

JIAHAO LI

(424)355-6278
ljhnick@g.ucla.edu
ljhnick.github.io

RESEARCH INTEREST

My research focuses on the areas of *robotics, AR/VR, and computational design & fabrication* in order to –
Turn everyday objects into robots

EDUCATION

University of California, Los Angeles (UCLA) Sep. 2017 - Present
Ph.D. Student in Mechanical Engineering
Shanghai Jiao Tong University, China (SJTU) Sep. 2013 - Jun. 2017
B.S. in Naval Architecture and Ocean Engineering

PROFESSIONAL EXPERIENCE

Adobe Research Summer 2021
Summer Research Intern, Will be advised by Li-Yi Wei and Rubaiat Habib Kazi
• To work on an AR/VR related project
Los Angeles, CA

UCLA HCI Research Fall 2018 - Present
Graduate Research Assistant, Advised by Xiang 'Anthony' Chen
• Developed a design tool to actuate everyday objects
• Developed an interactive design tool to turn everyday objects into transformable robots
• Developed a versatile magnetic gripper to enable generic robotic arm to manipulate everyday tools
Los Angeles, CA

UCLA LEMUR Lab Summer 2020
Graduate Research Assistant, Advised by Ankur Mehta
• Developed an evaluation system for indoor blimps based on user designed parameters
• Built a team of indoor blimps to participate in the 99+ aerial soccer game at IUB in Nov. 2020
Los Angeles, CA

PARC, A Xerox Company Summer 2019
Summer Research Intern, Mentored by Erva Ulu and Nurcan Ulu
• Developed a novel interactive support structure design method for additive manufacturing
Palo Alto, CA

DMAI, Inc Summer 2018 - Summer 2019
Hardware Engineer, Part-time Intern
• Developed two educational robots prototypes. The first is a fix-based goose-like robot aiming to interact with toddlers by playing the game *Simon Says*. The second is a biped robot aiming to supervise preschoolers under absence of parents
• Implemented a visual tracking function that enables the walking robot to keep eye on human while walking
• Took part in the system integration in Robotic Operating System (*ROS*)
• Designed outer look of the robots and inner structures to integrate all hardware
Los Angeles, CA

PUBLICATIONS

Full Paper in HCI

- [H4] **Jiahao Li**, Alexis Samoylov, Jeeun Kim, Xiang 'Anthony' Chen. Roa1ly: A Versatile Magnetic Gripper for Manipulating Everyday Tools with Passively Actuable Mechanisms. *Submitted to ACM UIST 2021*
- [H3] Abul Al Arabi, **Jiahao Li**, Xiang 'Anthony' Chen, Jeeun Kim. Mobiot. *Submitted to ACM UIST 2021*
- [H2] **Jiahao Li**, Meilin, Cui, Jeeun Kim, Xiang 'Anthony' Chen. Romeo: A Design Tool for Embedding Transformable Parts in 3D Models to Robotically Augment Default Functionality. *Proc. ACM UIST 2020. Acceptance Rate: 23%..*

- [H1] **Jiahao Li**, Jeeun Kim, Xiang ‘Anthony’ Chen. Robiot: A Design Tool for Actuating Everyday Objects with Automatically Generated 3D Printable Mechanisms. *Proc. ACM UIST 2019*. *Acceptance Rate: 24.4%.*

Full Paper in Other Areas

- [O2] Zhaoliang Zheng, **Jiahao Li**, Parth Agrawal, Ethan Uetrecht, Zhao Lei, Joseph Prince Mathew, Dinesh Kumar Karri, Ankur Mehta. User Design Parameters Based Design and Evaluation System for Indoor Airships. *Submitted to UR '21*.
- [O1] Erva Ulu, Nurcan Gecer Ulu, **Jiahao Li** and Walter Hsiao. Curvy: An Interactive Design Tool for Varying Density Support Structures. *Arxiv*.

Papers in Extended Abstracts (Posters, Demos, and Work-in-progress)

- [EA1] **Jiahao Li**, Jeeun Kim, Xiang ‘Anthony’ Chen. Robiot: A Design Tool for Actuating Everyday Objects with Automatically Generated 3D Printable Mechanisms. *Demo in ACM UIST 2019*.

Conference and Workshop Presentations without Proceedings

- [CP1] Ruolin Wang, Yuqi Tang, Hsuan Wei Fan, **Jiahao Li**, Xiang ‘Anthony’ Chen. AuxiScope: Improving Awareness Surroundings for People with Tunnel Vision. *UIST Student Innovation Competition, October 2019*.

SELECTED PRESS COVERAGE

Robiot

- *Turn any object into a robot using this program and a 3D printer.* **New Scientist**, Nov. 2019
- *Robiot Is a Design Tool That Generates Mechanisms to Motorize Everyday Objects.* **Hackster News**, Nov. 2019
- *Robiot Can Automatically Design Handy Household Machines.* **Fabbaloo**, Nov. 2019

PROFESSIONAL SERVICE

Program Committee

- ACM CHI Late Breaking Works (Associate Chair) '20 '21

Reviewer

- ACM UIST '20, ACM CHI '20 '21