

Principles of Machine Learning

CSCI-B455

Supervised Learning – I

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A simple classification task

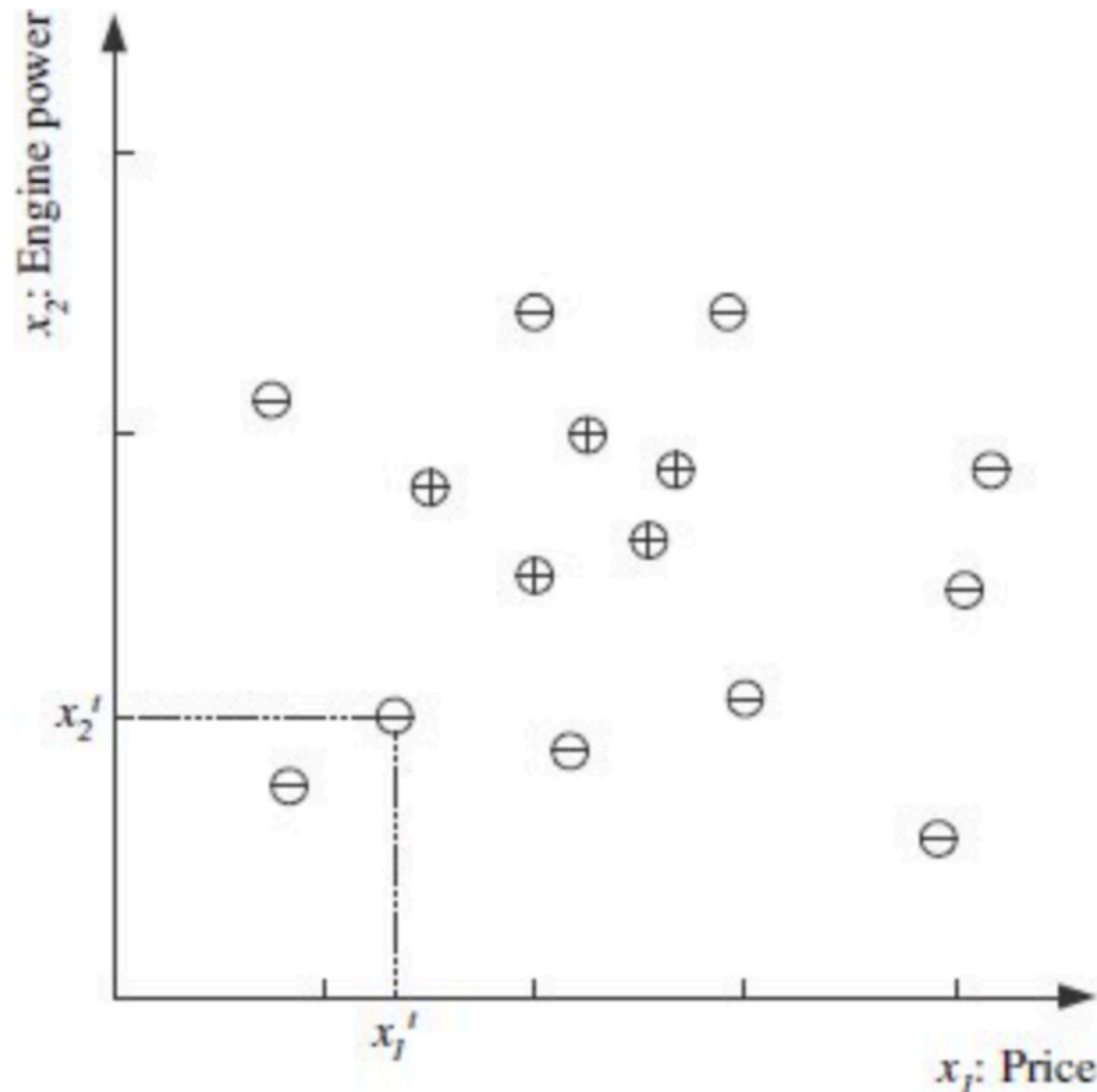
- Class **C** represents the **family cars**, and we aim to learn this class.
- Given a car, can we decide whether it is a family car ?
- Output is **yes (positive)** or **no (negative)**, a **binary classification**
- The purpose might be the
 - **Prediction:** When we see a new car, we want to answer the query
 - **Knowledge extraction:** The car manufacturer wants to get a good definition of a 'family car'
- Assume we decided to use the **price** and **engine power** as the input representation, the attributes or dimensions of the input
- We have previously **labeled** data, the cars in class C and outside of it, to use in our learning

Two-Class or Binary Classification

$$\mathcal{X} = \{x_1^t, x_2^t, r^t\}_{t=1}^N$$

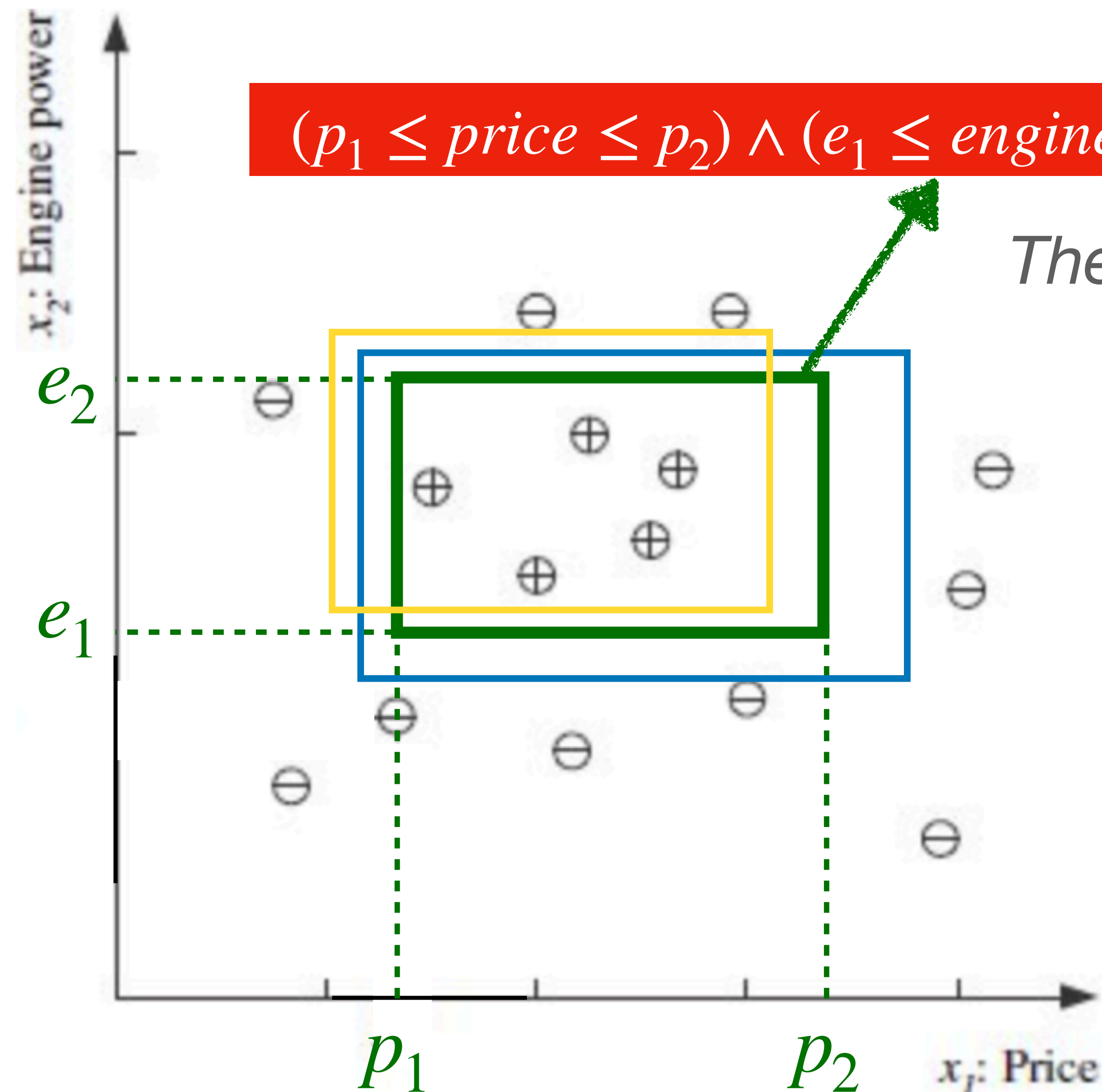
N **distinct** car samples the training set, where

- x_1^t is the price of the car t .
- x_2^t is the engine power of the car t .
- r^t is 1, if the car t is a family car, otherwise 0.



How would you mark the family car area on the figure left ?

Binary Classification



There can be many other guesses, right ?

Hypothesis class $\mathcal{H} = \{h_1, h_2, \dots\}$

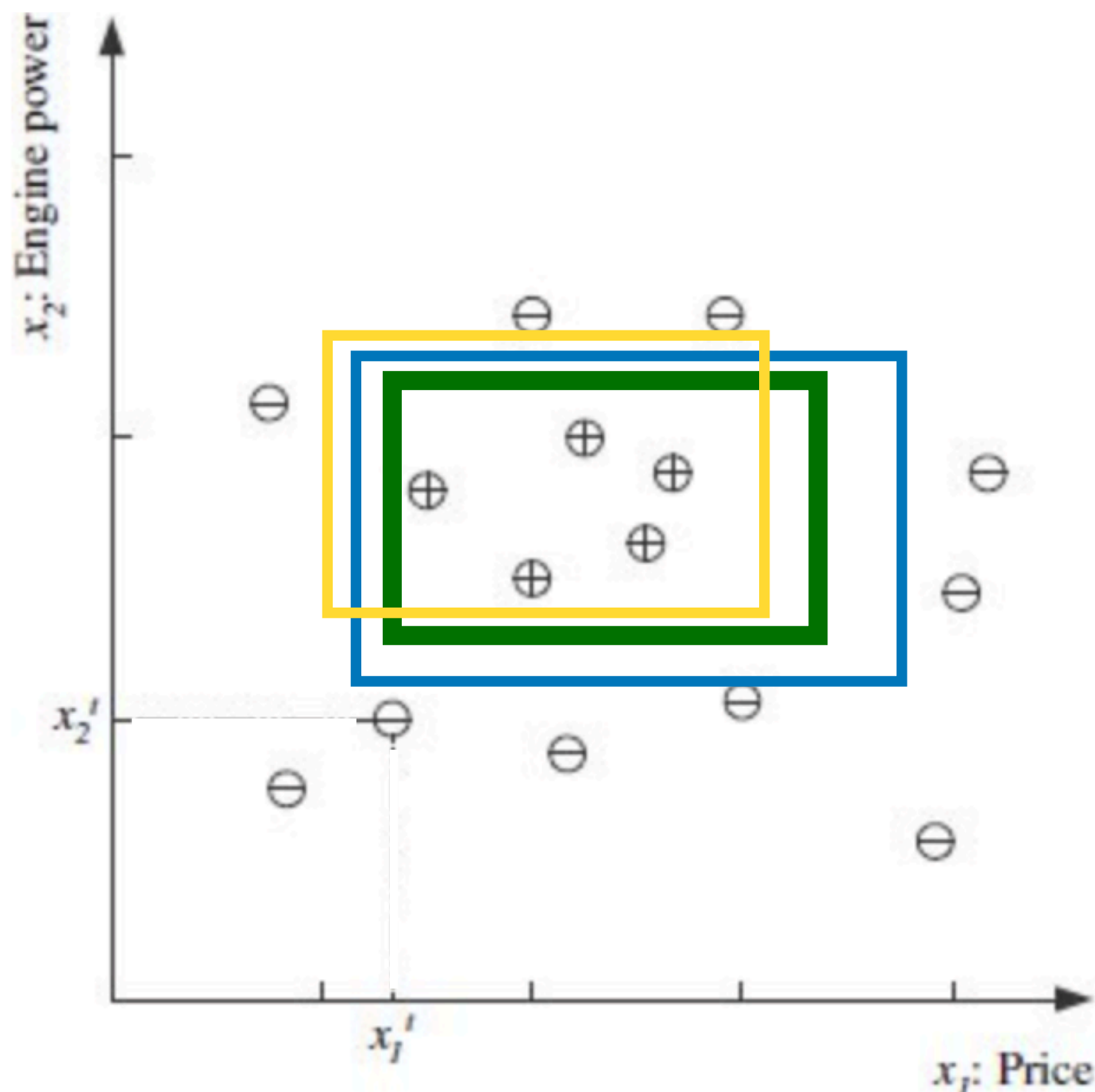
- $h_i \in \mathcal{H}$ is defined with $\langle p_1^i, p_2^i, e_1^i, e_2^i \rangle$.
- The learning algorithm just returns a $h_i \in \mathcal{H}$
- Is it the best one ? We never know !
- We can only try to minimize the **empirical error on training set**.

Binary Classification

Empirical error of a hypothesis h on training set \mathcal{X} is

$$E(h | \mathcal{X}) = \sum_{a=1}^N 1 \cdot (h(x^t) \neq r^t)$$

$(h(x^t) \neq r^t)$ is 1 if the output of h on x^t is not equal to r^t , else 0.



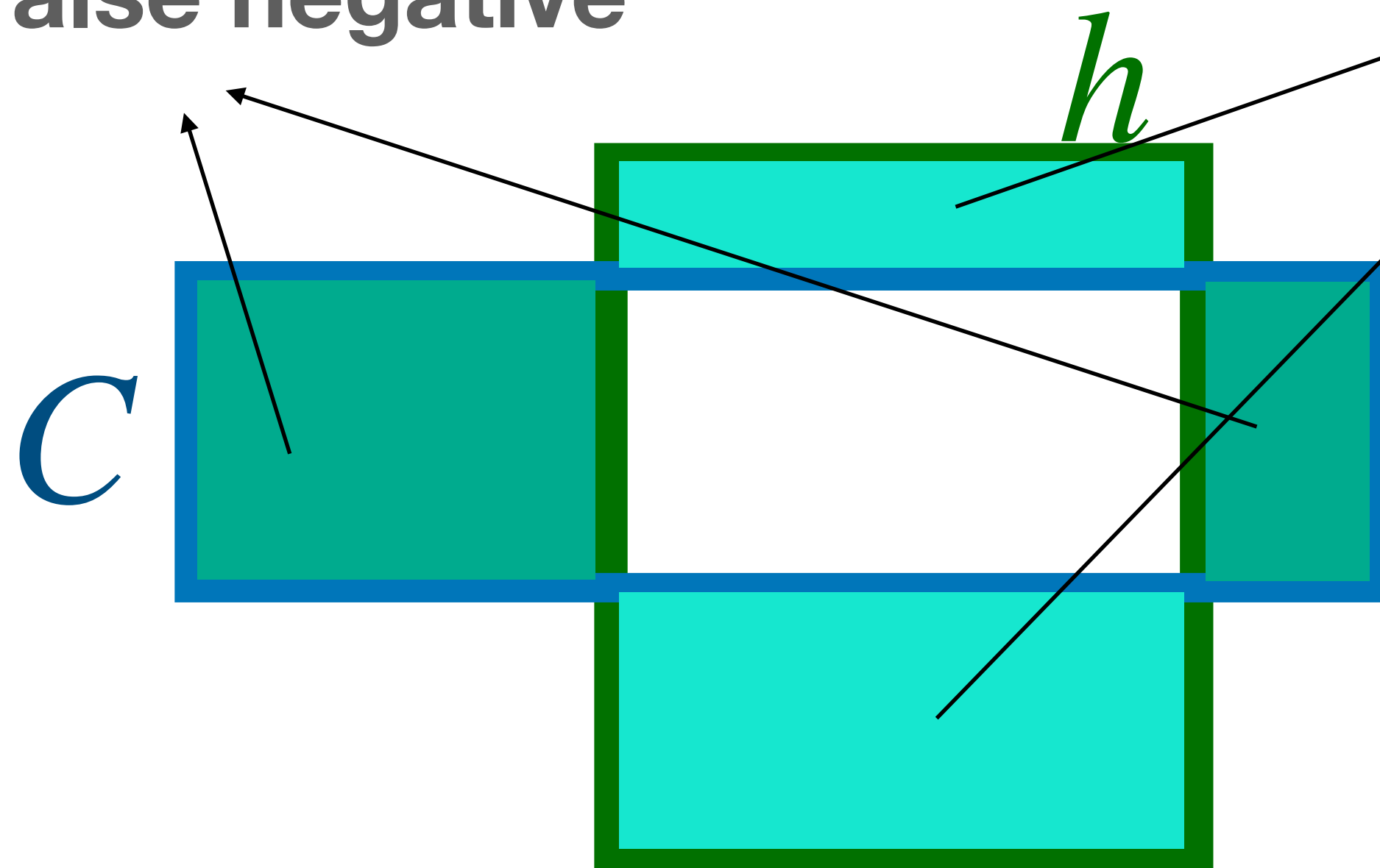
- Possibly many hypotheses h without error, $E(h | \mathcal{X}) = 0$
- **How will you choose among them ?**
- The future performance of chosen h cannot be known.
- This is the **generalization problem** in learning.

What can be the future implications of hypothesis h ?

Binary Classification

False negative

False positive



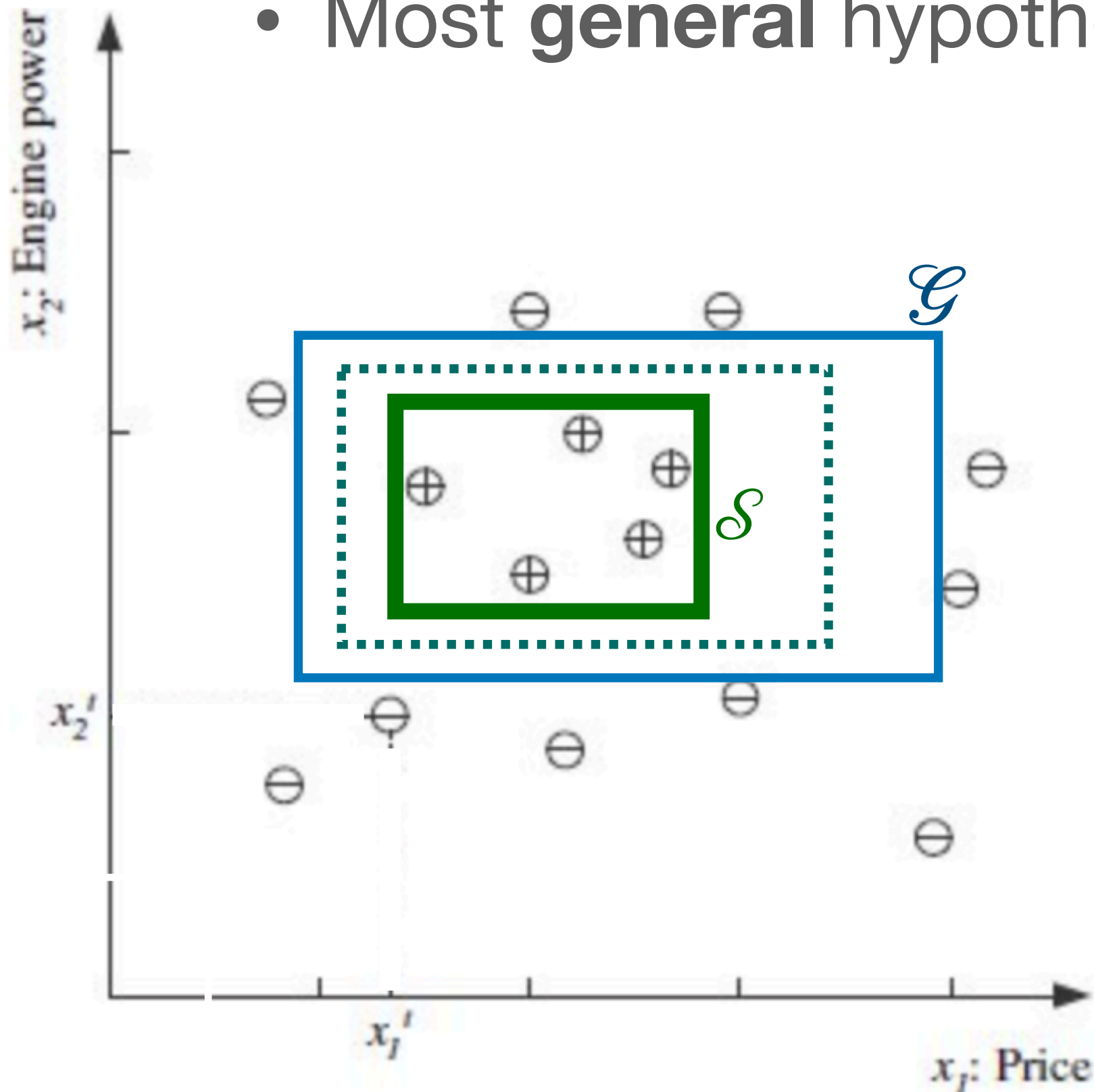
h is the learned hypothesis, and C is the actual class (ground truth)

The **cost** of false positive and false negatives can be **different**.

- High-risk, low-risk analysis for a credit customer?
- Is the customer a low-risk one ?
- Yes(positive), No (negative)
- False positive: A high-risk customer label as a low-risk. Credit granted and lost
- False negative: A low-risk customer labeled high-risk. Credit not granted, bank lost the opportunity of profit.

Binary Classification

- Most **specific** hypothesis \mathcal{S} : The smallest rectangle including all positives
- Most **general** hypothesis \mathcal{G} : The largest rectangle excluding all negatives

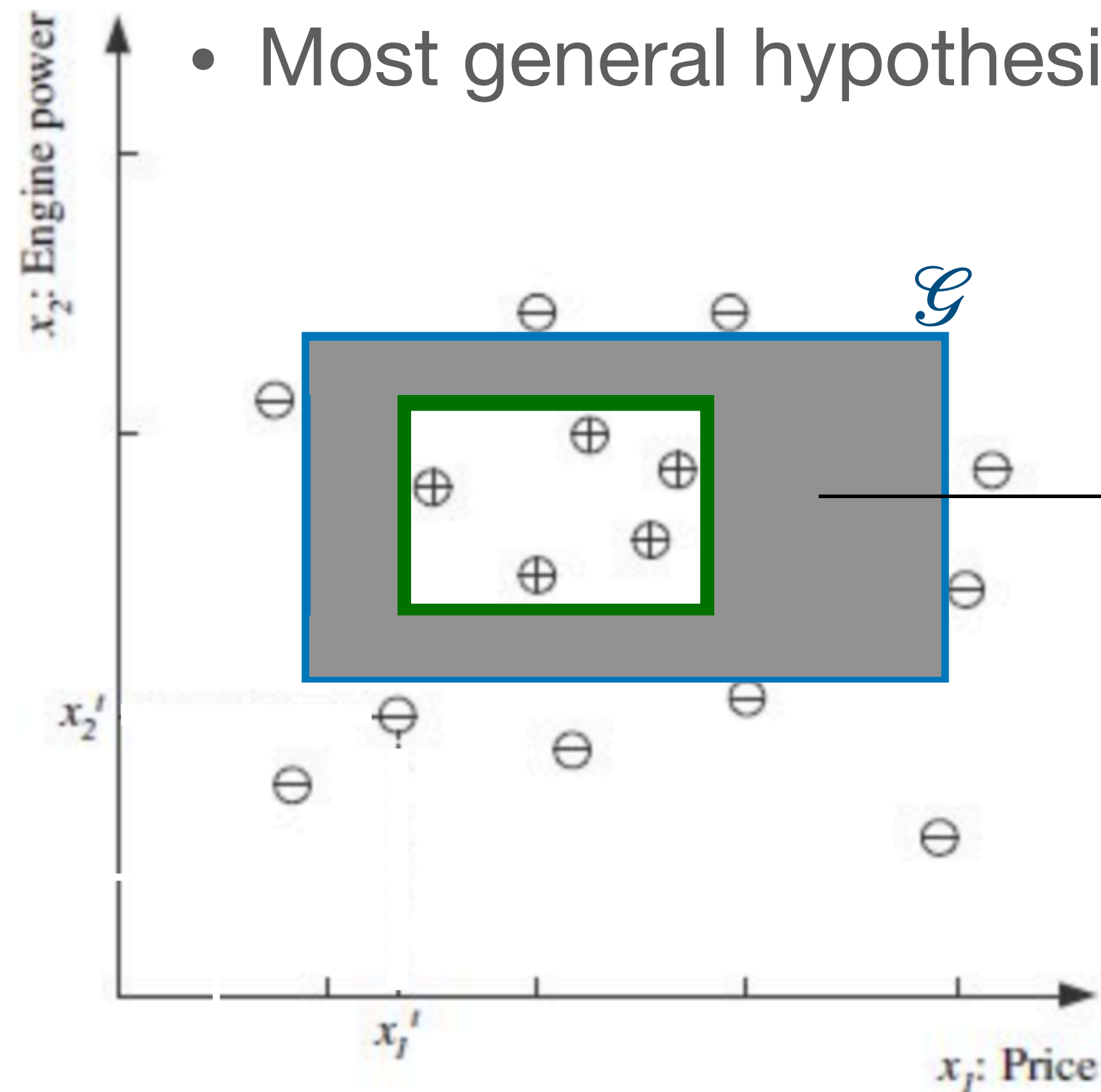


- All h in between \mathcal{S} and \mathcal{G} is called the **version space**.
- Any such h is **consistent** without error on \mathcal{X} .
- Having h in half-way between \mathcal{S} and \mathcal{G} seems intuitive.
- Why? Because, it increases the **margin, distance between boundary and its closest instances**.
- *To learn such an h , it needs a fix on the empirical error calculation !*

- $h(x)$ should return a distance value rather than 0/1
- This return value should be used in a loss function for the optimization
- **SVM**, support-vector-machine, is the typical example

Binary Classification

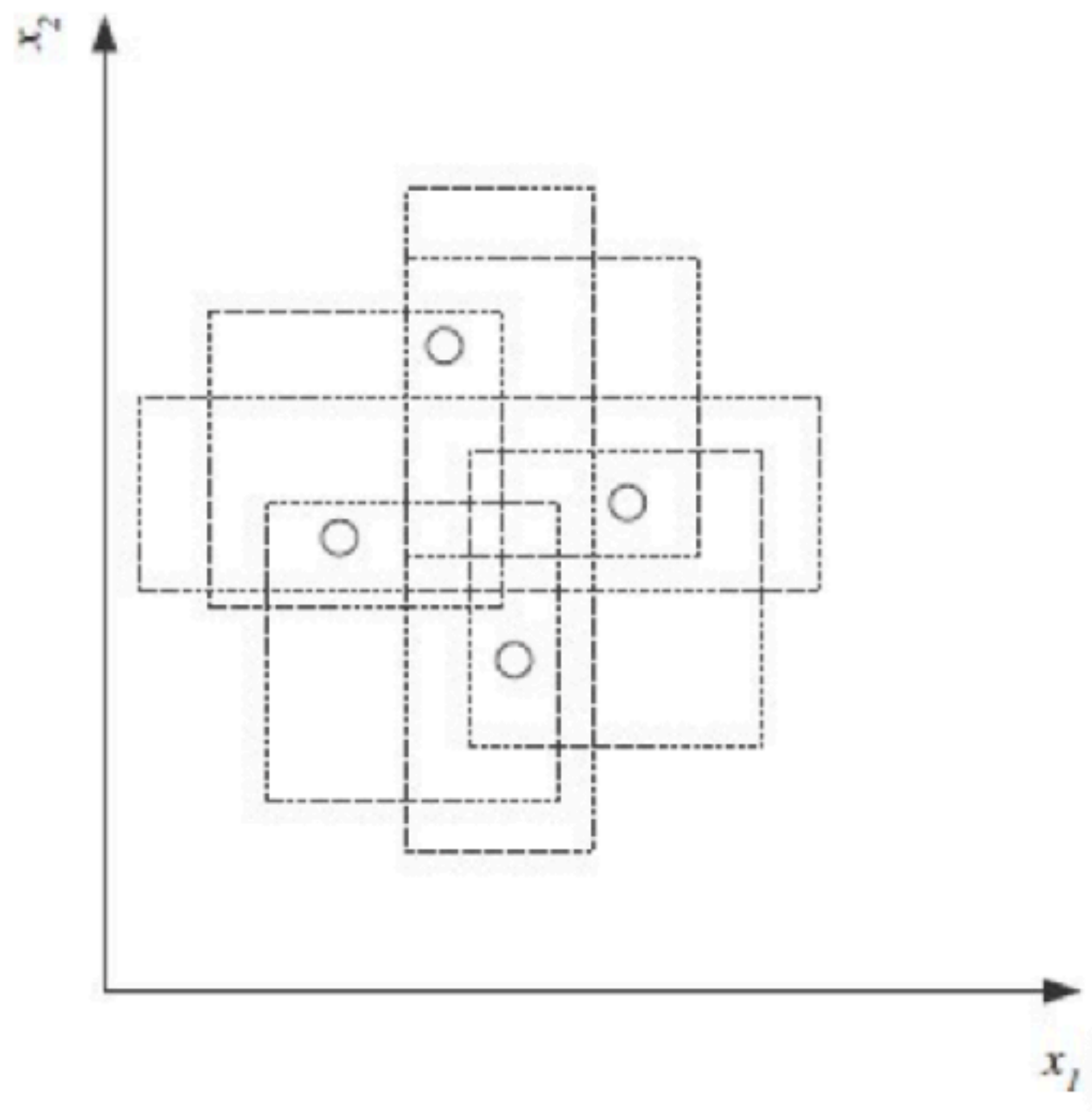
- Most specific hypothesis \mathcal{S} : The smallest rectangle including all positives
- Most general hypothesis \mathcal{G} : The largest rectangle excluding all negatives



In case, the consequences of false positives or negatives are very serious, the area in between \mathcal{S} and \mathcal{G} is assumed the **doubt** region, and forwarded to human judgement

Vapnik-Chervonenkis (VC) Dimension

- A measure of the capacity or the expressive power of a hypothesis set \mathcal{H}
- N points define 2^N different +/- attribution, each of which is a learning problem
- If there's an $h \in \mathcal{H}$ that solves all possible attributions, then \mathcal{H} **shatters** N points.
- This means the learning problem defined by N points can be solved without error.



Example:

Assume \mathcal{H} consists of axis-aligned rectangles, i.e. we draw an axis-aligned rectangle to separate positives from negatives or vice versa.

What is the VC-dimension of \mathcal{H} ?

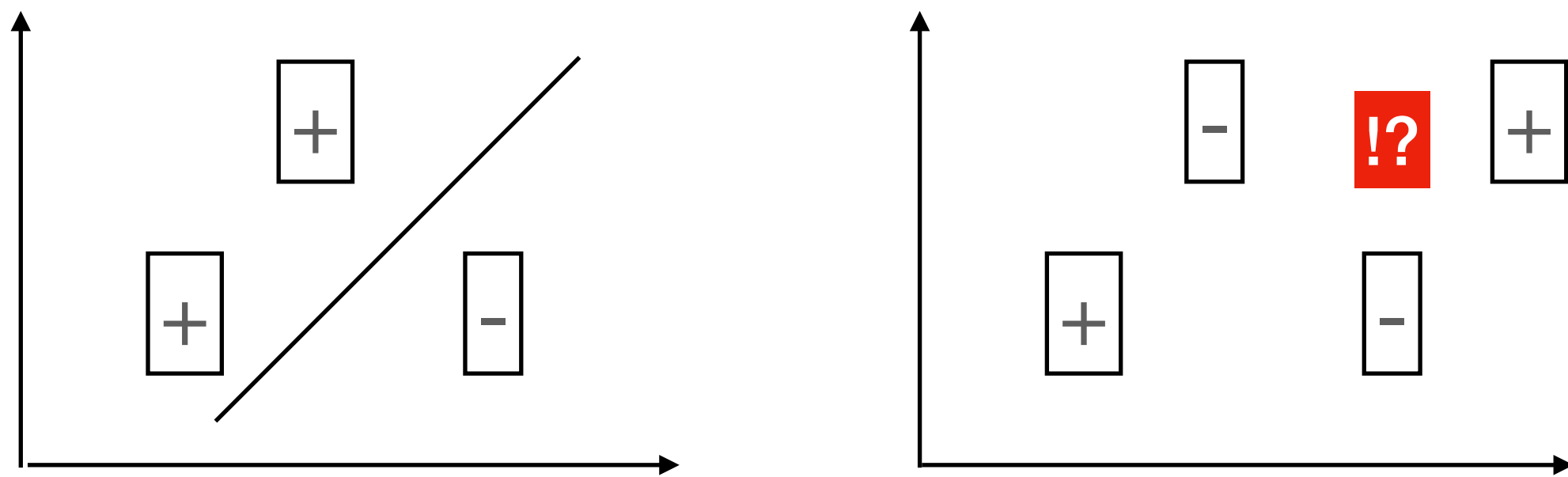
For the 4-points in 2D space, there is an axis-aligned rectangle that does the job for every possible +/- labeling of the points.

But, it does not hold for 5 points, so VC-dimension is 4.

Very pessimistic, it says you can only learn 4-point data sets with \mathcal{H} . Does it really that limiting in real-world?

Vapnik-Chervonenkis (VC) Dimension

- Assume \mathcal{H}' is consist of drawing lines in 2D space, instead of axis-aligned rectangles.
- What is the VC dimension of \mathcal{H}' ?
- There are $N = 3$ points all possible +/- assignments can be separated by a single line.
- Not possible to *shatter* for $N = 4$. Thus, VC dimension of \mathcal{H}' is 3.

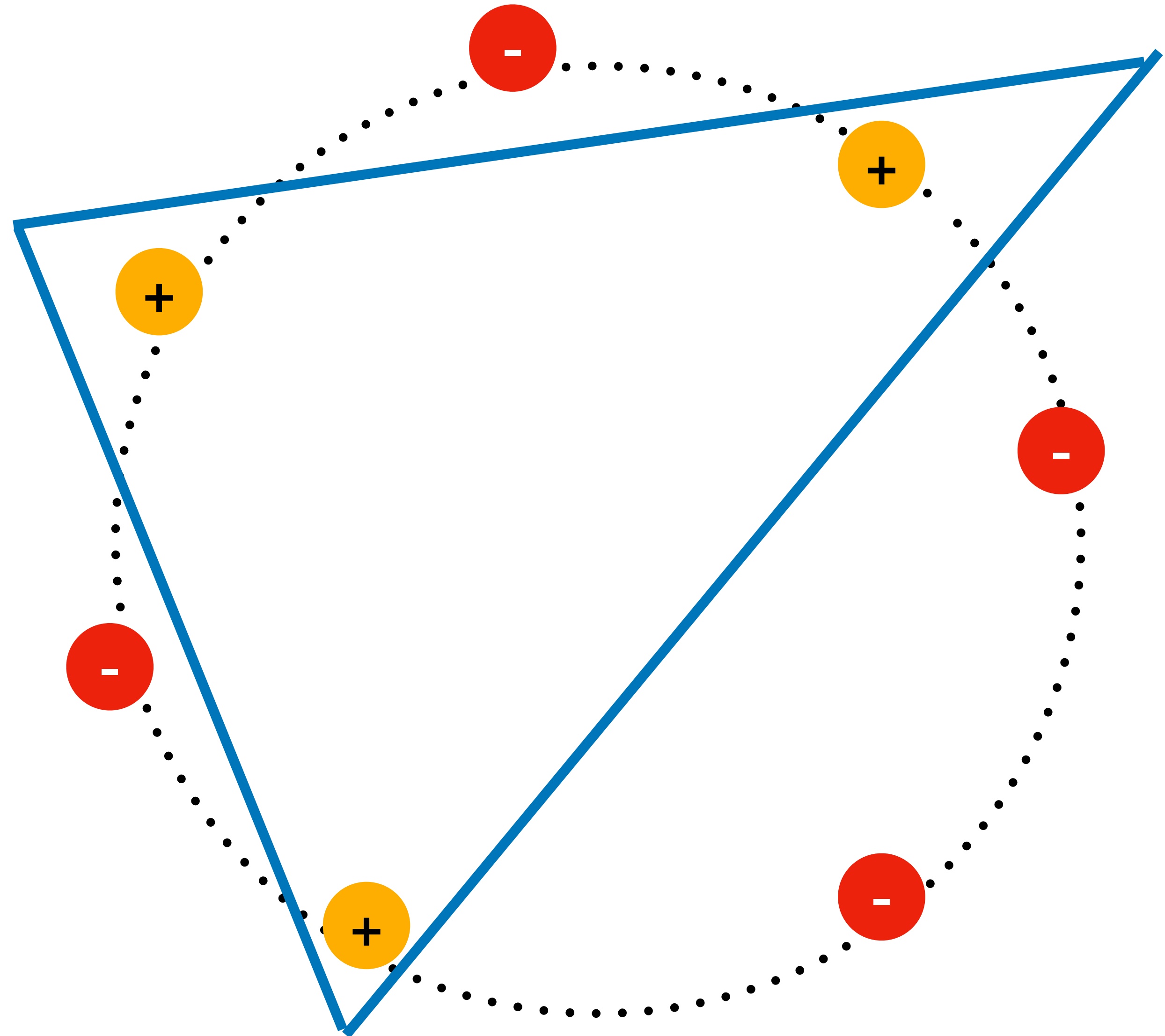


The expressive power, the capacity of learning, of \mathcal{H} is superior to \mathcal{H}' . \mathcal{H} can learn more complex data sets compared to \mathcal{H}' .

The VC dimension of \mathcal{H} is 4 while \mathcal{H}' is 3. What does it mean ?

Vapnik-Chervonenkis (VC) Dimension

- What is the VC dimension of a triangle on 2D space (or plane) ?
- 7 points in a plane can be shattered by a triangle. Thus, VC dimension of triangle on 2D is 7.
- *However, VC is still very pessimistic. With axis-aligned rectangles you can only learn 4-point data sets and with lines only 3-point data sets !*
- *Real-world practice is different, data points are not random, we are free to have errors on the training data, etc...*



Probably Approximately Correct (PAC) Learning

- **Accuracy:** We want the hypothesis h to be close to the true target class C .
- A **probability** that a given point is misclassified is at most ϵ , i.e., the error is at most ϵ
- The **level of desired accuracy** is denoted by ϵ .

	h : If (<i>weight</i> > 115) then Orange, else Apple	C : If (<i>weight</i> > 125) then Orange else Apple	
Training Data	Learned	True Class	
1. Apple 120g	1. Orange	1. Apple	h deviates from C by 20%, accuracy is 80%. Error rate is then $\epsilon = 0.2$. Does h provide a confidence ?
2. Orange: 150g	2. Orange	2. Orange	
3. Apple: 130g	3. Orange	3. Orange	
4. Orange: 140g	4. Orange	4. Orange	
5. Apple:110g	5. Apple	5. Apple	

- **Confidence:** We want to be confident that the h provides the desired level of accuracy.
- The level of desired accuracy is maintained with at least $(1 - \delta)$ probability.