

120



Differentiating velocity with respect to time allows for autocorrelation in time and spatially-varying drift in the model.

(Continuous Time Correlated Random Walk, Johnson et al. 2008)

Attention and location $\{X(t), Y(t)\}$,

$$\begin{bmatrix} \frac{dv_x(t)}{dt} \\ \frac{dv_y(t)}{dt} \end{bmatrix} = \beta \begin{bmatrix} (\mu_x - v_x(t)) \\ (\mu_y - v_y(t)) \end{bmatrix} + \sigma \begin{bmatrix} \frac{dW_{v_x}(t)}{dt} \\ \frac{dW_{v_y}(t)}{dt} \end{bmatrix}$$



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Instantaneous velocity at time t (damping force)



control station



Derivative of Brownian motion



We will numerically
approximate
(Euler-Maruyama)

Differentiating velocity with respect to time allows for autocorrelation in time and spatially-varying drift in the model.

At time t and location $\{X(t), Y(t)\}'$,

We will numerically approximate (Euler-Maruyama) \rightarrow

$$\begin{bmatrix} \frac{dv_x(t)}{dt} \\ \frac{dv_y(t)}{dt} \end{bmatrix} = \beta \begin{bmatrix} (\mu_x - v_x(t)) \\ (\mu_y - v_y(t)) \end{bmatrix} + \sigma \begin{bmatrix} \frac{dW_{v_x}(t)}{dt} \\ \frac{dW_{v_y}(t)}{dt} \end{bmatrix}$$

Annotations:

- Mean drift \rightarrow (points to μ_x)
- Instantaneous velocity at time t (damping force) \rightarrow (points to $v_x(t)$)
- Derivative of Brownian motion \rightarrow (points to $\frac{dW_{v_x}(t)}{dt}$)
- Controls autocorrelation \rightarrow (points to β)

(Continuous Time Correlated Random Walk, Johnson et al. 2008)

How can we understand this equation?

$$\begin{bmatrix} \frac{dv_x(t)}{dt} \\ \frac{dv_y(t)}{dt} \end{bmatrix} = \beta \begin{bmatrix} (\mu_x - v_x(t)) \\ (\mu_y - v_y(t)) \end{bmatrix} + \sigma \begin{bmatrix} \frac{dW_{v_x}(t)}{dt} \\ \frac{dW_{v_y}(t)}{dt} \end{bmatrix}$$