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How environmental tracking shapes species and communities in stationary and non-stationary systems

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1 Abstract

Climate change is reshaping the environments of all species. Predicting responses requires understanding the costs, benefits and constraints of how well species can track environmental change, and how such tracking shapes communities. Growing empirical evidence suggests that environmental tracking—how an organism shifts the timing of key life history events in response to the environment—is linked to species performance and is a structuring force of species and communities today. Here, we review current knowledge on tracking both in empirical data and through the lens of ecological theory. We provide a definition of environmental tracking that highlights both why it must be fundamentally related to fitness, and the challenges of defining it empirically. We then show how life history theory makes predictions for variation in tracking, and trade-offs with other traits, across species and environments. Finally, we examine how well basic community ecology theory can be extended to test the current paradigm that climate change should favor species with environmental tracking. We to aim provide a framework based on existing ecological theory to understand how tracking in stationary and non-stationary systems may shape species and communities and, thus, help predict the species- and community-level consequences of climate change.

17 Main text

Anthropogenic climate change is causing widespread changes in species distributions, with many species shifting in both time and space (IPCC, 2014). Reports often focus on species shifting 19 to higher elevations and poleward (Chen et al., 2011) and/or shifting their recurring life history 20 events (phenology) earlier as climate warms (Wolkovich et al., 2012; Cohen et al., 2018). These 21 general trends, however, hide high variability across species. A large proportion of species are 22 not shifting at all (Cook et al., 2012), which has raised concerns about whether these species may 23 be more vulnerable to population declines with continued warming. Such concerns come in part 24 from increasing research that links how well species track climate change—especially through 25 temporal shifts—to shifts in biomass, growth and other metrics related to performance (Cleland 26 et al., 2012). Tracking climate change may then be a major component to understanding and 27 predicting the indirect effects of climate change, including population declines, with cascading effects on community and ecosystem structure. 29

The hypothesis that tracking predicts fitness outcomes with climate change has gained significant traction in the ecological literature focused on global change (e.g., Cleland et al., 2012) and several areas of ecological theory support it. Considering tracking as a form of plasticity, evolutionary models predict species that track will be favored in novel environmental conditions. Similarly, some models of community assembly suggest that a warming climate should open up new temporal niche space and favor species that can exploit that space (Gotelli & Graves, 1996; Wolkovich & Cleland, 2011; Zettlemoyer et al., 2019). Yet not all studies find the purported link (e.g., Block et al., 2019), and there has been comparatively little work to improve predictions by formally connecting tracking to foundational ecological theory.

This disconnect could be because most ecological theory today is for stationary systems (e.g., Sale, 1977; Chesson & Huntly, 1997). While major arenas of research such as 'modern coexistence theory' or population ecology are now built on assumptions of a stochastic environment, they generally still assume stationarity, where the underlying distribution of the environment is unchanged across time (i.e., constant mean and variance, Barabas et al., 2018). This assumption is common to much of the theory that underlies ecology, evolution, and myriad other research fields (e.g., Milly et al., 2008; Nosenko et al., 2013).

Climate change upends the assumption of stationarity. By causing increases in temperature, larger pulses of precipitation, increased drought, and more storms (Stocker et al., 2013), climate change has fundamentally shifted major attributes of the environment from stationary to non-stationary regimes (see Fig. 1 and Box: Environmental variability & change). This transition is reshaping ecological systems, and, while new work has aimed to adapt coexistence theory to non-stationary environments (Chesson, 2017; Rudolf, 2019), there is still very little theoretical work on what such a transition may mean for communities and the species within them, despite growing empirical studies.

Here, we review current knowledge on tracking both in empirical data from the climate change impacts literature and through its related ecological theory. We provide a definition of environmental tracking that highlights why it must be fundamentally related to fitness and the complexity of defining it in empirical systems. We show how life history theory—specifically

drawing on optimal control, bet-hedging and plasticity—make predictions for variation in tracking across species and environments in stationary and non-stationary systems. We then examine how well basic community ecology theory can be extended to test the current paradigm that climate change should favor species with environmental tracking.

62 1.1 Defining environmental tracking

While tracking is a commonly used word in the phenology and climate change literature (e.g., Menzel et al., 2006; Cleland et al., 2012; Deacy et al., 2018), there are few, if any, definitions of it. Most interpretations of tracking relate to how well an organism matches the timing of a life history event to the ideal timing for that event, what we refer to as 'fundamental tracking'. Fundamental tracking thus rests on an assumption that there is a timing (an 'ideal timing') that yields maximum fitness, and event timings moving away from this ideal result in reduced fitness (a foundational concept of the trophic mismatch literature, Visser & Gienapp, 2019). Yet this ideal timing is generally only clear in simplified models or in retrospect, thus species must use environmental cues to attempt to predict and match their event timing to the ideal timing across environments in both space and time. Each organism's set of cues forms the biological basis for how a species tracks, but measuring environmental tracking requiers two more components.

The first component is the environment's variability—which aspects of the environment vary, how (e.g., temporally each year, spatially at x scale) and how much. If the varying components of the environment do not correspond closely to the organism's cues, then the species may not track this variability. Further, under this definition, identical genotypes will have different tracking across environments, depending on the interaction of the cues and environmental variability.

Second, which aspect(s) of the environment researchers measure will determine measured environmental tracking. If researchers know the exact cue (e.g., a thermal threshold) or suite of cues (e.g., a interaction of thermal sums and daylength) and can perfectly measure these in an environment where the cue(s) varies then an organism will track the environment perfectly. If researchers measure some related attribute (e.g., mean spring temperature in place of thermal sums) or only some of the organism's cues, then the organism will appear to track poorly (i.e., a noisier statistical relationship). If researchers measure an environmental variable that is not directly related to the cue(s) that the species actually uses, but one correlated with it (e.g., an insect tracks daylength but researchers measure temperature) then they have not measured tracking per our definition.

Accurately measuring environmental tracking thus requires a complete knowledge of an organism's cue(s), the environment's variability and the relationship between the actual cues and
measured environmental metrics. Knowing an organism's cues is inherently difficult, generally
requiring a suite of experiments, process-based models and in-situ data to show that the model
of cues is accurate. Not surprisingly then we lack this for almost all species, coming closest
for some model species (e.g., Arabidopsis thaliana, Kingsolver, 2007; Wilczek et al., 2009), or
species with very simple cues (e.g., coral Acropora millepora, Levy et al., 2007) and have some

basic information for some other species (e.g., the Great Tit, Parus major, Charmantier et al.,
 2008).

1.2 Measuring environmental tracking

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Attempting to measure environmental tracking and compare variation in it across species, space and time is a rapidly growing area of ecological research (e.g., Cook et al., 2012; Fu et al., 2015; 102 Thackeray et al., 2016; Cohen et al., 2018). Multiple meta-analyses now show plants' spring 103 phenology shifts with spring or annual temperatures 4-6 days/°C on average across species (Richardson et al., 2006; Wolkovich et al., 2012; Thackeray et al., 2016), but also highlight 105 high variation across species (Cook et al., 2012), even after examining multiple major climate 106 variables (Thackeray et al., 2016). Variability across species appears similar when examining 107 consumers tracking their prey (across diverse species tracking over time is 6.1 days/decade but 108 ranges from zero to 15 days/decade, see Kharouba et al., 2018). 109

All species-rich studies of phenology-climate relationships find high variation, including some 110 species that do not track or track poorly (i.e., high noise surrounding observed statistical 111 relationships). Researchers have worked to link such variation at times to the underlying cues 112 (e.g., Cook et al., 2012), species traits (e.g., Cohen et al., 2018) or trophic level (e.g., Thackeray 113 et al., 2016). These approaches hint at the three majors classes of reasons that underlie species 114 that do not appear to track climate (or appear to be poor trackers): (1) species do not track, 115 as perfect environmental tracking may either not be possible or optimal for all species, (2) lack 116 of firm biological understanding of the cues that underlie tracking, and (3) statistical artifacts 117 that make it difficult to measure tracking robustly. 118

Increasingly, research has outlined statistical difficulties in measuring tracking. These issues mostly relate to the challenges of observing phenological distributions (CITES) through anthropogenically defined temporal units (e.g., day or month) in non-stationary systems, and to the complexity of climate data (more further discussion, see Box 'Statistical challenges in measuring tracking').

Even without statistical issues, translating phenological and climate data into estimates of 124 tracking requires a firm biological understanding of an organism's cues, critical knowledge that researchers rarely have (Chmura et al., 2019). Currently, 'tracking' is often measured simply as 126 the relationship between the dates of the phenological event and a simple abiotic metric, such 127 as mean monthly temperature (with variation in temperature derived from multiple periods 128 of observation or induced through experiments). Simple environmental metrics, however, are 129 almost always proxies for a more complicated underlying physiology where simple cues—such 130 as warm temperatures—can be modified by other cues, such as photoperiod, drought or light spectra (Bagnall, 1993; Stinchcombe et al., 2004). Indeed, multiple studies have shown how sim-132 ple correlations between phenological events and environmental variables can mask complicated 133 relationships (Cook et al., 2012; Tansey et al., 2017). 134

Modeling multivariate cues well is inherently difficult (Chuine *et al.*, 2016), especially since one cue may dominate in many conditions. For example, woody plant leafout responds strongly to warm spring temperatures, but also to cool winter temperatures to prevent leafout in mid-

winter warm snaps that occur long before the last frost. Often this cool-temperature effect 138 may be masked by sufficiently cold conditions. With warming from climate change, however, 139 this additional trigger—which appears to vary by site, species and even inter-annual conditions 140 (Dennis, 2003)—may become critical (and potentially lead many phenological models to fail 141 spectacularly in the future as additional cues come into play, see Chuine et al., 2016). In some 142 semi-arid systems, species time growth to pulses of rain, but only when those rain events occur 143 with cooler temperatures that indicate the start of the rainy season, and not a rare summer 144 rainfall event in the middle of months of drought (Wainwright et al., 2012; Wainwright & 145 Cleland, 2013). Tracking in species with longer generation times may be especially complicated, 146 as species may track low frequency climate signals and make investment choices on far longer 147 timescales than species with shorter lifespans (Morris et al., 2008). 148

Researchers are increasingly recognizing the need to consider multiple climate variables, though currently most estimates are based on long-term observational data (e.g., Chmielewski *et al.*, 2013; Simmonds *et al.*, 2019), which can lead to sprurious correlations without experiments to test hypothesized cues (Chuine & Regniere, 2017). Further, estimates of 'tracking' from long-term data that are not linked to mechanistic experiments may sometimes serve as proxies (i.e., environmental variables correlated with one or more actual cue that a species uses) for an organism's environmental tracking, but may not directly connect to an organism's cue(s).

Limited understanding of organisms' phenological cues combined with statistical issues may make many current estimates of variation in tracking less reliable than they appear, and make robust quantitative analyses across species difficult (Brown et al., 2016; Kharouba et al., 2018). Yet these estimates provide the crucial first step to understand variation. As estimates improve, ecologists will better capture a picture of which species, when and where, do and do not track. Yet given the current difficulty of measuring environmental tracking, clear testable predictions from ecological theory are perhaps most critical to guide research today (Smaldino & McElreath, 2016).

1.3 Understanding variation in environmental tracking

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A number of research areas in ecology predict variation across species in how well they track the environment. Applying these areas of research to environmental tracking, however, first requires understanding phenological events. In particular, while phenological events are often coded as on/off switches (e.g., a seed does/does not germinate; a coral does/does not spawn), they are almost always defined by investment decisions that are part of a continuous developmental process (Inouye et al., 2019).

Phenological events are best considered as the outcome of a two-part sequential process that is repeatedly observed over time. At each temporal unit, an event can either happen or not (step 1) and, if it happens, there is a secondary part regarding the size or degree of investment of the event (step 2). This process is generally applied at the level of the individual (but it could potentially apply at lower levels, for example buds on a branch, or potentially higher levels, such as all the offspring from a parent). Across time, it produces an event's distribution. After starting, many events are entrained to continue based on the underlying physiological process: for example, laying eggs within one clutch (here, the first part of the process is whether to lay eggs or not and the second is whether to continue to invest in that process, which would lead to additional eggs, which researchers then observe as number of eggs per temporal unit) or flowering each growing season. In such cases, first events at the individual-level are somewhat unique from the rest of the event's distribution. In all cases, these individual-distributions scale up to the population-level estimates of these events generally used by researchers (see Inouye et al., 2019, for discussion of the outcomes of this scaling).

Considering the life history events that define part of environmental tracking as a two-part process highlights that tracking is ultimately shaped by resources that species need to grow 186 and reproduce, and circles back to an organism's fundamental tracking. This is perhaps best 187 recognized in the literature on trophic synchrony where there is often focus on how well con-188 sumers' environmental tracking matches to the seasonal distributions of their prey (Deacy et al., 189 2018; Kharouba et al., 2018). For example, decades of work has studied how birds (e.g., Parus 190 major) time their peak food demands—during their nesting season—to maximum prey (cater-191 pillar) abundance (e.g., Charmantier et al., 2008). Failure of environmental tracking to match 192 prey year-to-year or over time with long-term warming has been well tied to individual-level 193 fitness consequences in some systems (Charmantier et al., 2008), but not all (Visser et al., 194 2006), which may be due to the complexity of mechanisms that influence total fitness (Singer & 195 Parmesan, 2010; Johansson & Jonzen, 2012). Environmental tracking in plants and other lower trophic levels is also about resources. Alpine plant species that emerge in step with snowmelt or 197 temperature are likely responding, at least in part, to light resources for photosynthesis. Light 198 equally appears critical to the sequence of phenology in many temperate forests: with lowercanopy species, and younger (shorter) individuals of higher-canopy species, routinely risking 200 frost damage to leaf out before the canopy closes and access to light becomes severely reduced 201 (Vitasse, 2013; Heberling et al., 2019). These ultimate controllers on tracking—which deter-202 mine fundamental tracking—are then filtered through the abiotic environmental cues species 203 use to time events. From here, predicting tracking relates to predicting which cues an organism 204 should use: an optimal control problem.

206 Predicting variation in environmental tracking in stationary systems

An optimal control framing can help predict which cues an organism should have based on a consideration of the costs, benefits and constraints, in any one organism by environment system (Donahue *et al.*, 2015). First, it requires that benefits vary depending on the timing of event; this effect may be stronger in highly seasonal environments. Next, there must be a useful cue—some aspect of the environment that predicts resources or otherwise links to back to the ultimate factors that shape environmental tracking (Gremer *et al.*, 2016). Some environments may inherently lack useful predictors, such as desert systems where few early-season variables seem to predict high or consistent rainfall years.

From here, the exact cue or suite of cue(s) that an organism should have depends on the cost of those cues (e.g., the machinery of monitoring temperature or daylength), the benefits of a cue (for example, how much tissue is saved by avoiding a coldsnap). Ultimately the balance of the costs of cue(s) and their benefits should determine exactly what cue(s) a species uses: apparently poor cues may occur for organisms in environments where there is both a low cost

and low benefit to the cue(s). Similarly, expensive cues, such as complex multivariate ones, are
possible given a high pay-off. Most in-depth studies of species' phenological cues find evidence
for complex multivariate ones (Chuine & Regniere, 2017). These cues almost always appear
adapted to handle unusual—though not completely uncommon—years when the simple cue
alone would fail (that is, would trigger growth, reproduction or another life history event at a
suboptimal time), suggesting that multivariate cues may provide a large benefit in best coupling
the timing of cues to the ultimate controls (i.e., cues that couple environmental tracking strongly
to fundamental tracking).

Optimal control highlights that not all species should track, but instead that tracking is based 228 on an optimization of costs, benefits and constraints. In environments where there is no clear 229 optimal strategy, species should bet-hedge (de Casas et al., 2015). In general, species in highly 230 variable environments, or which otherwise face high uncertainty in when to time investment 231 decisions, should gain a substantial benefit from bet-hedging or employing other approaches that 232 spread out risk given uncertainty (Venable, 2007; Donaldson-Matasci et al., 2012). Assessing 233 bet-hedging in many systems, however, requires studies of fitness over longer timescales than 234 many current field experiments. 235

Constraints also shape cues and may limit tracking. Fundamental differences in life history im-236 pose constraints—for example, the type and amount of loss an organism can sustain each season 237 is limited by its generation time and other attributes related to long-lived lifestages that yield buffered population growth (Chesson & Huntly, 1997). Additionally, contraints may arise if a 239 species cannot closely measure relevant environmental cues (Arnold, 1992; Singer & Parmesan, 240 2010), through unavoidable trade-offs with tracking (Singer & Parmesan, 2010; Johansson & 241 Jonzen, 2012), or through evolutionary pathways. Gene flow from other environments may con-242 tinually push a population away from its local optimum (Lenormand, 2002), standing genetic 243 variation limits phenotypic variation and thus can slow the evolution of optimal cues (Franks 244 et al., 2007; Ghalambor et al., 2015), deeper evolutionary history may produce co-evolved traits 245 making it difficult for selection to act on a single trait axis (Ackerly, 2009), or other fundamental 246 evolutionary limits to the rates of trait change and what traits are possible (Gould & Lewontin, 247 1979). 248

49 Predicting variation in environmental tracking in non-stationary systems

Much of life-history theory, including optimal control and bet-hedging, rests on assumptions of 250 stationarity, thus a major open area of research is adapting life history theory to non-stationary 251 environments. Multivariate cues may be especially robust to a non-stationary environment if 252 they provide a tight coupling of cues to fundamental tracking, and that coupling is maintained 253 in the non-stationary environment (Dore et al., 2018). But multivariate cues may equally be 254 most vulnerable to failure if non-stationarity decouples the cues from fundamental tracking 255 (Bonamour et al., 2019). For example, consider an organism's whose cues evolved based on 256 a correlation between peak prey abundance and daylength—these cues may work well in a 257 stationary environment but fail if warming advances peak prey abundance. Predicting the 258 outcome of non-stationarity thus relies on knowing both the full cue system of an organism, 250 how it relates to fundamental tracking, and how both that cue system and the underlying fundamental model shift with non-stationarity. 261

Another area of life-history theory, that focused on plasticity, may be primed to provide insights 262 on non-stationarity (or 'sustained environmental change,' see Chevin et al., 2010). Considering 263 phenology as a trait (as we and others do, e.g., Charmantier et al., 2008; Nicotra et al., 2010; In-264 ouye et al., 2019), environmental tracking is one type of plasticity. Researchers could thus more 265 broadly understand environmental tracking through modeling an organism's reaction norms 266 (Pigliucci, 1998; Chmura et al., 2019) and understanding how cues and suites of cues—across 267 environments—determine how fundamentally plastic an organism may be in its tracking. For 268 example, multivariate cues should yield higher plasticity in this framework. From here, models 269 of the role of plasticity in novel environments provide an important bridge to understanding the 270 outcomes of non-stationarity, generally predicting non-stationarity should favor highly plastic 271 species. This outcome, however, assumes there are no costs related to plasticity (Ghalambor 272 et al., 2007; Tufto, 2015). If there are costs associated with plasticity, akin here directly to costs 273 associated with tracking, then species may evolve lower tracking, because it should trade-off 274 with other traits (Auld et al., 2010).

276 1.4 Tracking in multi-species environments

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Plasticity theory—in contrast to much of the life-history theory discussed above (where other 277 species are, at best, filtered into models as an aspect of the environment)—shows how critical 278 a multi-species perspective is to understanding environmental tracking (Metcalf et al., 2015). 279 In this light, tracking cannot be considered as a singular trait, but must be evaluated as part 280 of a trait syndrome (or mosaic of traits, Ghalambor et al., 2007) and selection in multi-species 281 environments should produce communities of species where tracking trades-off with other traits. 282 As tracking often relates to the timing of a resource pulse, traits related to resource acquisi-283 tion are likely contenders for a trade-off. Species with traits that make them poor resource 284 competitors may need to track the environment closely to take advantage of transient periods 285 of available resources, but will risk tissue loss to harsh environmental conditions more preva-286 lent early in the season (e.g., frost or snow). In contrast, species with traits that make them 287 superior resource competitors may perform well even if they track environments less closely, 288 because their resource acquisition is not strongly constrained by competitors. Examples in-289 clude under-canopy species leafing out earlier to gain access to light (Heberling et al., 2019) or 290 species with shallow roots starting growth sooner in an alpine meadow system, while species 291 with deeper roots begin growth later (Zhu et al., 2016). In such cases, tracking is akin to a 292 competition-colonization trade-off (Amarasekare, 2003), where species that track well gain pri-293 ority access to resources and, thus, may co-exist with superior competitors. Research to date 294 supports this, with several studies linking higher tracking to traits associated with being poor 295 competitors (Dorji et al., 2013; Lasky et al., 2016; Zhu et al., 2016). Further, many studies 296 have found a correlation between higher tracking and 'earlyness' each season, which has been 297 linked to resource acquisition traits associated with lower competitive abilities (Wolkovich & 298 Cleland, 2014, see Box 'Trait trade-offs with tracking'). 299

Understanding these trade-offs is clearly critical, but we also argue more theory is needed to understand the short-term dynamics of a changing environment and plasticity—most theory

predicts the outcome of a new environment, but non-stationarity in the climate today means further understanding of the trajectory to that outcome is most key. For example, models show 303 how plasticity may limit standing variation and thus reduce fitness in novel environments (Gha-304 lambor et al., 2007; Fox et al., 2019). Whether such findings extend to systems transitioning 305 from stationary to non-stationary will likely depend on how non-stationarity affects the rate 306 of adaptation (Chevin et al., 2010). Efforts to model expected outcomes given climate projec-307 tions and current understanding of plasticity and genetic variation underlying event timing in 308 some organisms provide the empirical start to this (e.g., Fournier-Level et al., 2016), but more 309 eco-evolutionary models that bridge this gap may prove especially useful. 310

311 Including tracking in multi-species community assembly models

Predicting how tracking may determine which species are effectively winners and losers with 312 climate change requires integrating non-stationary environments into models of plasticity and 313 community assembly. Recent advances in coexistence models, sometimes called 'modern coex-314 istence theory,' recognize that both mechanisms independent of fluctuations in the environment 315 (e.g., R* and other classical niche differences) and mechanisms dependent on fluctuations in 316 the environment (relative non-linearity and storage effect) can drive coexistence (Chesson & 317 Huntly, 1997; Chesson, 2000). These models, which underlie much of current community ecol-318 ogy research (Mayfield & Levine, 2010; Barabas et al., 2018; Ellner et al., 2019), provide a 319 framework to begin to model environmental tracking and non-stationarity.

How the environment is defined in most community models falls into two broad categories. In 321 some models the environment is expressed as variation in parameters related to species. For 322 example, in some lottery models the environment appears, effectively, as variation in birth and 323 death rates. Building a changing environment into such models thus requires knowing how 324 environmental shifts filter through to species-level parameters (Tuljapurkar et al., 2009). For 325 example, Rudolf (2019) added the temporal environment to competition models by defining 326 interaction strength as dependent on the temporal distance between species. In other models, 327 the environment is more specifically defined. Many of these models define the environment as a 328 resource (e.g., many seed germination models that begin with a resource pulse each year), and 329 thus generally model something close to fundamental tracking. Building a changing environment 330 into these models requires knowing how the environment is changing (see Box 'Environmental variability & change'). 332

Models that explicitly include the environment provide a major opportunity to predict how environmental tracking and non-stationarity determine future communities (see Box: Adding tracking and non-stationarity to a common coexistence model). Yet most current models generally examine the environment from only one of two important angles for tracking: they either represent the environment as used for species' cues (e.g., many models of plasticity) or they represent the environment as directly effecting fitness. Combining these two angles seems especially critical to understanding the costs and benefits of tracking in non-stationary environments.

Species responses to the (resource) environment are also be broadly grouped into two modeling camps: those that explicitly model when species start an event (e.g., spawning or germination) in response to the environment versus those that model the magnitude (e.g., the number of propagules or seeds) of response to the environment. Models that explicitly model when a

species starts an event are often focused on situations where order of arrival is critical to predicting coexistence outcomes. Models of priority effects through niche pre-emption highlight 345 the advantage tracking may provide when it allows species to be early (and when there is no 346 cost to being too early): early arrivals receive a head-start advantage, by gaining priority 347 access to resources (the environment) they can draw down the resources available to later 348 arrivals (Fukami, 2015). Other models canalize species' responses to the environment into 349 production and investment. For example most models of inter-annual competition (much of 350 'modern coexistence theory') fall into this camp. Species produce (via offspring, tissue etc.) 351 differentially depending on the environment each year and outcomes are mediated through 352 density. While these models superficially may seem disconnected from timing, they critically 353 highlight how phenology relates to production and, thus, investment in future years (in contrast, 354 priority effect models explicitly model timing). 355

A model where species vary both when they start an event and how much they produce de-356 pendent on the environment would capture the important attributes of tracking—combining 357 head-start advantages from being early with production variation based on the fitness of the 358 environment. To our knowledge, however, most models approach these questions separately, 359 though models of bet-hedging come closest (Gourbiere & Menu, 2009; Tufto, 2015). A model 360 that explicitly models the linked decisions of when to time an event and how much to off-361 spring/tissue to produce in the event could provide fundamental insights on the relative impor-362 tance of each aspect of this process. Such a model could be adapted to address multiple questions 363 of environmental tracking, including how these decisions may trade-off and which other traits 364 tracking may be most strongly linked to, as well as explicitly modeling the costs and benefits of 365 tracking in stationary systems, a critical precursor to extending it to non-stationary systems. 366

Extending models to non-stationary systems is crucial to fully testing how environmental track-367 ing relates to species persistence with climate change, and research has already begun to tackle 368 this non-trivial challenge (Chesson, 2017; Legault & Melbourne, 2019; Rudolf, 2019). Most work 369 to date, however, focuses on conclusions from stationary or non-stationary systems. Thus, the 370 transition between stationary and non-stationary is often ignored, yet we expect it may be most 371 critical. Communities formed in stationary environment periods (or periods with environments 372 lower non-stationarity) are effectively filtered and assembled by that environmental regime and 373 thus produce the base variation and assembly dynamics for a shifting environment. While an-374 alytical solutions for systems transitioning from stationary to non-stationary may take time to 375 develop (Chesson, 2017), simulation work can provide an immediate intuition and framework to address this challenge (see Box: Adding tracking and non-stationarity to a common coexistence 377 model). 378

379 1.5 Future directions

Growing empirical research highlights that environmental tracking is linked to species performance and, thus, may be critical to understanding the forces that assemble communities and determine species persistence—especially as anthropogenic climate change is reshaping the environment of all species. Ecological theory, including from areas of optimal control, plasticity

and community assembly, is clearly primed for understanding how a variable environment can shape the formation and persistence of species and communities. To understand what advances in theory may be most useful for making predictions in the Anthopocene we need more focus on understanding the attributes of an environment shaped strongly by humans. In turn, to test theory we need more robust estimates of environmental tracking and how it fits within a mosaic of other correlated traits. To this aim, we review several major areas of research that we believe could most rapidly unite empirical and theoretical research in environmental tracking to advance the field.

How is an organism's environment changing?

Currently, much research has focused on one major shift in the climate system (earlier growing seasons), but research on multivariate environmental shifts is growing and will be critical to understanding how climate change affects an organism's whole environment. Ecologists can guide these efforts by identifying environmental shifts that are often linked (e.g., warming temperatures may drive earlier seasons and higher evaporative loss of some resources such as water). Researchers can also aim to more consistently and fully characterize the environmental distributions of their systems that appear to most drive species performance and interactions: the environment of the years of study should be clearly reported and compared against long-term and recent climate for each system.

More interdisciplinary research with climate science could also speed a fuller understanding of what shifts are and are not expected with climate change, and what climate variables are inherently correlated. Such correlations make estimating cues and other biological parameters from long-term data especially precarious (Tansey et al., 2017). But these correlations are equally critical in considering how species may view their environment and whether environmental change will couple or uncouple links between proximate cues and fundamental tracking (Bonamour et al., 2019).

Understanding and measuring 'tracking'

Understanding how the environment is changing represents just one step towards robust measures of environmental tracking. Shifting environmental regimes must then be filtered through species cues. As robust estimates of these cues are currently available for few if any species, we suggest several major improvements on current methods to help interpret current trends and make comparisons more feasible.

Studies should clarify their definition of tracking, how the environment is defined and how well, or not, the underlying cue system is understood for study species. Currently, many studies examine fundamental and environmental tracking at once (e.g., Yang & Cenzer, 2020), which is clearly helpful in advancing the field. However, the more researchers can clarify when and how they are addressing fundamental tracking versus environmental tracking the more easily we can compare across studies. Next, and relatedly, studies should define their environment: are they considering primarily the abiotic environment or measuring an environment fundamentally shaped by other species? This difference connects to fundamental versus realized niches and whether systems are primarily top-down (resources and the environment may be strongly shaped

by other species) or bottom-up controlled. Finally, all researchers working on environmental tracking need to embrace their inner-physiologist, or collaborate with one. For many species 427 there is often a related species (albeit, sometimes distantly) whose cue system has been studied. 428 Thus, researchers should draw on the literature of their study species' close relatives to bracket 429 which environmental variables may represent environmental tracking and which may be proxies, 430 and to highlight uncertainty. We expect progress will come from a balance between measures of 431 fundamental tracking, estimating an organism's system of cues, and measuring environmental 432 tracking. Clear statements of what is and is not known and measured will help. 433

Embrace the sometimes contradictory pulls of conducting experiments to identify mechanistic 434 cues and the multivariate climate of the real world. Clearly, we need more experiments to 435 identify which specific aspects of the environment different species cue to and how these cues 436 are filtered by their actual environmental regime (as outlined above and see Chmura et al., 437 2019). Suites of experiments, which build from identifying cues to understanding how they act 438 when correlated, are a major gap for most organisms. 439

Build a model of your species' cues and interrogate it. As research progresses in trying to estimate environmental tracking, greater progress will come from fuller and more diverse interrogations of current (and future) models. Define the framework under which you expect your cue system developed or works (e.g., bet-hedging) then test how well it works, and where it fails (see Johansson & Bolmgren, 2019, for an example). Model interrogation can also use realistic environmental regimes to provide field predictions (Wilczek et al., 2010, 2009) or predict future species and communities. One example of this comes from in silica resurrection experiments of model organisms where future environmental regimes included a mix of regular climate projections and projections modified to test and advance understanding of environmental tracking for the study species (e.g., warmer winter and altered photoperiod scenarios in Fournier-Level et al., 2016). 450

What major traits trade-off with tracking?

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Basic theory of plasticity and competition suggest that environmental tracking must trade-off 453 with other traits to allow multi-species communities. Yet to date empirical work has mainly 454 documented tracking, linked it to performance, or focused on how it varies between native 455 and non-native species (Willis et al., 2010; Wolkovich et al., 2013; Zettlemoyer et al., 2019). 456 Such work lays the groundwork that environmental tracking is important, but future empirical 457 research should address how this trait co-occurs with other traits. Research has highlighted some traits that co-vary with tracking (e.g., Kharouba et al., 2014; Lasky et al., 2016; Zhu 459 et al., 2016), but to tie this empirical work to models requires more research on traits that link 460 clearly to theory, and a fuller understanding of how tracking and other traits jointly contribute 461 to performance under varying environments. 462

Traits that link to resource competition, as we focus on here (as others have as well, see Rudolf, 2019), may be especially fruitful for greater research, but should not be the only ones con-464 sidered. For example, traits related to predator tolerance or avoidance may also play a role, 465 but have been effectively unstudied. As empirical research in this area grows, models can aid progress in understanding the outcomes of these trade-offs for community assembly. 467

Developing new models for tracking in stationary to non-stationary systems 469

As outlined above many areas of ecological and evolutionary modeling contribute to our under-470 standing of environmental tracking. But most are limited in various ways. Community ecology 471 models generally bifurcate in modeling differenes in timing versus production amounts across 472 species, thus studies of whether these models lead to similar or different conclusions could help 473 predict community outcomes and advance our understanding of trade-offs. As outlined above, 474 understanding tracking likely requires models that combine effects. This includes models that 475 combine effects of variation in timing and production amounts and models that include environ-476 ment as impacting species' cues, as well as species' fitness. Such models would explicitly allow 477 the potential costs and benefits of tracking depending on how closely environmental tracking 478 matches fundamental tracking. 479

New models will also need to examine how relaxing assumptions of closed communities (i.e., 480 without dispersal or evolution) alter predictions. In practice, dispersal of species or individuals 481 with traits that make them better matched to the non-stationary environment would lead to new 482 communities that may persist longer or be continually re-assembled as long as the environment 483 remains non-stationary. Indeed, this logic underlies the argument that invasive species may 484 be superior trackers benefiting from how climate change has altered growing seasons (Willis 485 et al., 2010; Wolkovich & Cleland, 2011). Evolution equally could alter predictions by allowing 486 species traits to evolve in step with environmental change. Long-term population (e.g., Colautti 487 et al., 2017) and resurrection studies (Wilczek et al., 2014; Yousev et al., 2018), as well as 488 field experiments (Colautti et al., 2017; Exposito-Alonso et al., 2019), have repeatedly shown 489 species can shift to earlier flowering times, higher thermal tolerances or related genetically-490 controlled traits that confer higher fitness in warmer climates. Yet these studies also highlight 491 that responses can be lagged (e.g., Wilczek et al., 2014), associated with reduced population 492 viability (e.g., Colautti et al., 2017), or other factors that may constrain adaptive responses

Stationarity in the future 1.6 494

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While most environments today are climatically non-stationary and have been for decades, 495 the climate will return to stationarity in the future. There are many possible pathways to 496 climatic stabilization, but almost all require first the stabilization of greenhouse gases—the 497 subject of much policy and political debate. Once greenhouse gas emissions stabilize climate 498 will not quickly snap back to a new stationary phase. Instead systems will slowly approach a 499 new climatic stationarity depending on how they are effected by the earth's multiple thermal 500 reservoirs, and, in turn, how quickly those reservoirs stabilize. The timescale of this approach is 501 generally expected to be on the scale of centuries, but could be much longer in certain oceanic 502 systems (Collins et al., 2013). Thus, ecologists are—and will remain for the forseable future—in 503 a research area structured by climatic non-stationarity. 504

As paleobiologists and evolutionary biologists often point out, climatic nonstationarity is a 505 common part of the earth's history (Jansson & Dynesius, 2002)—even if stationary periods— 506 be they cold or warm (glacial and interglacial periods)—are more common. Indeed, while much of this work has examined how species survive for millions of years given large oscillations in climate (Provan & Bennett, 2008), the periods that provide the most dramatic community reshuffling are periods shifting from stationary to non-stationary climate regimes (Vrba, 1980, 1985). Such stories of the past are now fundamentally happening today, and ecology is challenged to understand how transitions between stationary and non-stationary environments are reshaping the species and communities we have today and will in our warmer future.

⁵¹⁴ 2 Acknowledgments

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3 **Boxes** 519

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3.1 Box: Environmental variability & change

Decades of ecological research highlight how temporally variable environments shape species and 521 their communities at multiple scales (Sale, 1977; Chesson & Huntly, 1997). In seasonal land-522 scapes, the environment limits periods for growth each year (e.g., by temperature or drought); 523 within-year variability in the environment (e.g., daily, hourly or finer resolution temperatures 524 or rainfall amounts) compounds into inter-annual variability that shapes the distribution of 525 the start and end of growing seasons. For long stretches of history this variability has been 526 effectively stationary; that is, the underlying probability distribution that describes the start 527 (or end) of the season (e.g., the date of the last major frost) does not change, even though the 528 date may be dramatically different from one year to the next. 529

In other time periods, variability has been non-stationary in one or multiple dimensions. For ex-530 ample, climate in the northern hemisphere includes long warming and then cooling periods (i.e., 531 increasing then decreasing means of the probability distribution) at the start of the Holocene, 532 when the earth was coming out of the last glacial maximum. Anthropogenic climate change is 533 a similar non-stationary process, with warming evident around the globe and knock-on effects 534 for other climate metrics, such as heat extremes and the size of precipitation events. 535

Understanding non-stationarity in ecological systems requires first identifying which aspects of 536 the environment have shifted—and how they have shifted with respect to one another—as the 537 underlying distributions transition from stationary to non-stationary (Fig. 1). For example, 538 with climate change, warming has increased mean temperatures over time, with minimum temperatures generally increasing more than maximum—this results in an underlying distribution 540 for daily temperature where the mean is increasing through time while the within-day vari-541 ance is decreasing (Stocker et al., 2013; Screen, 2014). Understanding the impacts of climate change further requires recognizing that many systems can be considered stationary or non-543 stationary depending on the timescale and period of study. Thus, predicting the consequences 544 of current non-stationarity in ecological systems benefits from identifying the type and scale of non-stationarity, relative to long-term trends. 546

3.2 Box: Statistical challenges in measuring tracking

A potentially widespread reason for observations of species that do not track is statistical bias 548 and artifacts, including non-stationarity in units and unrecognized low power. All of these can 549 be addressed given improved statistical approaches (e.g., Gienapp et al., 2005; Pearse et al., 550 2017), though such approaches may (uncomfortably) highlight how uncertain many current 551 estimates are (Brown et al., 2016). Non-stationarity in units comes in many forms—estimates 552 of mean days shifted per decade (i.e., days/decade, a common metric summarizing observed 553 shifts in phenology over time in long-term datasets) depend strongly on the climate of the 554 decade(s) studied, which is not consistent in many systems (Ault et al., 2011; McCabe et al., 555 2012). Estimates based on a relevant climate variable can sometimes ameliorate this problem, 556 but may be equally vulnerable to non-stationarity in units (e.g., Sagarin, 2001). For example, processes that depend on thermal sums reported as days/°C will generally appear to decline with warming, as the thermal sum of an average day has increased in most regions with climate change. Relatedly, estimates of long-term change using simple linear regression are influenced by the climate at the start of the time-series (with greater changes seen from time-series that started in unusually cold decades, such as the 1950s for much of North America). Impacts of start-years for long-term time-series can be muted by applying change-point or hinge models (e.g., Kharouba et al., 2018), while metrics that move away from calendar units (e.g., day) can help address non-stationarity in units.

Low power is widespread in ecology, where even 'long' time-series may be far too short for 566 robust analyses (Bolmgren et al., 2013; Kharouba et al., 2018). Authors should be especially 567 cautious if they find only large effects appear significant (e.g., CaraDonna et al., 2014), which is a well-known statistical bias associated with p-values (Loken & Gelman, 2017). Additionally, 569 effect sizes that are higher when climate variability is higher (for example, in temperate habitats 570 temperature is highly variable in the spring and autumn compared to summer) may be more 571 related to variation in statistical power than to biology (periods with higher variation yield 572 greater variation in the predictor variable, and thus higher power). Mixed models can help 573 better leverage understanding by pooling information across species, and often better capture 574 uncertainty (Pearse et al., 2017). We suggest mixed models should be used more widely along-575 side randomization and/or data-simulation approaches (e.g., Bolmgren et al., 2013; Kharouba 576 et al., 2018) to better estimate and communicate uncertainty in studies. And researchers should 577 identify what results bias may produce. For example, growing evidence suggests a potential 578 fundamental trade-off where early species track and possess a suite of traits to related to faster 579 growth and shorter lifespans, while later species track less and possess traits related to slower 580 growth and longer lifespans—these later species may bet-hedge more given their longer invest-581 ment window. This, however, could equally be an artifact where early species use simpler cues, 582 and, thus, their tracking is measured more accurately given current methods. 583

584 3.3 Box: Trait trade-offs with tracking

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Research on phenological tracking and traits has increased greatly in recent years, with a 585 major uptick in studies after 2010 (see SI Fig. S1). Most papers examining tracking and 586 other traits across species have focused on plants (20/30), followed by birds and Lepidoptera 587 (both 4/30), plankton and aphids (both 1/30). The most studied trait was how early or late a 588 phenophase occurred (e.g., date of flowering of start of migration for a species, termed 'earlyness' 589 by some authors), with earlier species tending to track more (studies included both birds and 590 Lepidotera, Diamond et al., 2011; Ishioka et al., 2013; Kharouba et al., 2014; Jing et al., 2016; 591 Du et al., 2017). While this is an important link, it is vulnerable to statistical challenges (see 592 Box 'Statistical challenges in measuring tracking'). Few studies examined whether tracking 593 correlates with resource acquisition traits; those that did generally found species with higher 594 tracking also had traits associated with lower competitive abilities under low resources (e.g., 595 being shallower or lacking a taproot rooted Dorji et al., 2013; Lasky et al., 2016; Zhu et al., 596 2016). These species were often also early (e.g., Dorji et al., 2013; Zhu et al., 2016), suggesting 597 tracking may relate to a syndrome of traits that allow species to be rapid colonizers each season, 598

but poor competitors for resources. Indeed, previous work has documented that species with earlier phenophases tend to have resource acquisition traits associated with lower competitive abilities (e.g., they tend to be of lower height, have shallower roots, narrower diameter vessels, thinner leaves, and grow faster, reviewed in Wolkovich & Cleland, 2014).

603 3.4 Box: Adding tracking and non-stationarity to a common coexistence model

To understand the role of environmental tracking by species in variable environments we use a simple model that allows within- and between-year dynamics to contribute to coexistence. 606 As the model is akin to many commonly used seed germination models (Chesson et al., 2004), 607 we follow a similar terminology for ease; however the basic structure of our model could apply 608 to other systems with one dominant (non-renewing) pulse of a limiting resource each season 609 (e.g., water from rain or snowpack), or a multivariate resource pulse that acts effectively as 610 one resource (e.g., nitrogen and light drawn down together over the season). In this model 611 the environment is included between-years via variable germination, and within-years the en-612 vironment is explicitly included as a resource pulse at the start of the season. We adjust the 613 biological start time of species (τ_i for species i) to also allow species to respond to the envi-614 ronment dynamically through what we refer to as tracking. Here, tracking effectively moves a 615 species intrinsic start time closer to the environmental start time in that year, resulting in a 616 higher germination fraction (see SI for complete description and equations). 617

Species can co-occur via equalizing mechanisms, but they require stabilizing mechanisms to coexist. Species that is, cannot coexist given only variation in tracking—coexistence requires variation in another trait axis. As theory and empirical work suggest this trade-off may involve traits related closely to resource competition, we varied species' R^* . With variation in tracking and in R^* species can persist together as long as those species with a temporal niche advantage are also the inferior competitors (Fig. 2). That is, species that can draw resources down to a lower level and are thus the superior within-season resource competitors (lower R^*) can persist with species with that are inferior competitors but have realized biological start times closer to the environmental start time—a finding inline with currently observed empirical trade-offs (see Box 'Trait trade-offs with tracking'). These trade-offs, however, are all environmentally dependent. They hold only so long as the environment is stationary.

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We examined how trade-offs may be transformed by a non-stationary environment, by transitioning a stationary environment—in which two-species communities had persisted for 500 years—to non-stationary, via an earlier start of season (earlier timing of the resource pulse, τ_p , Fig. 2a; see SI for more details). By changing a fundamental niche axis (the distribution of the environment, an axis along which these communities were structured), we shifted one major part of the trade-off: the new non-stationary environment favored an earlier start time than the previous stationary environment. This, in turn, reshaped our two-species communities, which depended on this trade-off for persistence.

While the non-stationary environment favored higher trackers (who in turn drove the extinction of species with lower tracking values from many two-species communities) some two-species

communities persisted (257 out of 1698 two-species communities persisting after end of station-639 ary, or 15.1%, Fig. 2). These two-species communities persisted because the same fundamental 640 trade-off between biological start time and within-season competitive ability, while narrowed, 641 was not fully lost (Fig. 2). Taken together, these simple simulations show how non-stationarity 642 can drive local species extinction and reshape the underlying assembly mechanisms of commu-643 nities. 644

Our simulations support growing work that tracking should not be considered alone (Diamond 645 et al., 2011; Dorji et al., 2013; Ishioka et al., 2013; Kharouba et al., 2014; Du et al., 2017), but 646 may be part of a larger trait syndrome. Indeed, this model trivially show that multi-species 647 communities cannot form given only variation in the temporal niche—a trade-off is required. 648 Our results thus support empirical work showing a trade-off where trackers are also inferior 649 resource competitors (Lasky et al., 2016; Zhu et al., 2016)—we show this must be the case for 650 multi-species persistence; otherwise, the species best matched to the environment would drive 651 the other extinct. 652

Finally, our results highlight that non-stationarity may reshape the balance of equalizing versus 653 stabilizing mechanisms. As environments shifted from stationarity to non-stationarity, species that co-occured via equalizing mechanisms persisted longer. While the outcome that equalized 655 species will be more similarly affected by environmental shifts is rather obvious, it has several 656 important implications. First, it may make identifying which traits climate change promotes through stabilizing mechanisms more difficult. Second, it suggests climate change—or other 658 factors that cause an environment to shift from stationary to non-stationary—may cause a 659 fundamental shift away from assembly via stabilizing mechanisms. Thus understanding the prevalence of stabilizing versus equalizing mechanisms (which ecology has worked on for many 661 decades, Caswell, 1976; Chesson, 2000) becomes critical for understanding the implications of 662 transitions to non-stationary environments.

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664 4 Figures

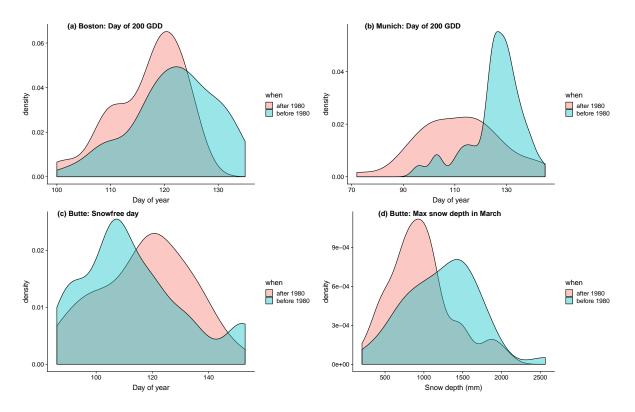


Figure 1: Examples of non-stationarity in climate variables linked to environmental tracking: shifts before and after 1980 (a major change-point in climate for many regions) in several metrics related to the start of growing seasons (a-c) or resource pulse connected to growing season length (d). Density plots of day of 200 growing degree day units (a metric of thermal sum, here based on 0 degree base temperature using daily minima in °C) in Boston, MA, USA (a), and Munich, Germany (b), first snowfree day (followed by at least 9 snowfree days) in Crested Butte, CO, USA (c) and maximum snowdepth (mm) in March (often the month before the first snowfree day) in Crested Butte, CO, USA (d). Note that (c) and (d) are likely related, with lower snowpacks leading to an earlier first snowfree day. We selected sites that have been studied for plant phenological data and included at least 80 years of daily climate data from a Global Historical Climatology Network site; we subsetted data so that there were 40 years before and after 1980 for all sites.

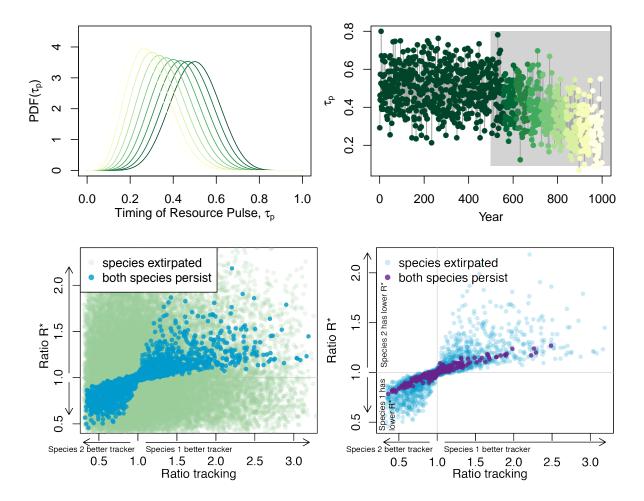


Figure 2: Example of how non-stationarity can reshape communities in a simple model. We shifted the environment (top panels) by changing the timing of the resource pulse from a stationary period ($\tau_p \sim \beta(10,10)$ for the 500 years) to a nonstationary period ($\tau_p \sim \beta(5,15)$ over the 500 years), then examined outcomes for two-species communities (bottom panels) where tracking (X axis: species 1/species 2) trades off with R^* (Y axis: species 1/species 2): each point represents one two-species community color-coded by whether both species persisted or one or more species was extirpated through 500 years of a stationary environment (bottom-left), followed by an additional 500 years of non-stationary environment (bottom-right, only two-species communities that persisted through the stationary period are shown).

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