CS2040S Tutorial 4

Admin matters

- Attendance taking
- Check in and PS4 discussion

PS4

- Some of you forgot to check for edge cases, such as when enumerateNodes is called on a node with no children
 - Be more careful!
- Start work early to prevent running out of time
- If your code has issues, please try to fix them because Problem Set 5 is a continuation of Problem Set 4
 - o If you are unable to do so/want me to verify correctness, feel free to approach me

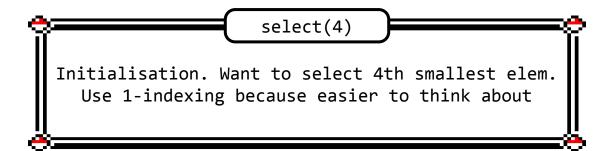
Recap (adapted from Christian's Slides)

- Quickselect
- Trees

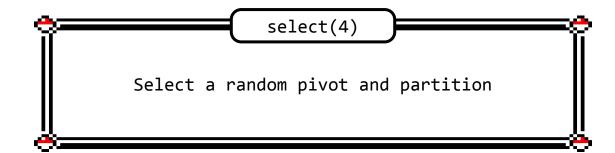
Quickselect

Quickselect

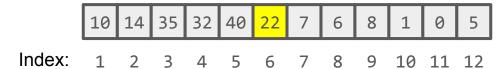
- An algorithm to select the kth smallest element in unsorted array
- Derives a similar idea from Quicksort
- Observation: When you finish partitioning, the pivot is already at the correct place!
- But instead of recursing on both sides, recurse on one side!

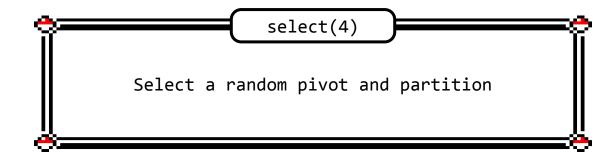


Index: 1 2 3 4 5 6 7 8 9 10 11 12



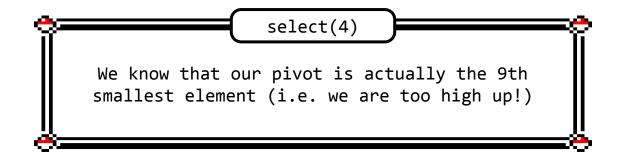
10 11 12





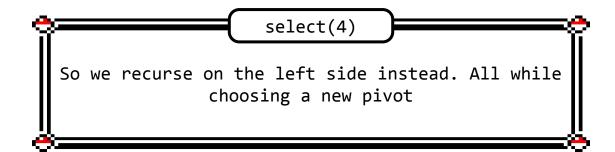
10 14 7 0 5 1 8 6 22 35 32 40

Index: 1 2 3 4 5 6 7 8 9 10 11 12



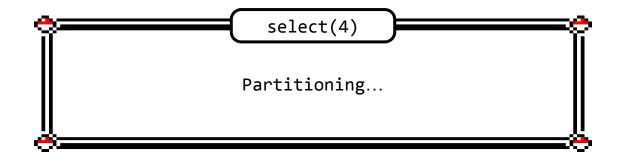
35 32 40

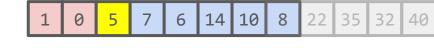
Index: 8 9 10 11 12



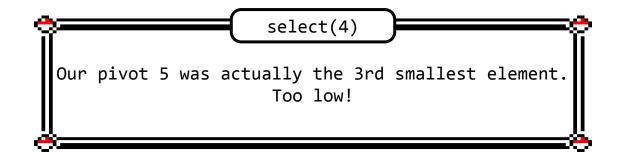
35 | 32

Index:



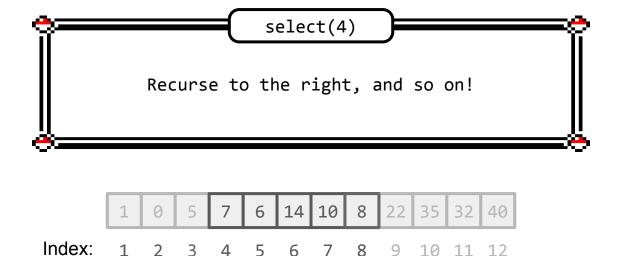


Index: 1 2 3 4 5 6 7 8 9 10 11 12



1 0 5 7 6 14 10 8 22 35 32 40

Index: 1 2 3 4 5 6 7 8 9 10 11 1



It is more important to understand the idea behind quickselect rather than being caught up in the indexing issues.

Quickselect Analysis

For an array of size n...

Recurrence Relation:

Time Complexity:

Quickselect Analysis

For an array of size n...

Recurrence Relation: T(n) = T(n/2) + O(n)

Time Complexity: O(n)

Ordered Dictionary ADT

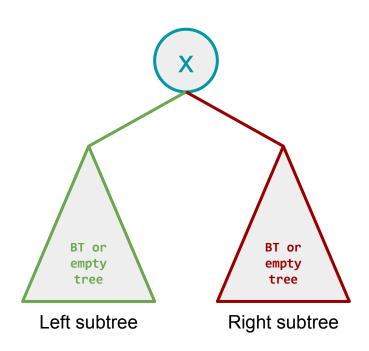
It should guarantee these operations:

Ordered Dictionary ADT

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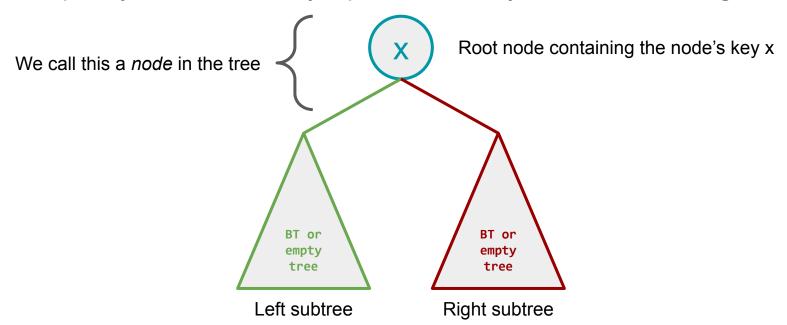
- insert(key, value)
- search(key)
- delete(key)
- contains(key)
- successor(key)
- predecessor(key)
- size()

Binary trees

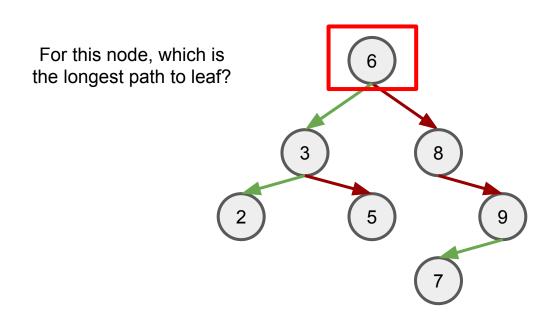


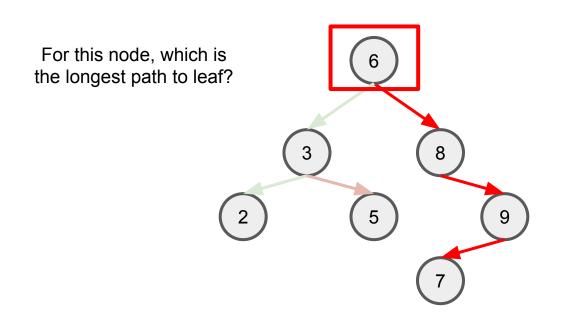
Binary trees

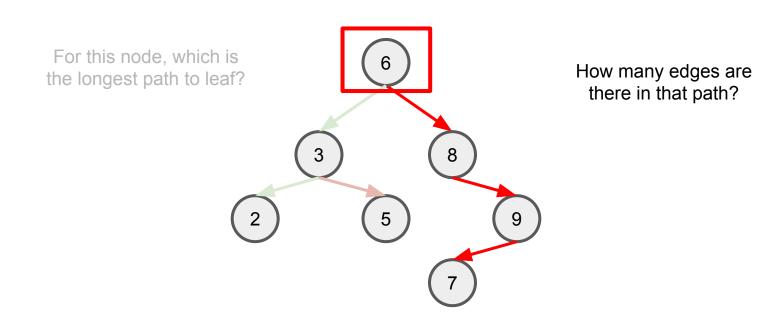
Conceptually, we often visually represent a binary tree in the following form

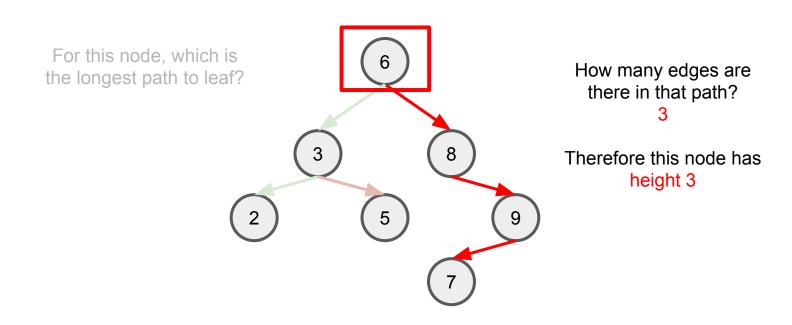


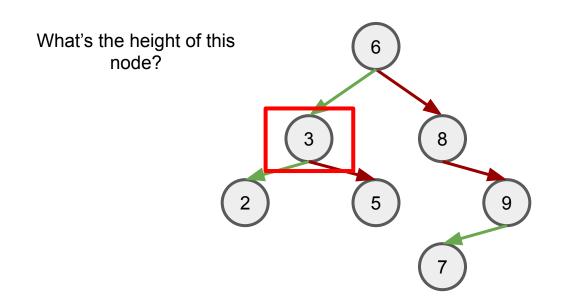
Realize that this diagram applies to EVERY NODE in the BT? I.E. every node in the BT is itself a BT!

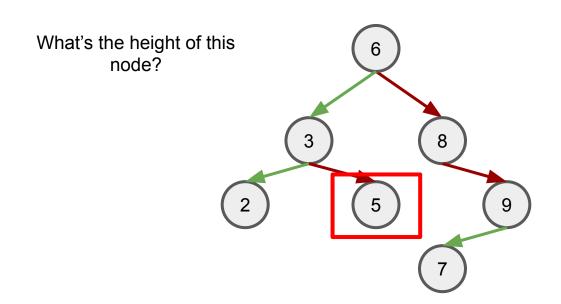


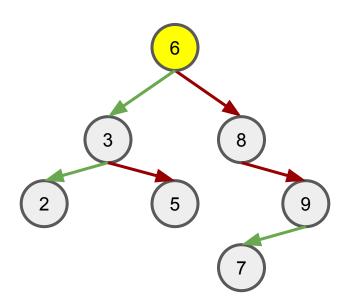


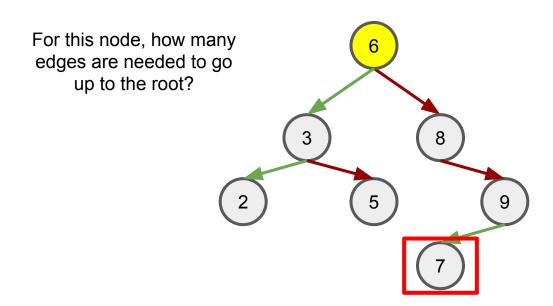


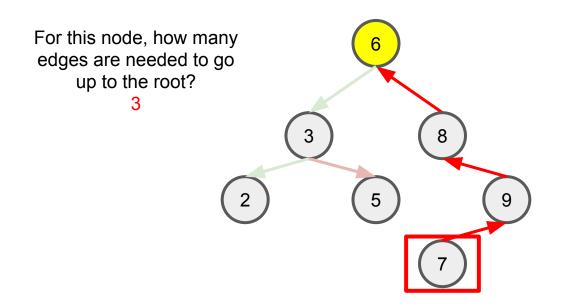


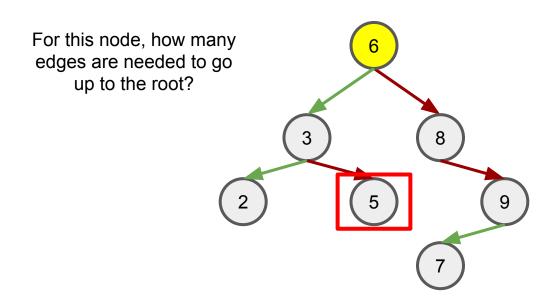


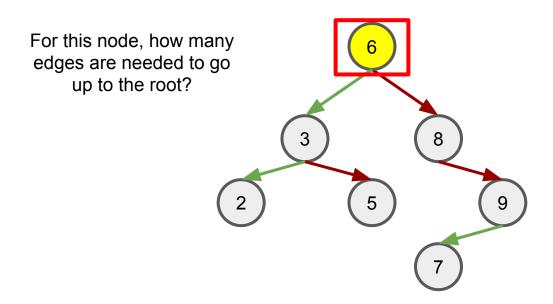












Binary Search Trees (BST)

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It is a binary tree with the following properties:

- A node's left subtree contains nodes strictly less than the node's key
- A node's right subtree contains nodes strictly greater than the node's key
- The left and right subtrees are binary trees
- All keys belong to a total order (no two different keys can be considered equal)

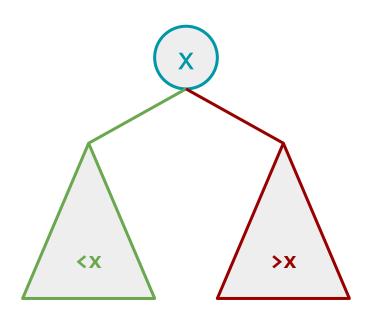
Binary Search Trees (BST)

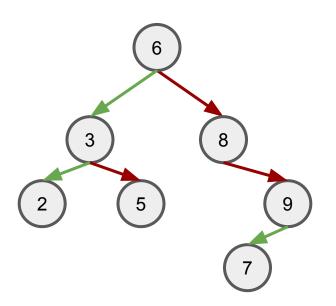
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- A node's left subtree contains nodes strictly less than the node's key
- A node's right subtree contains nodes strictly greater than the node's key
- The left and right subtrees are binary trees
- All keys belong to a total order (no two different keys can be considered equal)

Common mistake: Thinking that only the <u>direct</u> left/right child have to be less/greater. It is ALL the nodes in the left/right SUBTREE

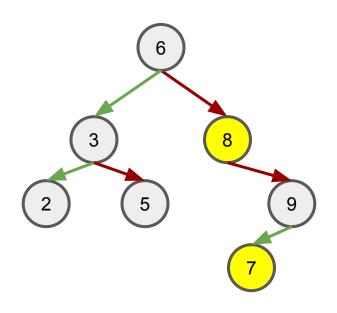
Binary Search Trees (BST)

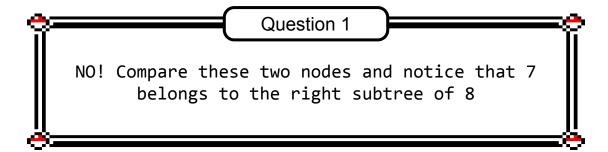


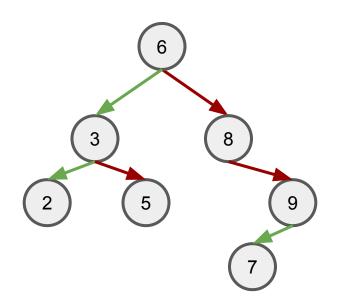


Question 1

Fun fact: There used to be CS2020, which is essentially a 6MC version of CS2030 + CS2040S in one mod

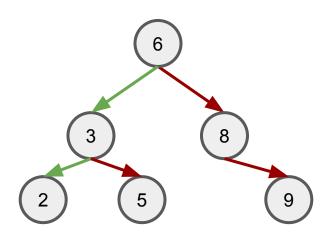


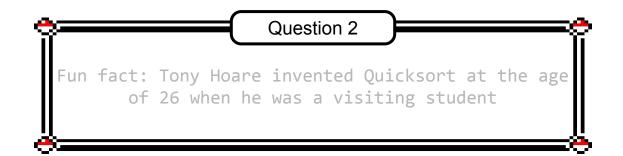


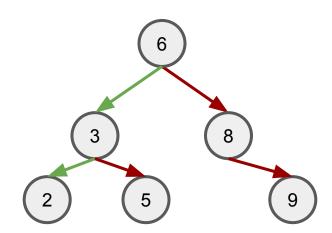


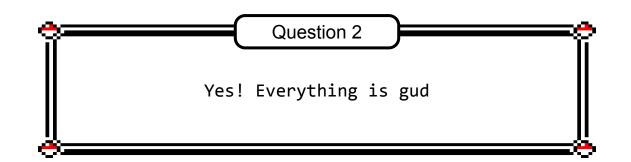
Question 1

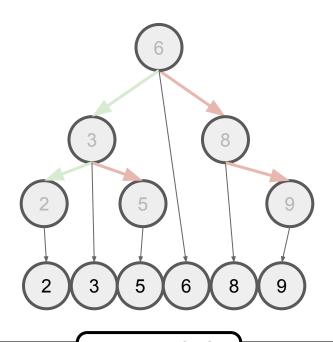
If you were to (wrongly) use the idea that *only* the direct left/right childs have to be smaller/greater, then this fits. BUT THIS IS NOT A BST





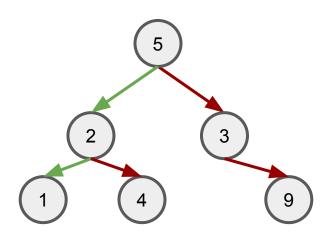


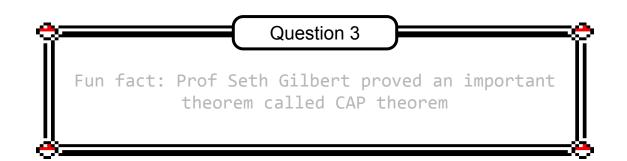


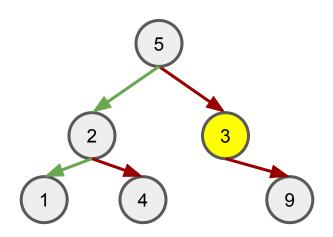


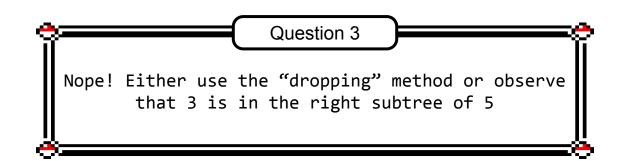
#LIFEHACKS

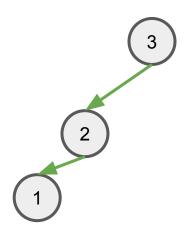
If you "drop" every node and it appears like a sorted sequence, then it is a BST







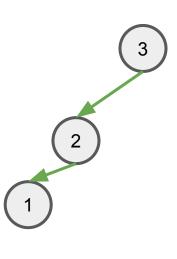


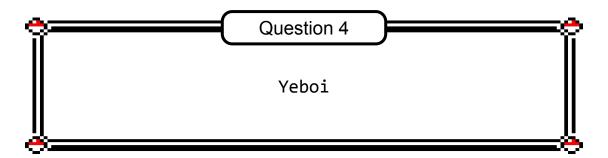


Question 4

Fun fact: Donald Knuth, the "father of analysis of algorithms" is *still* writing a book called The Art
Of Computer Programming since 1968





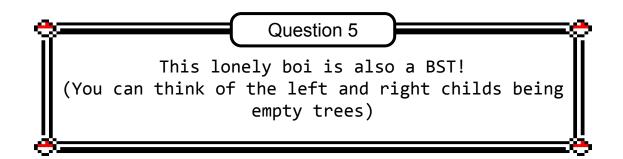




Question 5

Fun fact: COM3 which is being built, is the first building that is built for SoC (we inherited COM1 and COM2 from Law i think)





Summary

h(v) - height of a node: Number of **edges** on the *longest path* from node to leaf.

- h(v) = 0 (if v is a leaf)
- h(v) = max(h(v.left), h(v.right)) + 1

Questions?

Operations in a BST

- Searching
- Insertion
- Search Minimum and Maximum
- Successor and Predecessor
- Delete
- Traversal

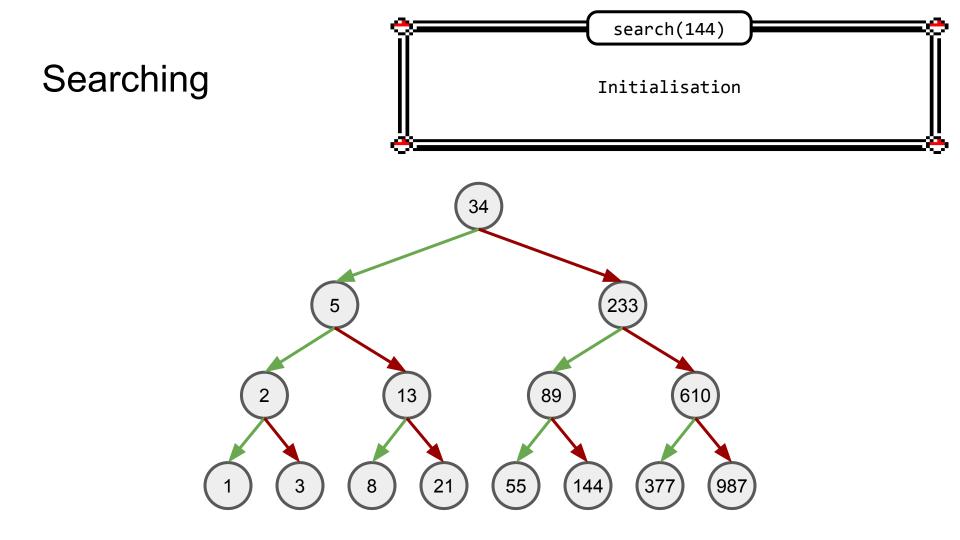
Operations in a BST

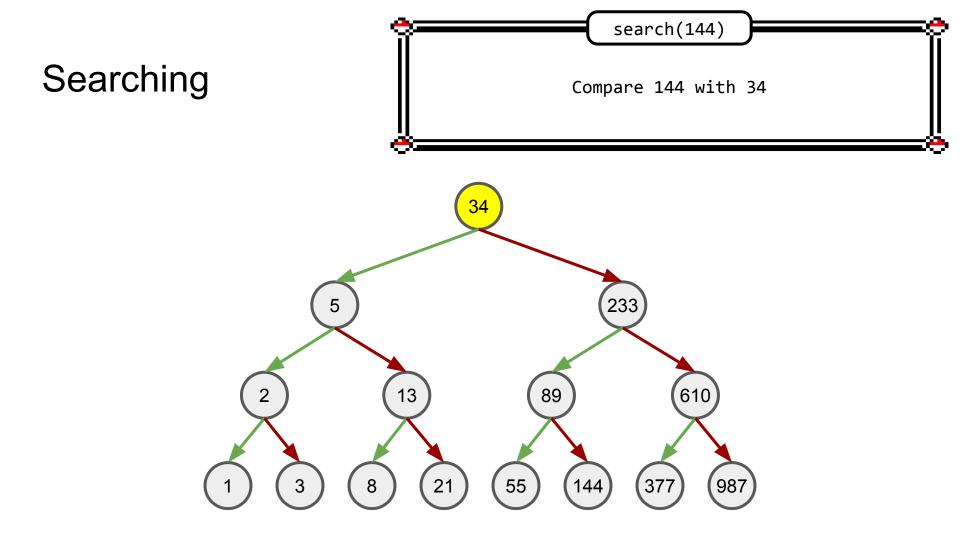
- Searching
- Insertion
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- Traversal

Searching

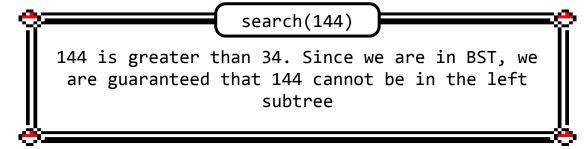
Idea:

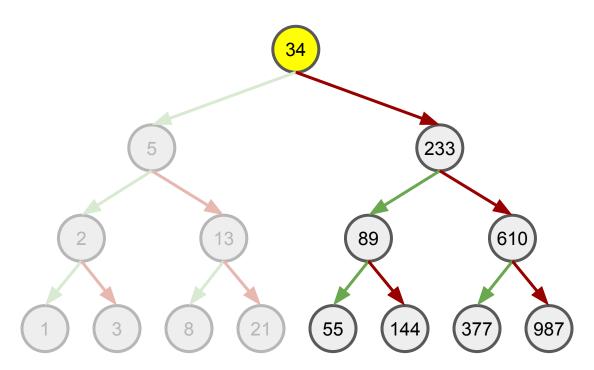
- Compare root vs element you are looking for
- If element == root, found!
- Else if element < root, recurse to the left subtree
- Else element > root, recurse to the right subtree

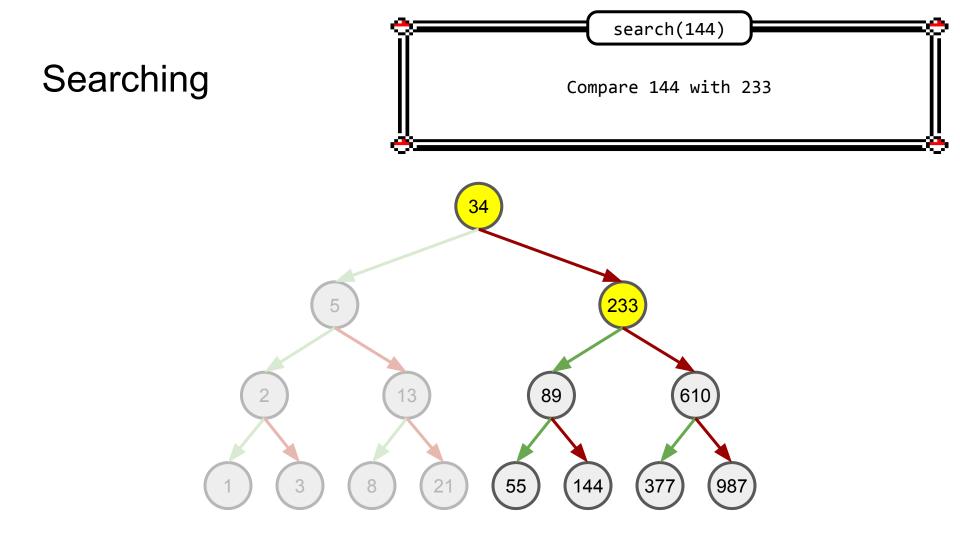


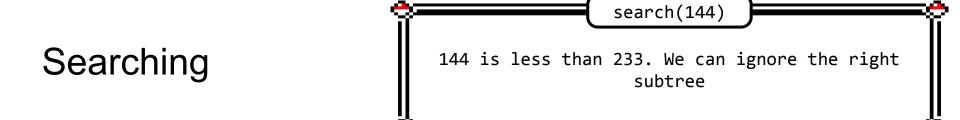


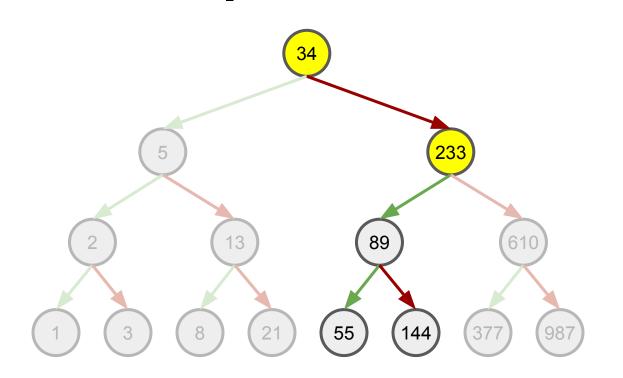


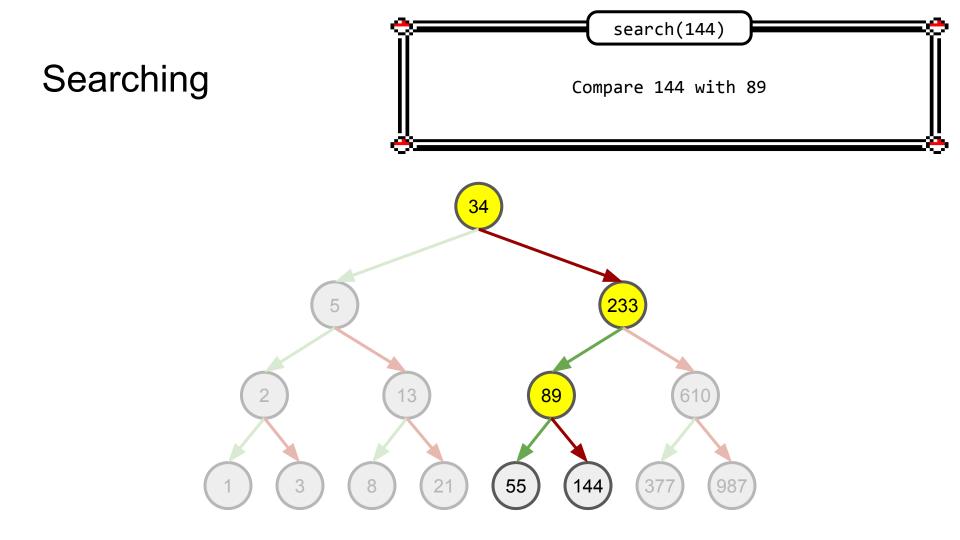




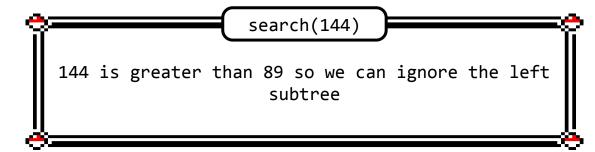


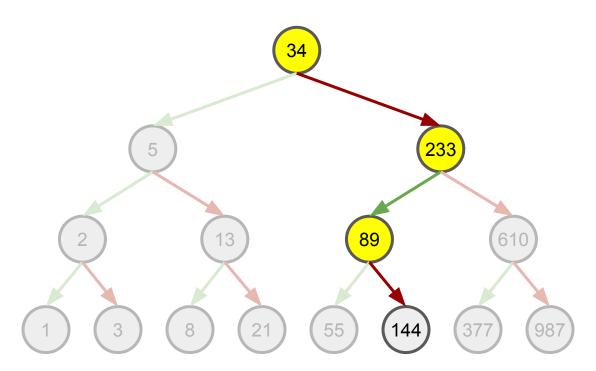


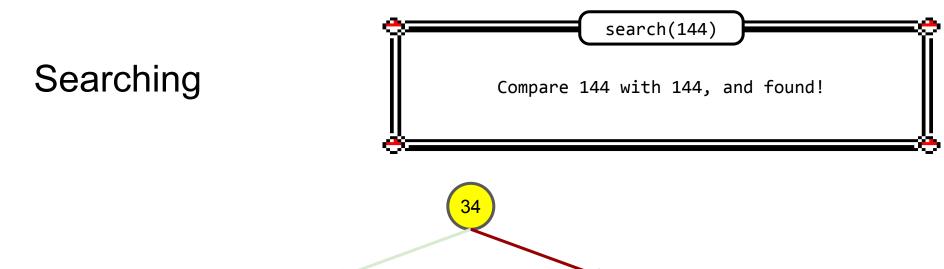


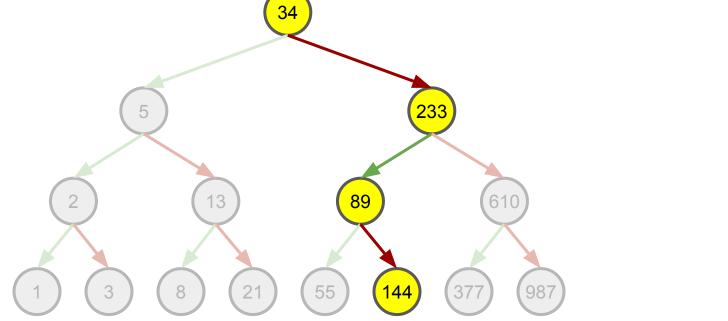








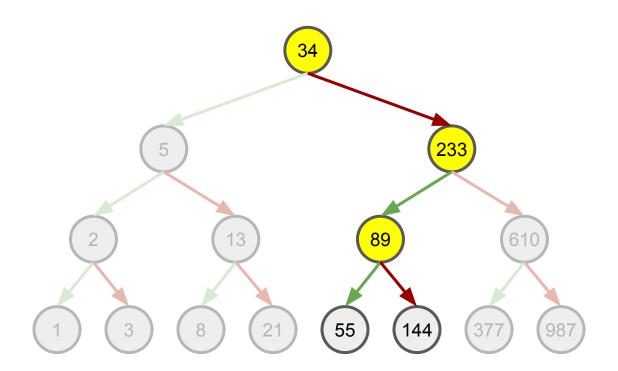




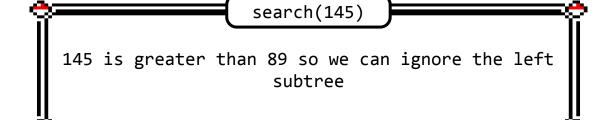


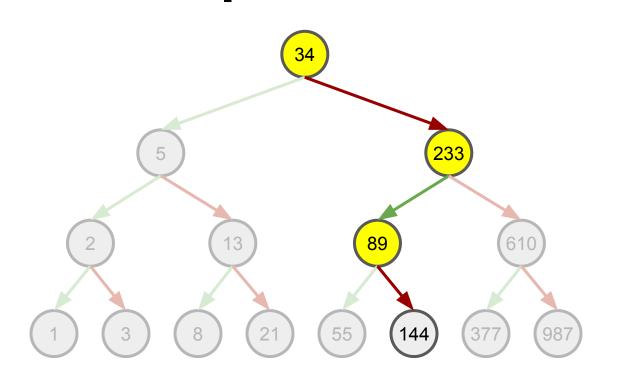
search(145)

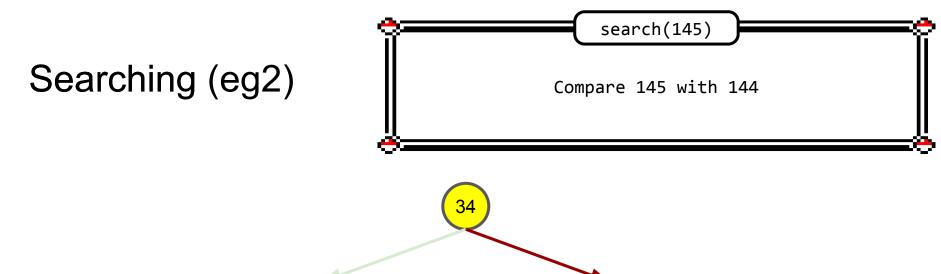
If for example we are searching for 145 instead of 144. Notice that everything is the same up to this point

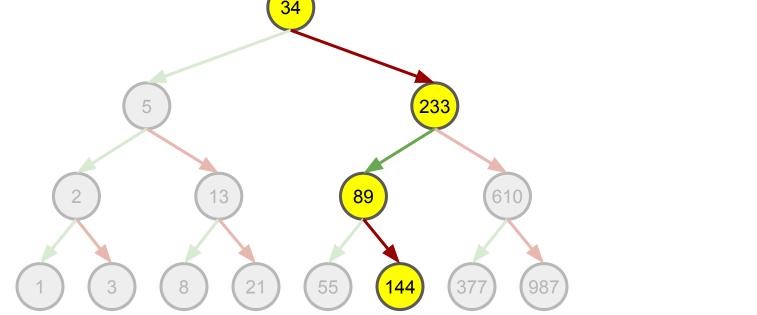




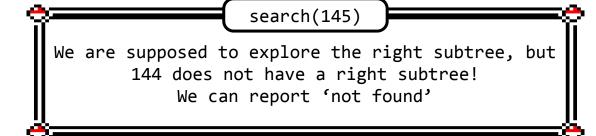


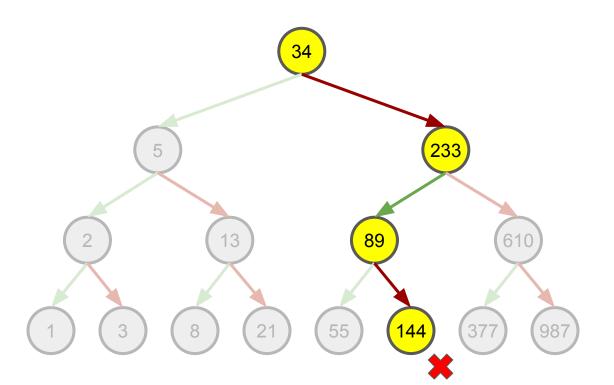


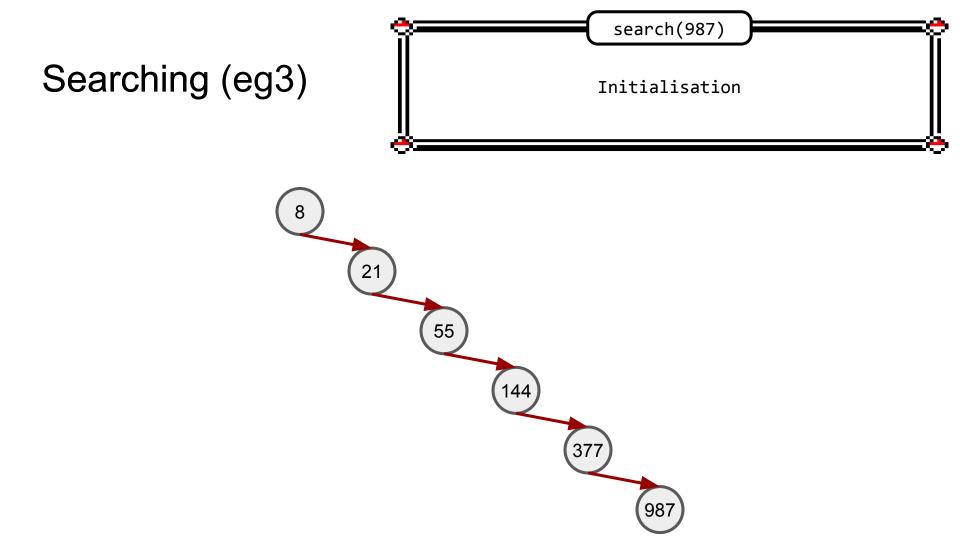


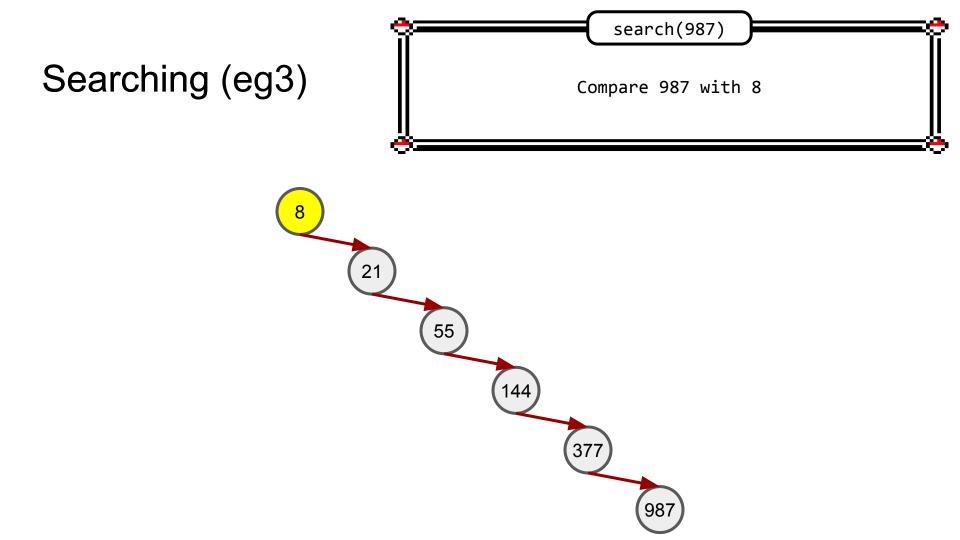


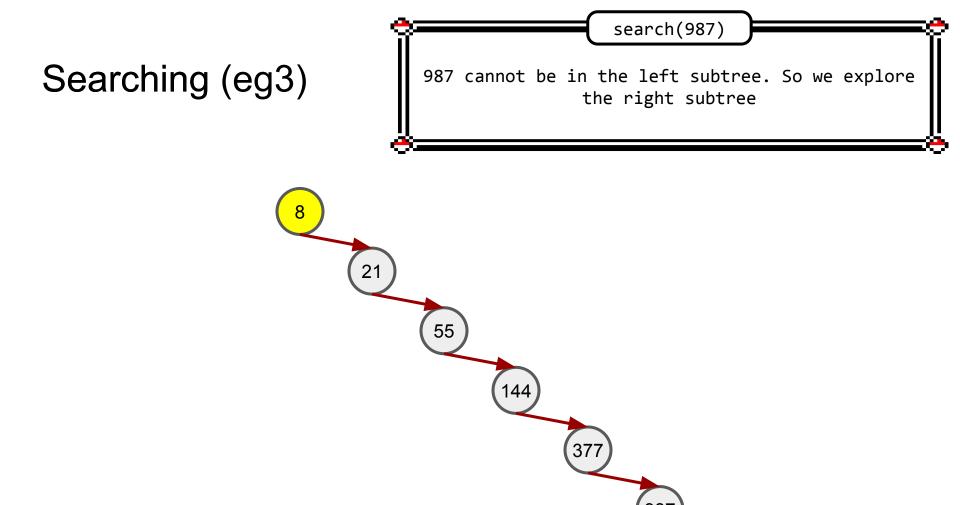


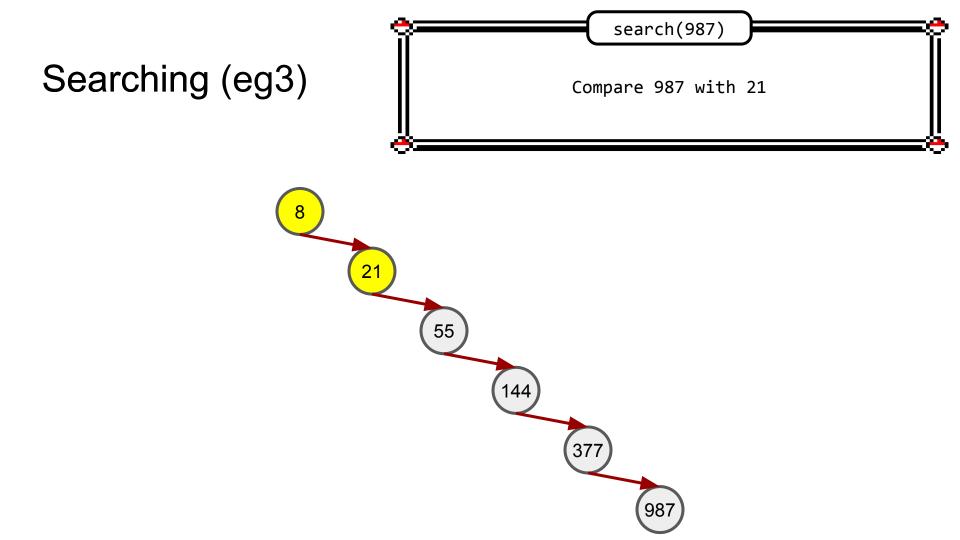


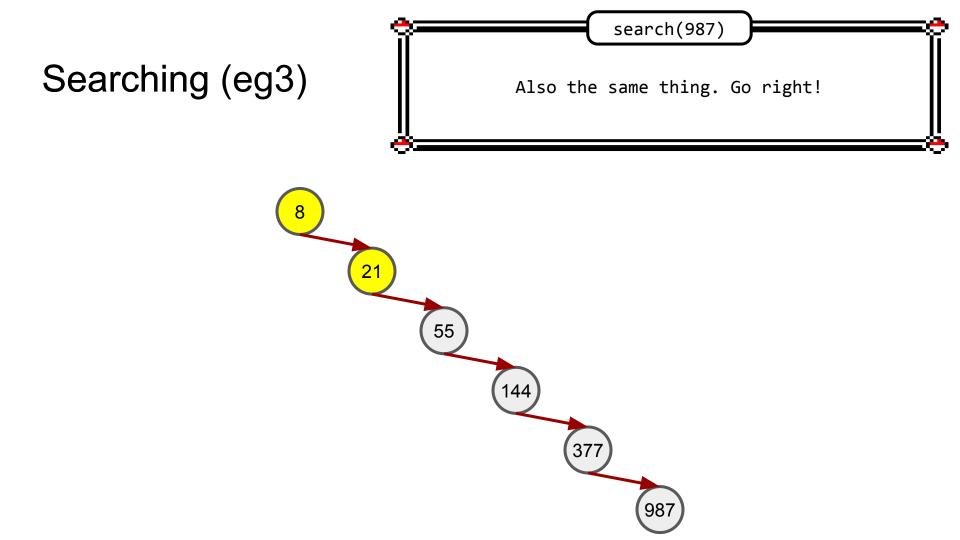


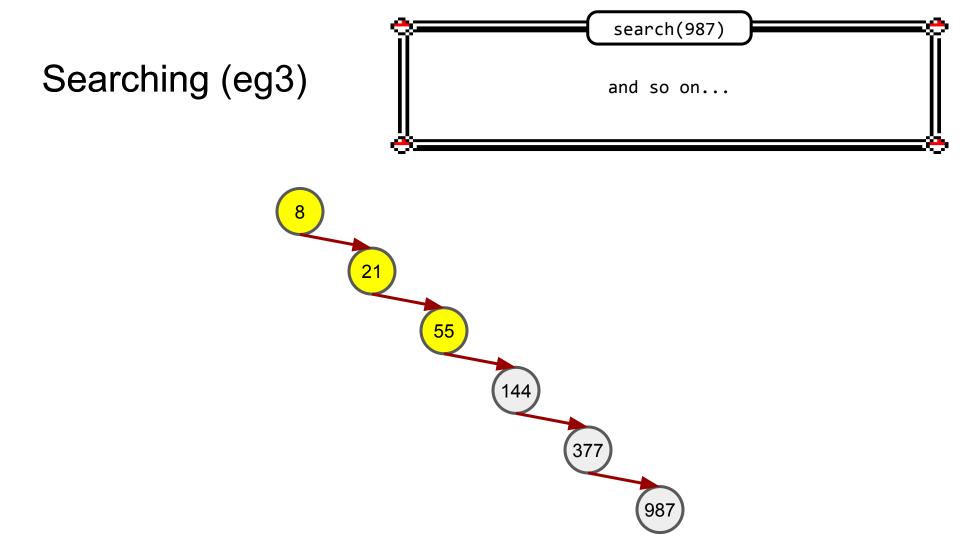


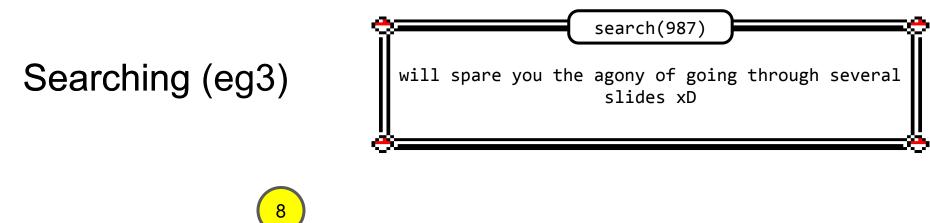


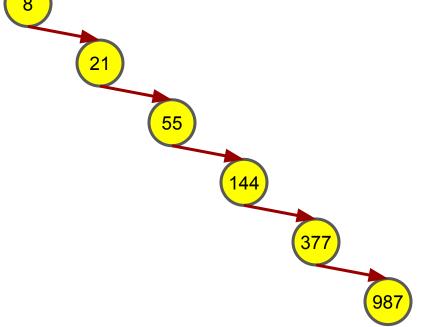




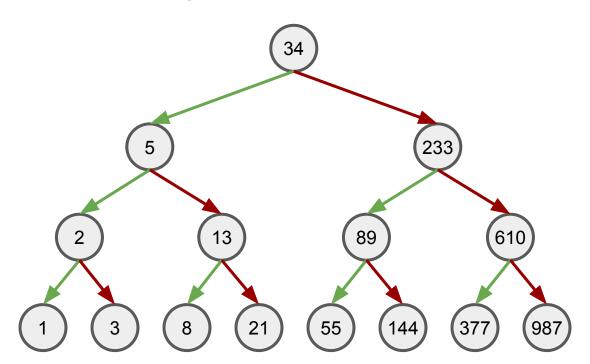




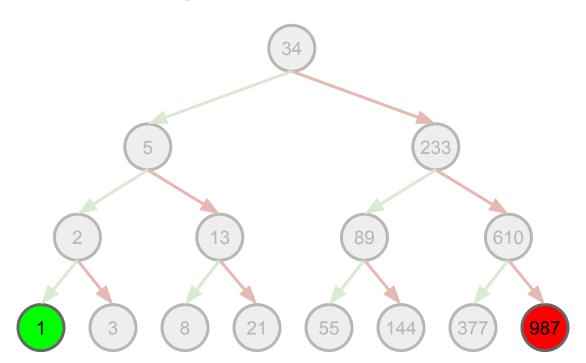




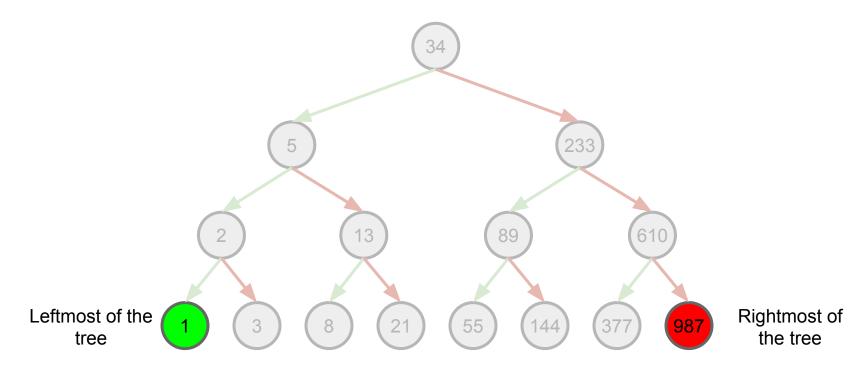
Where are the smallest and largest elements located in the tree?



Where are the smallest and largest elements located in the tree?



Where are the smallest and largest elements located in the tree?



The idea:

Just keep going down the left subtree (for min) or the right subtree (for max)
 'til you can't no more

Questions?

Successor and Predecessor

Successor and Predecessor

The successor of key x is basically the "next bigger key" in the tree

The predecessor of key x is basically the "previous smaller key" in the tree

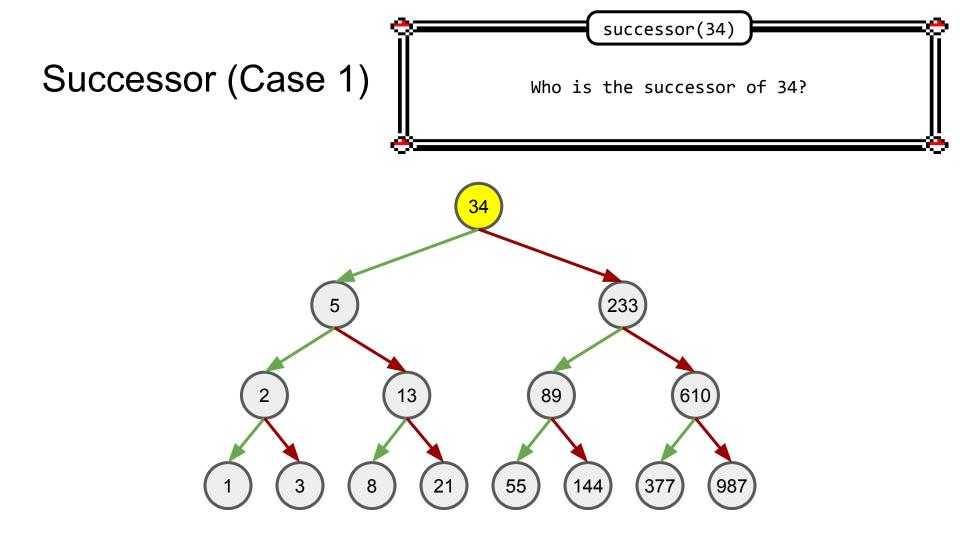
Successor and Predecessor

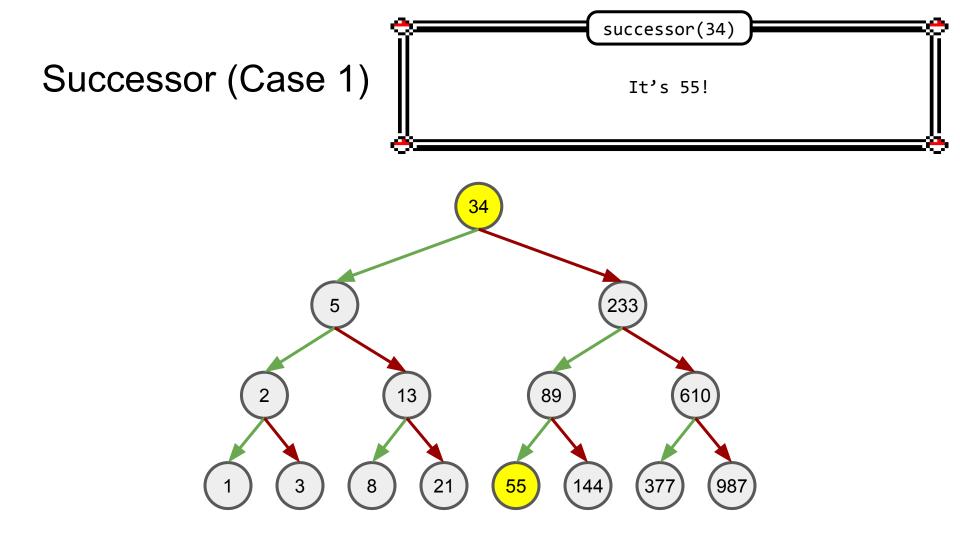
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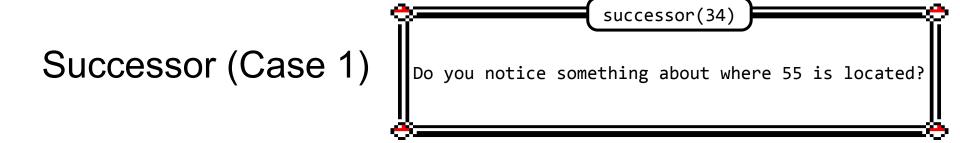
The predecessor of key x is basically the "previous smaller key" in the tree

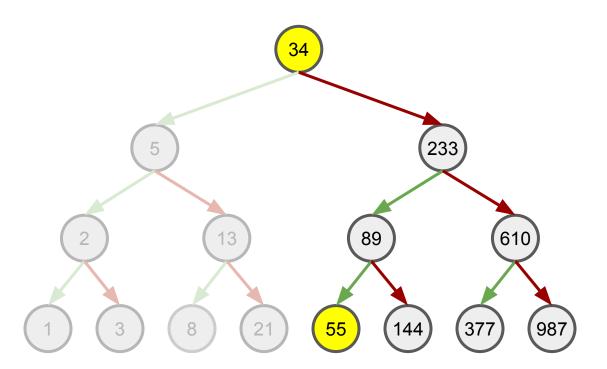
Another way to think about it: If you perform an in-order traversal ("write the keys in sorted order"), the successor is the next one in the sorted sequence and the predecessor is the previous one in the sorted sequence*

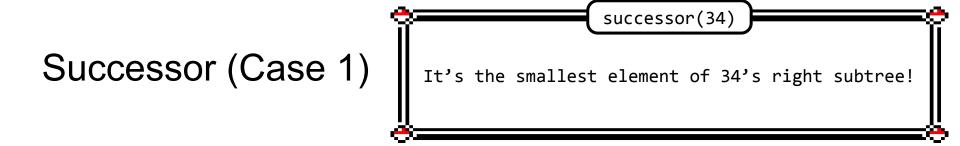
*If the key doesn't exist in the tree, pretend you have inserted it in the sorted order for visualisation

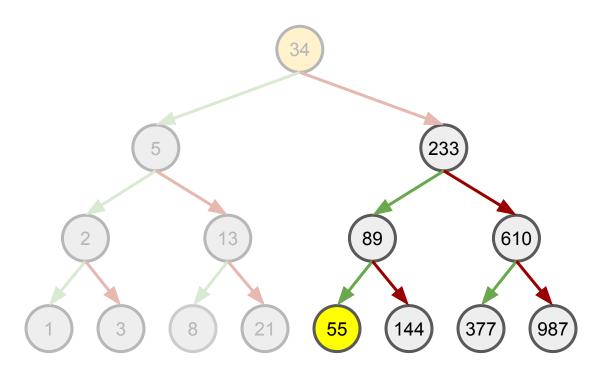








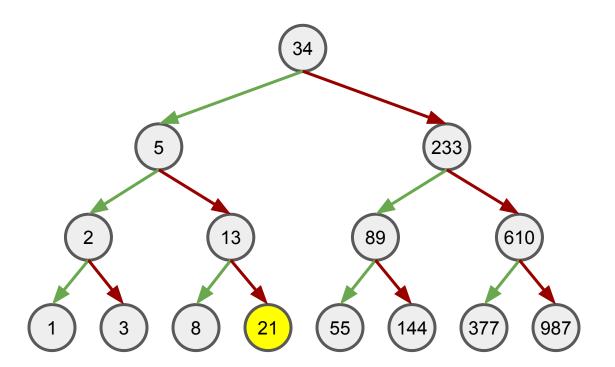


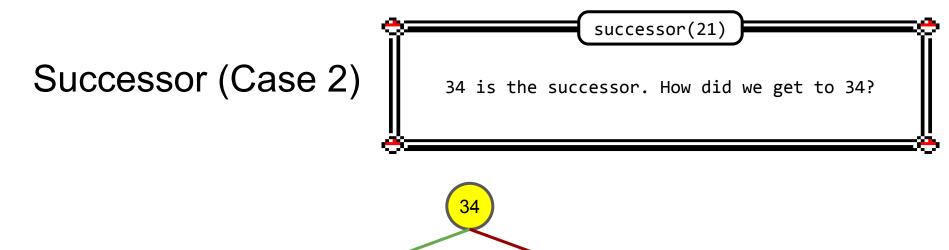


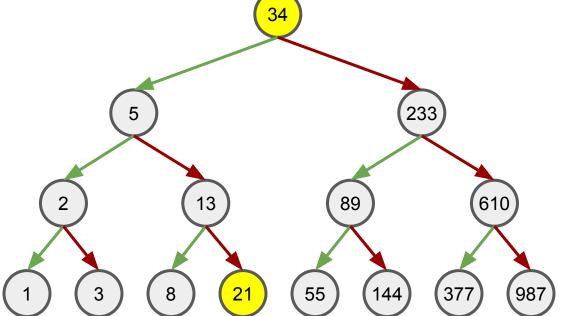


What if the node doesn't have a right subtree like this node with key 21 here?
First, what is this node's successor?

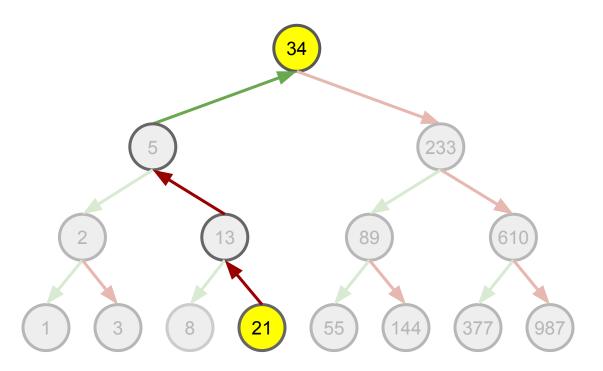
successor(21)

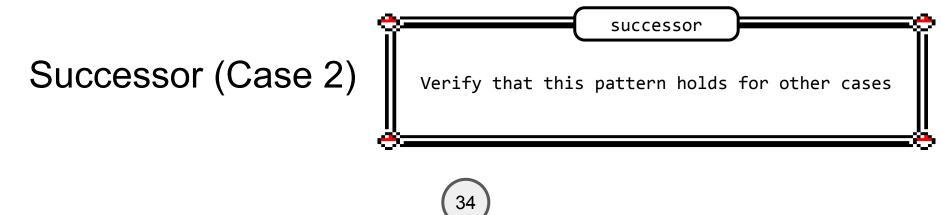


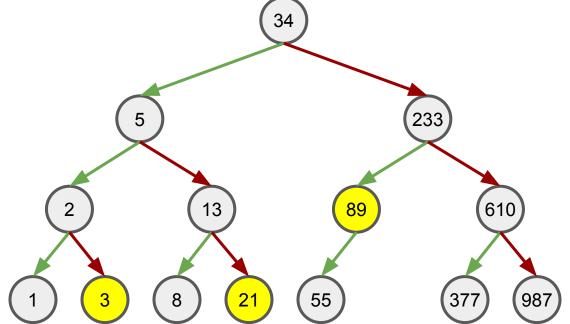












Questions?

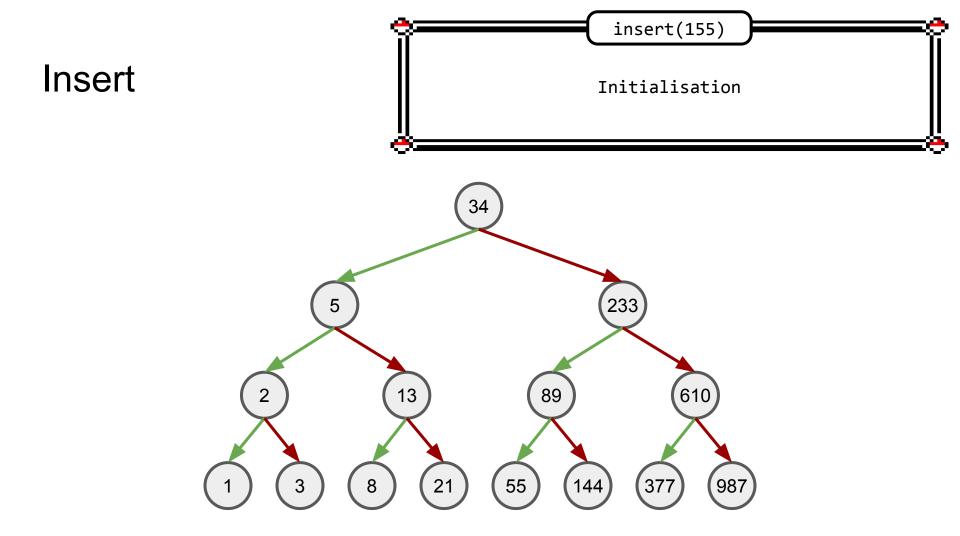
Insert

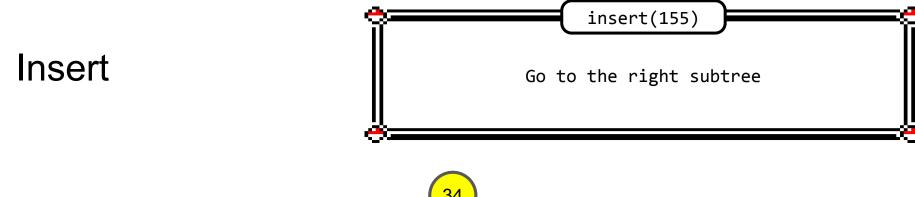
The idea:

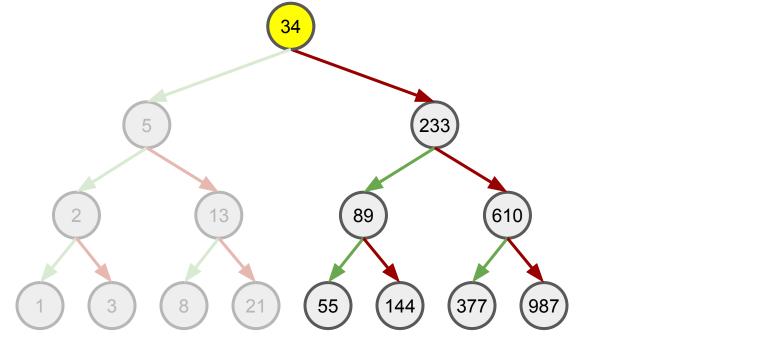
Insert

The idea:

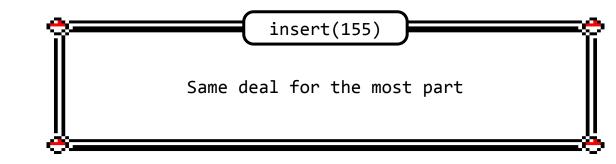
- Keep going as if you are "searching"
- Once you cannot go on anymore (because you need to go to the right/left subtree but the right/left subtree is empty), you have found the position to insert

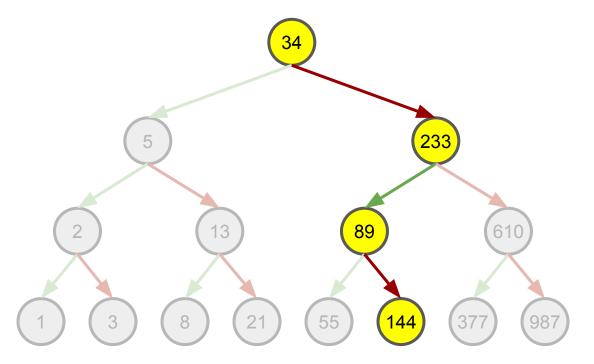




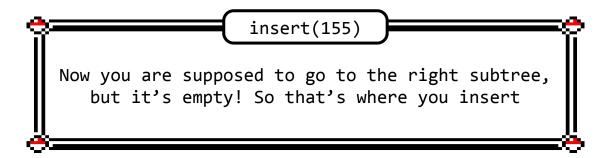


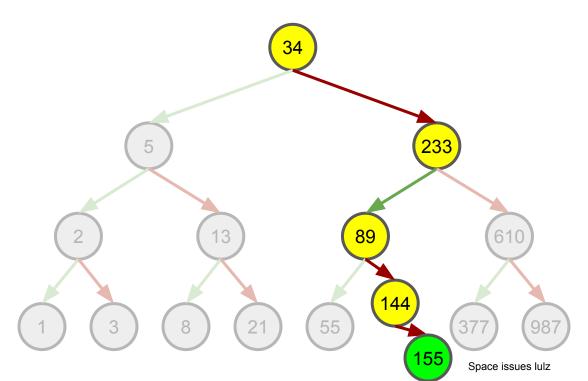












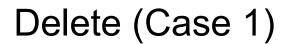
Questions?

Deletion

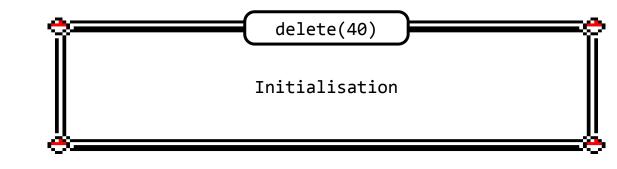
A data structure is not interesting if we cannot remove anything from it! We need to be able to perform deletions:

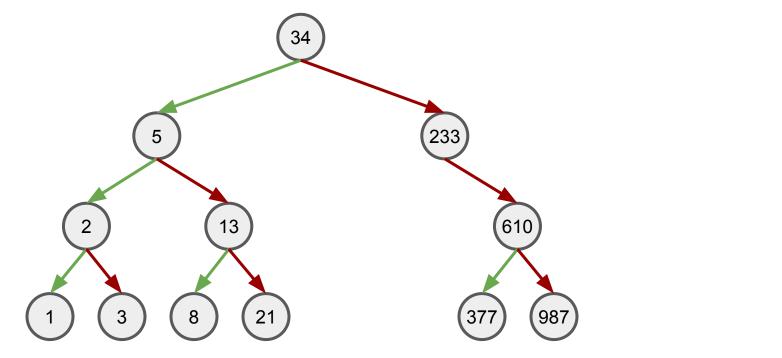
There are multiple cases for deletion with respect to the target node to delete:

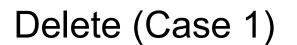
- Node is not found
- Node is at leaf
- Node is an internal node with 1 child
- Node is an internal node with 2 children



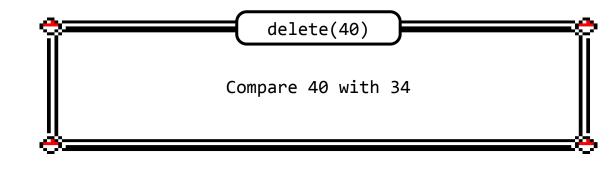
[Node not found]

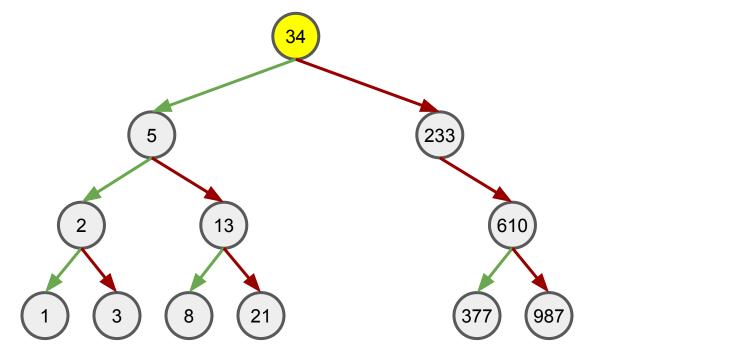






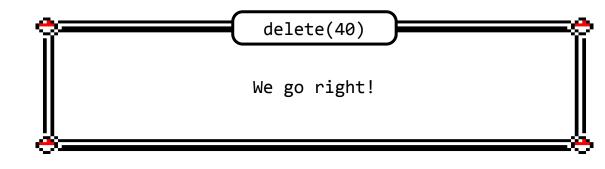
[Node not found]

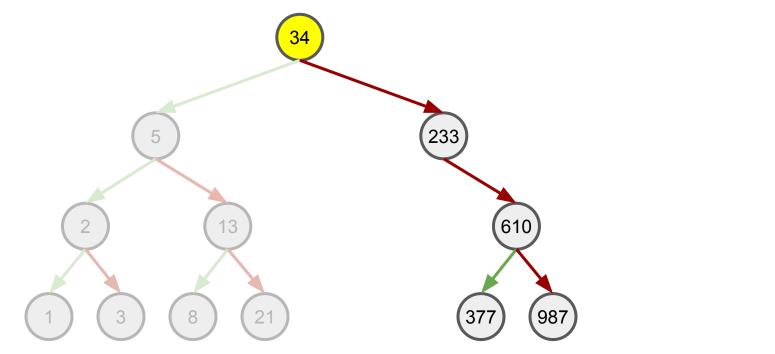




Delete (Case 1)

[Node not found]



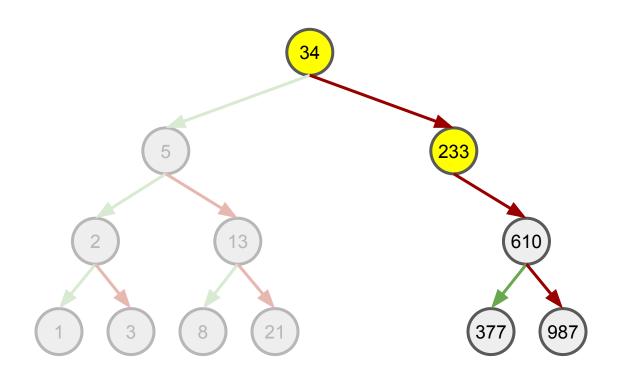


Delete (Case 1)

[Node not found]

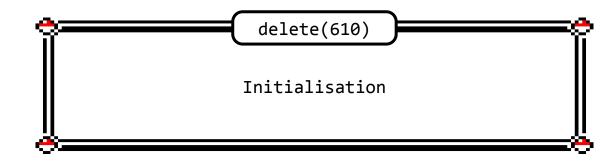
delete(40)

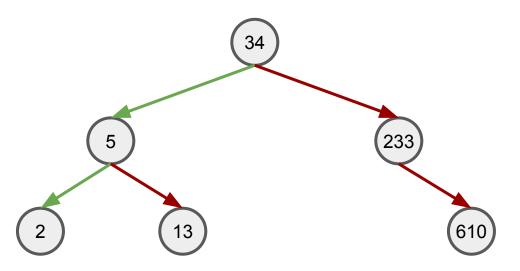
40 is less than 233. But the left subtree is empty so it must mean that 40 does not exist. Do nothing!



Delete (Case 2)

[Node is at a leaf]

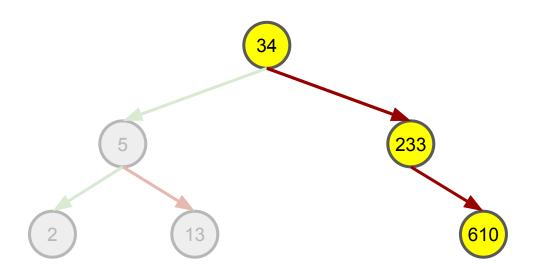




Delete (Case 2)

[Node is at a leaf]

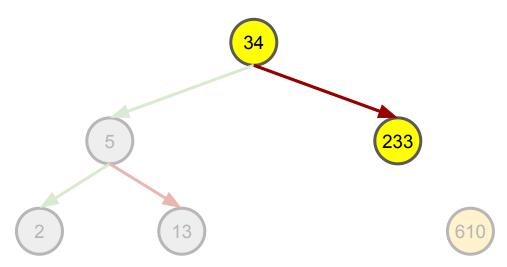
I'll skip the "searching" step :P
Let's say we have traversed all the way to the
right and found the node. wat do now



Delete (Case 2)

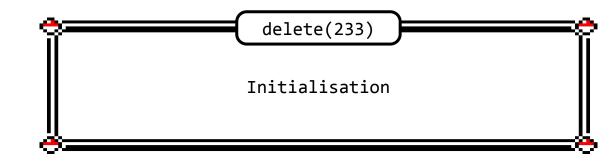
[Node is at a leaf]

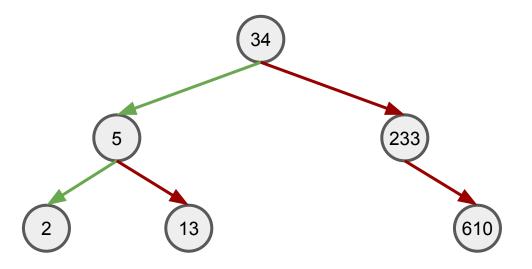




Delete (Case 3)

[Node has 1 child]



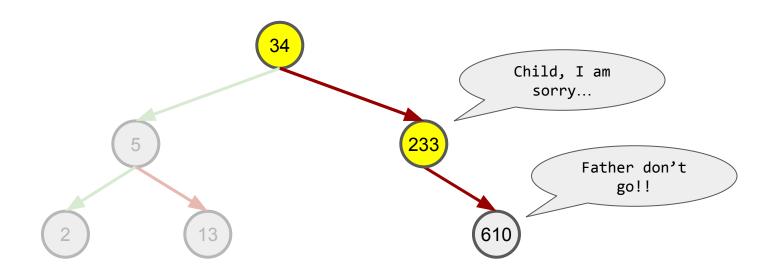


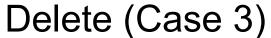
Delete (Case 3)

[Node has 1 child]

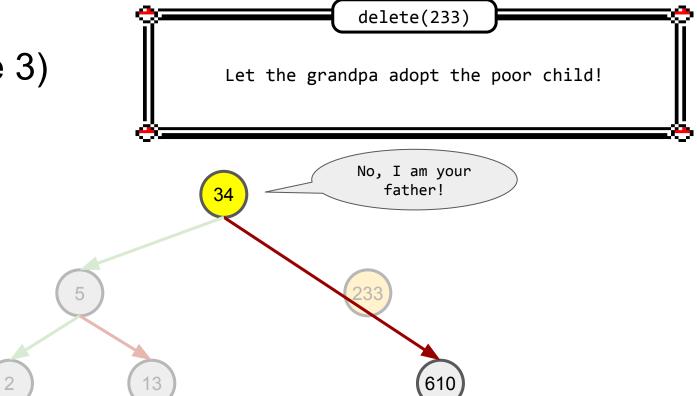
Gonna skip the "searching" again. Now if you directly remove this node, there will be orphans :0 wat to do

delete(233)

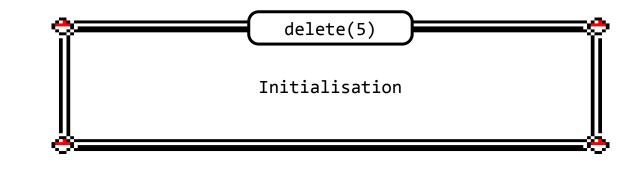


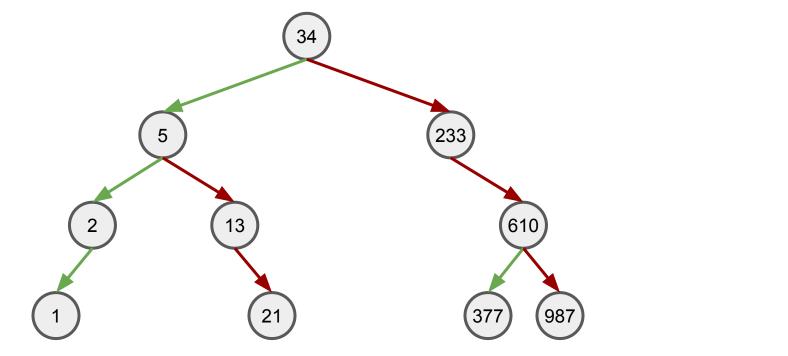


[Node has 1 child]





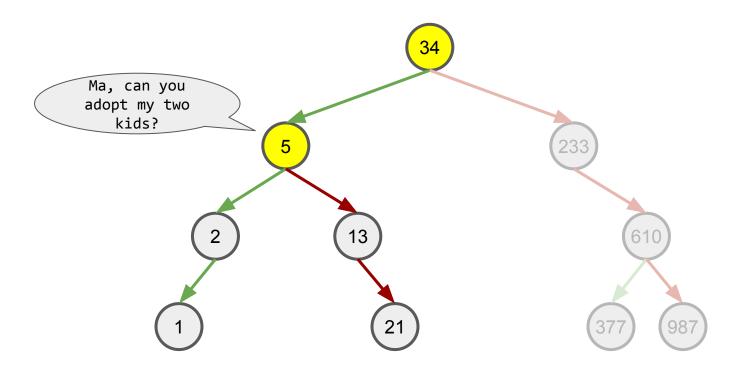


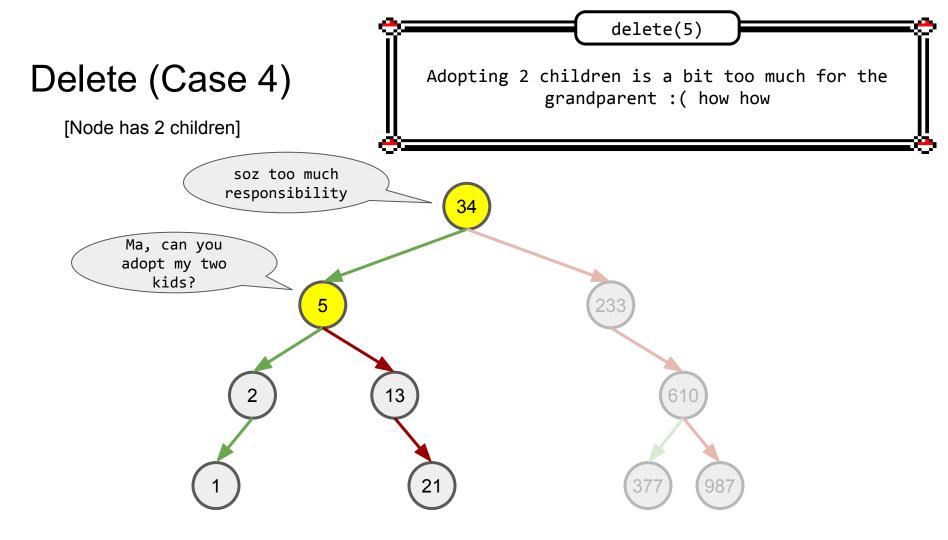


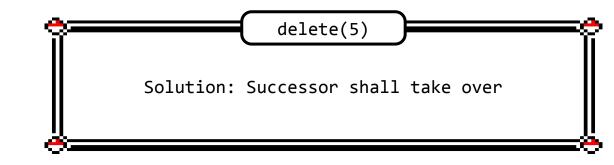
[Node has 2 children]

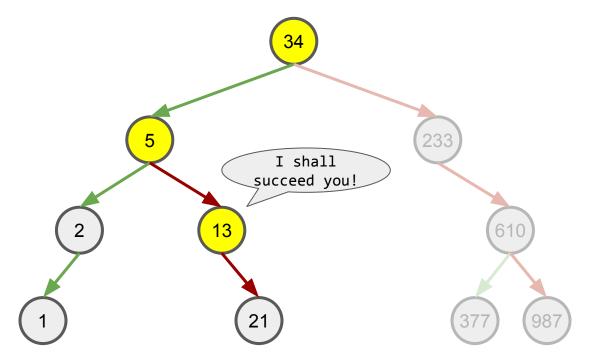
Skipping the search visualisation again... If we were to delete this node directly, there will be 2 orphans!

delete(5)





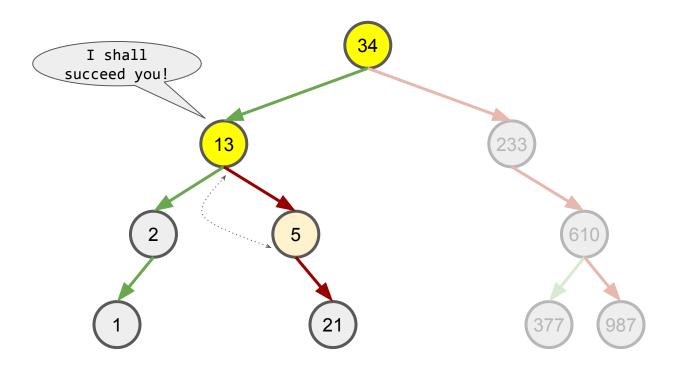


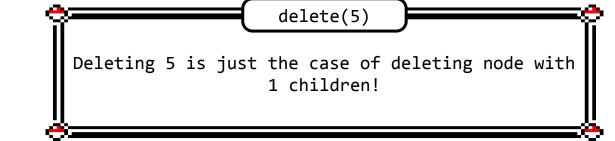


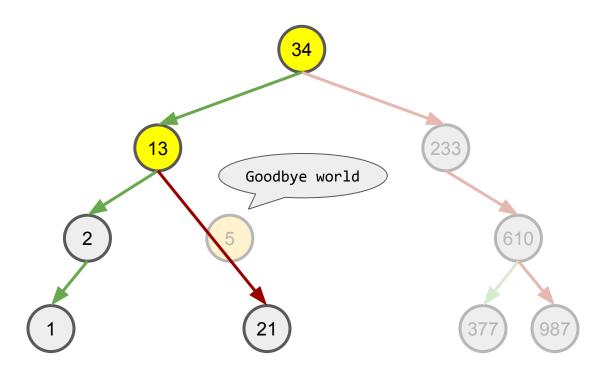
[Node has 2 children]

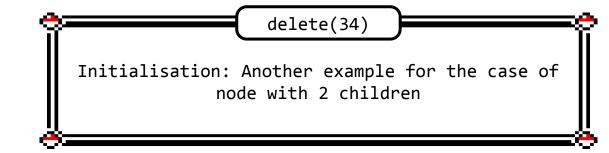
(Note that currently the BST property is violated.

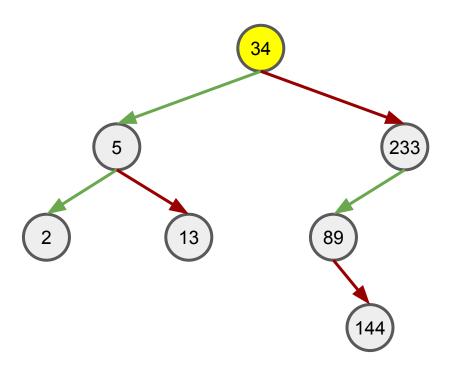
We shall fix it soon but how :0)

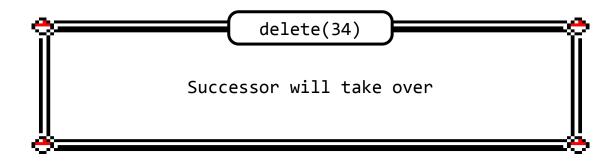


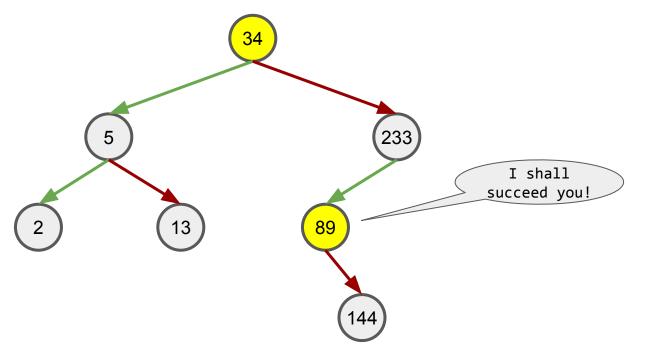


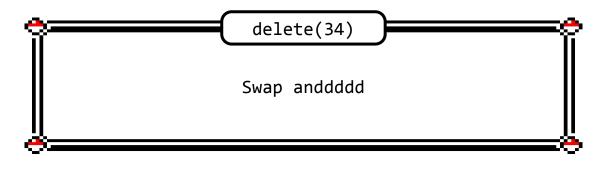


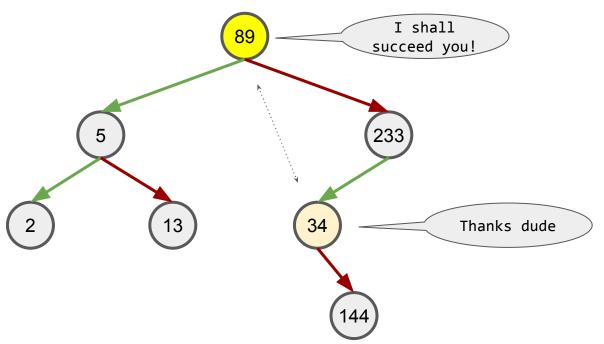


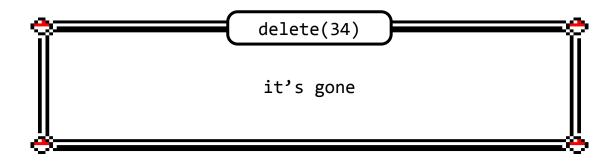


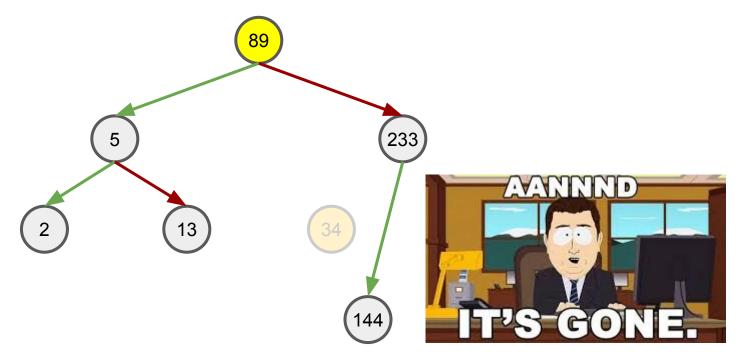












Deletion: Why does replacing with successor work?

We need to maintain the following:

Deletion: Why does replacing with successor work?

We need to maintain the following:

- 1. BST property is not violated when we swap
- 2. Successor has at most 1 child (why?)

Deletion: Why does replacing with successor work?

We need to maintain the following:

- 1. BST property is not violated when we swap
- 2. Successor has at most 1 child (because if 1 child, can just let grandparent adopt the child. If no child, can simply delete)

Questions?

Traversals

Different types of traversal:

- preorder:
- inorder:
- postorder:

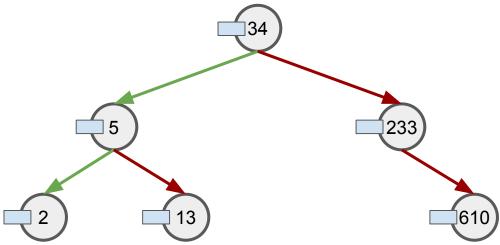
Traversals

Different types of traversal:

- preorder: print(root) traverse(left) traverse(right)
- inorder: traverse(left) print(root) traverse(right)
- postorder: traverse(left) traverse(right) print(root)

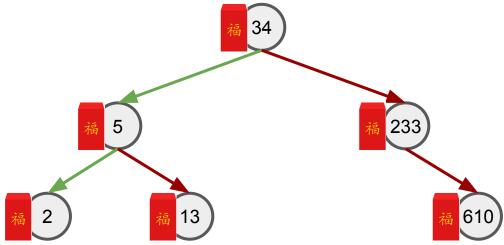
Pre-order Traversal

Lifehack: Put these "markers" at the left (pre)



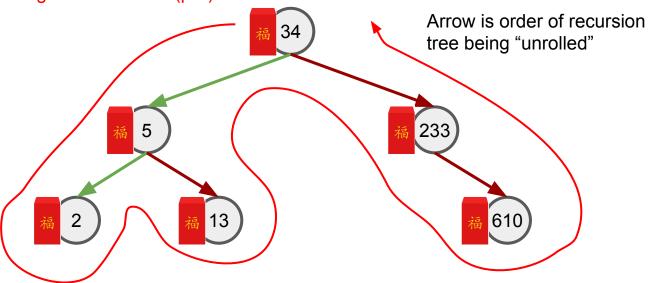
Pre-order Traversal

Lifehack: Put these hongbaos at the left (pre)



Pre-order Traversal

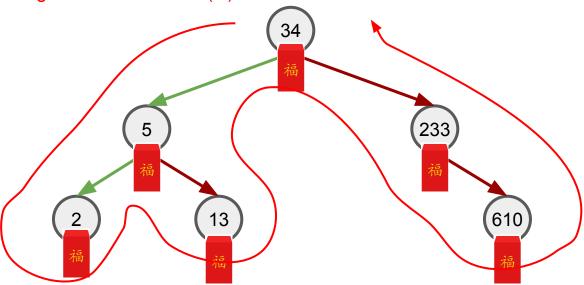
Lifehack: Put these hongbaos at the left (pre)



Order of hongbao collection: 34 5 2 13 233 610

In-order Traversal

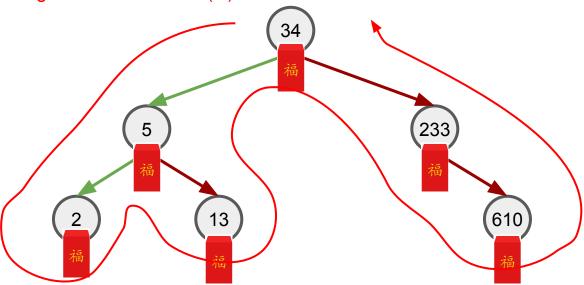
Lifehack: Put these hongbaos at the bottom (in)



Order of hongbao collection: ???

In-order Traversal

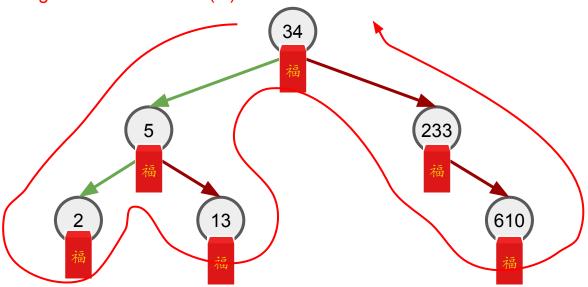
Lifehack: Put these hongbaos at the bottom (in)



Order of hongbao collection: 2 5 13 34 233 610

In-order Traversal

Lifehack: Put these hongbaos at the bottom (in)

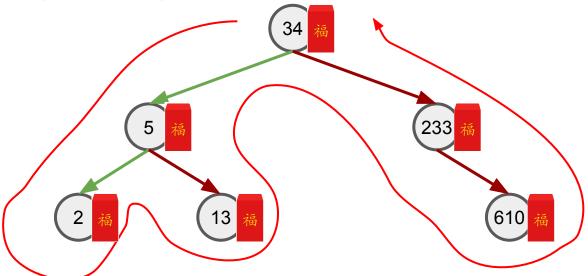


Order of hongbao collection: 2 5 13 34 233 610

Cool stuff: if your tree is BST, the inorder traversal appears in sorted order!

Post-order Traversal

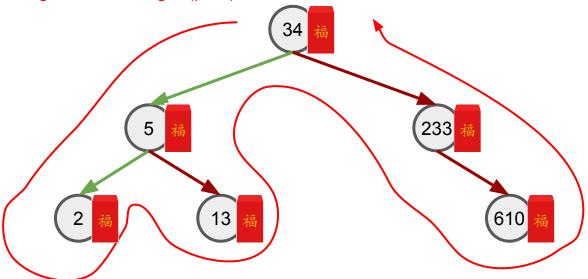
Lifehack: Put these hongbaos at the right (post)



Order of hongbao collection: ???

Post-order Traversal

Lifehack: Put these hongbaos at the right (post)



Order of hongbao collection: 2 13 5 610 233 34

Time to traverse?

Time to traverse?

- Intuitively, you are going through the entire tree.
- Therefore it is O(n) time

Time-complexity of BST operations

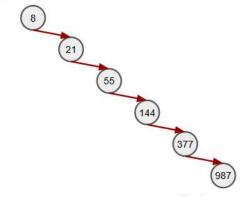
Time-complexity of BST operations

- Most of these operations are O(h) time where h is the height of the BST
- NOT necessarily *O*(*logn*) time where *n* is the number of elements in the tree

WHO WOULD WIN?

Computer Scientists who have worked hard to create a data structure that supports O(logn) search, insert, delete, successor, predecessor queries

ONE CHAINY BOI



Enter the AVL trees!

Enter the AVL trees!

- Named after Adelson-Velsky and Landis (two people not three)
- Idea: Since the time-complexities of most operations in BST are O(h), let's find a way to bound h by logn!

 This is the concept of height-balanced trees. AVL tree is not the only way we can achieve this. Other trees such as Red-Black trees, B-Trees, Splay Trees exist.

How to AVL tree

- Every node contains the variable for height
 - o height = max(left.height, right.height) + 1

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 - o height = max(left.height, right.height) + 1
- Invariant for height-balancing: For every node, the height of their children differ by at most 1.

How to AVL tree

- Every node contains the variable for height
 - o height = max(left.height, right.height) + 1
- Invariant for height-balancing: For every node, the height of their children differ by at most 1.
- If this particular invariant is broken, then the tree is not an AVL-tree anymore

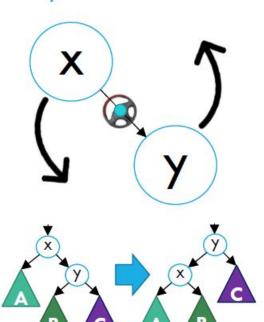
Rotations

Rotations

- How we achieve balance!
- Different kinds: left rotate, right rotate, left-left rotate, right-right rotate
- IMPORTANT: Has to preserve the BST properties!

HOW I REMEMBER IT

left / anti-clockwise



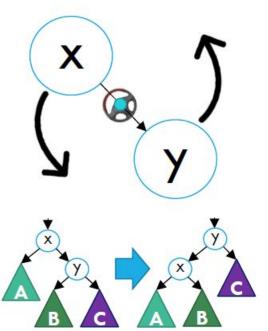






HOW I REMEMBER IT

left / anti-clockwise



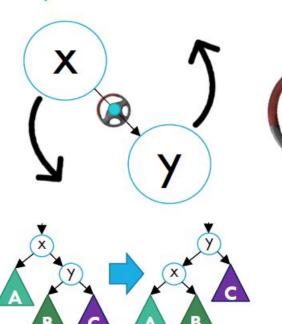






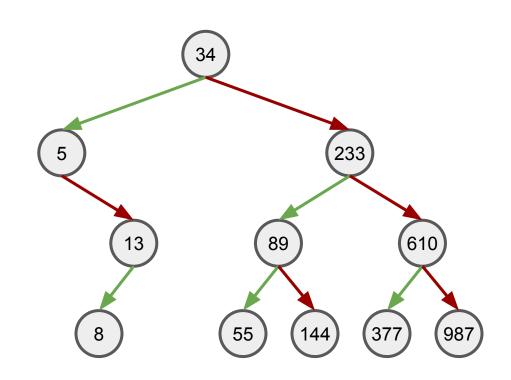
HOW I REMEMBER IT

left / anti-clockwise

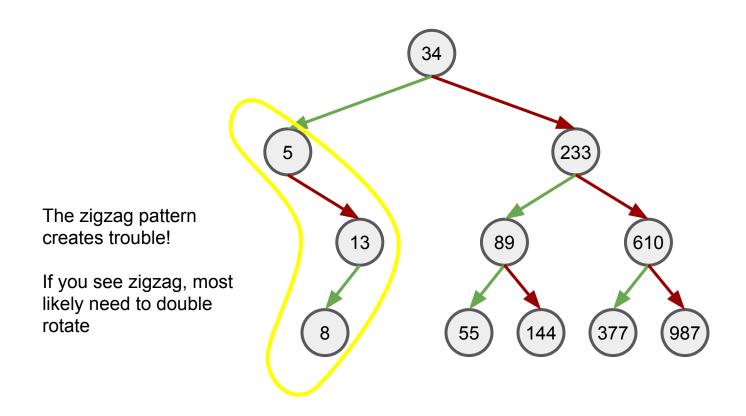




Imbalanced?? How should we rotate this?

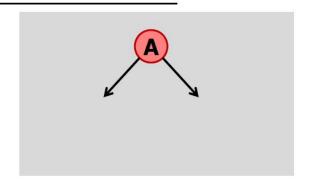


Imbalanced?? How should we rotate this?



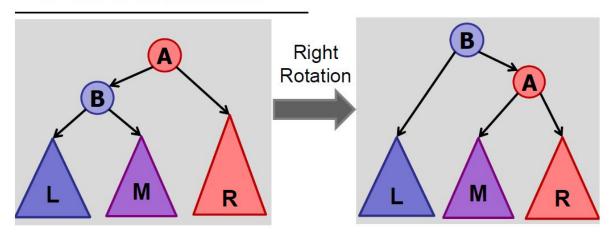
Rotations

```
right-rotate(v)
                       // assume v has left != null
    w = v.left
    w.parent = v.parent
    v.parent = w
    v.left = w.right
                                        W
    w.right = v
```



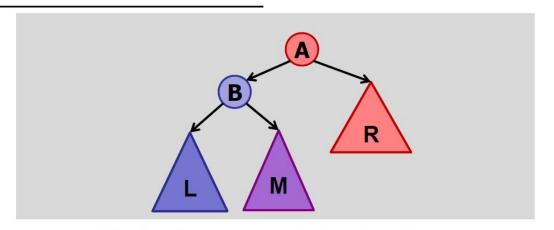
A is **LEFT-heavy** if left sub-tree has larger height than right sub-tree.

A is **RIGHT-heavy** if right sub-tree has larger height than left sub-tree.



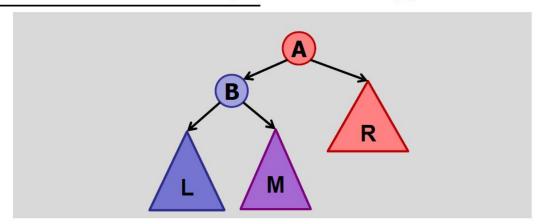
Use tree rotations to restore balance.

After insert, start at bottom, work your way up.



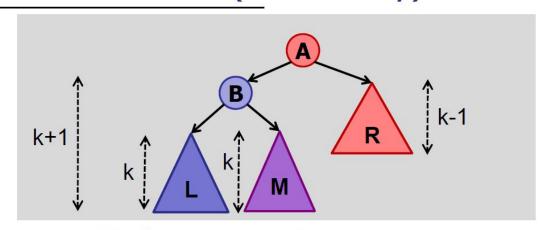
Assume **A** is the lowest node in the tree violating balance property.

Assume A is **LEFT-heavy**.



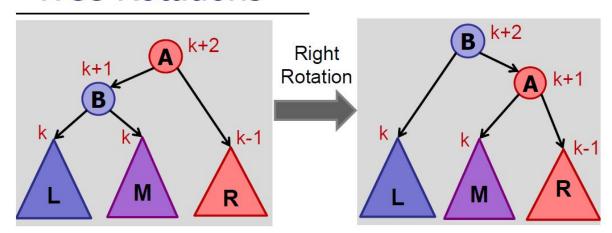
Case 1: **B** is balanced :
$$h(L) = h(M)$$

 $h(R) = h(B) - 2$



Case 1: **B** is balanced :
$$h(L) = h(M)$$

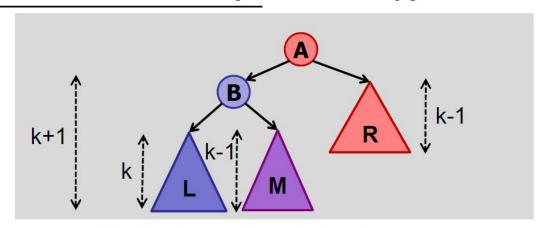
 $h(R) = h(M) - 1$



right-rotate:

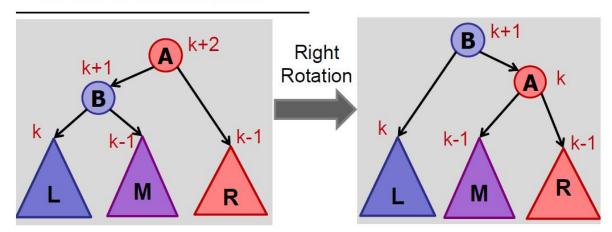
Case 1: **B** is balanced :
$$h(L) = h(M)$$

 $h(R) = h(M) - 1$



Case 2: **B** is left-heavy :
$$h(L) = h(M) + 1$$

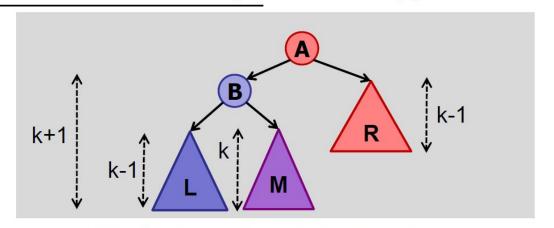
 $h(R) = h(M)$



right-rotate:

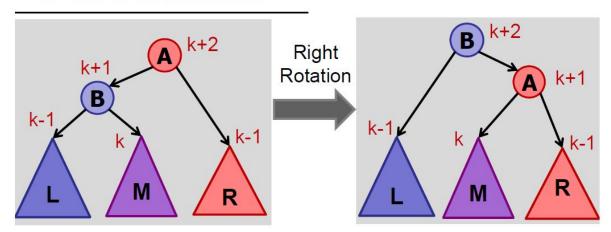
Case 2: **B** is left-heavy:
$$h(\mathbf{L}) = h(\mathbf{M}) + 1$$

 $h(\mathbf{R}) = h(\mathbf{M})$



Case 3: **B** is right-heavy :
$$h(L) = h(M) - 1$$

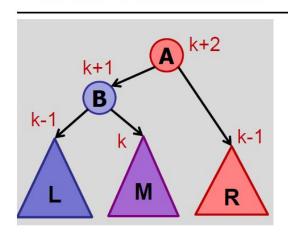
 $h(R) = h(L)$



right-rotate:

Case 3: **B** is right-heavy:
$$h(L) = h(M) - 1$$

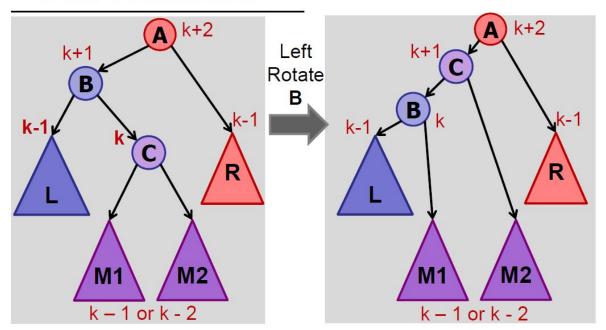
 $h(R) = h(L)$



Let's do something first before we right-rotate(A)

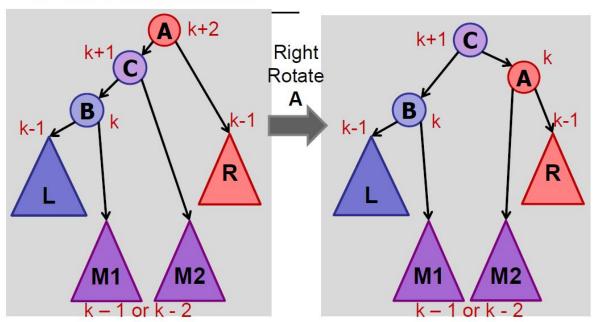
right-rotate:

Case 3: **B** is right-heavy: $h(\mathbf{L}) = h(\mathbf{M}) - 1$ $h(\mathbf{R}) = h(\mathbf{L})$



Left-rotate B

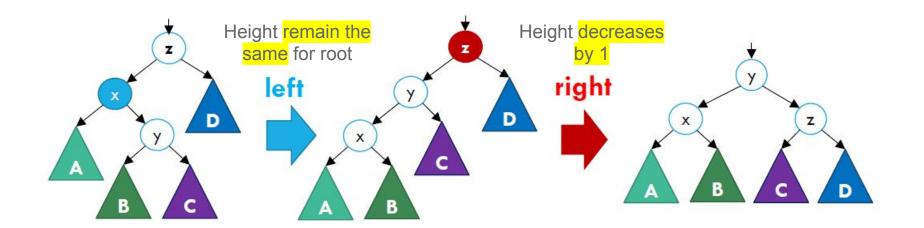
After left-rotate B: A and C still out of balance.

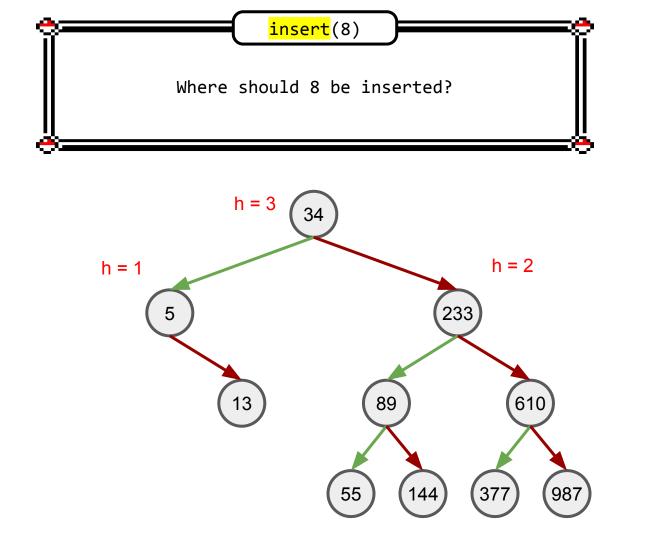


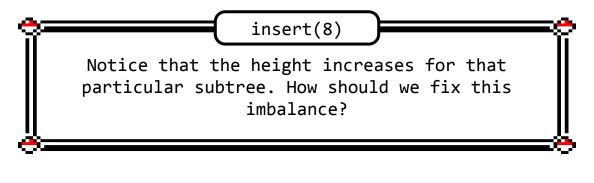
After right-rotate A: all in balance.

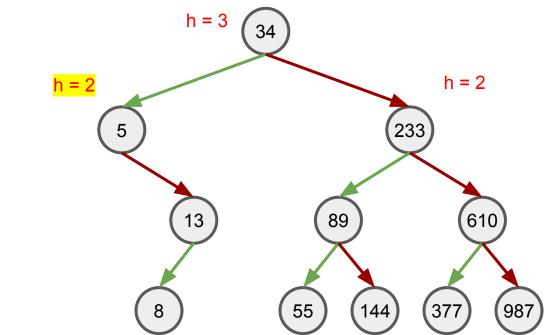
How is height affected after *rotation*?

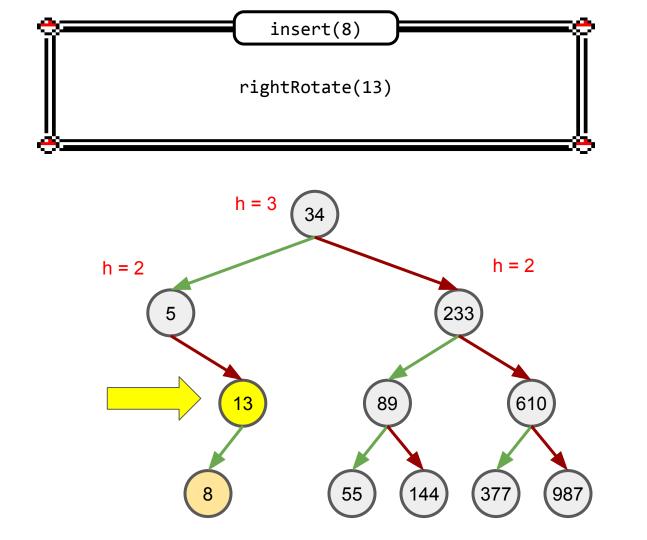
- The goal of rotation is to fix height imbalances!
- Height should either decrease by 1 or remain the same (peek double rotation)

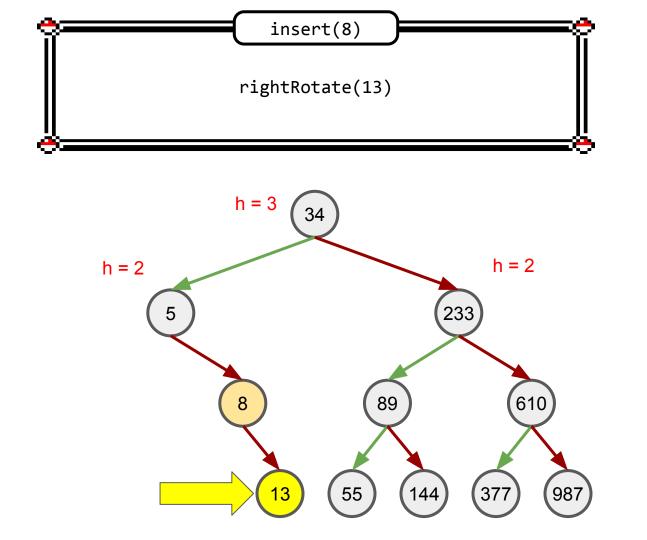


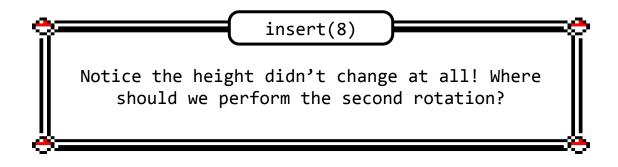


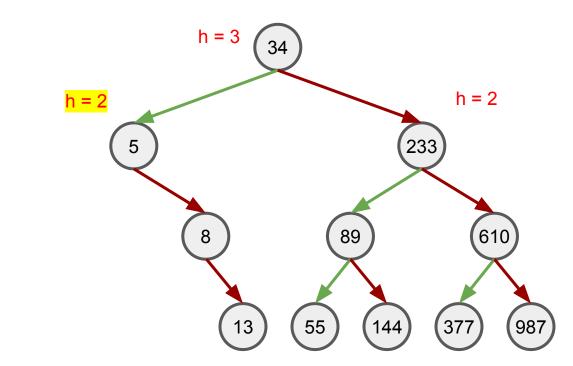


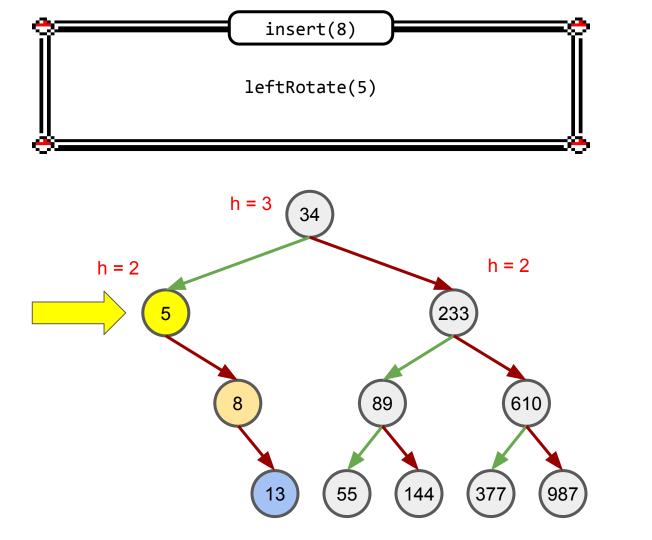


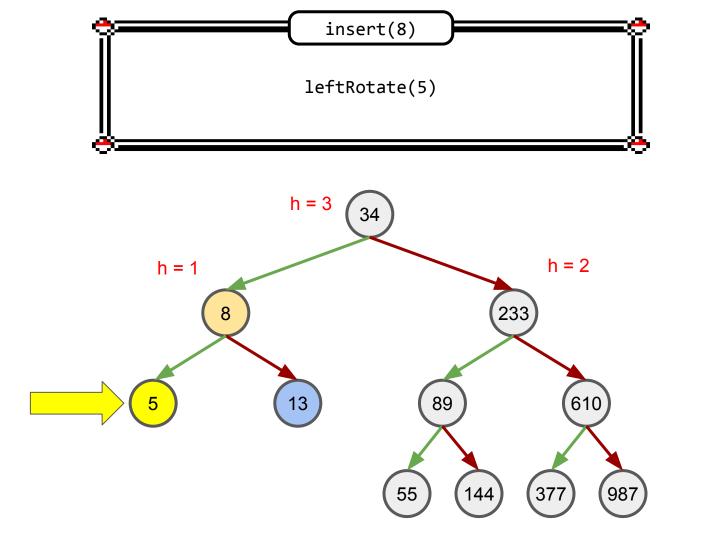


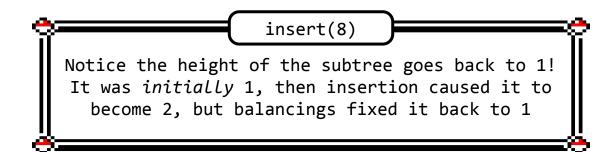


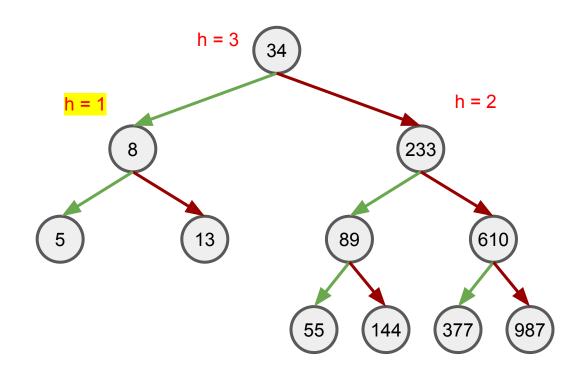


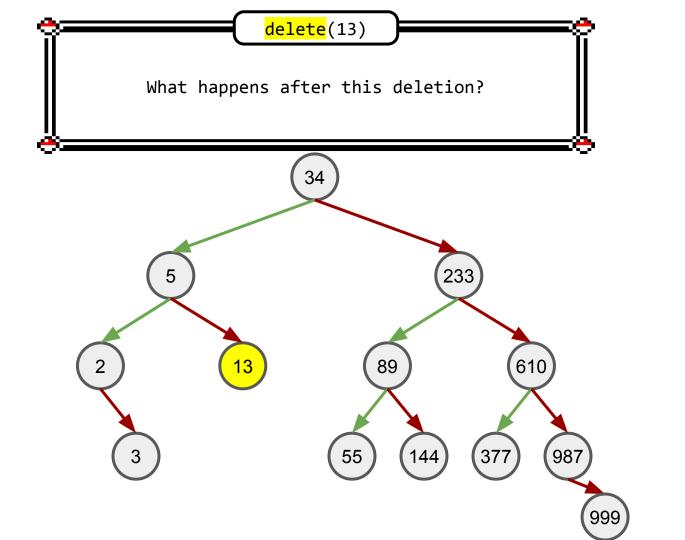


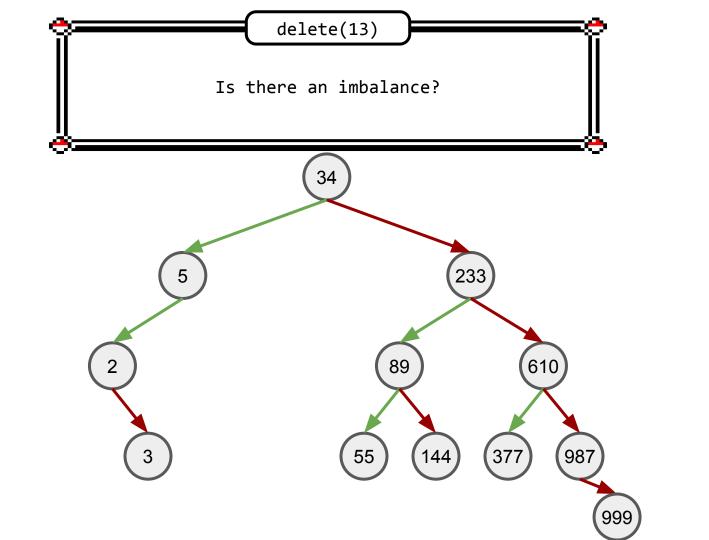


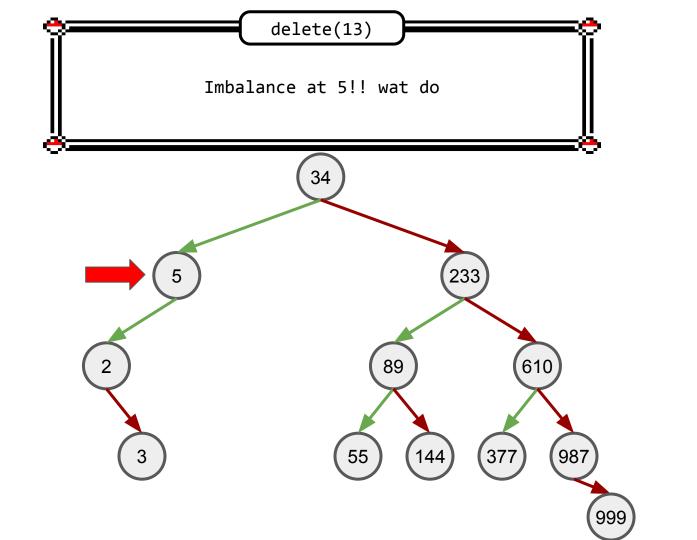


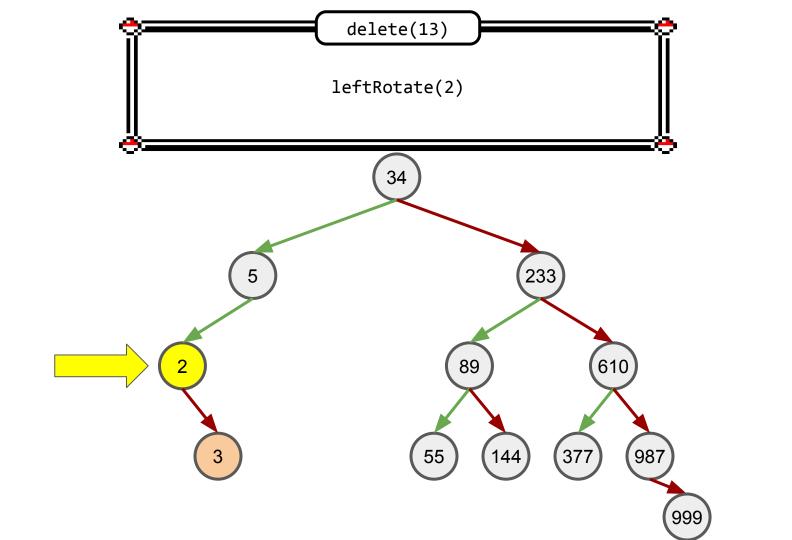


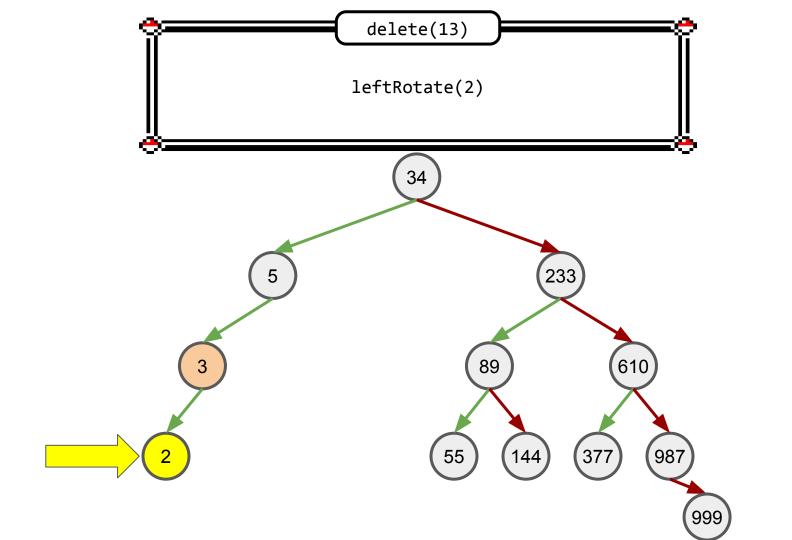


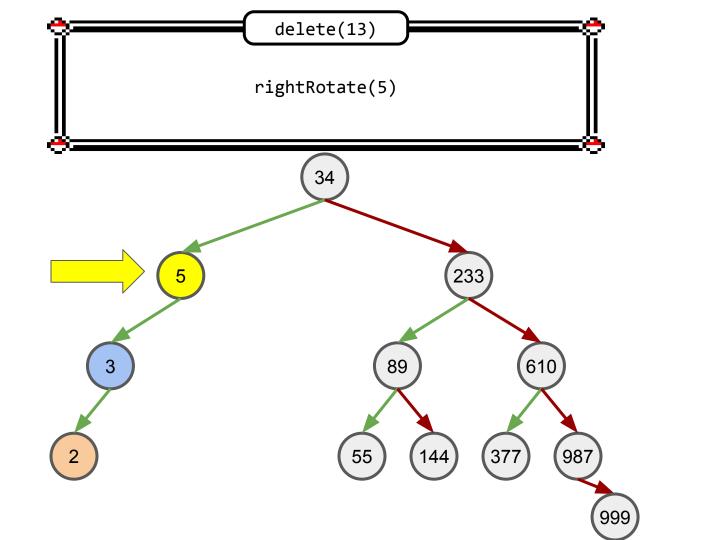


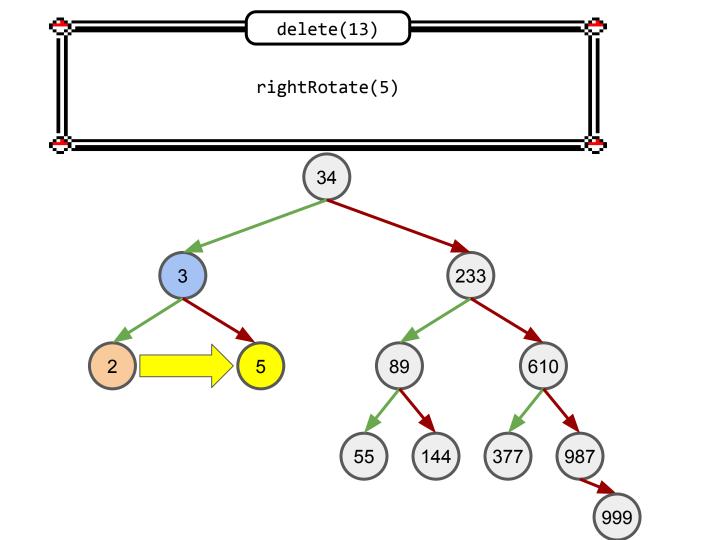


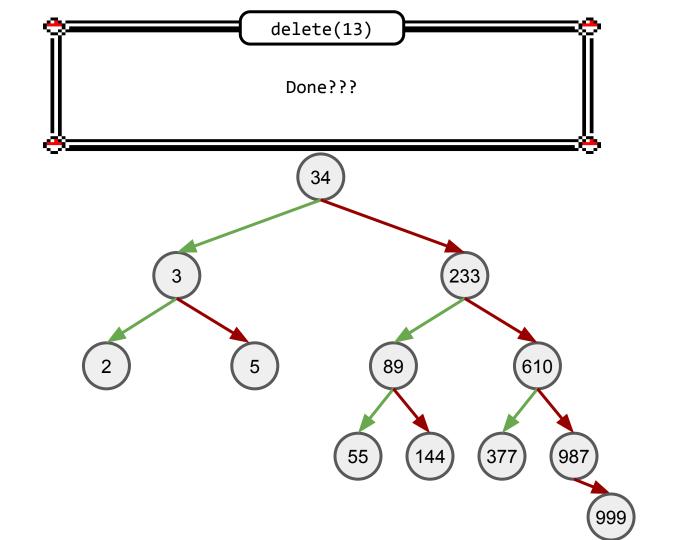


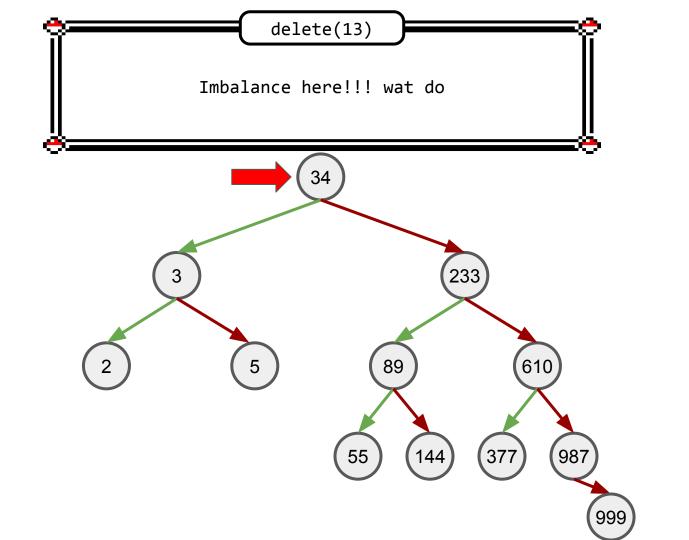


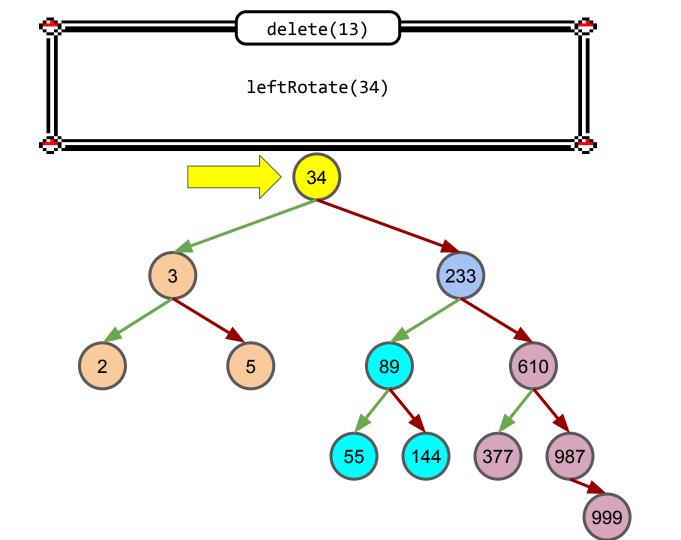


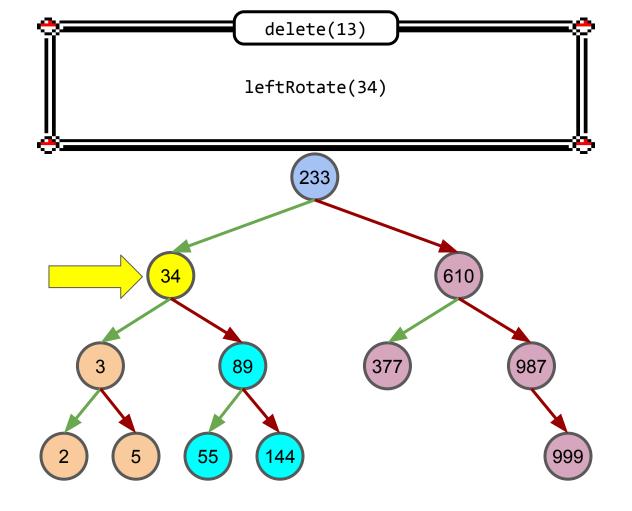












Rotations

Summary:

If v is out of balance and left heavy:

- 1. v.left is balanced: right-rotate(v)
- 2. v.left is left-heavy: right-rotate(v)
- 3. v.left is right-heavy: left-rotate(v.left) right-rotate(v)

If v is out of balance and right heavy: Symmetric three cases....

Number of rotations

- For insert:
- For delete:

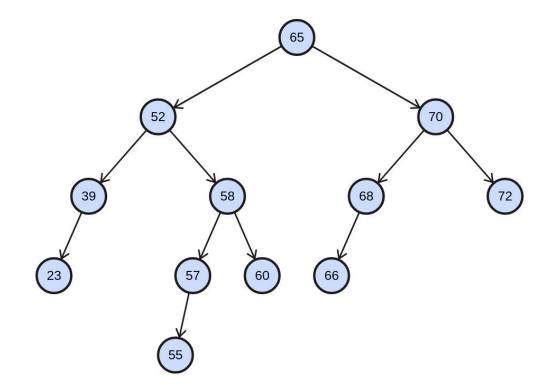
Number of rotations

- For insert: at most 2
- For delete: O(logn), because you may have to rotate all the way up to the root

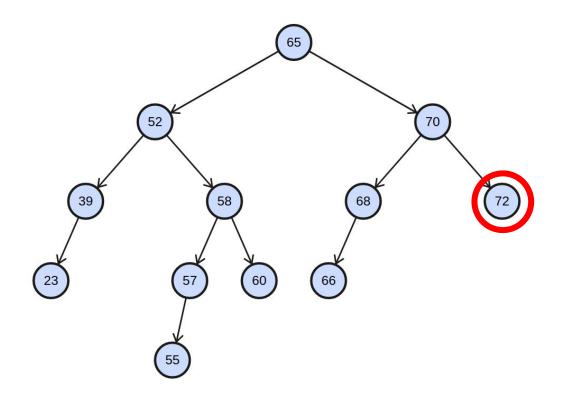
Tutorial Time

Slides for tutorials are taken and adapted from lan

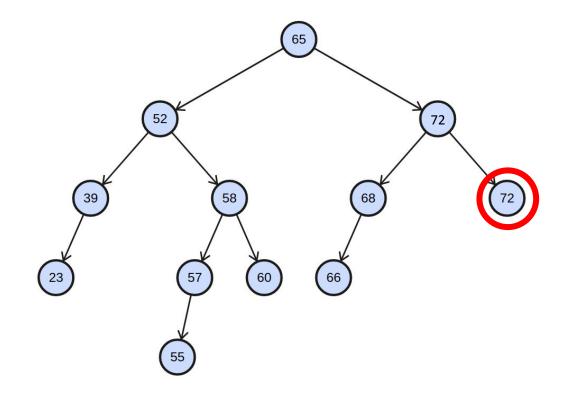
Trace the deletion of the node with the key 70.



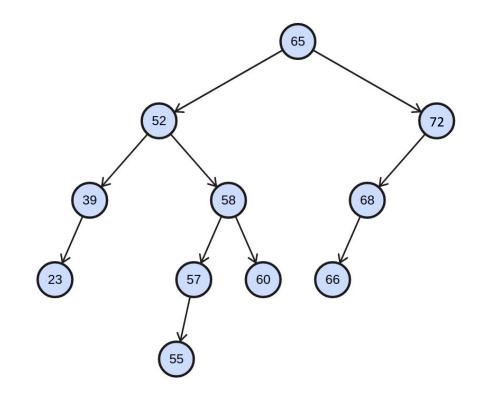
First, find the successor of 70, which is 72.



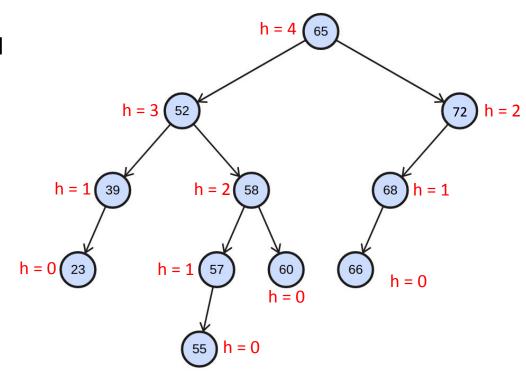
Copy the value of the successor over.



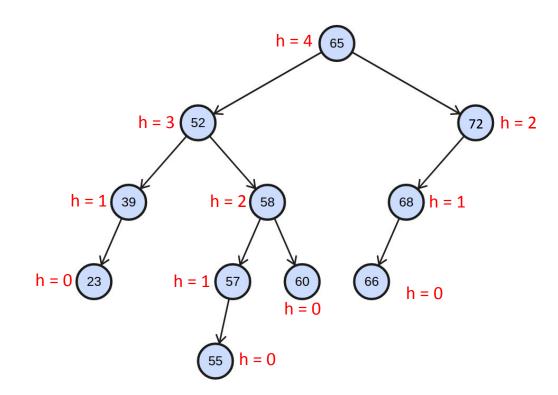
Then, delete the successor.



Now, the subtree rooted at the node with key 72 is unbalanced!

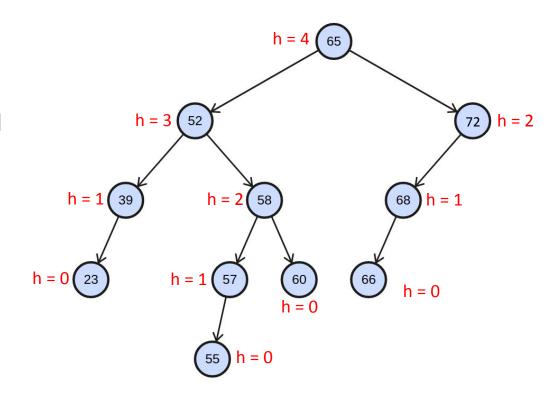


Let the node with key 72 be v.



Let the node with key 72 be v.

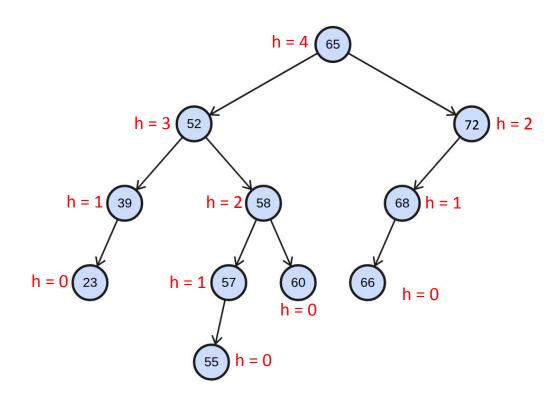
v is out of balance and left heavy.



Let the node with key 72 be v.

v is out of balance and left heavy.

v.left is left heavy.

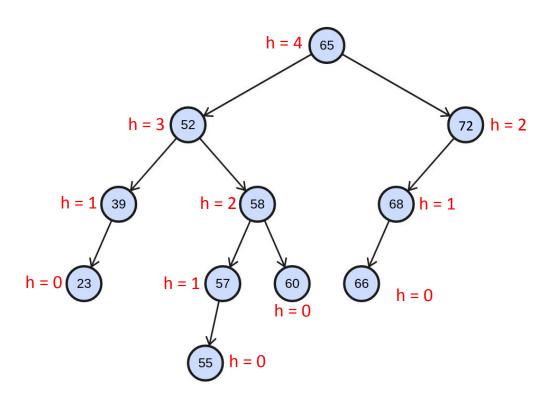


Let the node with key 72 be v.

v is out of balance and left heavy.

v.left is left heavy.

Perform a right rotation on v!

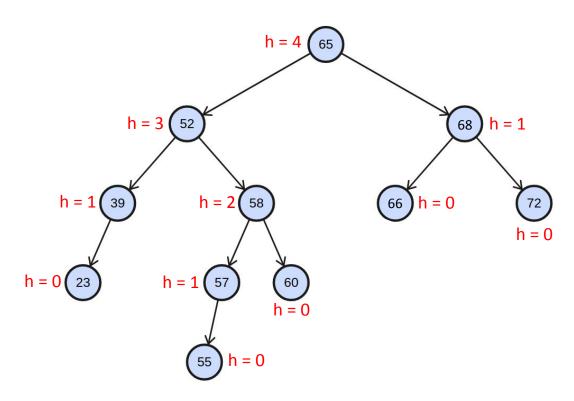


Let the node with key 72 be v.

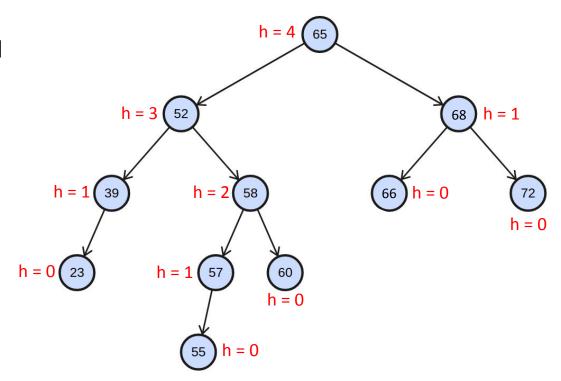
v is out of balance and left heavy.

v.left is left heavy.

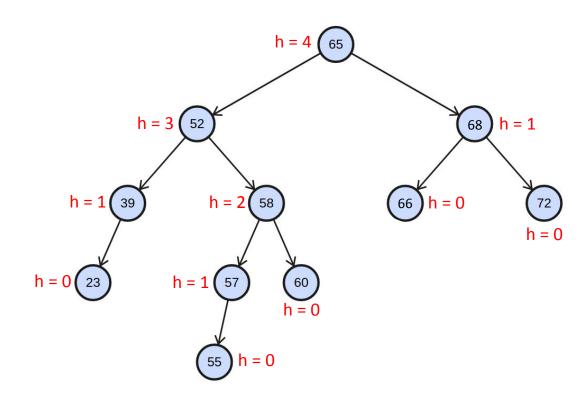
Perform a right rotation on v!



Now, the subtree rooted at the node with key 65 is unbalanced.

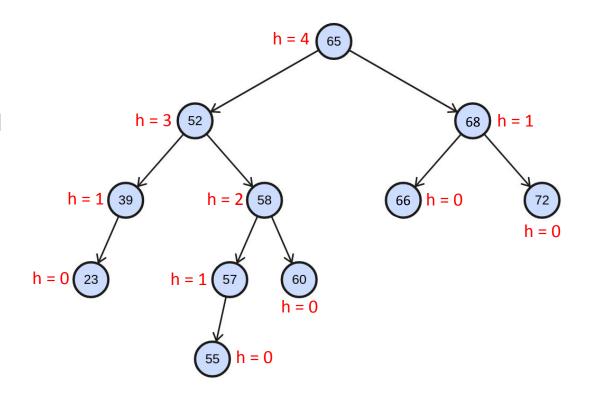


Let the node with key 65 be v.



Let the node with key 65 be v.

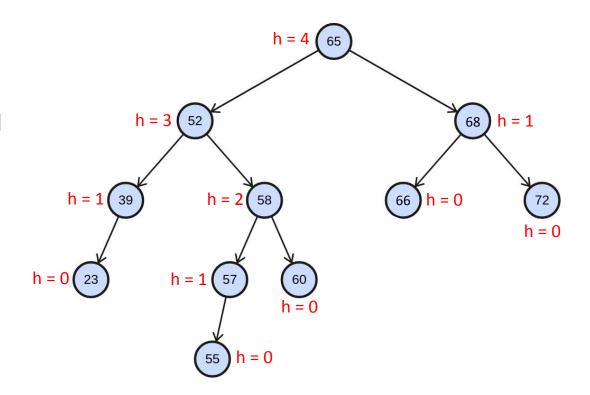
v is out of balance and left heavy.



Let the node with key 65 be v.

v is out of balance and left heavy.

v.left is right heavy.

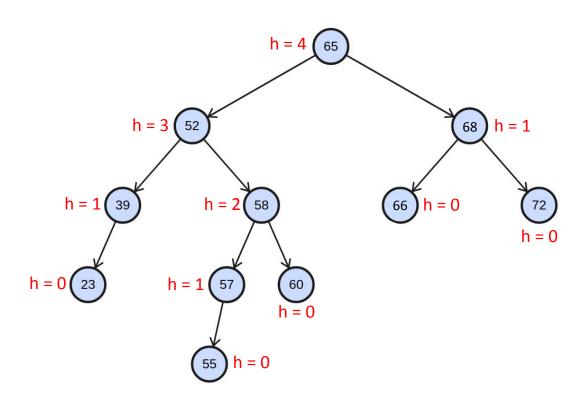


Let the node with key 65 be v.

v is out of balance and left heavy.

v.left is right heavy.

Perform a left rotation on v.left, then a right rotation on v!

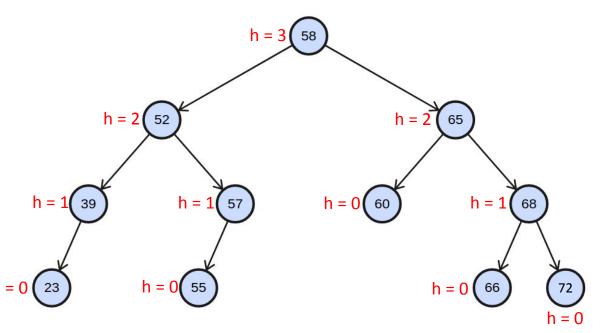


Let the node with key 65 be v.

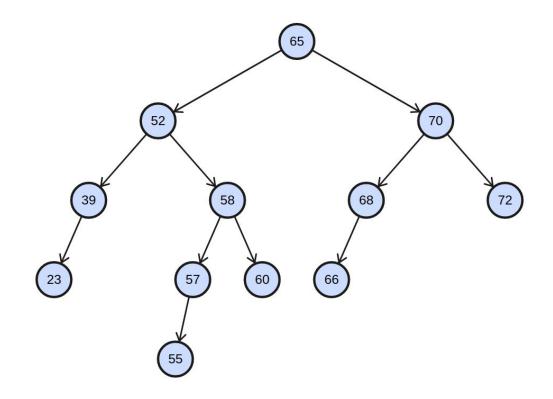
v is out of balance and left heavy.

v.left is right heavy.

Perform a left rotation on v.left, then a right rotation on v!

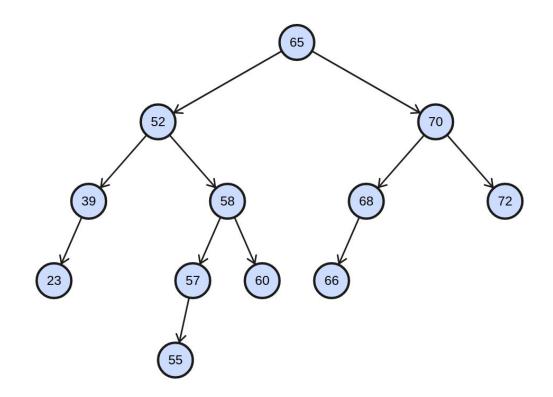


dentify the roots of all maximally imbalanced AVL subtrees in the original tree. A maximal imbalanced tree is one with the minimum possible number of nodes given its height *h*.



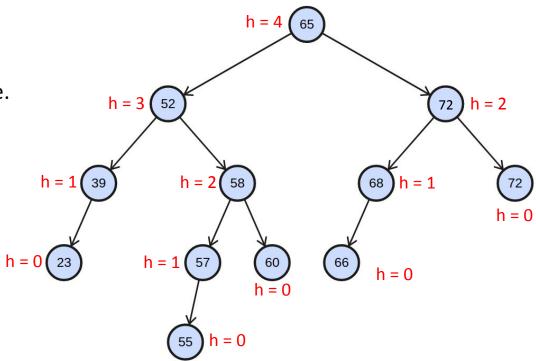
dentify the roots of all maximally imbalanced AVL subtrees in the original tree. A maximal imbalanced tree is one with the minimum possible number of nodes given its height *h*.

All of them!



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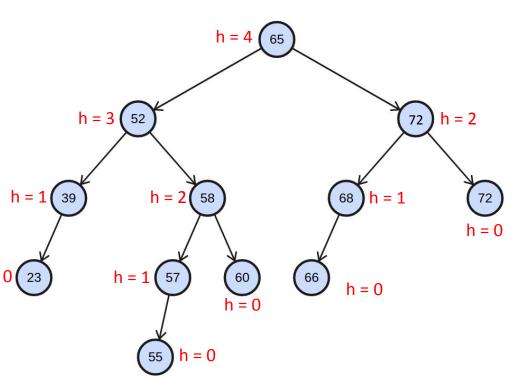
All of them!



• An AVL tree of height h with the minimum possible number of nodes has two subtrees of heights h-1 and h-2 with the minimum possible number of nodes

•
$$S(h) = S(h-1) + S(h-2) + 1$$

 This means that a maximally imbalanced AVL tree has all its subtrees be maximally imbalanced



Lecture 1: AVL Tree Review

During lectures, we've learnt that we need to store and maintain height information for each AVL tree node to determine if there is a need to rebalance the AVL tree during insertion and deletion. However, if we store height as an int, each tree node now requires 32 extra bits. Can you think of a way to reduce the extra space required for each node to 2 bits instead?

Lecture 1: AVL Tree Review

- Instead of storing the height, we can store and maintain the balance factor for each node
- Balance factor is equal to the difference between the left and right subtrees
 of a node
- Remember our invariant!
 - An AVL tree is a height balanced tree
 - A tree is height balanced if every node in the tree is height balanced
 - A node v is height balanced if the difference between v.left.height and v.right.height is less than or equals to 1
- As such, the balance factor only needs to take up the values -1, 0 or 1.
- This requires only 2 bits which gives us $2^2 = 4 > 3$ distinct representations.

- Put the first plate on your table.
- Go through all the remaining plates. For each plate, taste the chicken rice on the plate, as well as the chicken rice on the table to determine which is better.
 - If the new plate is better than the one on the table, replace the plate on the table with the new plate.
- 3. When you are done, the plate on your table is the winner!

Assume each plate begins containing n bites of chicken rice. When you are done, in the worst-case, how much chicken rice is left on the winning plate?

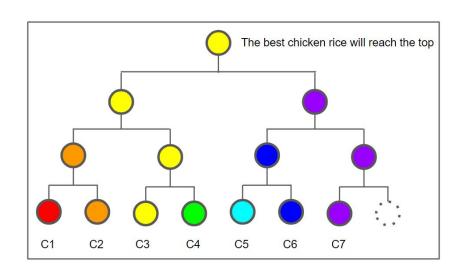
- Only one bite left!
- In the worst case, the first plate on the table is already the best plate of chicken rice
- Thus, it is used to compare against all the remaining n-1 plates, resulting in n-1 bites being taken

Oh no! We want to make sure that there is as much chicken rice left on the winning plate as possible (so you can take it home and give it to all your friends). Design an algorithm to maximise the amount of remaining chicken rice on the winning plate, once you have completed the testing/tasting process.

- 1. How much chicken rice is left on the winning plate?
- 2. How much chicken rice have you had to consume in total?

Give a tight asymptotic bound for both questions above.

- Use a tournament tree!
 - Group the plates of chicken rice into pairs and compare within each pair to get a winner
 - Group the winners of the previous round into pairs and compare within each pair to get a winner
 - Repeat until we have only 1 plate left
- In the worst case, we consume
 - $O(\log n)$ bites from the winning plate
 - Height of the tree
 - O(n) bites overall
 - Each comparison takes 2 bites
 - Each comparison removes 1 plate



Now, I do not want to find the best chicken rice, but the **median** chicken rice. Again, design an algorithm to maximise the amount of remaining chicken rice on the median plate once you have completed the testing/tasting process.

- 1. How much chicken rice is left on median plate?
- 2. How much chicken rice have you had to consume in total?

Give a tight asymptotic bound for both questions above. If your algorithm is randomised, give your answers in expectation.

- Use quickselect!
- Analysis
 - In one step of quickselect (with an array of size n)
 - The pivot plate has n-1 bites eaten
 - All other plates have 1 bite eaten
 - If the pivot plate is chosen at random, the median plate has an expected cost of $\frac{1}{n}(n-1) + \left(1 \frac{1}{n}\right)1 = 2\left(1 \frac{1}{n}\right) = 2 \frac{2}{n} \le 2$ bites eaten
 - In other words, at each level of recursion, there are at most 2 bites eaten from the median plate in expectation

- Analysis
 - With high probability and in expectation, the recursion will terminate in $O(\log n)$ levels
 - In the average case, we consume
 - $O(\log n)$ bites from the median plate
 - O(n) bites overall
 - If we select pivots randomly, we should get a good split most of the time

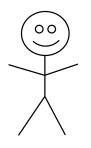
- In the solution sheet, an alternative mentioned is to use an AVL tree
- However, since this solution is deterministic (not randomised), it is possible for there to be the following bad input:
 - Insert the median plate into the AVL tree
 - By default, the first plate inserted will be the root of the AVL tree
 - Insert all other plates in an order such that no rotations ever occur
 - This means that the median plate stays at the root throughout
- In the worst case, we consume O(n) bites from the median plate!

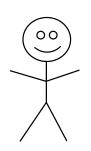
Main Question Idea: You want to divide the dataset into "equi-wealth" age ranges, and given parameter k, you should output k different lists $A_1, A_2, ..., A_k$ with the following properties:

1. All the ages of people in set A_j should be less than or equal to the ages of people in A_{j+1}. That is, each set should be a subset of the original dataset containing a contiguous age range.

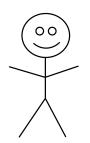
2. The sum of wealth in each set should be (roughly) the same

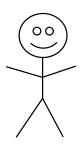
Problem 3: Example











18 yo, wealth: 1,000

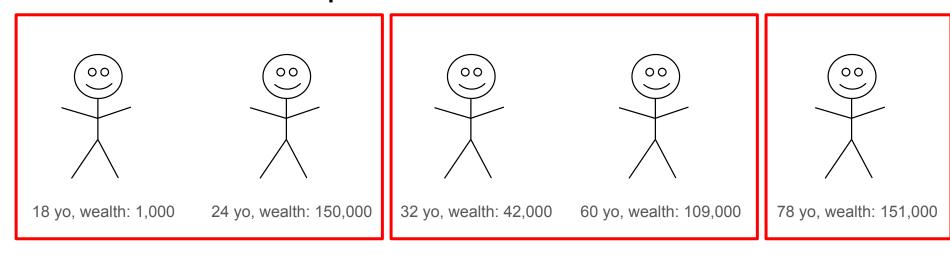
24 yo, wealth: 150,000

32 yo, wealth: 42,000

60 yo, wealth: 109,000

78 yo, wealth: 151,000

Problem 3: Example



Equi-wealth partition: 151,000

Design the most efficient algorithm you can to solve this problem/do the partition, and analyse its time complexity.

Feeling lost?

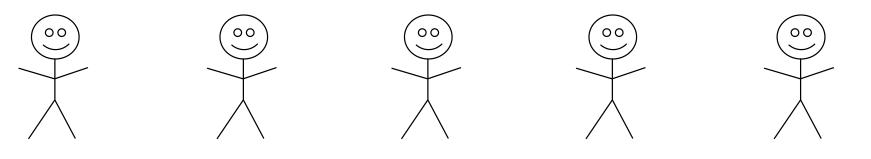
Try to model this question to similar problems/algorithms you have seen before!

Order Statistics?

Order Statistics?

We are trying to find the 1/k, 2/k, ..., (k-1)/k order statistics of the weighted sum!

First and foremost, we would need to find the equi-wealth partition



24 yo, wealth: 150,000

32 yo, wealth: 42,000

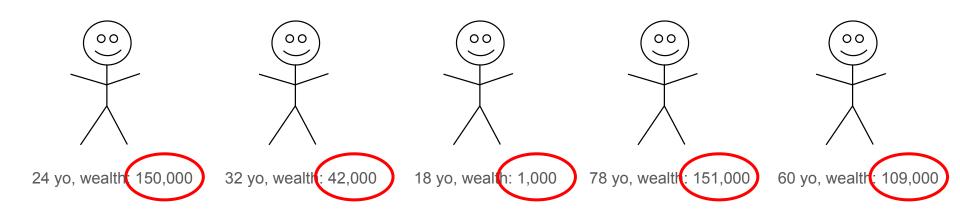
18 yo, wealth: 1,000

78 yo, wealth: 151,000

60 yo, wealth: 109,000

Equi-wealth partition: 151,000

First and foremost, we would need to find the equi-wealth partition

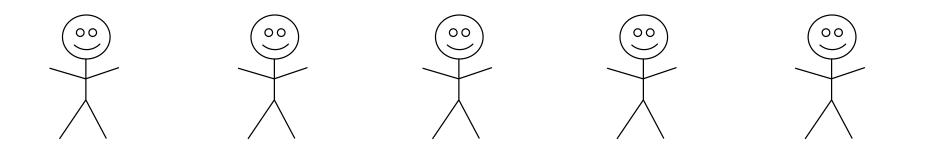


Go through everyone to find total wealth of the population, and divide by k

32 yo, wealth: 42,000

24 yo, wealth: 150,000

Next, we want to find the smallest ages with total wealth of at most 151,000



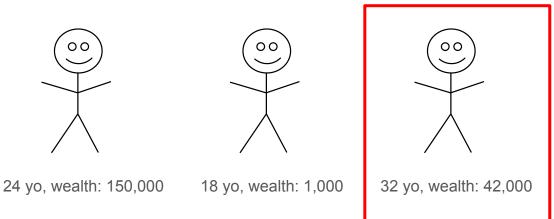
18 yo, wealth: 1,000

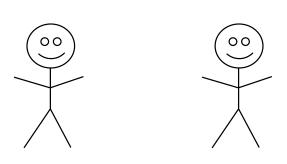
78 yo, wealth: 151,000

60 yo, wealth: 109,000

REMEMBER: this is not sorted! So what algorithm can we use?

1. Use QuickSelect to find median based on age, and then partition around the median to find the first target (1/k)



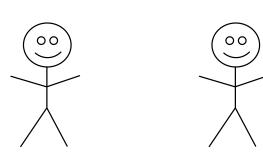


78 yo, wealth: 151,000

60 yo, wealth: 109,000

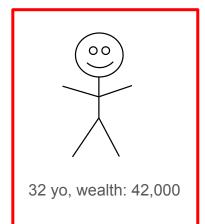
This is the median

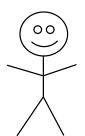
2. Sum the totals on the left and right halves, and decide on which side to recurse on. (If target < median, recurse on the left. If target > medium, then target = target - total wealth of the left half.)



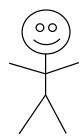
24 yo, wealth: 150,000

18 yo, wealth: 1,000





78 yo, wealth: 151,000



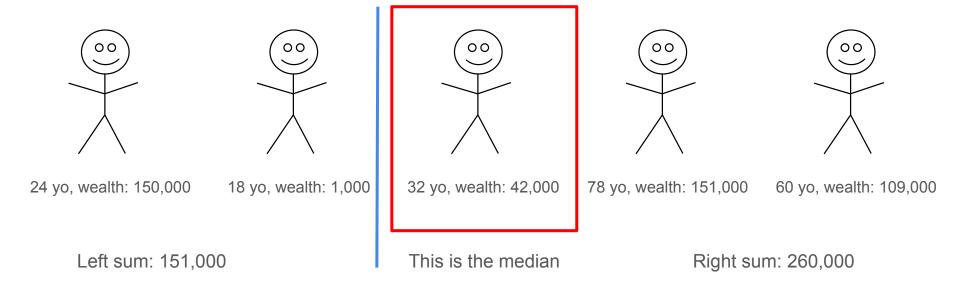
60 yo, wealth: 109,000

Left sum: 151,000

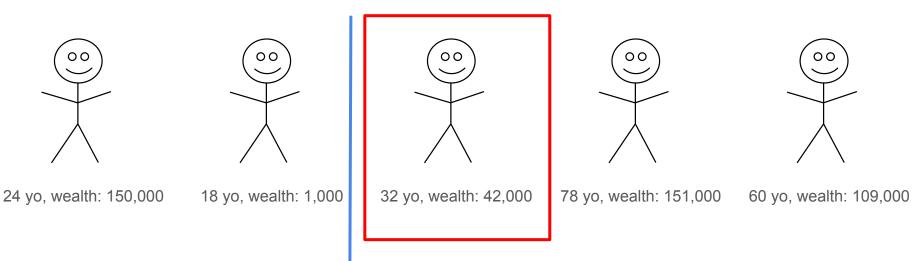
This is the median

Right sum: 260,000

2. Here, there is no need to recurse to the left anymore, since you know the partition is between the 18 and 32 yo.



3. Repeat for the k - 1 targets (2/k, 3/k, ... (k-1)/ k



Left sum: 151,000

This is the median

Right sum: 260,000

Each QuickSelect: O(n)

Each QuickSelect: O(n)

Total time taken for k targets: O(nk)

Modifications?

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Can use random pivot instead of median

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- Can use random pivot instead of median
- Can find all k "breakpoints" at once → less repeated work done partitioning the array

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Runtime?

Analysing runtime of more efficient method:

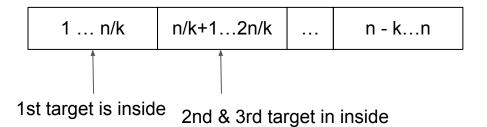
1. First divide the array up into k equal sized parts (in terms of the number of elements) by running QuickSort for log(k) levels of recursion.

1 n/k	n/k+12n/k		n - kn
-------	-----------	--	--------

Each level divides the array in half, so at this point, you have <u>k different equal</u> sized pieces \rightarrow O(n log k) time

Analysing runtime of more efficient method:

- 2. For each of the k targets, figure out which piece it is in by:
 - 1. summing the wealth in each equally sized part \rightarrow O(n)
 - 2. binary search k times for which of the k pieces it belongs to \rightarrow O(k log k)



Analysing runtime of more efficient method:

3. Now run the initial algorithm for each target on the correct subarray of size O(n/k), which takes O(n/k) time each. Since there are k targets, the total time will be O(n).

1 n/k n/k+12n/k		n - kn
-----------------	--	--------

Initial algorithm:

Use QuickSelect to find the median based on age, and then partition around the median. Sum the totals on the left and right halves, and decide on which side to recurse on. If target is on the left, simply recurse on the left.

If your target is on the right, then subtract from your target the total wealth of the left half.

Analysing runtime of more efficient method:

Recurrence Relation:

$$T(n, k) = O(n) + O(k) + T(n/2, k_1) + T(n/2, k_2)$$
 where $k_1 + k_2 = k$

At each level:

O(n) to partition the array into left and right using a pivot O(k) to decide for each target if it is in the left and right halves T (...) parts are for the two recursive calls

Modifications

- Can use random pivot instead of median
- Can find all k "breakpoints" at once → less repeated work done partitioning the array

Runtime? O(n log k) // yay better!

Design a data structure for Order Maintenance. The goal here is to maintain a total order over some arbitrary objects. The data structure supports two operations:

- 1. InsertBefore(A, B): insert B immediately before A
- 2. InsertAfter(A, B): insert B immediately after A.
- 3. IsAfter(A, B): is B after A in the total order?

Note: InsertAfter(A, B) adds B immediately after A, while the query operation IsAfter(A, B) asks whether B is anywhere after A in the total order

Expected time complexity of each operation is O(log n), where n is the number of items in the data structure.

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Hint: Which data structure has a time complexity of O(log n) for each operation?

AVL Trees!

InsertAfter(A, B):

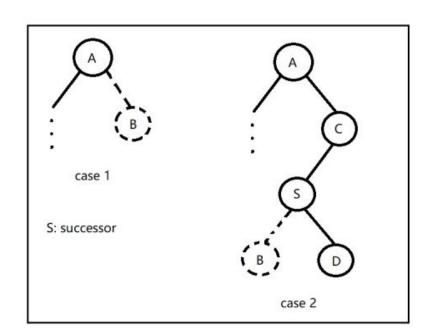
1. If A has no right child, then insert B as the right child of A.

InsertAfter(A, B):

- 1. If A has no right child, then insert B as the right child of A.
- 2. Otherwise, find the successor of A and insert B as the left child of the successor.

InsertAfter(A, B):

- 1. If A has no right child, then insert B as the right child of A.
- 2. Otherwise, find the successor of A and insert B as the left child of the successor.



InsertBefore(A, B):

When inserting B before A, do the same thing in reverse:

- 1. Insert B as the left child (if none exists)
- 2. Insert B as the right child of the predecessor of A.

IsAfter(A, B):

IsAfter(A, B):

 Walk up the tree, until we find a common ancestor of A and B (i.e. when their paths "meet")

IsAfter(A, B):

- 1. Walk up the tree, until we find a common ancestor of A and B (i.e. when their paths "meet")
- 2. Will need to store each step along the path (in an array), the key and whether the node was entered from the left or right.

IsAfter(A, B):

- 1. Walk up the tree, until we find a common ancestor of A and B (i.e. when their paths "meet")
- 2. Will need to store each step along the path (in an array), the key and whether the node was entered from the left or right.
- 3. Compare the two tree walks and find the common ancestor where one path entered from the left and the other from the right.

Cost of all operations:

Cost of all operations: O(log n), since the height of an AVL tree of n nodes is at most O(log n)

Our job is now to simulate a binary tree. Each node has zero, one, or two children, and the tree is of height h. Unfortunately, it is not a balanced tree. By preprocessing the binary tree, design and implement an auxiliary data structure to support the following operations efficiently:

- 1. InsertLeft(x, y): insert y as a left child of x in the binary tree.
- 2. InsertRight(x, y): insert y as a right child of x in the binary tree.
- 3. IsAncestor(x, y): is x an ancestor of y in the binary tree that contains them?

Hint: Think about how you answer the IsAncestor(x, y) query without the extra data structure. What would the cost of that operation be? How can you improve this?

Change way of traversal?

New type of traversal in which each node in the tree appears twice:

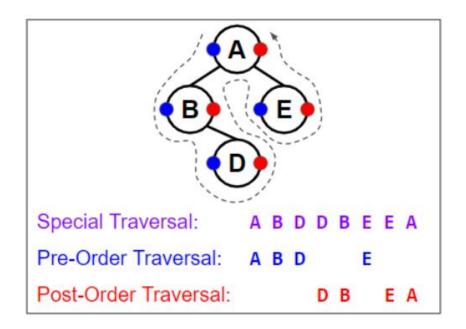
Once before all of its children and once after all of its children.

For a node v with children y and z, we define traverse(v) recursively as follows:

print(v) traverse(y) traverse(z) print(v)

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If v has no children, then its traversal consists of just two elements: v v.

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print(v) traverse(y) traverse(z) print(v)

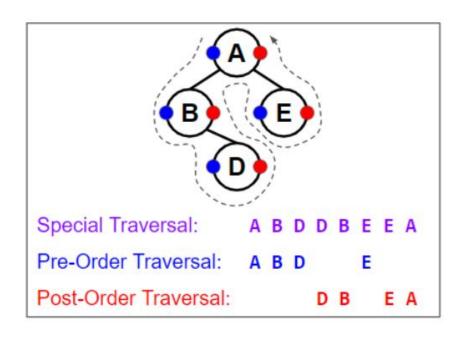
If v has no children, then its traversal consists of just two elements: v v.

Let's consider the sequence that we obtain out of this traversal. We'll call the first time a node is printed as start(v), and the second time end(v).

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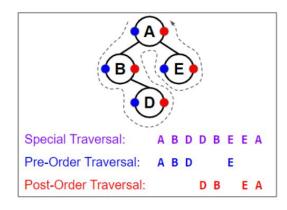
Focusing only on the first printings: resulting total order is exactly a pre-order traversal

Focusing only on the second printings, resulting total order is exactly a post-order traversal



Given two nodes v and w, we observe that v comes before w in a pre-order traversal of the original (unbalanced) tree if start(v) comes before start(w) in the traversal.

Similarly, v comes before w in a post-order traversal of the original (unbalanced) tree if end(v) comes before end(w) in the traversal.



IsAncestor(x,y):

 Check whether x precedes y in the pre-order traversal and whether y precedes x in the post-order traversal.

IsAncestor(x,y):

• Check whether x precedes y in the pre-order traversal and whether y precedes x in the post-order traversal.

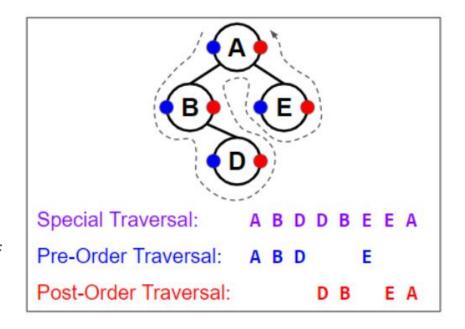
Lemma:

Node x is an ancestor of y if and only if x comes before y in a pre-order traversal and x comes after y in a post-order traversal.

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Looking at BDDB here, B is an ancestor of D



Insertions:

To insert a new node w as a child of x, we need to insert start(w) and end(w)

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If w is the only child of x, or w is the left child of x, then we insert start(w) after x and end(w) after start(w).

Otherwise, if w is the right child of x, then we insert end(w) immediately before end(x) and we insert start(w) immediately before end(w).

So what kind of operations we need to support?

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Given 2 items, we need to be able to check whether one is before the other, and also, we need to be able to insert items as either directly before or directly after them.

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Exactly the previous question! Qn 4: Order Maintenance

So what kind of operations we need to support?

Possibly maintain some additional index structures, e.g., a tree to translate the name of a node to its location in the new traverse data structure, and/or the name of a node to its location in the unbalanced binary tree. This tree would allow us to lookup x, find start(x) and end(x) in the tree, and use them to answer the IsAncestor(x,y) query.

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O(log n)

So what kind of operations we need to support?

Can use hashing (taught later in the course) for O(1) time instead