

Midterm 1

DO NOT REMOVE THIS PAGE DURING SUBMISSION:

The student understands that all required components should be submitted in complete for grading of this assignment.

NO	SUBMISSION ITEM	COMPLETED (Y/N)	MARKS (/MAX)
1	COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS		
2.	INITIAL CODE OF TASK 1/A		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 2/B		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 3/C		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 4/D		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 5/E		
4.	SCHEMATICS		
5.	SCREENSHOTS OF EACH TASK OUTPUT		
5.	SCREENSHOT OF EACH DEMO		
6.	VIDEO LINKS OF EACH DEMO		
7.	GOOGLECODE LINK OF THE DA		

1. COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS

Atmega328P

FTDI Chip

LM34 Temp Sensor

ESP 8266

Attempted to use NodeMCU Chip - It started smoking

2. INITIAL/DEVELOPED CODE OF TASK 1/A

Transmit data using USART with the ESP chip – display results on Thingspeak (unsuccessful).

```
#define F_CPU 16000000UL

#include <stdlib.h>
#include <avr/io.h>
#include <stdint.h>
#include <util/delay.h>
#include <avr/interrupt.h>

#define FOSC 16000000 // Clock speed 16Mhz
#define BAUD 9600 // BAUD Rate Defined
#define MYUBRR FOSC/8/BAUD-1

volatile unsigned char AT[] = "AT\r\n";
volatile unsigned char CIPMUX[] = "AT+CIPMUX=0\r\n";
volatile unsigned char CIPSTART[] = "AT+CIPSTART=\"TCP\", \"184.106.153.149\", 80\r\n";
//ip of thingspeak
volatile unsigned char SEND_DATA[] = "GET /update?key=RLJISPGVOR00D77R&field1="; //update
thingspeak

volatile unsigned char CIPSIZE[] = "AT+CIPSEND=45\r\n"; //send data
volatile unsigned char CWMODE[] = "AT+CWMODE=3\r\n"; //wifi mode
volatile unsigned char CONNECTWIFI[] = "AT+CWJAP=\"Liz\", \"*****\"\r\n"; //connect to
ap
volatile unsigned char FIRMWARE[] = "AT+GMR\r\n";
volatile unsigned char BREAK[] = "\r\n\r\n";

//global variables
volatile uint8_t adc_val; // Value read from Temperature Sensor in ADC
volatile unsigned char temp[5];

//prototypes
void init_USART(); // Initialize USART function
void send_AT(volatile unsigned char AT[]); // Send commands

int main(void)
{
    ADMUX = 0; // read from ADC 0
    ADMUX |= (1 << REFS0); // use AVcc as the reference
    ADMUX |= (1 << ADLAR); // Right adjust for 8 bit resolution

    ADCSRA |= (1 << ADPS2) | (1 << ADPS1) | (1 << ADPS0); // 128 as prescaler
    ADCSRA |= (1 << ADSC); // Set ADC Auto Trigger Enable
    ADCSRB = 0;
    ADCSRA |= (1 << ADEN); // Enable ADC
    ADCSRA |= (1 << ADIF); // Enable Interrupts
    ADCSRA |= (1 << ADSC); // ADC Conversion

    init_USART();

    _delay_ms(1500);
    send_AT(AT); //at
```

```

    _delay_ms(1500);
    send_AT(FIRMWARE); //firmware
    _delay_ms(1500);
    send_AT(CWMODE); //wifi mode
    _delay_ms(1500);
    send_AT(CONNECTWIFI); //connect with WiFi
    _delay_ms(5000);
    send_AT(CIPMUX); //enable

    sei();
    while (1)
    {
        _delay_ms(500);
        send_AT(CIPSTART); // start connection
        _delay_ms(500);
        send_AT(CIPSIZE); // size
        _delay_ms(500);
        send_AT(SEND_DATA);
        send_AT(temp); //temperature
        send_AT(BREAK);
    }
    return 0;
}

void init_USART() {
    // Setting BAUD rate
    UBRR0H = ((MYUBRR) >> 8);
    UBRR0L = MYUBRR;

    UCSR0A |= (1<< U2X0);
    UCSR0B |= (1 << TXEN0); // Enable transmitter
    UCSR0C |= (1 << UCSZ01) | (1 << UCSZ00); // Set frame: 8data, 1 stp
}

// Interrupt subroutine for ADC value
ISR(ADC_vect) {
    unsigned char i;
    char tmptemp[5];

    adc_val = (ADCH << 1);
    itoa(adc_val, tmptemp, 10);
    for(i = 0 ; i < 5 ; i++)
        temp[i] = tmptemp[i];
}

void send_AT(volatile unsigned char AT[]) {
    volatile unsigned char a;
    volatile unsigned char length = 0;

    while(AT[length] != 0)
        length++; // find length

    for(a = 0 ; a < length ; a++)
    {
        while(!(UCSR0A & (1<<UDRE0)));
        UDR0 = AT[a];
    }
}

```

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"This assignment submission is my own, original work".

Elizabeth Heider