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How phenological tracking shapes species and communities in non-stationary environments

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Abstract

Climate change reshapes the environments of all species. Predicting species responses requires understanding how well species can track environmental change, and how such tracking shapes communities. Growing empirical evidence suggests that how species track environmental change phenologically—how an organism shifts the timing of major biological events in response to the environment—is linked to species performance and is a structuring force of species and communities today. Such research tantalizingly suggests a potential framework to predict the winners and losers of climate change, and the future communities we can expect. But developing this framework requires far greater efforts to ground empirical studies of phenological tracking in relevant ecological theory.

Here, we review the concept of tracking in empirical studies and through the lens of coexistence theory in community ecology. We argue that much current theory for tracking ignores the importance of a multi-species context beyond trophic interactions. Yet community assembly theory predicts competition should drive variation in tracking and trade-offs with other traits. Existing community assembly theory can help us understand tracking in stationary and non-stationary systems and, thus, predict the species- and community-level consequences of climate change. But it will require greater efforts to integrate priority effects into modern coexistence theory and improved empirical estimates of environmental change, phenological tracking and underlying environmental cues.

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1 Introduction

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to tracking.

Anthropogenic climate change is causing widespread changes in species distributions, with many species shifting in both time and space (IPCC, 2014; Hoegh-Guldberg et al., 2018). Species are moving to higher elevations and poleward (Chen et al., 2011), shifting their recurring life history events (phenology) earlier (Wolkovich et al., 2012; Cohen et al., 2018), or both as climate warms (Amano et al., 2014; Socolar et al., 2017). These general trends, however, hide high variability across species. A large proportion of species are not shifting (Cook et al., 2012; Amano et al., 2014), which has raised concerns about whether these species may be more vulnerable to population declines with continued warming. Such concerns come in part from increasing research that links how well species track climate change by shifting their 10 phenology to changes in biomass, growth and other metrics related to performance (Cleland 11 et al., 2012). Tracking may then be a major component to understanding and predicting the fitness consequences of climate change, including population declines, with cascading effects on community and ecosystem structure (Menzel et al., 2006; Parmesan, 2006). The hypothesis that tracking improves fitness outcomes with climate change has gained significant traction in the ecological literature (e.g., Cleland et al., 2012) and several areas of 16 theory support it. Niche models of community assembly suggest that a warming climate should 17 open up new temporal niche space and favor species that can exploit that space (Gotelli & Graves, 1996; Wolkovich & Cleland, 2011; Zettlemoyer et al., 2019). However, there has been 19 comparatively little work connecting tracking to community assembly theory. Yet theory shows 20

This disconnect could be because most ecological theory was constructed for stationary systems (e.g., Chesson & Huntly, 1997). While major arenas of research such as 'modern coexistence theory' or population ecology now embrace environmental stochasticity, they generally still assume stationarity, where the underlying distribution of the environment is unchanged across time (i.e., constant mean and variance, Barabas et al., 2018).

temporal sequencing and environmental variability can alter the relative fitness and niche differ-

ences between species that determine coexistence—suggesting important ecological constraints

Climate change upends the assumption of stationarity. By causing increases in temperature, larger pulses of precipitation, shifts in snowpack, increased drought, and more storms (Stocker et al., 2013), climate change has fundamentally shifted major attributes of the environment from stationary to non-stationary regimes (see Fig. 1). This transition is reshaping ecological systems. New work has aimed to adapt coexistence theory to non-stationary environments (Chesson, 2017; Rudolf, 2019). Yet there is still little theoretical work on what such a transition may mean for communities and the species within them, including how community-level processes might feedback to modify species responses.

Here, we review the concept of phenological tracking as commonly used in the empirical climate change impacts literature and in related ecological theory. We begin by providing the necessary definitions to link empirical estimates to ecological theory: specifically we distinguish between measuring tracking in current environments and evaluating the fitness outcomes of tracking. After a brief review of current estimates of tracking, and basic theory that predicts variation in tracking across species and environments, we examine how well community assembly theory—especially priority effects and modern coexistence theory—can be extended to predict the community consequences of climate change. We close by reviewing the major hurdles to linking empirical estimates of phenological tracking and new ecological theory in the future.

46 2 Defining & measuring tracking

47 2.1 Phenological events

Understanding the role of phenological tracking in community assembly first requires an understanding of phenological events. In empirical studies in climate change today, phenological events are often coded as on/off switches (e.g., a seed does/does not germinate; a coral does/does 50 not spawn), yet these events are almost always defined by investment decisions that are part of 51 a continuous developmental process (Chuine & Regniere, 2017; Inouve et al., 2019)—a critical distinction to help understand the forces that shape phenological tracking, and, in turn, how it 53 may structure communities with climate change. Phenological events can be considered as the outcome of a two-part process that is repeatedly observed over time. At each temporal unit, an event can either happen or not (when—part 1) and, if it happens, the event can vary in size or degree of investment (how much—part 57 2). This process is generally applied at the level of the individual (but it could potentially apply at lower levels, for example buds on a branch, or potentially higher levels, such as all the offspring from a parent). Across time, it produces an event's distribution (Gotelli & Graves, 1996: Steer et al., 2019). After starting, many events are entrained to continue based on the underlying physiological process: for example, laying eggs within one clutch (here, the first part of the process is whether to lay eggs or not and the second is whether to continue to invest in that process, which would lead to additional eggs, which researchers then observe as number of eggs per temporal unit) or flowering each growing season. In such cases, first events at the individual-level are somewhat unique from the rest of the event's distribution. In all cases, these individual-level distributions scale up to the population-level estimates of these events generally used by researchers (see Inouye et al., 2019, for discussion of the outcomes of this scaling). Variation in these events forms the basis of phenological tracking.

0 2.2 Defining tracking

Tracking is a commonly used word in studies of how phenology is shifting with climate change (e.g., Menzel et al., 2006; Parmesan, 2006; Cleland et al., 2012; Deacy et al., 2018). Yet there are few, if any, definitions of it. Conceptual and theoretical treatments of tracking often relate how well an organism matches the timing of a life history event to the ideal timing for that event, what we refer to as 'fundamental tracking.' In contrast, empirical studies of tracking often focus on estimating a change in the timing of an event relative to a measured environmental variable, with the aim of measuring what we refer to as 'environmental tracking' (Fig. 2-3)—the phenological change due to an organism's cue system given change in the environment (though

9 most studies lack the required knowledge of the underlying cue system, Chmura et al., 2019).

Fundamental tracking rests on an assumption that there is a timing (an 'ideal timing') that
yields maximum fitness, and event timings moving away from this ideal result in reduced fitness
(a foundational concept of the trophic mismatch literature, Visser & Gienapp, 2019). Yet this
ideal timing is generally only clear in simplified models or in retrospect, thus species must
use environmental cues to attempt to predict and match their phenology to the ideal timing
across environments in both space and time (Fig. 2); this match between ideal timing and
actual timing if often referred to as cue reliability (Donaldson-Matasci et al., 2012; Bonamour
et al., 2019). Each organism's set of cues forms the biological basis for how a species tracks the
environment.

An organism's cues combined with the environment's variability—which aspects of the environment vary, how (e.g., temporally each year, spatially at x scale) and how much—determine what we refer to as 'environmental tracking' (Fig. 3)—the phenological change due to an organism's cue system given change in the environment. While fundamental tracking forms the focus of most conceptual and theoretical treatments of phenological tracking, the majority of empirical studies focus on estimating environmental tracking.

Our definition of environmental tracking is sufficiently exact to be something that can be accurately modeled, but its exactness also highlights the difficulty of measuring it. If the varying 96 components of the environment are not in the organism's set of cues, then the organism does 97 not 'track' per this definition (although covariation with other environmental components might 98 give the appearance of tracking). Which aspect(s) of the environment researchers measure will determine their estimates of environmental tracking. If researchers know the exact cue (e.g., a 100 thermal threshold) or suite of cues (e.g., a interaction of thermal sums and daylength) and can 101 perfectly measure these in an environment where the cue(s) varies, then an organism will track 102 the environment perfectly. If researchers measure some related attribute (e.g., mean spring 103 temperature in place of thermal sums) or only some of the organism's cues, then the organ-104 ism will appear to track poorly (i.e., a noisier statistical relationship from poor measurement quality). Most empirical studies, however, lack the required knowledge of the underlying cue 106 system (Chmura et al., 2019), making most current estimates difficult to evaluate. 107

108 2.3 Measuring tracking

Measuring 'tracking' and comparing variation in it across species, space and time is a rapidly 109 growing area of ecological research (e.g., Cook et al., 2012; Fu et al., 2015; Thackeray et al., 110 2016; Cohen et al., 2018). Studies that directly quantify fundamental tracking are uncommon 111 (but see Visser et al., 2006; Charmantier et al., 2008), given in part the difficulty of estimating 112 fitness, though many studies in the synchrony literature attempt to link consumer change to 113 resource change, with an assumption that the measured resource is the dominant determinant of ideal timing for the consumer (though this may rarely be true, see Singer & Parmesan, 115 2010: Johansson & Jonzen, 2012: Reed et al., 2013). Instead, most studies focus on estimates 116 closer to environmental tracking. Some studies estimate simply change in days over time (e.g., 117 Parmesan, 2007; Kharouba et al., 2018), though most studies now estimate shifts as responses per unit temperature (for example, multiple meta-analyses show plants' spring phenology shifts with spring or annual temperatures 4-6 days/°C on average across species, Richardson *et al.*, 2006; Wolkovich *et al.*, 2012; Thackeray *et al.*, 2016) or precipitation (Inouye *et al.*, 2002; Craine *et al.*, 2012).

All species-rich studies of phenology-climate relationships find high variation (Cook et al., 2012; Thackeray et al., 2016), including some species that do not track or track poorly (i.e., 124 high noise surrounding observed statistical relationships). Researchers have worked to link such 125 variation to the underlying cues (e.g., Cook et al., 2012), species traits (e.g., Cohen et al., 2018) and trophic level (e.g., Thackeray et al., 2016). These approaches hint at the three majors 127 explanations for why some species do not appear to track climate or appear to track poorly: 128 (1) environmental tracking is either not possible or optimal for all species or in all environments 129 (discussed below in 'Tracking in single-species environments') (Simons, 2011), (2) researchers 130 have measured the wrong environmental variable (i.e., a variable species do not track, Chmura 131 et al., 2019), and (3) statistical artifacts that make it difficult to measure tracking robustly 132 (discussed below in section 'Robust comparable measures of phenological tracking'). 133

These confounding factors may make many current estimates of interspecific variation in tracking less reliable than they appear. This in turn makes robust quantitative analyses across species difficult (Brown et al., 2016; Kharouba et al., 2018), yielding a muddy picture of which species, when, and where, do and do not track. Given this difficulty, clear testable predictions from ecological theory would be especially valuable in guiding the field forward (Smaldino & McElreath, 2016).

¹⁴⁰ 3 Tracking in single-species environments

Community assembly theory provides a major paradigm to predict and understand variation in phenological tracking. Like most of ecology it builds upon theory from evolutionary biology of when and where tracking should evolve. Thus, before discussing models of community assembly, we review briefly foundational evolutionary theory for single-species systems (where most work has focused, but see ADDCITES).

146 3.1 Predicting variation in environmental tracking in stationary systems

Evolutionary models predict selection for tracking in heterogeneous—yet predictable—environments 147 where there are cues for the ideal timing of events (Piersma & Drent, 2003; Reed et al., 2010) 148 and the underlying genetics to develop a heritable cue system (tracking is likely strongly heritable, given that many cue systems are themselves heritable e.g., van Asch et al., 2007; Wilczek 150 et al., 2010). The predictability of the environment via relevant cues that an organism can 151 monitor is particularly critical for irreversible plastic traits, which includes many phenological 152 traits, and must exist at an appropriate timescale for an organism to monitor and respond 153 to. Given such a predictable environment, the strength of selection is then determined by the 154 costs and benefits of cues (Donahue et al., 2015). The costs include the machinery an organ-155 ism uses to monitor its environment (e.g., accumulated temperature or daylength), while the 156

benefits are the increases in fitness gained from better timing (e.g., how much tissue is saved 157 by avoiding a coldsnap). Selection, however, can be lower than expected from reaction norms 158 predicted by simple evolutionary models for many reasons, including trade-offs with tracking 159 (Singer & Parmesan, 2010; Johansson & Jonzen, 2012), gene flow from other environments that 160 may continually push a population away from its local optimum (Lenormand, 2002), limits due 161 to standing genetic variation (Franks et al., 2007; Ghalambor et al., 2015), or deeper evolution-162 ary history that may produce co-evolved traits making it difficult for selection to act solely on 163 tracking (Ackerly, 2009). 164

Apparently poor cues may occur for organisms in environments where there is both a low cost and low benefit to the cue(s). Whereas expensive cues, such as complex multivariate systems, are possible given a high pay-off. Most in-depth empirical studies of species' phenological cues find evidence for complex multivariate systems that appear adapted to handle unusual—though not completely uncommon—years (Chuine & Regniere, 2017). This suggests that multivariate cues may better couple environmental tracking to fundamental tracking, while simple cues are more likely to trigger growth or reproduction at a suboptimal time.

Tracking should generally not be favored in unpredictable environments (e.g., when early season climate cannot be used to predict later season climate), or environments where species otherwise 173 face high uncertainty in the timing of investment decisions. Instead theory suggests the optimal 174 strategy may often be to bet-hedge (Venable, 2007; Donaldson-Matasci et al., 2012; de Casas et al., 2015) via a high diversity of timings or a conservative timing. Because bet-hedging, 176 by definition, maximizes geometric-mean fitness in the long-run, its short-term outcomes can 177 appear maladaptive. How often observed 'maladaptations,' which may easily include species 178 that do not track or appear to track poorly, are actually the outcome of bet-hedging is difficult 179 to estimate, as robustly assessing bet-hedging requires studies of fitness over longer timescales 180 than many current field experiments (Simons, 2011). Environmental variation, however, is 181 rarely simply predictable or not; it more often includes both predictable and less predictable 182 aspects. In such cases theory predicts organisms may evolve tracking that is a mixed strategy 183 between bet-hedging and plasticity (Wong & Ackerly, 2005). 184

Evolutionary theory, which integrates over the sometimes hidden costs and benefits of particular cue systems and considers environmental predictability, thus provide multiple reasons species may not track or track weakly. This suggests that—even in simple single-species stationary systems—we should expect a number of species that do not track.

189 3.2 Predicting variation in environmental tracking in non-stationary systems

A major open area of research is whether conclusions derived from evolutionary theory developed for stationary systems extend to non-stationary systems (Chevin *et al.*, 2010). In regards to phenological tracking a major question is whether tracking should be more or less favored in non-stationary environments.

One approach to this focuses on cue systems and makes predictions based on whether cue systems maintain their reliability with change; i.e., whether they consistently yield high fundamental tracking (Bonamour *et al.*, 2019). Consider a simple case in which an organism's cues

evolved based on a correlation between peak prev abundance and daylength: in a stationary 197 environment the daylength cue may be fairly reliable (generally predicting peak prey abundance 198 based on daylength, with some interannual variation), but would become unreliable, and lead 199 to fitness declines, if warming continually advances peak prey abundance. Multivariate cues are 200 often argued to be more reliable because they can capture multiple attributes of the environ-201 ment (Dore et al., 2018; Bonamour et al., 2019), but they may be equally vulnerable to failure 202 if non-stationarity decouples the cues from fundamental tracking (Bonamour et al., 2019) and 203 thus optimal fitness is no longer associated with the cue system. Under this framework, pre-204 dicting whether tracking is more or less favored in non-stationary environments requires that 205 researchers know: (1) the full cue system of an organism, (2) how it relates to fundamental 206 tracking, and (3) how both that cue system and the underlying fundamental model shift with a 207 changing environment. Given this high bar for prediction, researchers have also worked towards 208 more general predictions based on models of trait evolution. 209

In recent years plasticity theory has developed to provide insights on non-stationarity (or 'sustained environmental change,' see Chevin et al., 2010). Models of the role of plasticity in novel environments provide an important bridge to understanding the outcomes of non-stationarity, generally predicting non-stationarity should favor highly plastic species. At the individual level, environmental tracking is a plastic response, and thus this theory would predict greater individual tracking in non-stationary environments. This outcome, however, assumes there are no costs related to plasticity (Ghalambor et al., 2007; Tufto, 2015). If there are costs associated with tracking (as discussed above in stationary systems), then species may evolve lower tracking (Auld et al., 2010). Further, such findings may not hold if ecological dynamics reshape the environment as systems transition from stationary to non-stationary. The importance of such short-term dynamics of a changing environment with plastic species highlights how much we need—and yet how little we have—ecological theory for tracking.

4 Tracking in multi-species environments

Life history theory often ignores other (non-focal) species or abstracts them as an aspect of 223 the environment. While the trophic mis-match literature has addressed this gap for trophic 224 interactions (Visser & Both, 2005; Visser & Gienapp, 2019), there is little consideration of 225 competitive coexistence. Yet competition is a driving force of community assembly (Hutchinson, 226 1959: Chesson, 2000) and critical to understanding environmental tracking (Metcalf et al., 227 2015). Considering how selection in multi-species environments is structured by competition 228 highlights that tracking cannot be considered as a singular trait, but must be evaluated as part of a trait syndrome (or mosaic of traits, Ghalambor et al., 2007) and should ultimately produce 230 communities of species where tracking trades-off with other traits. 231

232 4.1 Trait trade-offs with tracking

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As tracking often relates to the timing of a resource pulse, traits related to resource acquisition are likely contenders for a trade-off. Species with traits that make them poor resource com-

petitors may need to track the environment closely to take advantage of transient periods of 235 available resources, but will risk tissue loss to harsh environmental conditions more prevalent early in the season (e.g., frost or snow) and thus may need to be more stress tolerant. In 237 contrast, species with traits that make them superior resource competitors may perform well 238 even if they track environments less closely, because their resource acquisition is not strongly 239 constrained by competitors. Examples include under-canopy species leafing out earlier to gain 240 access to light (Heberling et al., 2019) or species with shallow roots starting growth sooner in an 241 alpine meadow system, while species with deeper roots begin growth later (Zhu et al., 2016). In 242 such cases, tracking is akin to a competition-colonization trade-off (Amarasekare, 2003), where 243 species that track well gain priority access to resources and, thus, may co-exist with superior 244 competitors. 245

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To examine support for a competition-tracking trade-off in the empirical literature we reviewed research on phenological tracking and other traits (see Supplement 'Literature review of studies examining tracking & other traits' for search terms and additional methods). This research area has increased greatly in recent years, with a major uptick in studies after 2010 (see Fig. 4). Most papers examining tracking and other traits across species focused on plants (20/30), followed by birds and Lepidoptera (both 4/30), plankton and aphids (both 1/30). The most studied trait was how early or late a phenophase occurred (e.g., date of flowering, or start of migration for a species, termed 'earlyness' by some authors), with earlier species tending to track more (studies included both birds and Lepidotera, Diamond et al., 2011; Ishioka et al., 2013; Kharouba et al., 2014; Jing et al., 2016; Du et al., 2017). This correlation between higher tracking and 'earlyness' each season has been linked to resource acquisition traits associated with lower competitive abilities (e.g., they tend to be of lower height, have shallower roots, narrower diameter vessels, thinner leaves, and grow faster, reviewed in Wolkovich & Cleland, 2014), but our review found few studies that directly examined whether tracking correlates with resource acquisition traits. Those that did generally found species with higher tracking also had traits associated with lower competitive abilities under low resources (e.g., being shallower rooted or lacking a taproot, Dorji et al., 2013; Lasky et al., 2016; Zhu et al., 2016). These species were often also early (e.g., Dorji et al., 2013; Zhu et al., 2016), supporting the hypothesis that tracking may relate to a syndrome of traits that allows species to be rapid colonizers each season, but poor competitors in lower-resource periods.

Including tracking in multi-species community assembly models 4.2

Predicting how tracking may determine which species are winners and losers with climate change 267 requires integrating non-stationary environments into models of community assembly. Recent 268 advances in coexistence models, sometimes called 'modern coexistence theory,' recognize that 269 both mechanisms independent of fluctuations in the environment (e.g., R* and other classical 270 niche differences) and mechanisms dependent on fluctuations in the environment (relative non-271 linearity and storage effect) can lead to coexistence (Chesson & Huntly, 1997; Chesson, 2000). 272 These models, which underlie much of current community ecology research (Mayfield & Levine, 273 2010; Barabas et al., 2018; Ellner et al., 2019), provide a framework to begin to integrate tracking and non-stationarity into community ecology theory. 275

How the environment is defined in most community models falls into two broad categories. In some models the environment is expressed as variation in species' parameters. For example, 277 in an early formalization of the lottery model (Chesson & Warner, 1981), the environment ap-278 pears as interannual variation in birth and death rates. In later generalizations of competitive 270 coexistence in temporally-varying environments, including the storage effect model (Chesson & 280 Huntly, 1997), the environment is formalized as the 'species response to the environment' (E_i) , 281 which translated environmental variation into the common currency of species' low density per 282 capita growth rates. Building a changing environment into such models thus requires knowing 283 how environmental shifts filter through to species-level parameters (Tuljapurkar et al., 2009) to 284 impact fundamental tracking. For example, storage effect models predict shifts in communities 285 when environmental change alters the long-term covariance between the environment and com-286 petition (i.e., decreasing $cov(E_i, C_i)$), leading to a decrease in the storage effect as a means of 287 competitive coexistence. In another example, Rudolf (2019) added the temporal environment 288 to competition models by defining interaction strength as dependent on the temporal distance between species. This is somewhat similar to models that include the environment effectively 290 through different levels of asynchrony (e.g., Nakazawa & Doi, 2012; Revilla et al., 2014). 291

In other models, the environment is more specifically defined as a resource (e.g., seed germination models where an explicit resource pulse each year initiates germination) and models something close to fundamental tracking. Models that explicitly include the environment provide a major opportunity to predict how tracking and non-stationarity determine future communities. As an example, we modeled a shift to earlier growing seasons using a common coexistence model where the environment is defined as a limiting resource that determines the start of growth each year.

299 4.3 Adding tracking and non-stationarity to a common coexistence model

To show how resource-based coexistence models can be adapted to study tracking in non-300 stationary environments we used a simple model that allows within- and between-year dynamics to contribute to coexistence. As the model is akin to many commonly used seed germination 302 models (Chesson et al., 2004), we follow a similar terminology for ease here; however the basic 303 structure of the model could apply to other systems with one dominant (non-renewing) pulse of 304 a limiting resource each season (e.g., water from rain or snowpack), or a multivariate resource 305 pulse that acts effectively as one resource (e.g., nitrogen and light drawn down together over 306 the season). In this model the environment is included between-years via variable germination, 307 and within-years explicitly modeled as a resource pulse at the start of the season. The timing of 308 the resource relative to each species' ideal timing determines how much each species germinates 309 each year, allowing us to include fundamental tracking. Specifically, in the model 'tracking' 310 moves a species intrinsic start time (τ_i for species i) closer to the environmental start time (τ_P), 311 resulting in a higher germination fraction—making it, effectively, a superior colonizer (see SI 312 for complete description and equations). 313

As with all coexistence models, species can co-occur via equalizing mechanisms, but require stabilizing mechanisms to coexist. Thus species cannot coexist given only variation in trackingcoexistence requires variation in another trait axis. Following the theory and empirical work reviewed above we included a trade-off between species' tracking and R^* (where species with lower R^* are superior competitors). With variation in tracking and in R^* species can persist together as long as those species with a temporal niche advantage are also the inferior competitors (Fig. 5). These trade-offs, however, are all environmentally dependent. They hold only so long as the environment is stationary.

We examined how trade-offs may be transformed by a non-stationary environment, by transitioning a stationary environment—in which two-species communities had persisted for 500 years—to non-stationary, via an earlier start of season (earlier timing of the resource pulse, τ_p , Fig. 5; see SI for more details). By changing a fundamental niche axis (the distribution of the environment, an axis along which these communities were structured), we shifted one major part of the trade-off: the new non-stationary environment favored an earlier start time than the previous stationary environment. This, in turn, reshaped our two-species communities, which depended on this trade-off for persistence.

While the non-stationary environment favored higher trackers (who in turn drove the extinction of species with lower tracking values from many two-species communities) some two-species
communities persisted (257 out of 1698 two-species communities persisting after end of stationary, or 15.1%, Fig. 5). These two-species communities persisted because the same fundamental
trade-off between biological start time and within-season competitive ability, while narrowed,
was not fully lost. Taken together, these simulations show how non-stationarity can drive local
species extinction and reshape the underlying assembly mechanisms of communities.

Our simulations support growing work that tracking should not be considered alone (Diamond et al., 2011; Dorji et al., 2013; Ishioka et al., 2013; Kharouba et al., 2014; Du et al., 2017), but may be part of a larger trait syndrome. Indeed, this model trivially shows that multi-species communities cannot form given only variation in the temporal niche—a trade-off is required. Our results thus support empirical work showing a trade-off where trackers are also inferior resource competitors (Lasky et al., 2016; Zhu et al., 2016)—this must be the case for multi-species persistence. Otherwise, the species best matched to the environment would drive the other extinct.

Additionally, our results highlight that non-stationarity may reshape the balance of equalizing 345 versus stabilizing mechanisms. As environments shifted from stationarity to non-stationarity, 346 species that co-occurred via equalizing mechanisms persisted longer. While the outcome that 347 equalized species will be more similarly affected by environmental shifts is rather obvious once 348 observed, it has several important implications. First, it may make identifying which traits 349 climate change promotes through stabilizing mechanisms more difficult. Second, it suggests 350 climate change—or other factors that cause an environment to shift from stationary to non-351 stationary—may cause a fundamental shift away from assembly via stabilizing mechanisms. 352

³⁵³ 4.4 Fundamental versus environmental tracking in multi-species models

Most current models—including the previous example—examine the environment from only one of two relevant perspectives: they represent the environment through its effects on fitness

(e.g., the storage effect model), or they represent the environment as used for species' cues (e.g., many models of plasticity). Combining these two perspectives, which connect to fundamental and environmental tracking, respectively, may be especially critical to understanding the costs, benefits and community outcomes of tracking in non-stationary environments.

Layered onto these different views of the environment is how species responses are defined. In general, species responses to the environment can be broadly grouped into models that explicitly 361 define when species start an event (e.g., spawning or germination) versus those that model the 362 magnitude of response (e.g., the number of propagules or seeds, as discussed above in 'Adding 363 tracking and non-stationarity to a common coexistence model'). Models that explicitly include 364 when a species starts an event are often focused on situations where order of arrival is critical. 365 For example, models of priority effects through niche pre-emption highlight the advantage tracking may provide when it allows species to be early: early arrivals receive a head-start 367 advantage, by gaining priority access to resources (the environment) they can draw down the 368 resources available to later arrivals (Fukami, 2015). Such models predict early-arriving species 369 to out-compete other species, unless there is a cost to being too early or there are trade-offs 370 with other species' traits (see Fig. 6). 371

Other models canalize species' responses to the environment into production and investment. 372 Most models of inter-annual competition (most explicit examples of 'modern coexistence the-373 ory,' e.g., Chesson et al., 2004; Angert et al., 2009) fall into this camp. Species produce (via investment in offspring, tissue etc.) differentially depending on the environment each year 375 and outcomes are mediated through density. While these models superficially may seem dis-376 connected from timing, they highlight how phenology often relates to production and, thus, 377 investment across years. Further, they almost always model the environment as a distribu-378 tion (see Fig. 6), which provides the opportunity for the environment to alter the competitive 379 environment each year and, thus, structure coexistence. 380

A model where species vary both when they start an event and how much they invest would capture the important attributes of fundamental tracking—combining head-start advantages from being early with production variation based on the resource environment. To our knowledge, however, most models approach these questions separately, though models of bet-hedging come closest (Gourbiere & Menu, 2009; Tufto, 2015).

4.5 Frontiers of community assembly models

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A model that explicitly includes the linked decisions of when to time an event and how much offspring/tissue to produce during the event could provide insights on the relative importance of each aspect of this process. Such a model could be adapted to address multiple questions of tracking, including how these decisions ('when' and 'how much') may trade-off and which other traits may be most strongly linked to tracking, as well as explicitly modeling the costs and benefits of tracking in stationary systems—a critical precursor to extending it to non-stationary systems.

Extending models to non-stationary systems is crucial to testing how environmental tracking relates to fundamental tracking and species persistence with climate change, and research has

already begun to tackle this non-trivial challenge (Chesson, 2017; Legault & Melbourne, 2019; Rudolf, 2019). Most work to date, however, focuses on conclusions from systems that are 397 initialized as non-stationary, ignoring the transition between stationary and non-stationary environments. Yet we expect this transition may be critical because communities formed in 390 stationary environments (or periods with lower non-stationarity) are effectively filtered and 400 assembled by that environmental regime and thus produce the baseline of variation and assembly 401 dynamics for a shifting environment. While analytical solutions for systems transitioning from 402 stationary to non-stationary may take time to develop (Chesson, 2017), simulation work can 403 provide an immediate intuition and framework to address this challenge. 404

Outcomes for such community assembly models also depend on how effectively closed commu-405 nities are. Dispersal of species or individuals with traits that make them better matched to the non-stationary environment would lead to new communities that may persist or be continually 407 re-assembled as long as the environment remains non-stationary. Indeed, this logic underlies the 408 argument that invasive species may be superior trackers benefiting from how climate change 409 has altered growing seasons (Willis et al., 2010; Wolkovich & Cleland, 2011). Evolutionary 410 responses could also rescue species with low plasticity. Long-term population (e.g., Colautti 411 et al., 2017) and resurrection studies (Wilczek et al., 2014; Yousey et al., 2018), as well as field 412 experiments (Colautti et al., 2017; Exposito-Alonso et al., 2019), have repeatedly shown species 413 can shift to earlier flowering times, higher thermal tolerances or related genetically-controlled 414 traits that confer higher fitness in warmer climates. Yet these studies also highlight that re-415 sponses can be lagged (e.g., Wilczek et al., 2014), associated with reduced population viability 416 (e.g., Colautti et al., 2017), and that other factors may constrain adaptive responses. 417

⁴¹⁸ 5 Linking empirical and theoretical research

Growing empirical research highlights that environmental tracking is linked to species perfor-419 mance and, thus, may be critical to understanding the forces that assemble communities and 420 determine species persistence, especially as anthropogenic climate change reshapes the environ-421 ment. We have outlined above how current community ecology theory could make advances 422 through models that combine effects of variation in timing and production amounts and mod-423 els that include the environment as impacting species' cues, as well as species' fitness. Such 424 models would explicitly include the potential costs and benefits of tracking depending on how 425 closely environmental tracking matches fundamental tracking. But to best test and develop 426 such models we need a greater understanding of how the environment is changing alongside 427 more robust estimates of environmental tracking and how it fits within a mosaic of correlated traits that determine individual fitness. 429

430 5.1 Defining an organism's environment changing

Currently, much research has focused on one major shift in the climate system (rising temperatures), but research on multivariate environmental shifts is growing and will be critical to understanding how climate change affects an organism's whole environment (e.g., Chevin & Lande, 2015). We can help guide these efforts by identifying environmental shifts that are often linked (e.g., Wadgymar et al., 2018). For example, warming temperatures may drive earlier seasons and higher evaporative water loss. Researchers can also aim to more consistently and fully characterize the environmental distributions of their systems that appear to drive species performance and interactions: the environment of the years of study should be clearly reported and compared against long-term and recent climate for each system.

More interdisciplinary research with climate science could also speed a fuller understanding
of what shifts are and are not expected with climate change, and what climate variables are
inherently correlated. Such correlations make estimating cues and other biological parameters
from long-term data especially precarious (Tansey et al., 2017). But these correlations are
equally critical in considering how species may view their environment and whether environmental change will couple or uncouple links between proximate cues and fundamental tracking
(Bonamour et al., 2019).

447 5.2 Robust comparable measures of phenological tracking

Understanding how the environment is changing represents just one step towards robust mea-448 sures of environmental tracking. Shifting environmental regimes must then be filtered through 449 species cues to impacts on growth and survival. Studies should clarify their definition of track-450 ing, how the environment is defined, how an event relates to fitness, and how well—or not—the 451 underlying cue system is understood. Currently, many studies examine fundamental and envi-452 ronmental tracking simultaneously (e.g., Visser et al., 2006; Charmantier et al., 2008; Cleland 453 et al., 2012; Yang & Cenzer, 2020), which is clearly helpful in advancing the field. The more 454 researchers can clarify when and how they are addressing fundamental tracking versus environ-455 mental tracking, however, the more easily we can compare results across studies. 456

Even with clearer definitions, progress in documenting and understanding empirical variation requires more robust estimates of phenological tracking. Increasingly, research has outlined statistical difficulties in measuring tracking, which may underlie many observations of species that do not track. These issues mostly relate to the challenges of: non-stationarity in units caused by using discrete (calendar) time, low power, and the complexity of climate data.

Non-stationarity in units comes in many forms—estimates of mean days shifted per decade 462 depend strongly on the climate of the decade(s) studied, which is not consistent in many systems 463 (McCabe et al., 2012). Estimates based on a relevant climate variable can sometimes ameliorate 464 this problem, but may be equally vulnerable to non-stationarity in units (e.g., Sagarin, 2001). 465 For example, processes that depend on thermal sums reported as days/°C will generally appear 466 to decline with warming, as the thermal sum of an average day has increased in most regions with climate change. Relatedly, estimates of long-term change using simple linear regression 468 depend on the climate at the start of the time-series (with greater changes seen from time-series 469 that started in unusually cold decades, such as the 1950s for much of North America). 470

Even 'long' time-series may be too short for robust analyses of trends (Bolmgren *et al.*, 2013).

Authors should be especially cautious if they find only large effects appear significant (e.g.,

CaraDonna *et al.*, 2014), which is a well-known statistical bias associated with p-values (Loken

& Gelman, 2017). Additionally, effect sizes that are higher when climate variability is higher (for example, in temperate habitats temperature is highly variable in the spring and autumn compared to summer) may be more related to variation in statistical power than to biology.

Many statistical issues can be addressed by improved statistical approaches (e.g., Gienapp 477 et al., 2005; Pearse et al., 2017), though such approaches may uncomfortably highlight how 478 uncertain many current estimates are (Brown et al., 2016) or reveal lower effect sizes. Impacts 479 of start-years for long-term time-series can be muted by applying change-point or hinge models 480 (e.g., Kharouba et al., 2018). We suggest mixed models should be used more widely alongside 481 randomization and/or data-simulation approaches (e.g., Bolmgren et al., 2013), and we need 482 models that can discriminate among confounding factors. For example, we reviewed above 483 growing evidence that suggests a potential fundamental trade-off where early species track, 484 grow fast and die young, while later species track less, grow slowly and live longer—this might 485 suggest later species bet-hedge more given their longer investment window. Or it could be 486 an artifact where early species use simpler cues, and, thus, their tracking is measured more 487 accurately given current methods. 488

Even without statistical issues, translating event date and climate data into estimates of tracking requires a firm biological understanding of an organism's cues, which we rarely have (Chmura 490 et al., 2019). Currently, 'tracking' is often measured as the relationship between the dates 491 of an event and a simple abiotic metric. Such measures, however, are almost always proxies for a more complicated underlying physiology where simple cues—such as warm temperatures 493 or snowpack—can be modified by other cues, such as photoperiod, drought or light spectra 494 (Bagnall, 1993; Stinchcombe et al., 2004). Modeling multivariate cues, however, is inherently 495 difficult (Chuine et al., 2016), especially since one cue may dominate in many conditions (and 496 potentially lead many phenological models to fail spectacularly in the future, see Chuine et al.. 497 2016). Tracking in species with longer generation times may be especially complicated, as 498 species may track low frequency climate signals and make investment choices on far longer 490 timescales than species with shorter lifespans (Morris et al., 2008). 500

Addressing these issues is possible if we embrace our inner physiologists, or collaborate with one, to develop models that explicitly include species' cues, and consider the framework under which we expect cue systems have evolved (e.g., bet-hedging). We then must interrogate these models to understand when they work and where they fail (see Johansson & Bolmgren, 2019, for an example). This approach can help embrace the contradictory pulls of conducting experiments to identify mechanistic cues and understanding how they are filtered through the multivariate climate of the real world (see Wilczek et al., 2010, 2009).

5.3 What major traits trade-off with tracking?

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Basic theory of plasticity and competition suggest that environmental tracking must trade-off with other traits to allow multi-species communities. Yet to date empirical work has mainly documented tracking, linked it to performance, or focused on how it varies between native and non-native species (Willis *et al.*, 2010; Wolkovich *et al.*, 2013; Zettlemoyer *et al.*, 2019). Research has highlighted some traits that co-vary with tracking (e.g., Kharouba *et al.*, 2014;

Lasky *et al.*, 2016; Zhu *et al.*, 2016), but to tie this work to models requires more research on traits that link clearly to theory, and a fuller understanding of how tracking and other traits jointly contribute to performance under varying environments.

Traits that link to resource competition, as we focused on here, may be especially fruitful for greater research, but should not be the only ones considered. For example, traits related to stress, predator tolerance and avoidance may also play a role, but have been effectively unstudied. As empirical research in this area grows, models can aid progress in understanding the outcomes of these trade-offs for community assembly.

522 6 Conclusions

While most environments today are climatically non-stationary and have been for decades, the 523 climate will return to a more stationary form in the future—likely some centuries after the stabilization of greenhouse gases (Collins et al., 2013). As paleobiologists and evolutionary 525 biologists often point out, climatic nonstationarity is a common part of the earth's history 526 (Jansson & Dynesius, 2002)—even if stationary periods—be they cold or warm (glacial and 527 interglacial periods), or dry or wet (e.g., megadroughts or pluvials)—are more common. Indeed, 528 while much of this work has examined how species survive for millions of years given large 529 oscillations in climate (Provan & Bennett, 2008), the periods that provide the most dramatic 530 community reshuffling are periods shifting from stationary to non-stationary climate regimes 531 (Vrba, 1980, 1985). Such stories of the past are now fundamentally happening today, and 532 ecology is challenged to understand how transitions between stationary and non-stationary 533 environments are reshaping the species and communities we have today and will in the altered 534 climates of our future.

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541 8 Figures

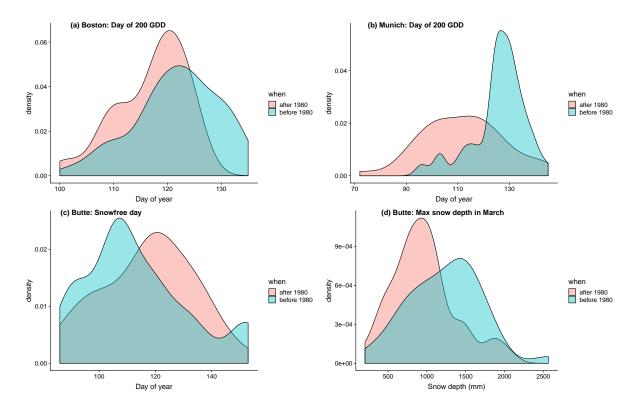


Figure 1: Understanding non-stationarity in ecological systems requires first identifying which aspects of the environment have shifted—and how they have shifted with respect to one another (e.g., Cook & Wolkovich, 2016; Wadgymar et al., 2018)—as the underlying distributions transition from stationary to non-stationary. Here we show examples of non-stationarity in climate variables that affect phenology by comparing before and after 1980 (a major change-point in climate for many regions) in several metrics related to the start of growing seasons (a-c) or resource pulse connected to growing season length (d). Density plots of day of 200 growing degree day units (a metric of thermal sum, here based on 0 degree base temperature using daily minima in °C) in Boston, MA, USA (a), and Munich, Germany (b), first snowfree day (followed by at least 9 snowfree days) in Crested Butte, CO, USA (c) and maximum snowdepth (mm) in March (often the month before the first snowfree day) in Crested Butte, CO, USA (d). Note that (c) and (d) are likely related, with lower snowpacks leading to an earlier first snowfree day. We selected sites that have been studied for plant phenological data and included at least 80 years of daily climate data from a Global Historical Climatology Network site; we subsetted data so that there were 40 years before and after 1980 for all sites.

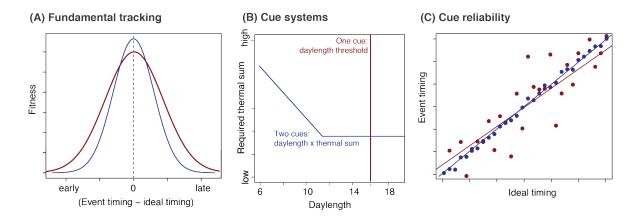


Figure 2: Fundamental tracking (A) represents how an organism matches the actual timing of a life history event (phenology) to the timing that maximizes its fitness (i.e., ideal timing). Here, we show a common conceptualization where fitness declines as event timing moves away from the ideal timing, though realizations in nature may take diverse forms. As the ideal timing is generally only clear in simplified models or in retrospect, species that phenologically track must use a cue system (B) to try to match their phenology to the ideal timing across environments (temporally and/or spatially). Here we show two cue systems: one single cue system dependent only on daylength (red line: the event occurs when the organism's environment exceeds a certain daylength) and one multivariate cue system, which depends on a combination of daylength and thermal sums (navy line: the event occurs when the organism accumulates enough temperature for the current daylength). The match between ideal timing and actual timing represents cue reliability (C).

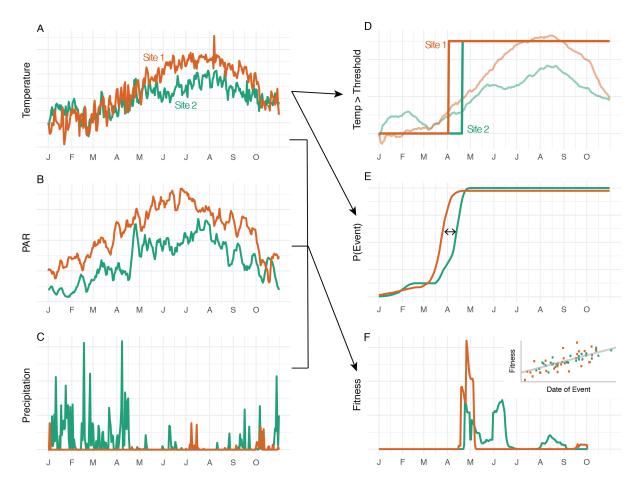


Figure 3: Phenological tracking: Different components of a multivariate environment (A: air temperature, B: cumulative photosynthetically active radiation, C: precipitation) are included in measurements of the environment to understand the timing of an event (D), in an organism's cueing from the environment which triggers the event (E), and in an organism's fitness outcome that results from the event (F), conceptualized here for two sites. While we may often use simple measurements to estimate tracking (D: measured environmental tracking modeled as a temperature threshold), an organism's cue system may be more complex (E: environmental tracking, here shown as a multivariate cue system where the changing probability of the event is a function of accumulated degree chilling hours and degree heating hours, based on the temperature environment in A). Ultimately, fitness is determined by the joint distribution of many environmental variables through time (F: fundamental tracking, shown here as the endof-season fitness as a function of the timing a start-of-season life history event, where we model fitness dependent on (1) growth as a unimodal function of temperature and a saturating function of PAR and soil moisture, and (2) survival as a function of early season frost and summer heat stress). Of ultimate value to the organism—especially under a changing climate—is cue reliability (inset in F): the correlation between the timing of the event (E) and the fitness of the organism (F) across years. See SI 'Fig. 3 methods' for further methods and details.

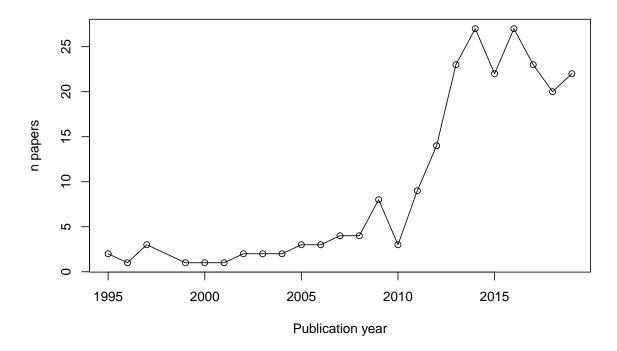


Figure 4: Trends in all papers examining tracking & other traits from a systematic literature review. We searched ISI (four searches: (1) Topic: 'phenolog* chang*' and Title: phenolog* AND trait*, (2) Topic: 'warming shift*' AND trait* and Title: phenolog*, (3) Topic: 'phenolog* track*' AND trait* and Title: phenolog*, (4) Topic: 'phenolog* sensitiv*' AND trait* and Title: phenolog*), which resulted in 231 papers, 83% of which were published in 2011 or onward. Of papers from which we could extract data 25 of 30 were published in the same period. See SI, 'Literature review of studies examining tracking & other traits,' for detailed methods.



Figure 5: Example of how non-stationarity can reshape communities in a simple coexistence model. We shifted the environment (top panels) by changing the timing of the resource pulse from a stationary period ($\tau_p \sim \beta(10,10)$ for the 500 years) to a nonstationary period ($\tau_p \sim \beta(5,15)$ over the 500 years), then examined outcomes for two-species communities (bottom panels) where tracking (X axis: species 1/species 2) trades off with R^* (Y axis: species 1/species 2): each point represents one two-species community color-coded by whether both species persisted or one or more species was extirpated through 500 years of a stationary environment (bottom-left), followed by an additional 500 years of non-stationary environment (bottom-right, only two-species communities that persisted through the stationary period are shown).

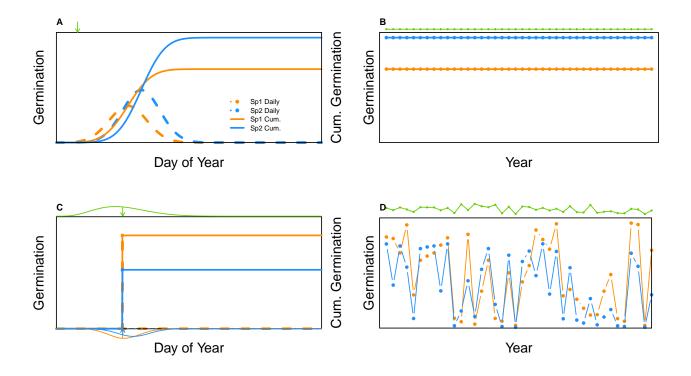


Figure 6: Tracking can be conceptualized as changes in priority effects or changes in storage effects. In a priority effect model (A,B), the coexistence mechanism is a within-year tradeoff between, an early-germinating species that pre-empts resources (sp 1) and late-germinating species that is a superior resource competitor (sp 2) (A, where green arrow indicates the start of season); no between-year variation is required to maintain coexistence. In a storage effect model (C,D), variation in the timing of the start of season (indicated by the distribution in green, top of C) results results in differential species-response to the environment (illustrated by species-specific germination curves, bottom of C); this interannual variation in species-response to the environment (D)—along with a seedbank or other interannual storage mechanism—can maintain coexistence through reduced interspecific competition.

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