

Calibrating Noise to Sensitivity in Private Data Analysis

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A generalization

Consider the privacy problem in a statistical database $\in D^n$.
Previous work:

- specific function: noisy sums $f = \sum_i g(x_i)$ and g maps rows to $[0, 1]$

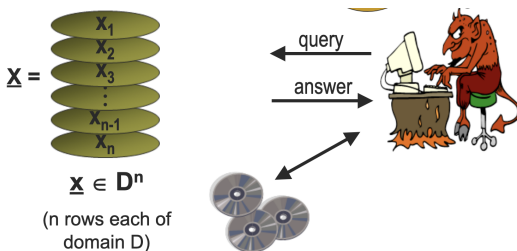
This work:

- general function f
- new definition: ϵ — indistinguishability
- general method: **sensitivity**-based perturbation

New Definition

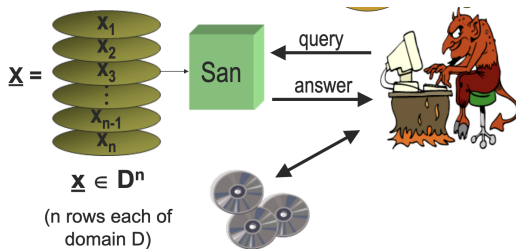
The Setting

- Statistical database $\mathbf{x} \in D^n$: n rows, each row $x_i \in D$.
 - D can be $\{0, 1\}^d$ or \mathbb{R}^d .
- User/Adversary \mathcal{A} : a probabilistic interactive Turing machine.



The Setting

- Database access protocol San.
- Transcript $\mathcal{T}_{\text{San}, \mathcal{A}}(\mathbf{x})$: $[Q_1, a_1, \dots, Q_d, a_d]$.
- The Hamming distance $d_H(\cdot, \cdot)$ over D^n : #entries in which two databases differ.



ϵ – indistinguishability

Definition (ϵ – indistinguishability)

A mechanism is ϵ -indistinguishable if for all pairs $\mathbf{x}, \mathbf{x}' \in D^n$ which differ in only one entry, for all adversaries \mathcal{A} , and for all transcripts t :

$$\left| \ln \left(\frac{\Pr[\mathcal{T}_{\mathcal{A}}(\mathbf{x}) = t]}{\Pr[\mathcal{T}_{\mathcal{A}}(\mathbf{x}') = t]} \right) \right| \leq \epsilon. \quad (1)$$

Remark:

- ϵ is called *leakage*.
- $\epsilon \rightarrow 0$, $\ln(1 + \epsilon) \approx \epsilon$. Then $\frac{\Pr[\mathcal{T}_{\mathcal{A}}(\mathbf{x})=t]}{\Pr[\mathcal{T}_{\mathcal{A}}(\mathbf{x}')=t]} \in 1 \pm \epsilon$.

More discussions on ϵ – indistinguishability

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Example (Noisy Sum)

Suppose $\mathbf{x} \in \{0, 1\}^n$, and the user wants to learn $f(\mathbf{x}) = \sum_i x_i$, the total number of 1's in the database. Consider adding noise to $f(\mathbf{x})$ according to a Laplace distribution:

$\mathcal{T}(x_1, \dots, x_n) = \sum_i x_i + Y$, where $Y \sim \text{Lap}(1/\epsilon)$ This mechanism is ϵ -indistinguishable.

Proof of Noisy Sum

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Proof.

Lap(λ) has density function $h(y) \propto \exp(-|y|/\lambda)$.

For $y, y' \in \mathbb{R}$, $\frac{h(y)}{h(y')} = \exp(\frac{1}{\lambda}(|y'| - |y|)) \leq e^{\epsilon|y-y'|}$.

Since $\mathbf{x}, \mathbf{x}' \in \{0, 1\}^n$ differ in a single entry,

$$|f(\mathbf{x}) - f(\mathbf{x}')| = 1.$$

Thus, for $t \in \mathbb{R}$,

$$\frac{\Pr(\mathcal{T}(\mathbf{x}) = t)}{\Pr(\mathcal{T}(\mathbf{x}') = t)} = \frac{h(t - f(\mathbf{x}))}{h(t - f(\mathbf{x}'))} \leq e^{\epsilon|f(\mathbf{x}) - f(\mathbf{x}')|} = e^{\epsilon},$$

which concludes the proof. □

More discussions on ϵ – indistinguishability

A more common metric for cryptography:

Definition (total variation distance/statistical difference (SD))

The total variation distance between two probability measures P and Q on a sigma-algebra \mathcal{F} of subsets of the sample space Ω is defined via

$$\delta(P, Q) = \sup_{A \in \mathcal{F}} |P(A) - Q(A)|.$$

However, ϵ – indistinguishability is more stringent.

- Example: $p_P(a) \neq 0$ and $p_Q(a) = 0$. Ratio in Eq. (1) is infinite while SD could be small.

More discussions on ϵ – indistinguishability

Example (Candidate Sanitization)

Consider the candidate sanitization

$$\mathcal{T}(x_1, \dots, x_n) = (i, x_i) \quad \text{where } i \in_R \{1, \dots, n\}.$$

If \mathbf{x} and \mathbf{x}' differ in a single position,

- $\text{SD}(\mathcal{T}(\mathbf{x}), \mathcal{T}(\mathbf{x}')) = 1/n$.
- Every transcript **reveals individual private information**.
- no ϵ – indistinguishability: Say \mathbf{x} and \mathbf{x}' differ in the i th coordinate.

$$\Pr(\mathcal{T}(\mathbf{x}') = (i, x_i)) = 0$$

can not satisfy

$$\left| \ln \left(\frac{\Pr[\mathcal{T}_{\mathcal{A}}(\mathbf{x}) = t]}{\Pr[\mathcal{T}_{\mathcal{A}}(\mathbf{x}') = t]} \right) \right| \leq \epsilon.$$

Sensitivity and Privacy

L_1 Sensitivity

Definition (L_1 Sensitivity)

The L_1 sensitivity of a function $f : D^n \rightarrow \mathbb{R}^d$ is the smallest number $S(f)$ such that for all $\mathbf{x}, \mathbf{x}' \in D^n$ which differ in a single entry,

$$\|f(\mathbf{x}) - f(\mathbf{x}')\|_1 \leq S(f).$$

Remark:

- Sensitivity is a Lipschitz condition on f :
for all pairs of databases $\mathbf{x}, \mathbf{x}' \in D^n$:

$$\frac{\|f(\mathbf{x}) - f(\mathbf{x}')\|_1}{d_H(\mathbf{x}, \mathbf{x}')} \leq S(f).$$

- Can we use other distance metrics?

Examples about L_1 Sensitivity

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Example (Sums)

if $D = \{0, 1\}$ and $f(\mathbf{x}) = \sum_{i=1}^n x_i$ (viewed as a real number),
 $S_{L_1}(f) = 1$.

Examples about L_1 Sensitivity

Example (Histograms)

Consider an arbitrary domain D , partitioned into d disjoint bins B_1, \dots, B_d .

$f : D^n \rightarrow \mathbb{Z}^d$, computing the number of database points which fall into each bin, is called a histogram for B_1, \dots, B_d .

We have $S_{L_1}(f) = 2$, **independent of d** .

To see why:

- Changing one point in the database can change at most two of these counts: one bin loses a point, another bin gains one.

Calibrating Noise According to $S(f)$

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Proposition (Non-interactive Output Perturbation)

For all $f : D^n \rightarrow \mathbb{R}^d$, the following mechanism is ϵ -indistinguishable: $\text{San}_f(\mathbf{x}) = f(\mathbf{x}) + (Y_1, \dots, Y_d)$ where the Y_i are drawn i.i.d. from $\text{Lap}(S(f)/\epsilon)$.

Calibrating Noise According to $S(f)$

Proof.

Recall: if $y, y' \sim \text{Lap}(\lambda)$, then $h(y)/h(y') \leq e^{|y-y'|/\lambda}$.

Extend to high dimensions: if Y is a vector of d independent Laplace variables, the density function at y is proportional to $\exp(-\|y\|_1/\lambda)$.

For all $t \in \mathbb{R}^d$,

$$\frac{\Pr(z + Y = t)}{\Pr(z' + Y = t)} = \frac{\Pr(Y = t - z)}{\Pr(Y = t - z')} \in \exp\left(\pm \frac{\|z - z'\|_1}{\lambda}\right).$$

Let $\frac{S(f)}{\lambda} = \epsilon$, we have $\lambda = \frac{S(f)}{\epsilon}$.

Then,

$$\frac{\Pr(z + Y = t)}{\Pr(z' + Y = t)} \leq \exp(\epsilon).$$



Adaptive Query

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*What if the i th query can depend on
 $1, \dots, i - 1$ th queries?*

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More notations:

- A transcript $t = [Q_1, a_1, Q_2, a_2, \dots, Q_d, a_d]$ is a sequence of questions and answers.
- Assume that Q_i is a well defined function of a_1, \dots, a_{i-1} , and that we can therefore truncate our transcripts to be only a vector $t = [a_1, a_2, \dots, a_d]^6$.
- For any transcript t , we will let $f_t : D^n \rightarrow R^d$ be the function whose i th coordinate reflects the query Q_i , determined by the first $i - 1$ components of t .

Privacy Guarantee on Adaptive Query

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Consider a trusted server, holding \mathbf{x} .

- receive an adaptive sequence of queries $f_1, f_2, f_3, \dots, f_d$.
- each $f_i : D^n \rightarrow \mathbb{R}$.

For each query, the server San

- either refuses to answer,
- or answers $f_i(\mathbf{x}) + \text{Lap}(\lambda)$.

Theorem (Privacy Guarantee on Adaptive Query)

For an arbitrary adversary \mathcal{A} , let $f_t(\mathbf{x}) : D^n \rightarrow \mathbb{R}^d$ be its query function as parameterized by a transcript t . If $\lambda = \max_t S(f_t) / \epsilon$, the mechanism above is ϵ -indistinguishable.

Privacy guarantee on Adaptive Query

Proof.

Using conditional probability and writing t_i for the indices of t ,

$$\frac{\Pr[\text{San}_f(\mathbf{x}) = t]}{\Pr[\text{San}_f(\mathbf{x}') = t]} = \prod_i \frac{\Pr[\text{San}_f(\mathbf{x})_i = t_i \mid t_1, \dots, t_{i-1}]}{\Pr[\text{San}_f(\mathbf{x}')_i = t_i \mid t_1, \dots, t_{i-1}]}.$$

For the i th term,

$$\frac{\Pr[\text{San}_f(\mathbf{x})_i = t_i \mid t_1, \dots, t_{i-1}]}{\Pr[\text{San}_f(\mathbf{x}')_i = t_i \mid t_1, \dots, t_{i-1}]} \leq \exp(|f_t(\mathbf{x})_i - f_t(\mathbf{x}')_i| / \lambda).$$

Thus,

$$\begin{aligned} \prod_i \frac{\Pr[\text{San}_f(\mathbf{x})_i = t_i \mid t_1, \dots, t_{i-1}]}{\Pr[\text{San}_f(\mathbf{x}')_i = t_i \mid t_1, \dots, t_{i-1}]} &\leq \prod_i \exp(|f_t(\mathbf{x})_i - f_t(\mathbf{x}')_i| / \lambda) \\ &= \exp(\|f_t(\mathbf{x}) - f_t(\mathbf{x}')\|_1 / \lambda). \end{aligned}$$

We complete the proof using the bound $\forall t, S(f_t) \leq \lambda\epsilon$.

Sensitivity in General Metric Spaces

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What if the distance metric is not L_1 ?

Sensitivity in General Metric Spaces

We extend L_1 distance to the general distance metric $d_{\mathcal{M}}$ on the output $f(\mathbf{x})$.

- Symmetry: $d_{\mathcal{M}}(x, y) = d_{\mathcal{M}}(y, x)$.
- The triangle inequality: $d_{\mathcal{M}}(x, y) \leq d_{\mathcal{M}}(x, z) + d_{\mathcal{M}}(z, y)$.

Definition (Sensitivity in General Metric Spaces)

Let \mathcal{M} be a metric space with a distance function $d_{\mathcal{M}}(\cdot, \cdot)$. The sensitivity $S_{\mathcal{M}}(f)$ of a function $f : D^n \rightarrow \mathcal{M}$ is the amount that the function value varies when a single entry of the input is changed.

$$S_{\mathcal{M}}(f) \stackrel{\text{def}}{=} \sup_{\mathbf{x}, \mathbf{x}': d_H(\mathbf{x}, \mathbf{x}')=1} d_{\mathcal{M}}(f(\mathbf{x}), f(\mathbf{x}')) .$$

New Mechanism on New Sensitivity

Lap(λ) **only applies to L_1 sensitivity!**

Given a point $z \in \mathcal{M}$, (and a measure on \mathcal{M}) we define a probability density function

$$h_{z,\epsilon}(y) \propto \exp\left(\frac{-\epsilon \cdot d_{\mathcal{M}}(y, z)}{2 \cdot S_{\mathcal{M}}(f)}\right).$$

To reveal an approximate version of $f(\mathbf{x})$ with sensitivity S , one can sample a value according to $h_{f(\mathbf{x}),\epsilon/S}()$.

$$\Pr[\mathcal{T}(\mathbf{x}) = y] = \frac{\exp\left(\frac{-\epsilon}{2S_{\mathcal{M}}(f)} \cdot d_{\mathcal{M}}(y, f(\mathbf{x}))\right)}{\int_{y \in \mathcal{M}} \exp\left(\frac{-\epsilon}{2S_{\mathcal{M}}(f)} \cdot d_{\mathcal{M}}(y, f(\mathbf{x}))\right) dy}.$$

Theorem (Privacy Guarantee of New Mechanism)

In a metric space where $h_{f(\mathbf{x}),\epsilon}()$ is well-defined, adding noise to $f(\mathbf{x})$ as above yields an ϵ -indistinguishable scheme.

Proof of New Mechanism

Proof.

Let \mathbf{x} and \mathbf{x}' be two databases differing in one entry.

First, $d_{\mathcal{M}}(f(\mathbf{x}), f(\mathbf{x}')) \leq S(f)$.

For any y ,

$$\begin{aligned} \frac{\exp(d_{\mathcal{M}}(y, f(\mathbf{x})))}{\exp(d_{\mathcal{M}}(y, f(\mathbf{x}')))} &= \exp(d_{\mathcal{M}}(y, f(\mathbf{x})) - d_{\mathcal{M}}(y, f(\mathbf{x}'))) \\ &\leq \exp(d_{\mathcal{M}}(f(\mathbf{x}'), f(\mathbf{x}))) \leq e^{S(f)}. \end{aligned}$$

Similarly,
$$\frac{\exp\left(\frac{-\epsilon}{2S(f)} \cdot d_{\mathcal{M}}(y, f(\mathbf{x}))\right)}{\exp\left(\frac{-\epsilon}{2S(f)} \cdot d_{\mathcal{M}}(y, f(\mathbf{x}'))\right)} \leq e^{\epsilon/2}.$$

Finally, the normalization constant $\int_{y \in \mathcal{M}} \exp\left(\frac{-\epsilon \cdot d_{\mathcal{M}}(y, f(\mathbf{x}))}{2S(f)}\right) dy$ also differs by a factor of at most $e^{\epsilon/2}$ between \mathbf{x} and \mathbf{x}' .

Thus,

$$h_{f(\mathbf{x}), \epsilon}(y) / h_{f(\mathbf{x}'), \epsilon}(y) \leq e^{\epsilon/2} \cdot e^{\epsilon/2} = e^{\epsilon}.$$

Discussions on New Mechanism

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We denote the new mechanism as \mathcal{G} .

Comparison between Lap and \mathcal{G} :

- Sensitivity.
 - Lap uses L_1 sensitivity.
 - \mathcal{G} uses general distance metrics.
- Method.
 - Lap draws a noise and adds onto the output.
 - \mathcal{G} directly draws the output from the distribution.
- Distribution.
 - Lap: $h(y) \propto \exp[-\epsilon \|y\|_1 / S_{L_1}(f)]$.
 - \mathcal{G} : $h(y) \propto \exp(-\epsilon \cdot d_{\mathcal{M}}(y, f(\mathbf{x})) / 2S_{\mathcal{M}}(f))$.

Discussions on New Mechanism: Transform \mathcal{G} to Lap

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Let us see how \mathcal{G} can be equal to Lap when $d_{\mathcal{M}}$ is L_1 distance.

Let $d_{\mathcal{M}}$ be L_1 distance.

Recap:

$$\mathcal{G} : h(y) \propto \exp(-\epsilon \cdot d_{\mathcal{M}}(y, f(\mathbf{x}))/2S_{\mathcal{M}}(f)) .$$

We can view y as $f(x) + \eta$, where η is a noise we draw. Then, we will get the distribution of η similar to Lap,

$$\mathcal{G} : h(\eta) \propto \exp(-\epsilon \cdot \|\eta\|_1/2S_{L_1}(f)) .$$

We can actually get rid of the factor of 2.

How?

Discussions on New Mechanism: Transform \mathcal{G} to Lap

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Recap how we prove the privacy guarantee previously, where we bound the influence of the normalization factor,

$$\frac{\int_{y \in \mathcal{M}} \exp\left(\frac{-\epsilon \cdot d_{\mathcal{M}}(y, f(\mathbf{x}))}{2S(f)}\right) dy}{\int_{y \in \mathcal{M}} \exp\left(\frac{-\epsilon \cdot d_{\mathcal{M}}(y, f(\mathbf{x}'))}{2S(f)}\right) dy} \leq e^{\epsilon/2}.$$

If the normalization factor does not depend on $f(\mathbf{x})$, this equation is equal to 1 and further we can use a relatively smaller noise, by removing the factor 2, which is exactly

$$\text{Lap} : h(\eta) \propto \exp[-\epsilon \|\eta\|_1 / S_{L_1}(f)].$$

Non-interactive Mechanisms

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Interactive setting:

- answer queries of the form $f_g(\mathbf{x}) = \sum_{i=1}^n g(i, x_i)$ where $g : [n] \times D \rightarrow [0, 1]$.
- $S_{L_1}(f_g) = 1$.

Interactive and Non-interactive

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Suppose the domain D is $\{0, 1\}^d$.

For non-interactive ϵ -indistinguishable mechanism San :

- Many functions f_g “cannot be answered” by \mathcal{T}_{San} .
which means, it is not possible to distinguish
 - the sanitization of a database where all entries satisfy $g(i, x_i) = 0$
 - a database where all entries satisfy $g(i, x_i) = 1$
- Unless the database consists of at least $2^{\Omega(d)}$ points.

Interactive and Non-interactive

Consider Boolean functions $g_{\mathbf{r}}$ of a specific form.

- n non-zero binary strings $\mathbf{r} = (r_1, r_2, \dots, r_n)$, $r_i \in \{0, 1\}^d$
- $g_{\mathbf{r}}(i, x)$: the inner product, modulo 2, of r_i and x , that is $g_{\mathbf{r}}(i, x) = \bigoplus_j x^{(j)} r_i^{(j)}$, denoted $r_i \odot x$, written as g .

Theorem (Non-interactive Schemes Require Large Databases)

Suppose that San is an ϵ -indistinguishable non-interactive mechanism with domain $D = \{0, 1\}^d$. For at least $2/3$ of the functions of the form $f_g(\mathbf{x}) = \sum_i g(i, x_i)$, the following two distributions have statistical difference $O(n^{4/3} \epsilon^{2/3} 2^{-d/3})$:

Distribution 0: $\mathcal{T}_{\text{San}}(\mathbf{x})$ where $\mathbf{x} \in_R \{\mathbf{x} \in D^n : f_g(\mathbf{x}) = 0\}$

Distribution 1: $\mathcal{T}_{\text{San}}(\mathbf{x})$ where $\mathbf{x} \in_R \{\mathbf{x} \in D^n : f_g(\mathbf{x}) = n\}$

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For any r , partition the domain D into two sets:

- $D_r = \{x \in \{0, 1\}^d : r \odot x = 0\}$
- $\bar{D}_r = D \setminus D_r = \{x \in \{0, 1\}^d : r \odot x = 1\}$
- We abuse notation and let D_r also stand for a random vector chosen uniformly from that set (similarly for D and \bar{D}_r).

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Lemma (Random Subsets Approximate the Output Distribution (RSAOD))

Let $Z : D \rightarrow \{0, 1\}^*$ be a randomized map such that for all pairs $x, x' \in D$, and all outputs z , $\frac{\Pr[Z(x)=z]}{\Pr[Z(x')=z]} \in \exp(\pm\epsilon)$. For all $\alpha > 0$: with probability at least $1 - \alpha$ over $r \in \{0, 1\}^d \setminus \{0^d\}$,

$$\mathbf{SD}(Z(D_r), Z(D)) \leq O\left(\frac{\epsilon^2}{\alpha \cdot 2^d}\right)^{1/3}$$

The same statement holds for \bar{D}_r .

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A Appendix

Proof.

Let $p(z|x)$ denote the probability that $Z(x) = z$. If x is chosen uniformly in $\{0, 1\}^d$, then

$$p(z) = \sum_x p(z|x)p(x) = \frac{1}{2^d} \sum_x p(z|x).$$

For symmetry and simplification, we pick an offset bit b , and look at the set $D_{r,b} = \{x \in \{0, 1\}^d : r \odot x = b\}$.

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Then,

- Let $\hat{p}(z) = \Pr[Z(D_{r,b}) = z]$, where the probability is taken over the coin flips of Z and the choice of $x \in D_{r,b}$.
- For a fixed z , $\hat{p}(z)$ is a random variable depending on the choice of r, b .
- $\mathbb{E}_{r,b}[\hat{p}(z)] = p(z)$.

We want that

- $\text{Var}_{r,b}[\hat{p}(z)]$ is constrained.

Claim

$$\text{Var}_{r,b}[\hat{p}(z)] \leq \frac{2 \cdot \tilde{\epsilon}^2 \cdot p(z)^2}{2^d}, \text{ where } \tilde{\epsilon} = e^\epsilon - 1.$$

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We say a value z is δ - good for a pair (r, b) if

$$\hat{p}(z) - p(z) \leq \delta \cdot p(z).$$

By the Chebyshev bound $\Pr(|X - \mu| \geq k\sigma) \leq \frac{1}{k^2}$, with
 $k^2 = \frac{\delta^2 p(z)^2}{\text{Var}[\hat{p}(z)]}$, for all z ,

$$\Pr_{r,b}[z \text{ is not } \delta\text{-good for } (r, b)] \leq \frac{\text{Var}[\hat{p}(z)]}{\delta^2 p(z)^2} \leq \frac{2\tilde{\epsilon}^2}{\delta^2 2^d} = \beta.$$

If we take the distribution on z given by $p(z)$, then with probability at least $1 - \alpha$ over pairs (r, b) , the fraction of z 's (under $p(\cdot)$) which are good is at least $1 - \beta\alpha$.

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Finally, if a $1 - \beta\alpha$ fraction of the z 's are δ -good for a particular pair (r, b) , set $\delta = \sqrt[3]{\frac{2\epsilon^2\alpha}{2^d}}$ and we have

$$\mathbf{SD}(\hat{p}(z), p(z)) \leq 2(1 - \beta\alpha)\delta + 2\beta\alpha \leq 2(\beta\alpha + \delta) \leq 4\delta.$$

Since $\tilde{\epsilon} < 2\epsilon$ for $\epsilon \leq 1$,

$$4\delta \leq 4\sqrt[3]{12\epsilon^2 2^{-d}},$$

for at least a $1 - \alpha$ fraction of the pairs (r, b) .

The bit b is unimportant here, since it only switches D_r and its complement \bar{D}_r .

We also have

$$\mathbf{SD}(Z(D_r), Z(D)) = \mathbf{SD}(Z(\bar{D}_r), Z(D)),$$

since $Z(D)$ is the mid point between the two.

Q.E.D.

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Lemma (Random Subsets Approximate the Output Distribution (RSAOD))

Let $Z : D \rightarrow \{0, 1\}^*$ be a randomized map such that for all pairs $x, x' \in D$, and all outputs z , $\frac{\Pr[Z(x)=z]}{\Pr[Z(x')=z]} \in \exp(\pm\epsilon)$. For all $\alpha > 0$: with probability at least $1 - \alpha$ over $r \in \{0, 1\}^d \setminus \{0^d\}$,

$$\mathbf{SD}(Z(D_r), Z(D)) \leq O\left(\frac{\epsilon^2}{\alpha \cdot 2^d}\right)^{1/3}$$

The same statement holds for \bar{D}_r .

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"Distribution 0" in the statement is $\mathcal{T}_{\text{San}}(D_{r_1}, \dots, D_{r_n})$.

We want to show: With high probability over the choice of the r_i 's,

$$\mathcal{T}_{\text{San}}(D_{r_1}, \dots, D_{r_n}) \text{ is close to } \mathcal{T}(D, \dots, D)$$

We proceed by a hybrid argument, adding one constraint at a time. For each i , we want to show

$$\mathcal{T}_{\text{San}}(D_{r_1}, \dots, D_{r_i}, D, D, \dots, D) \text{ is close to}$$

$$\mathcal{T}_{\text{San}}(D_{r_1}, \dots, D_{r_i}, D_{r_{i+1}}, D, \dots, D)$$

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Suppose we have chosen r_1, \dots, r_i already.

For any $x \in \{0, 1\}^d$, consider the randomized map where the $(i+1)$ -th coordinate is fixed to x :

$$Z(x) = \mathcal{T}_{\text{San}}(D_{r_1}, \dots, D_{r_i}, x, D, \dots, D)$$

Note that $Z(D)$ is equal to the i -th step in the hybrid, and $Z(D_{r_{i+1}})$ is equal to the $(i+1)$ th step.

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By ϵ -indistinguishability of San,

$$\frac{\Pr[Z(x) = z]}{\Pr[Z(x') = z]} \in \exp(\pm \epsilon).$$

Use Lemma RSAOD and set $\alpha = \frac{1}{6n}$. With $\Pr \geq 1 - \frac{1}{6n}$,

$$\mathbf{SD}(Z(D_{r_i}), Z(D)) \leq O\left(\frac{n\epsilon^2}{2^d}\right)^{1/3} = O(\sigma),$$

denoted as event A_j .

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By a union bound,

$$\Pr(\cup_{i=1}^n \bar{A}_i) \leq \sum_{i=1}^n \Pr(\bar{A}_i) \leq \frac{1}{6n} \cdot n = \frac{1}{6}.$$

Thus,

$$\Pr(\cap_{i=1}^n A_i) \geq \frac{5}{6}.$$

In this case, the total distance is $n\sigma$. Denote $A = \cap_{i=1}^n A_i$. Similarly, for Distribution 1, with probability at least $\frac{5}{6}$, the total distance is $n\sigma$, denoted as B .

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Again by a union bound,

$$\Pr(\bar{A} \cup \bar{B}) \leq \frac{1}{3}.$$

Thus,

$$\Pr(A \cap B) \geq \frac{2}{3},$$

and the distance between Distributions 0 and 1 is at most $2n\sigma = O(n^{4/3}\epsilon^{2/3}2^{-d/3})$.

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*Thanks.
Questions?*

Appendices

Prove Claim

Claim

$$\text{Var}_{r,b}[\hat{p}(z)] \leq \frac{2 \cdot \tilde{\epsilon}^2 \cdot p(z)^2}{2^d}, \text{ where } \tilde{\epsilon} = e^\epsilon - 1.$$

Proof.

Recall:

- $\hat{p}(z) = \Pr[Z(D_{r,b}) = z].$
- $p(z) = \frac{1}{2^d} \sum_x p(z|x).$
- $\mathbb{E}_{r,b}[\hat{p}(z)] = p(z).$

Let:

- p^* be the minimum over x of $p(z|x).$
- $q_x = p(z|x) - p^*$ and $\bar{q} = p(z) - p^*.$

We can write:

$$\hat{p}(z) - p^* = \frac{2}{2^d} \sum_x q_x \chi_0(x),$$

where $\chi_0(x)$ is 1 if $x \in D_{r,b}$. And $\mathbb{E}[\hat{p}(z) - p^*] = \bar{q} = \frac{1}{2^d} \sum_x q_x.$

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$$\text{Var}_{r,b}[\hat{p}(z)] = \text{Var}_{r,b}[\hat{p}(z) - p^*]$$

$$= \mathbb{E}_{r,b} \left[\left(\frac{2}{2^d} \sum_x q_x \chi_0(x) - \frac{1}{2^d} \sum_x q_x \right)^2 \right]$$

$$= \mathbb{E}_{r,b} \left[\left(\frac{1}{2^d} \sum_x q_x (2\chi_0(x) - 1) \right)^2 \right]$$

Now $(2\chi_0(x) - 1) = (-1)^{r \odot x \oplus b}$. Thus,

$$\mathbb{E}_{r,b}[2\chi_0(x) - 1] = 0.$$

Moreover, for $x \neq y$,

$$\mathbb{E}_{r,b}[(2\chi_0(x) - 1)(2\chi_0(y) - 1)] = 1/2^d.$$

(if we chose r with no restriction it would be 0, but we have the restriction that $r \neq 0^d$).

Prove Claim

Expanding the square of the variance,

$$\begin{aligned}\mathrm{Var}_{r,b}[\hat{p}(z)] &= \frac{1}{2^{2d}} \sum_x q_x^2 + \frac{1}{2^{3d}} \sum_{x \neq y} q_x q_y \\ &= \frac{1 - \frac{1}{2^d}}{2^{2d}} \sum_x q_x^2 + \frac{1}{2^d} \left(\frac{1}{2^d} \sum_x q_x \right)^2 \\ &\leq \frac{1}{2^d} \left(\max_x q_x^2 + \bar{q}^2 \right) .\end{aligned}$$

By the indistinguishability condition,

$$\left(\max_x q_x \right) \leq (e^\epsilon - 1) p^* \leq \tilde{\epsilon} \cdot p(z) ,$$

$$\bar{q} \leq (e^\epsilon - 1) p^* \leq \tilde{\epsilon} \cdot p(z) .$$

Plugging this into the last equation proves Claim 1 .

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Applications

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