Lydia Jin, Xi Qian, Yuyang Wang DATS 6203-12 Group Final Report

Image Classification - IAM Handwriting

Introduction

This project addresses an image classification problem, and further application of the image classification explored in class. The IAM Handwriting Dataset chosen for this project is comprised of a collection of handwritten passages by various writers. The goal of this project is to use deep learning to classify the writers by their writing styles. The results of this project can be used in future applications, such as identifying criminals by signature in fraudulent cases. This report will discuss the dataset, network and training algorithm, experiment setup, results, and conclusions drawn from this analysis.

Dataset Description

The dataset utilized for this project is the IAM Handwriting Dataset taken from the Kaggle website. The database contains 1539 (unique case) pages of scanned text sentences written by 657 writers. The data was grouped by writer, with each writer given a set of sentences to transcribe from different passages. The sentences were taken separately and preprocessed. We only used 50 writer's handwritten images in our project. In total, this dataset contains 4899 images placed in a data_subset folder. Each image file is in png format and of different pixel size.

Network and Training Algorithm Description

This project will utilize a Convolutional Neural Network (CNN). In neural networks, convolutional neural networks one of the main categories for performing image recognition and classification. CNN image classification takes an input image, processes it and classifies it under certain categories. Technically, the CNN model passes the input images through a series of layers containing different filters, pooling layers, fully connected layers; and applies the Softmax function to classify objects based on probabilistic values ranging from 0 to 1. The following figure shows a general process of how CNN model classifies images.

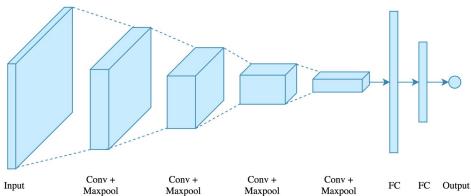


Fig1. Example of CNN architecture

In CNN the convolution operation is applied on the input data, using a convolution filter to produce a feature map. CNN has a hierarchical processing pipeline, where the features in lower layers are primitive, while those in upper layers are high-level abstract feature made from combinations of lower-level features. Therefore, more kernels are utilized in the upper layers, because they contain richer information than previous layers.

Experimental Setup

Data Preprocessing:

As mentioned above in the dataset description, the image files are of different sizes. For the images to be used as input in the Convolutional Neural Network, they must be of suitable pixel size. Therefore, the first pre-processing step was to create a target list that included the writer's number according to their handwriting scripts. Then, the target names (e.g., 000 to 0, 001 to 1) were label encoded to allow for simpler processing.

Training the Network:

The dataset was split into training, validation and testing sets, with a ratio of size 7:1.5:1.5. Next, the images were resized and cropped to receive randomly equal sized patches from each image file. After several rounds of testing, the chosen pixel size was 113*113. Parts of the code used for pre-processing were influenced by reference code found online. The generator function (see Appendix A) has multiple functions, such as scanning through each sentence and generating random patches of size 113*113. It is also used to get the pixel values of the images in the training, validation and testing sets and perform a grayscale normalization to reduce the effect of illumination's differences. Dividing the X_train images files by 255 allows the CNN to converge faster on [0..1] data compared to the original [0..255] data.

The CNN in this project was implemented with the Keras framework. Keras allows the data to be run on GPU and is the best for deep learning models with stacked layers. The analysis in this report compares models with 3 and 4 layers and varying parameters and optimizers. The images and classification are complicated, so it is necessary to try different architectures with different number of convolution layers. For judging performance, Keras also has functions such as fit_generator that can return accuracy and loss values.

Minibatches can simplify the process of updating parameters for the CNN. Large batch methods tend to converge to sharp minimizers of the loss function, leading to sensitive loss values. In contrast, small batch methods tend to converge to flat minimizers, leading to nonsensitive loss values. After experimentation with various batch sizes (e.g., 5, 10, 16, 40), a batch size of approximately 16 was found to be the best fit for this model. Similar experimentation with learning rates for the models found that the default learning rates provided for each optimizer (e.g., 0.01 for SGD, 0.001 for Adam) returned the best results.

Overfitting can be detected in some cases by looking at training, validation, and testing accuracy and loss. If the training, validation, and testing sets have very different

performances, then that can be a large indication of overfitting. The training set will almost always perform better than the validation and testing sets, but a good model is expected to generalize and reduce the gap between performances.

For this analysis, dropout layers were added in our model to prevent overfitting through regularization. Dropout randomly turns off neurons, based on an assigned probability, during the training process to reduce dependency on the training set. The dropout ratio used is about 0.4-0.5, which is commonly used in CNN.

Results

Describe the results of your experiments, using figures and tables wherever possible. Include all results (including all figures and tables) in the main body of the report, not in appendices. Provide an explanation of each figure and table that you include. Your discussions in this section will be the most important part of the report.

The most commonly used optimizers in CNN are SGD, Adam and RMSprop. SGD has the simplest computation formula:

$$\eta_t = \alpha \cdot g_t$$

Because SGD updates frequently, sometimes significant fluctuations may occur; the model may get stuck at the local minima or saddle point, where it is difficult for SGD to escape. RMSProp optimizer is usually a good choice for recurrent neural network (RNN), and is not appropriate for use with image data. For Adam, it usually works well even with very little hyperparameter tuning. Adam combines the best properties of the AdaGrad and RMSProp algorithms to provide an optimization algorithm that can handle sparse gradients on noisy problems. The update equations are shown as following:

$$m_t = eta_1 \cdot m_{t-1} + (1 - eta_1) \cdot g_t \ V_t = eta_2 \cdot V_{t-1} + (1 - eta_2) g_t^2$$

To determine the optimizer that will return the best performance, this analysis will explore two 3-layer CNN models with the optimizers Adam and SGD. To make comparisons on the effects of the two optimizers, the number of convolution layers will be controlled at 3, and the same values for the various parameters (e.g., number of filters, kernel size) will be used.

The two plots below show the accuracy of the models. There is a clear increase in accuracy for the model with the Adam optimizer as the epochs increase. In contrast, the SGD optimizer model remains at a constant 20% accuracy regardless of the number of epochs. For the image classification of this IAM dataset, the Adam optimizer is the clear choice for better classification accuracy for a 3-layer CNN.

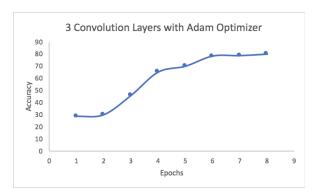


Fig2. Accuracy of 3 CNN layers with Adam Optimizer

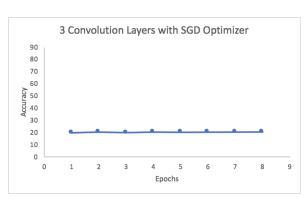


Fig3. Accuracy of 3 CNN layers with SGD Optimizer

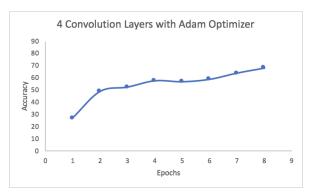


Fig4. Accuracy of 4 CNN layers with Adam Optimizer

```
1000/1000 [=
Epoch 00001: saving model to check-01-2.4752.hdf5
Epoch 2/8
      Epoch 00002: saving model to check-02-1.6918.hdf5
Epoch 3/8
     1000/1000 [=
Epoch 00003: saving model to check-03-1.5528.hdf5
1000/1000 [=
     Epoch 00004: saving model to check-04-1.3610.hdf5
Epoch 5/8
Epoch 00005: saving model to check-05-1.4090.hdf5
Epoch 00006: saving model to check-06-1.3654.hdf5
     1000/1000 [=
Epoch 00007: saving model to check-07-1.1765.hdf5
Epoch 00008: saving model to check-08-1.0508.hdf5
```

Fig3. Loss and accuracy for 4-layer-CNN-model with Adam Optimizer

Summary and Conclusions

Summarize the results you obtained, explain what you have learned, and suggest improvements that could be made in the future.

References

In addition to references used for background information or for the written portion, you should provide the links to the websites or github repos you borrowed code from.

Dataset: https://www.kaggle.com/tejasreddy/iam-handwriting-top50
https://www.learnopencv.com/image-classification-using-convolutional-neural-networks-in-k
https://www.learnopencv.com/image-classification-using-convolutional-neural-networks-in-k
https://www.learnopencv.com/image-classification-using-convolutional-neural-networks-in-k

Figure 1:

https://towardsdatascience.com/applied-deep-learning-part-4-convolutional-neural-networks -584bc134c1e2

Checkpoint code:

https://machinelearningmastery.com/check-point-deep-learning-models-keras/

Generator code:

https://www.kaggle.com/tejasreddy/offline-handwriting-recognition-cnn/notebook

CNN Background Information:

https://www.learnopencv.com/image-classification-using-convolutional-neural-networks-in-k eras/

Save/Load Keras models: http://faroit.com/keras-docs/2.0.2/models/about-keras-models/

Appendix

Appendix A:

```
def generate_data(samples, target_files, batch_size=batch_size, factor=0.1):
    num_samples = len(samples)
    from sklearn.utils import shuffle
    while 1: # Loop forever so the generator never terminates
        for offset in range(0, num_samples, batch_size):
            batch_samples = samples[offset:offset + batch_size]
            batch_targets = target_files[offset:offset + batch_size]

        images = []
        targets = []
        for i in range(len(batch_samples)):
            batch_sample = batch_samples[i]
            batch_target = batch_targets[i]
        im = Image.open(batch_sample)
```

```
cur_width = im.size[0]
  cur_height = im.size[1]
  height_fac = 113 / cur_height
  new_width = int(cur_width * height_fac)
  size = new_width, 113
  imresize = im.resize((size), Image.ANTIALIAS)
  now_width = imresize.size[0]
  avail_x_points = list(range(0, now_width - 113))
  pick_num = int(len(avail_x_points) * factor)
  random_startx = sample(avail_x_points, pick_num)
  for start in random_startx:
     imcrop = imresize.crop((start, 0, start + 113, 113))
     images.append(np.asarray(imcrop))
     targets.append(batch_target)
X_train = np.array(images)
y_train = np.array(targets)
X_train = X_train.reshape(X_train.shape[0], 113, 113, 1)
X_train = X_train.astype('float32')
X_train /= 255
#convert a class vector to binary class matric
y_train = to_categorical(y_train, num_classes)
yield shuffle(X_train, y_train)
```

Appendix B