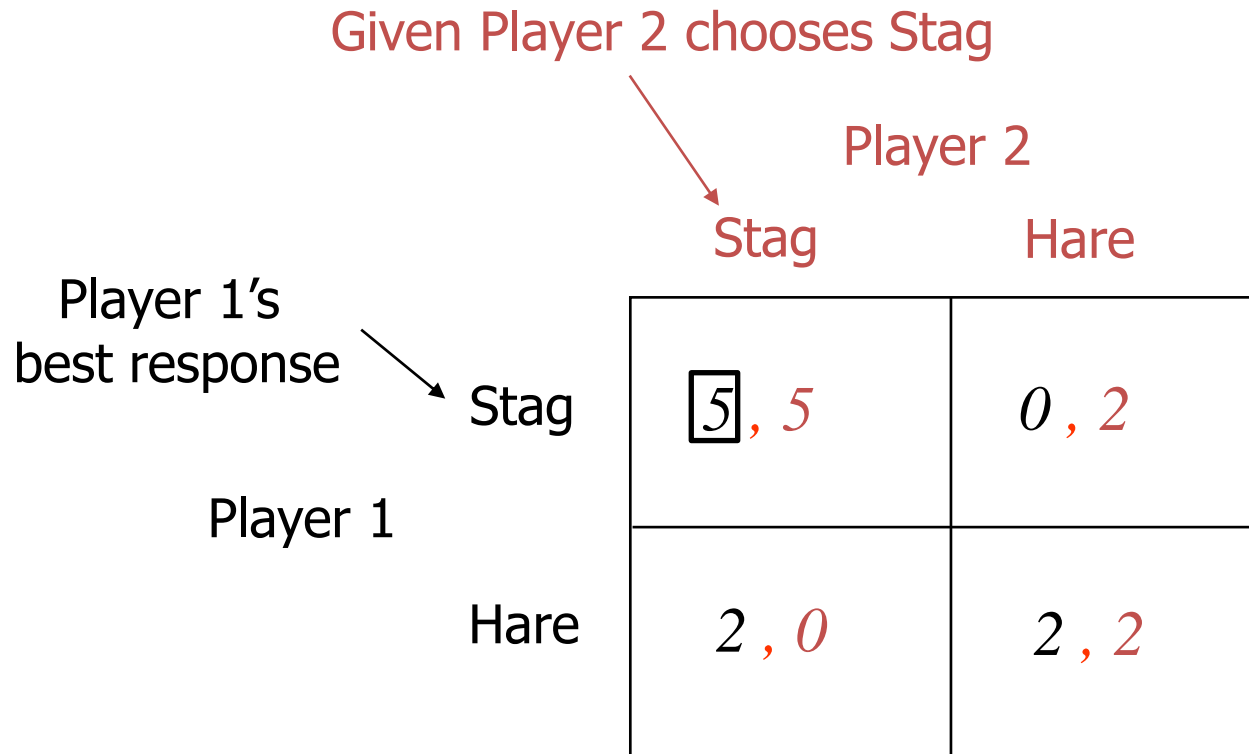
Player 2

Stag Hare

Player 1's best response

Player 1

Stag	5 , 5	0, 2
Hare	2, 0	2, 2

A diagram of a Stag Hunt game matrix. The matrix is a 2x2 grid. The columns are labeled 'Stag' and 'Hare' under the heading 'Player 2'. The rows are labeled 'Stag' and 'Hare' under the heading 'Player 1'. The payoffs are: (Stag, Stag) = (5, 5) with the 5 boxed; (Stag, Hare) = (0, 2); (Hare, Stag) = (2, 0); (Hare, Hare) = (2, 2). Annotations include 'Given Player 2 chooses Stag' with an arrow pointing to the Stag column, and 'Player 1's best response' with an arrow pointing to the Stag row.

Stag Hunt

Given Player 2 chooses Hare

Player 2

Stag Hare

Player 1

Stag

Hare

Player 1's best response

	Stag	Hare
Stag	5 , 5	0, 2
Hare	2, 0	2 , 2

Stag Hunt

		Player 2	
		Stag	Hare
Player 1	Stag	5, 5	0, 2
	Hare	2, 0	2, 2

NE of the game

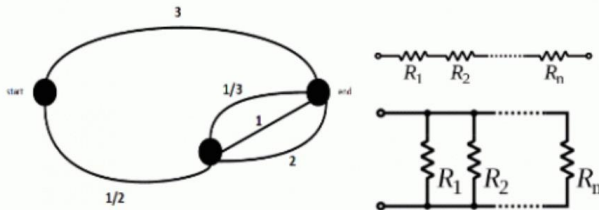
Player 2's best responses

NE is a state of mutual best responses

Stag Hunt

- Two Nash equilibria exist
- (Stag, Stag) is **payoff dominant**
 - Both players get the best payoff possible
 - Require trust among players to achieve coordination
- (Hare, Hare) is **risk dominant**
 - Minimum risk if player is uncertain of each other's choice

SURPRISING Connection Between Game Theory And Electrical Engineering



Using Computational Game Theory To Guide Verification and Security in Hardware Designs

Andrew M. Smith^{*†}, Jackson R. Mayo[‡], Vivian Kammler[§], Robert C. Armstrong^{*}, and Yevgeniy Vorobeychik[¶]

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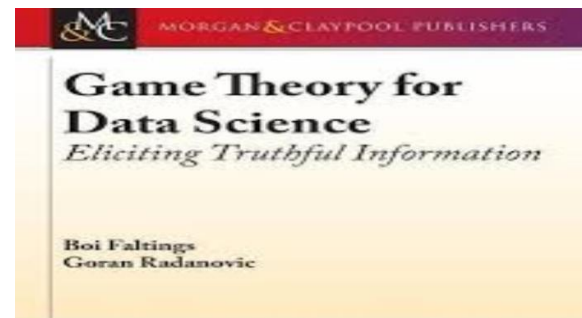
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Swarm Intelligence



Reinforcement Learning + Game Theory = Multiagent Learning

