

Nerve, Cech, and Rips Complexes

Lecture 4 - CMSE 890

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Section 2.2 Goals

Goals for today:

- Complexes from point clouds: Rips & Čech complexes
- Sparse Complexes: Alpha complex

Recall: Geometric vs Abstract Simplicial Complex

- Given a collection of points $V \subseteq \mathbb{R}^N$
- For a subset of these $\{a_0, \dots, a_n\}$, a (geometric) n -simplex is the convex hull of the points.
- A simplicial complex is a collection of geometric n simplices so that
 - ▶ Every face of a simplex is also in the complex.
 - ▶ The intersection of any two simplices is either empty or a face of both.

- Given a finite set V
- An abstract simplex is a subset of V .
- An abstract simplicial complex is a set K of finite subsets of some V such that if $\sigma \in K$ and $\tau \subseteq \sigma$, then $\tau \in K$.

???

need extra info

forget

Section 1

Čech and Rips Complexes

Point cloud

A point cloud is a (finite) collection of points in a metric space (M, d) .

(general position)

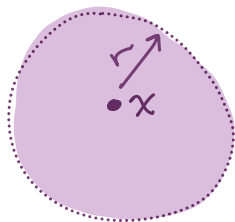
$$X = \{x_1, \dots, x_n\}$$

$$\hookrightarrow (\mathbb{R}^n, \|\cdot\|_2)$$

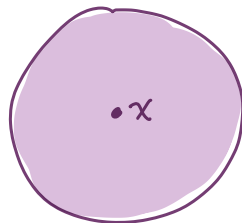


Ball

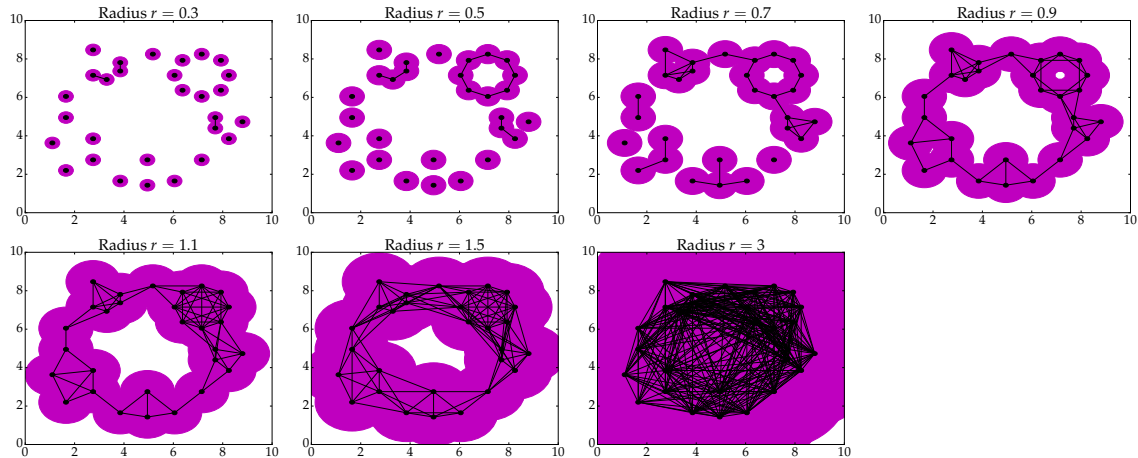
$$B_o(x, r) = \{y \in M \mid d(x, y) < r\}$$



$$B(x, r) = \{y \in M \mid d(x, y) \leq r\}$$



What we want to study

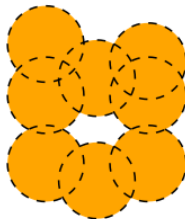


From last time: Nerve

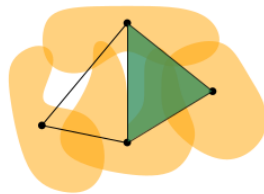
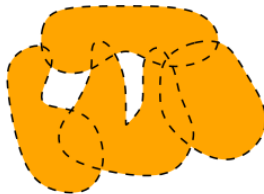
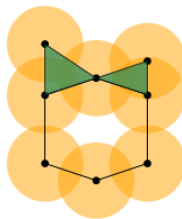
Given a finite collection of sets \mathcal{F} ,
the **nerve** is

$$\text{Nrv}(\mathcal{U}) = \{X \subseteq \mathcal{F} \mid \bigcap_{U \in X} U \neq \emptyset\}.$$

\mathcal{U}



$N(\mathcal{U})$



From earlier: Homotopy type

Definition

Two topological spaces T and U are homotopy equivalent if there exist maps $g : T \rightarrow U$ and $h : U \rightarrow T$ such that $h \circ g$ and $g \circ h$ are homotopic to the appropriate identity maps.

- *Intuition:* Can deform one space into the other.
- Example: Divide the alphabet into *equivalence classes*: collections of letters that are all homotopy equivalent to every other letter in their collection.



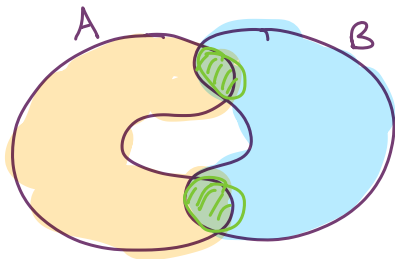
Semi-covered in lecture 2

Nerve lemma (Metric space version)

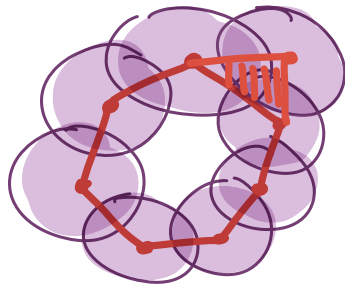
Theorem

Given a finite cover \mathcal{U} (open or closed) of a metric space M , the underlying space $|N(\mathcal{U})|$ is homotopy equivalent to M if every non-empty intersection $\bigcap_{i=0}^k U_{\alpha_i}$ of cover elements is homotopy equivalent to a point (contractible).

Yellow on last page



Does
not
satisfy
thm

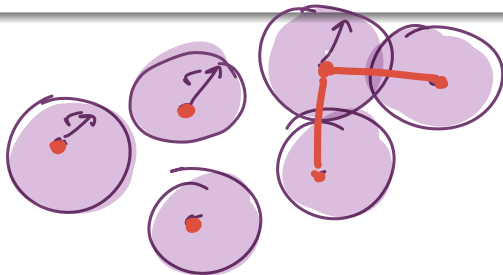


Čech complex

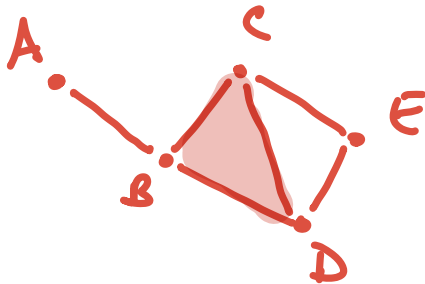
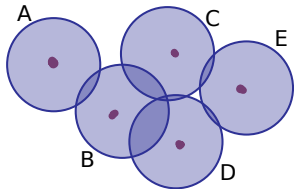
Definition

Let $P \subset (M, d)$ be a finite point cloud. Fix $r \geq 0$. The Čech complex is

$$\begin{aligned}\check{C}^r(P) &= \left\{ \sigma \subseteq P \mid \bigcap_{x \in \sigma} B(x, r) \neq \emptyset \right\} \\ &= \overset{Nrv}{\mathbb{X}}(\{B(x, r)\}_{x \in P})\end{aligned}$$

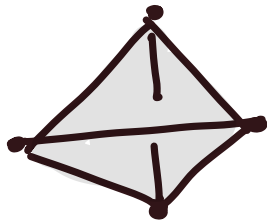
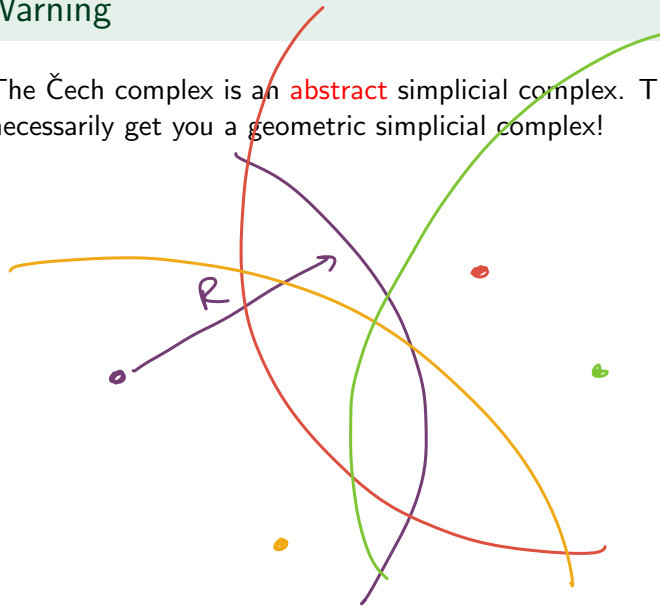


Example: Čech complex



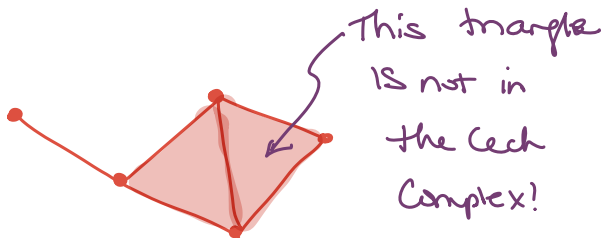
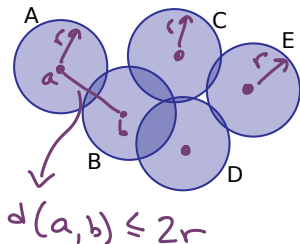
Warning

The Čech complex is an **abstract** simplicial complex. The obvious map into \mathbb{R}^N doesn't necessarily get you a geometric simplicial complex!

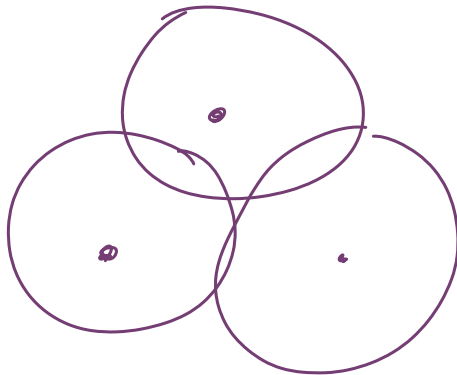
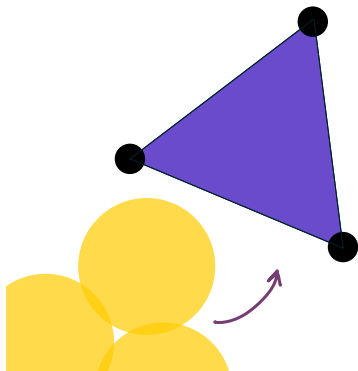


Example: Rips complex

$$VR^r(P) = \{\sigma \subseteq P \mid d(x_i, x_j) \leq 2r \text{ for all } x_i, x_j \in \sigma\}$$



Equilateral triangle example



Rips-Čech Lemma

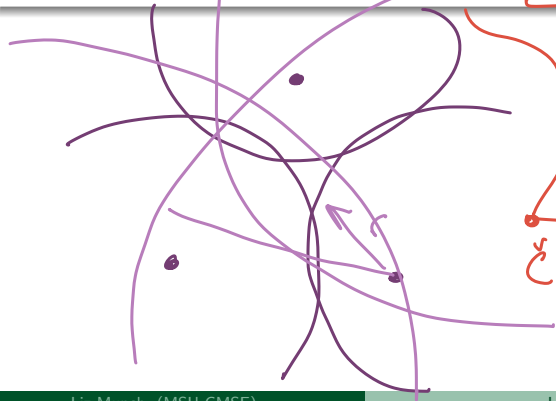
Theorem

Given point cloud $P \subset (M, d)$ and $r \geq 0$,

$$\check{C}^r(P) \subseteq VR^r(P) \subseteq \check{C}^{2r}(P)$$

"Topologically correct" representation

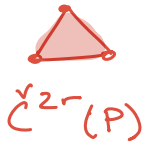
Computable



\subseteq

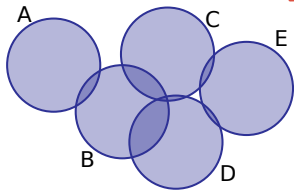


\subseteq



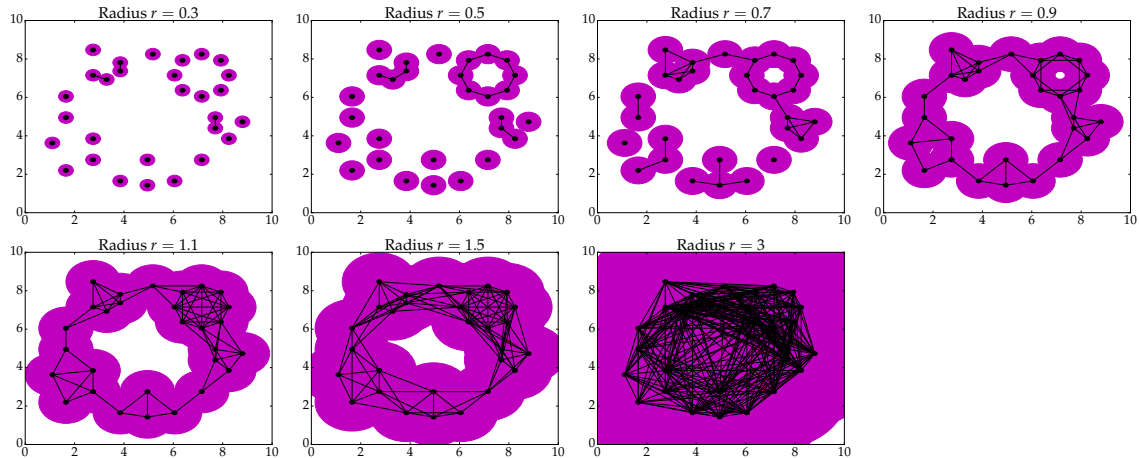
Warning: Radius vs diameter

$$VR^r(P) = \{\sigma \subseteq P \mid d(x_i, x_j) \leq 2r \text{ for all } x_i, x_j \in \sigma\}$$



$$VR^{\text{diam}}(P) = \{\sigma \subseteq P \mid d(x_i, x_j) \leq \text{diam} \forall x_i, x_j \in \sigma\}$$

What we want to study



Section 2

Alpha complex

Warning: Rips complexes can be VERY Big!

↳ Complete simplicial complex
Exponential size

Voronoi diagram

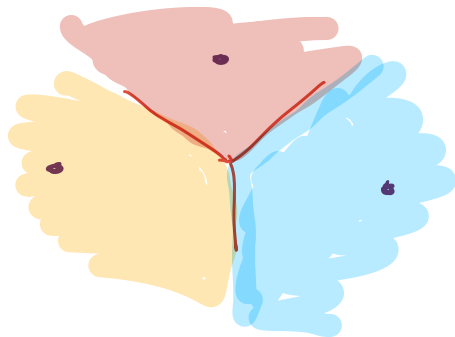
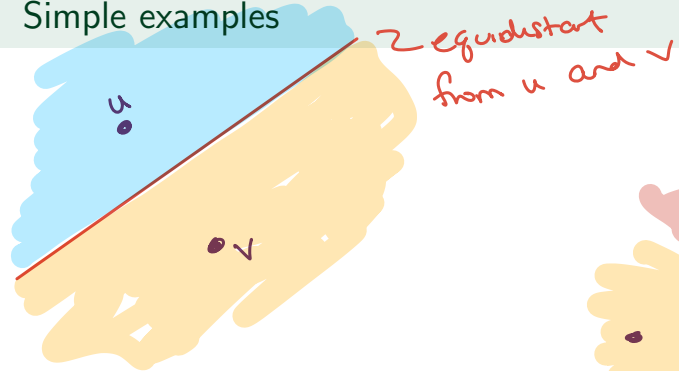
Given a point cloud $P \subseteq \mathbb{R}^N$.

The Voronoi cell of $u \in P$ is

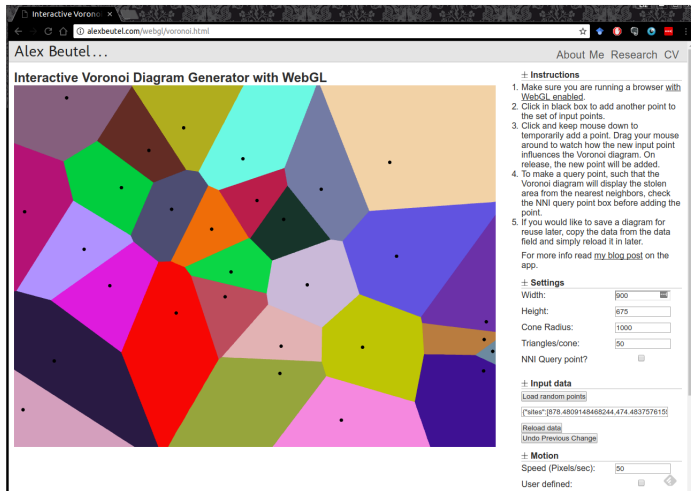
$$V_u = \{x \in \mathbb{R}^d \mid \|x - u\| \leq \|x - v\|, v \in P\}$$

The Voronoi diagram is the collection of Voronoi cells $\text{Vor}(P) = \{V_u \mid u \in P\}$.

Simple examples



<http://alexbeutel.com/webgl/voronoi.html>



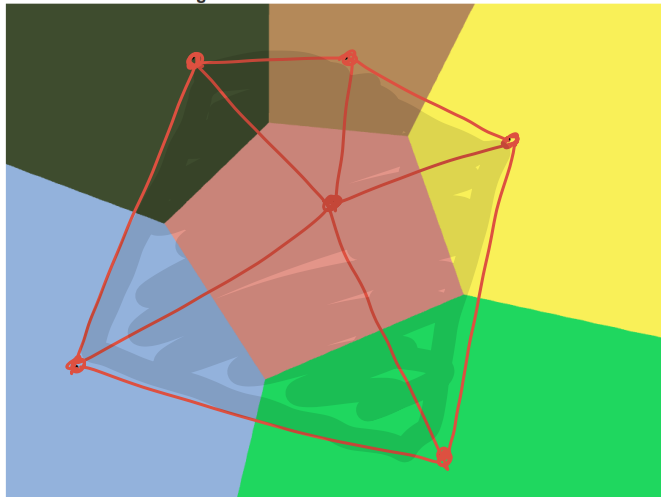
Delaunay triangulation

The Delaunay complex of point cloud $P \subseteq \mathbb{R}^N$ is the nerve of the Voronoi diagram.

$$\text{Del}(P) = \{\sigma \subseteq P \mid \bigcap_{u \in \sigma} V_u \neq \emptyset\}.$$

Example

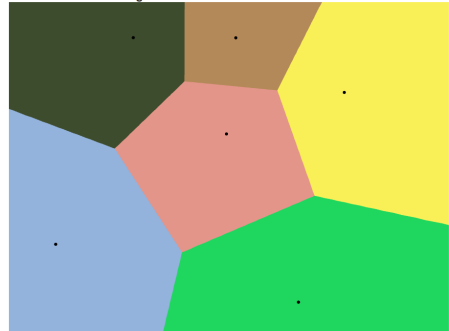
Interactive Voronoi Diagram Generator with WebGL



Properties

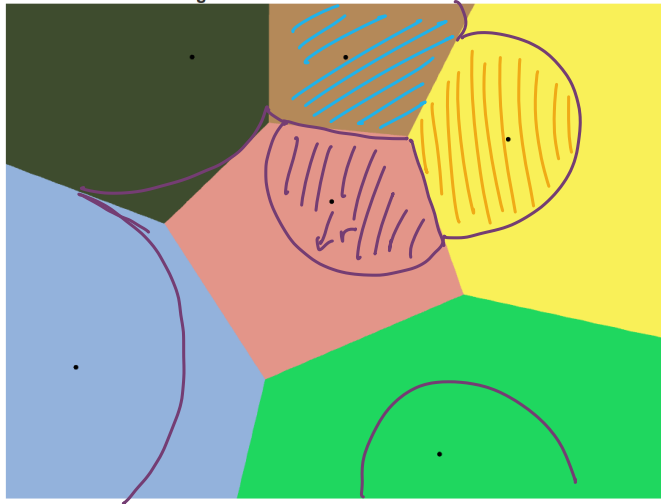
- Delaunay is an abstract simplicial complex.
- If we have points in general position, the obvious embedding gives a geometric simplicial complex.
- Delaunay is FIXED (has nothing to do with a radius or diameter parameter....)

Interactive Voronoi Diagram Generator with WebGL



Leading up to the alpha complex

Interactive Voronoi Diagram Generator with WebGL

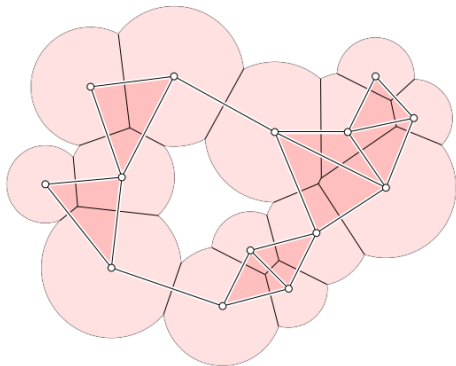


Alpha complex

$\text{Del}_p^\alpha = \{x \in B(p, \alpha) \mid d(x, p) \leq d(x, q) \text{ for all } q \in P\} = B(p, r) \cap V_p$

The alpha complex for point cloud P with radius $r \geq 0$ is the nerve

$$\text{Del}_p^\alpha = \text{Nrv}(\{D_p^\alpha \mid p \in P\}).$$



Properties

\check{C}
Delaunay

- $\text{Alpha}(r) \subseteq \text{Delaunay}$
- $\text{Alpha}(r) \subseteq \check{C}(r)$
- $\text{Alpha}(r)$ has the same homotopy type as the union of balls of radius r .

For next time

- EH III.7 (p75) Let $P \subseteq \mathbb{R}^d$ be a finite set of points in general position. Denote by $\check{C}(r)$ and $\text{Alpha}(r)$ as the Čech and alpha complexes for radius $r \geq 0$, respectively.

Is it true that $\text{Alpha}(r) = \check{C}(r) \cap \text{Delaunay}$?

If yes, prove the following two subcomplex relations. If no, give examples to show which subcomplex relations are not valid.

- 1 $\text{Alpha}(r) \subseteq \check{C}(r) \cap \text{Delaunay}$.
- 2 $\check{C}(r) \cap \text{Delaunay} \subseteq \text{Alpha}(r)$