# Semiring Algebraic Structure for Metarouting with Automatic Tunneling

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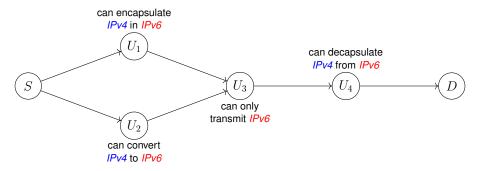




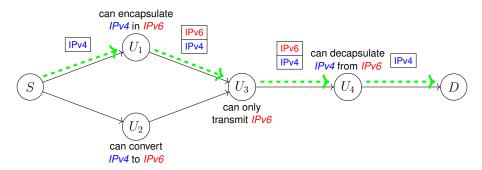


#### **Outline**

- Motivation
- Network Model and Path Validity
- Algebraic Model and Properties
- Semiring with Tunnels
- 5 Algebra and Algorithm Convergence
- Conclusion and Future Work

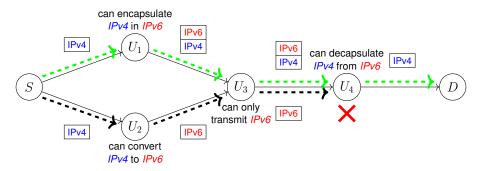


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- The top path (in green) is valid with a tunnel from  $U_1$  to  $U_4$ .
- The bottom path (in black) is invalid.



- The computation of paths (routing) in networks with tunnels is not yet fully automated. (e.g., Teredo, 6over4, 6to4, ISATAP, etc.)
- The path computation in multi-protocol networks with conversions and encapsulations, cannot be performed by using classical path computation algorithms. (e.g., Dijkstra, Bellman-Ford, etc.)
- There are a few path computation algorithms which take into account encapsulations and conversions. (e.g., Stack-Vector, etc.)
- The valid path problem under bandwidth constraints is NP-hard.

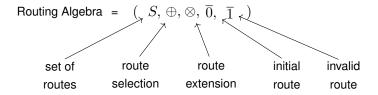
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Metarouting is an algebraic model of routing protocols.
 (semiring, Sobrinho's algebra and algebra of endomorphisms.)



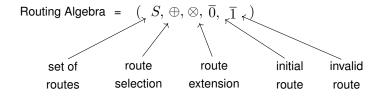
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- Separates the routing data and algorithm. (route exchange and route update.)
- Study the properties of routing protocols.
   (convergence and the set of optimal paths.)



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Our contribution is to generalize the semiring structure for modeling the routing problem with automatic tunneling and to study some algebraic properties of convergence.

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- A set of adaptation functions,  $\mathcal{F}$  of type:
  - $(x \to x)$  is the retransmission of the protocol x
  - $(x \rightarrow y)$  is the conversion of the protocol x to y
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- A weight function,  $\omega: \mathcal{V} \times \mathcal{F} \times \mathcal{V} \to \mathcal{R}^+$



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- The set of all stacks starting with the sub-stack xy is  $H_{xy} \in \mathcal{H}$ .
- An adaptation function  $f = (x \to xy)$  is defined as  $f : H_x \to H_{xy}$ .

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And

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The set of all identity functions (classical retransmission) is:

$$\mathcal{F}_{id} = \left\{ x \to x, y \to y, \dots \right\}$$



• A path  $p = h_i v_i f_i v_{i+1} f_{i+1} \dots v_{j-1} f_{j-1} h_j v_j$  from  $v_i$  to  $v_j$  is a mixed sequence of nodes and adaptation functions and it is valid iff:

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• The weight of a valid path p from  $v_i$  to  $v_j$  is the sum of the weights of its links and its adaptation functions,

$$\omega(p) \stackrel{def}{=} \sum_{k=i}^{j-1} \omega(v_k, f_i, v_{k+1})$$

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# Semiring and Properties

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Problem	S	$\oplus$	$\otimes$	$\overline{0}$	1
shortest paths $(SM_{sp})$	$\mathbb{N}_{\infty}$	min	+	$+\infty$	0
widest paths	$\mathbb{N}_{\infty}$	max	min	0	$+\infty$
most reliable paths	[0, 1]	max	×	0	1
accessible paths	$\{0,1\}$	max	min	0	1

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If  $\oplus$  is idempotent then the relation  $\leq_{\oplus}$  is a partial order over S:

$$(a \leq_{\oplus} b) \equiv (a = a \oplus b)$$
$$(a <_{\oplus} b) \equiv (a = a \oplus b \neq b)$$

Note that this order is total when the operation  $\oplus$  is selective



# Matrix Semirings

Given a semiring  $(S, \oplus, \otimes, \overline{0}, \overline{1})$ , the semiring of  $n \times n$  matrix is  $(\mathbf{M}_n(S), \oplus, \otimes, \mathbf{N}, \mathbf{I})$ , where:

- $\mathbf{N}_{i,j} = \overline{0}$
- $\mathbf{I}_{i,j} = \left\{ \begin{array}{ll} \overline{1} & \text{if } (i=j) \\ \overline{0} & \text{otherwise} \end{array} \right.$

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And for any two matrices  $X, Y \in \mathbf{M}_n(S)$ , the two operations  $\oplus$  and  $\otimes$  are defined as follow:

- $\bullet (\mathbf{X} \oplus \mathbf{Y})_{i,j} = \mathbf{X}_{i,j} \oplus \mathbf{Y}_{i,j}$
- $\bullet \ (\mathbf{X} \otimes \mathbf{Y})_{i,j} = \bigoplus_{k=1}^{n} \mathbf{X}_{i,k} \otimes \mathbf{Y}_{k,j}$



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• The weighted adjacency matrix  $A \in M_n(S)$  of the graph  $\mathcal{G}$  is:

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• The power of a matrix  $A \in M_n(S)$  is:

$$\mathbf{A}^{\mathbf{k}} = \left\{ egin{array}{ll} \mathbf{I} & ext{if } k = 0 \\ \mathbf{A} \otimes \mathbf{A}^{\mathbf{k} - 1} & ext{otherwise} \end{array} 
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Let  $\mathcal{P}_{i,j}^k$  be the set of all paths from node  $v_i$  to node  $v_j$  of size k Let  $\mathcal{P}_{i,j}^{(k)}$  be the set of all paths from  $v_i$  to  $v_j$  of size at most k.

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 The global optimal solution for the generalized path computation problem consists in finding (if it exists) the matrix A\*,

$$\mathbf{A}^* = \bigoplus_{k \ge 0} A^{(k)} = \bigoplus_{p \in \mathcal{P}^{(k)}} \omega(p)$$

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$$SM_{sp} = \left(\mathbb{N}^{\infty}, min, +, +\infty, 0\right)$$
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#### Where:

- $\mathcal{P}(\hat{\mathcal{F}})$  is the power set of all functions closed under compositions.
- $\odot$  is the composition operation of subsets in  $\mathcal{P}(\hat{\mathcal{F}})$ :

$$\hat{F}_1\odot\hat{F}_2=\left\{\hat{f}_1\odot\hat{f}_2\,|\,\hat{f}_1\in\hat{F}_1 ext{ and }\hat{f}_2\in\hat{F}_2
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•  $\mathcal{F}_{id}$  is the set of identity adaptation functions  $\{x \to x, y \to y, \dots\}$ .

• The valid shortest paths semiring is the semi-directed product:

$$SM_{vsp} = SM_{vp} \rtimes SM_{sp} = \left(\mathcal{P}(\hat{\mathcal{F}} \times \mathbb{N}^{\infty}), \bigcup_{min}, (\odot \times +), \emptyset, (\mathcal{F}_{id} \times 0)\right)$$

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$$S_1 \underset{min}{\cup} S_2 = \left\{ (\hat{f}, \omega_{\hat{f}}) \mid (1) \ \lor \ (2) \right\} \qquad \forall S_1, S_2 \in \mathcal{P} \big( \hat{\mathcal{F}} \times \mathbb{N}^\infty \big)$$

$$(\hat{f}, \omega_{\hat{f}}) \in S_1 \land \forall \, (\hat{g}, \omega_{\hat{g}}) \in S_2, \, (\hat{f} = \hat{g}) \Rightarrow \omega_{\hat{f}} = min[\omega_{\hat{f}}, \omega_{\hat{g}}] \tag{1}$$

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• The partial order relation over elements of  $\mathcal{P}(\hat{\mathcal{F}} \times \mathbb{N}^{\infty})$ :

$$S_1 \subseteq S_2 \equiv \forall (\hat{f}, \omega_{\hat{f}}) \in S_1 \Rightarrow \exists (\hat{g}, \omega_{\hat{g}}) \in S_2, (\hat{f} = \hat{g}) \land (\omega_{\hat{f}} \le \omega_{\hat{g}})$$



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#### Proposition

The direct product operator  $(\odot \times +)$  over the power set  $\mathcal{P}(\hat{\mathcal{F}} \times \mathbb{N}^{\infty})$  is isotonic and not monotonic.

Theorem [B. A. Carré, 71]

$$\mathbf{A}^* = \mathbf{A}^{(n-1)} = \mathbf{I} \oplus \mathbf{A} \oplus \mathbf{A}^2 \oplus \cdots \oplus \mathbf{A}^{n-1}$$

#### Theorem [B. A. Carré, 71]

$$\mathbf{A}^* = \mathbf{A}^{(n-1)} = \mathbf{I} \oplus \mathbf{A} \oplus \mathbf{A}^2 \oplus \cdots \oplus \mathbf{A}^{n-1}$$

- A multilayer circuit is a valid path  $p = h_i v_i f_i \dots f_{j-1} h_j v_j$  where:
  - The node  $v_i$  is the same node  $v_j$ , i.e.,  $v_i = v_j$
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  - The starting and the ending stacks are the same, i.e.,  $h_i = h_j$
- A multilayer elementary path is a valid path in which its circuits (if it exists) are non multilayer circuits.
- A free multilayer network is a network in which all of its multilayer circuits have positive weights.

#### **Theorem**

In a free multilayer network  $\mathcal{N}$  we have:

$$\mathbf{A}^* = \mathbf{A}^{(k)} = \mathbf{I} \oplus \mathbf{A} \oplus \mathbf{A}^2 \oplus \cdots \oplus \mathbf{A}^k$$

Where k is the maximum length of the multilayer elementary paths in  $\mathcal{N}$ , and it is equal to  $2^{(\lambda+1)\lambda^2n^2}-1$ .

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Proposition [M. L. Lamali, S. Lassourreuille, S. Kunne, and J. Cohen, 19]

For any multilayer network  $\mathcal{N}$ , the valid shortest path (if any) between two nodes is upper bounded by  $2^{(\lambda+1)\lambda^2n^2}$ .

#### Conclusion and Future Work

- New routing algebra based on semirings for path computation with automatic tunneling: an isotonic and non-monotonic algebra with a partial order.
- A generalization of the iterative convergence theorem for the optimal solution of the valid shortest paths problem.

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- New routing algebra based on semirings for path computation with automatic tunneling: an isotonic and non-monotonic algebra with a partial order.
- A generalization of the iterative convergence theorem for the optimal solution of the valid shortest paths problem.
- The adaptation of the other existing algebraic structures (algebra
  of endomorphisms and Sobrinho's algebra) to the valid shortest
  paths problem.
- The generalization of the asynchronous convergence theorem for the stack-vector protocol.



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