

## 第11.3节

### 方向导数与梯度 (gradient)

## 一、方向导数

### Definition

设  $\vec{l} \in \mathbb{R}^n$ , 且  $\vec{l} \neq 0$ . 过  $X_0$  引一条射线  $L$  使得其方向(包括指向)与  $\vec{l}$  一致. 如果  $\lim_{L \ni X \rightarrow X_0} \frac{f(X) - f(X_0)}{|X - X_0|}$  收敛, 则称其极限值为  $f(X)$  在  $X_0$  沿  $\vec{l}$  的方向导数, 记为  $\frac{\partial f}{\partial \vec{l}}(X_0)$ .

不妨

设  $\vec{l} = (\cos \alpha_1, \dots, \cos \alpha_n)$ ,  $\cos^2 \alpha_1 + \dots + \cos^2 \alpha_n = 1$ , 则

$$\begin{aligned} \frac{\partial f}{\partial \vec{l}}(X_0) &= \lim_{t \rightarrow 0^+} \frac{f(X_0 + t \vec{l}) - f(X_0)}{t} \\ &= \lim_{t \rightarrow 0^+} \frac{f(x_{01} + t \cos \alpha_1, \dots, x_{0n} + t \cos \alpha_n) - f(x_{01}, \dots, x_{0n})}{t}. \end{aligned}$$

## 方向导数与偏导数的关系

$f(X)$ 在 $X_0$ 沿 $x_i$ 轴正向和负向的方向导数分别记为 $\frac{\partial f}{\partial x_i^+}(X_0)$ 和 $\frac{\partial f}{\partial x_i^-}(X_0)$ .

$\frac{\partial f}{\partial x_i}(X_0)$ 存在  $\Leftrightarrow \frac{\partial f}{\partial x_i^+}(X_0)$ 和 $\frac{\partial f}{\partial x_i^-}(X_0)$ 都存在, 且

$$\frac{\partial f}{\partial x_i^+}(X_0) = -\frac{\partial f}{\partial x_i^-}(X_0).$$

若 $\frac{\partial f}{\partial x_i}(X_0)$ 存在, 则

$$\frac{\partial f}{\partial x_i}(X_0) = \frac{\partial f}{\partial x_i^+}(X_0).$$

例题（注：方向导数存在且相等,但偏导数不存在）

### Example

$f(X) = |X| = \sqrt{x_1^2 + \cdots + x_n^2}$ , 对于任一方向  $\vec{l}$ ,  $|\vec{l}| = 1$ , 则

$$\frac{\partial f}{\partial \vec{l}}(O) = \lim_{t \rightarrow 0^+} \frac{f(t \vec{l}) - f(O)}{t} = 1.$$

故  $f(X)$  在  $O$  点沿任意方向的方向导数均为 1, 从而  $\frac{\partial f}{\partial x_i}(O)$  不存在.

例题 (注: 偏导数存在, 但方向导数不存在)

### Example

$$f(x, y) = \begin{cases} \frac{|x|^{\frac{1}{2}}|y|^{\frac{1}{2}}}{\sqrt{x^2 + y^2}}, & x^2 + y^2 \neq 0, \\ 0, & x^2 + y^2 = 0. \end{cases}$$

显然  $\frac{\partial f}{\partial x}(0, 0) = \frac{\partial f}{\partial y}(0, 0) = 0$ , 但取  $\vec{l} = \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}\right)$ , 由于

$$\lim_{t \rightarrow 0^+} \frac{f\left(\frac{\sqrt{2}}{2}t, \frac{\sqrt{2}}{2}t\right) - f(0, 0)}{t} = \lim_{t \rightarrow 0^+} \frac{\sqrt{2}}{2t} = +\infty,$$

从而  $\frac{\partial f}{\partial \vec{l}}(0, 0)$  不存在.

### Theorem

设 $f(X)$ 在 $X_0 \in \mathbb{R}^n$ 点可微, 则对于任

意 $\vec{l} = (\cos \alpha_1, \dots, \cos \alpha_n)$ ,  $\cos^2 \alpha_1 + \dots + \cos^2 \alpha_n = 1$ ,  
 $\frac{\partial f}{\partial \vec{l}}(X_0)$ 存在, 且

$$\frac{\partial f}{\partial \vec{l}}(X_0) = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(X_0) \cos \alpha_i = \langle \nabla f(X_0), \vec{l} \rangle.$$

一般地, 对任意非零向量 $\vec{l}$ , 有

$$\frac{\partial f}{\partial \vec{l}}(X_0) = \langle \nabla f(X_0), \frac{1}{|\vec{l}|} \vec{l} \rangle = \frac{1}{|\vec{l}|} \langle \nabla f(X_0), \vec{l} \rangle.$$

证明 由 $f(X)$ 在 $X_0$ 点可微知

$$f(X_0 + t \vec{l}) - f(X_0) = t \sum_{i=1}^n \frac{\partial f}{\partial x_i}(X_0) \cos \alpha_i + o(|t|).$$

由此可得

$$\begin{aligned} \lim_{t \rightarrow 0^+} \frac{f(X_0 + t \vec{l}) - f(X_0)}{t} &= \lim_{t \rightarrow 0^+} \left[ \sum_{i=1}^n \frac{\partial f}{\partial x_i}(X_0) \cos \alpha_i + \frac{o(|t|)}{t} \right] \\ &= \sum_{i=1}^n \frac{\partial f}{\partial x_i}(X_0) \cos \alpha_i, \end{aligned}$$

即 $\frac{\partial f}{\partial l}(X_0)$ 存在.

偏导数存在, 方向导数存在, 不可微, 但  $\frac{\partial f}{\partial \vec{l}} \neq \langle \nabla f, \vec{l} \rangle$

### Example

$$f(x, y) = \begin{cases} \frac{xy}{\sqrt{x^2 + y^2}}, & x^2 + y^2 \neq 0, \\ 0, & x^2 + y^2 = 0. \end{cases}$$

可知  $f'_x(0, 0) = f'_y(0, 0) = 0$ , 沿  $\vec{l} = (1, 1)$  的方向导数为  $\frac{\partial f}{\partial \vec{l}}(0, 0) = \frac{1}{2} \neq \langle \nabla f, \vec{l} \rangle = 0$ .



### Example

$$f(x, y) = \begin{cases} \frac{x^3 y}{x^8 + y^2}, & (x, y) \neq (0, 0) \\ 0, & (x, y) = (0, 0). \end{cases}$$

沿任何方向  $\vec{l}$ :  $\frac{\partial f}{\partial \vec{l}}(0, 0) = 0$ , 偏导数  $f'_x(0, 0) = f'_y(0, 0) = 0$ .

$f(x, y)$  在  $(0, 0)$  点不连续, 进而  $f(x, y)$  在  $(0, 0)$  点不可微. 事实上, 沿曲线  $\Gamma: y = x^4, x > 0$  有

$$\lim_{\Gamma \ni (x, y) \rightarrow (0, 0)} f(x, y) = \lim_{x \rightarrow 0^+} \frac{1}{2x} = +\infty.$$

## 二、梯度的性质（沿梯度方向函数增长最快）

设  $f(X)$  在  $X_0 \in \mathbb{R}^n$  可微,  $|\vec{l}| = 1$ , 由  $\frac{\partial f}{\partial \vec{l}}(X_0) = \langle \nabla f(X_0), \vec{l} \rangle \leq |\nabla f(X_0)|$ .

(i)  $\nabla f(X_0) = 0$ , 则对任意方向  $\vec{l}$  均有  $\frac{\partial f}{\partial \vec{l}}(X_0) = 0$ .

(ii)  $\nabla f(X_0) \neq 0$ , 上式等号成立当且仅当向量  $\vec{l}$  与向量  $\nabla f(X_0)$  方向相同, 则存在唯一的向量  $\vec{l}_0$  (即  $\nabla f(X_0)$ ) 使得  $\frac{\partial f}{\partial \vec{l}_0}(X_0) = |\nabla f(X_0)| = |\vec{l}_0|$ , 这时  $f(X)$  在  $X_0$  沿该方向的方向导数取值最大, 从而沿这个方向函数增长最快. 因此当梯度非零时, 它是函数增长最快的方向.

## 负梯度流(flow)

设  $H : \mathbb{R}^n \rightarrow \mathbb{R}$ , 考虑如下方程

$$\dot{\phi}(t) = -\nabla H(\phi(t)).$$

方程的解  $\phi : \mathbb{R} \rightarrow \mathbb{R}^n$  称为  $H$  的负梯度流.

函数  $H$  沿着负梯度流的值是单调不增的.

## 复习：重访复合函数求导的链式法则

设  $f: \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $G: \mathbb{R}^l \rightarrow \mathbb{R}^n$ , 令  $U(X) = f(G(X))$ , 则

$$G(X) = \begin{pmatrix} y_1(x_1, \cdots, x_l) \\ \vdots \\ y_n(x_1, \cdots, x_l) \end{pmatrix}, \quad (x_1, \cdots, x_l) \in \mathbb{R}^l.$$

$$dU(X_0) = J_f(Y_0)dG(X_0) = J_f(Y_0)J_G(X_0)\Delta X^T.$$

$$\Rightarrow \frac{\partial U}{\partial x_i}(X_0) = \sum_{j=1}^n \frac{\partial f}{\partial y_j}(Y_0) \frac{\partial y_j}{\partial x_i}(X_0), \quad i = 1, \cdots, l,$$

## 梯度的运算(链式法则,四则运算)

Theorem (复合函数的链式法则:  $\mathbb{R}^n \longrightarrow \mathbb{R}^m \longrightarrow \mathbb{R}$ )

设  $f(u_1, \dots, u_m)$  在  $U_0 = (u_{01}, \dots, u_{0m}) \in \mathbb{R}^m$  可微. 每个  $u_i$  在  $X_0 = (x_{01}, \dots, x_{0n}) \in \mathbb{R}^n$  可微,  $u_i(X_0) = u_{0i}$ , 记  $g(X) = f(u_1(X), \dots, u_m(X))$ , 则  $g$  在  $X_0$  可微, 且

$$\nabla g(X_0) = \sum_{i=1}^m \frac{\partial f}{\partial u_i}(U_0) \nabla u_i(X_0),$$

$$\left( \frac{\partial g}{\partial x_1}, \dots, \frac{\partial g}{\partial x_n} \right) = \left( \frac{\partial f}{\partial u_1}, \dots, \frac{\partial f}{\partial u_m} \right) \begin{pmatrix} \frac{\partial u_1}{\partial x_1} & \dots & \frac{\partial u_1}{\partial x_n} \\ \vdots & \vdots & \vdots \\ \frac{\partial u_m}{\partial x_1} & \dots & \frac{\partial u_m}{\partial x_n} \end{pmatrix}$$

$$\nabla g(X_0) = \nabla f(U_0) J_U(X_0) = \nabla f(U_0) \frac{\partial(u_1, \dots, u_m)}{\partial(x_1, \dots, x_n)}(X_0).$$

# 例题1

## Example

设函数 $u(x, y)$ 有一阶连续偏导数, 令 $x = r \cos \theta$ ,  $y = r \sin \theta$ , 证明

$$\left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 = \left(\frac{\partial u}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial u}{\partial \theta}\right)^2.$$

**证明** 由复合函数的链式法则得到

$$\begin{aligned}\frac{\partial u}{\partial r} &= \frac{\partial u}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial r} = \frac{\partial u}{\partial x} \cos \theta + \frac{\partial u}{\partial y} \sin \theta, \\ \frac{\partial u}{\partial \theta} &= \frac{\partial u}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial \theta} = -r \frac{\partial u}{\partial x} \sin \theta + r \frac{\partial u}{\partial y} \cos \theta.\end{aligned}$$

## 例题1

### Example

设函数 $u(x, y)$ 有一阶连续偏导数, 令 $x = r \cos \theta$ ,  $y = r \sin \theta$ , 证明

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**证明** 由链式法则

$$\begin{aligned} \left(\frac{\partial u}{\partial r}, \frac{\partial u}{\partial \theta}\right) &= \left(\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}\right) \begin{pmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{pmatrix} \\ &= \left(\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}\right) \begin{pmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{pmatrix}. \end{aligned}$$

$$\left(\frac{\partial u}{\partial r}, \frac{1}{r} \frac{\partial u}{\partial \theta}\right) = \left(\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}\right) \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}.$$

两边转置并相乘得

$$\begin{aligned} & \left(\frac{\partial u}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial u}{\partial \theta}\right)^2 \\ &= \left(\frac{\partial u}{\partial r}, \frac{1}{r} \frac{\partial u}{\partial \theta}\right) \left(\frac{\partial u}{\partial r}, \frac{1}{r} \frac{\partial u}{\partial \theta}\right)^T \\ &= \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2. \end{aligned}$$



## 例题2

### Example

设二阶偏导数连续的函数  $z = z(x, y)$  满足  $z''_{xx} + z''_{yy} = 0$ .

令  $x = r \cos \theta$ ,  $y = r \sin \theta$ ,  $w(r, \theta) = z(r \cos \theta, r \sin \theta)$ ,

求  $w = w(r, \theta)$  所满足的方程.

解

$$\frac{\partial w}{\partial r} = \frac{\partial z}{\partial x} \cos \theta + \frac{\partial z}{\partial y} \sin \theta,$$

$$\frac{\partial w}{\partial \theta} = -\frac{\partial z}{\partial x} r \sin \theta + \frac{\partial z}{\partial y} r \cos \theta.$$

从上式两等式中解得

$$\frac{\partial z}{\partial x} = \frac{\partial w}{\partial r} \cos \theta - \frac{\partial w}{\partial \theta} \frac{1}{r} \sin \theta,$$

$$\frac{\partial z}{\partial y} = \frac{\partial w}{\partial r} \sin \theta + \frac{\partial w}{\partial \theta} \frac{1}{r} \cos \theta.$$

$$\begin{aligned}
\frac{\partial^2 z}{\partial x^2} &= \frac{\partial}{\partial x} \frac{\partial z}{\partial x} = \left( \cos \theta \frac{\partial}{\partial r} - \frac{1}{r} \sin \theta \frac{\partial}{\partial \theta} \right) \left( \frac{\partial w}{\partial r} \cos \theta - \frac{\partial w}{\partial \theta} \frac{1}{r} \sin \theta \right) \\
&= \frac{\partial^2 w}{\partial r^2} \cos^2 \theta - \frac{\partial^2 w}{\partial r \partial \theta} \frac{1}{r} \sin \theta \cos \theta + \frac{\partial w}{\partial \theta} \frac{1}{r^2} \sin \theta \cos \theta \\
&\quad - \frac{\partial^2 w}{\partial \theta \partial r} \frac{1}{r} \sin \theta \cos \theta + \frac{\partial w}{\partial r} \frac{1}{r} \sin^2 \theta + \frac{\partial^2 w}{\partial \theta^2} \frac{1}{r^2} \sin^2 \theta \\
&\quad + \frac{\partial w}{\partial \theta} \frac{1}{r^2} \sin \theta \cos \theta.
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2 z}{\partial y^2} &= \frac{\partial^2 w}{\partial r^2} \sin^2 \theta + \frac{\partial^2 w}{\partial r \partial \theta} \frac{1}{r} \sin \theta \cos \theta - \frac{\partial w}{\partial \theta} \frac{1}{r^2} \sin \theta \cos \theta \\
&\quad + \frac{\partial^2 w}{\partial \theta \partial r} \frac{1}{r} \sin \theta \cos \theta + \frac{\partial w}{\partial r} \frac{1}{r} \cos^2 \theta + \frac{\partial^2 w}{\partial \theta^2} \frac{1}{r^2} \cos^2 \theta \\
&\quad - \frac{\partial w}{\partial \theta} \frac{1}{r^2} \sin \theta \cos \theta.
\end{aligned}$$

$$\frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial y^2} = \frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} + \frac{1}{r^2} \frac{\partial^2 w}{\partial \theta^2} = 0.$$

## Theorem

设  $D \subseteq \mathbb{R}^n$  是凸区域,  $f : D \rightarrow \mathbb{R}$  是可微函数, 则对任意  $X_1, X_2 \in D$ , 在以  $X_1, X_2$  为端点的线段上存在一点  $\xi$ , 使得

$$f(X_2) - f(X_1) = \langle \nabla f(\xi), X_2 - X_1 \rangle.$$

注: 该结论对向量值函数不成立. 例如  $F : [0, 2\pi] \rightarrow \mathbb{R}^2$ ,

$$F(t) = \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}, \quad t \in [0, 2\pi].$$

(反证) 若存在  $\xi \in [0, 2\pi]$  使得

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = F(2\pi) - F(0) = J_F(\xi)(2\pi - 0) = 2\pi \begin{pmatrix} \cos \xi \\ -\sin \xi \end{pmatrix}, \quad \text{矛盾.}$$

以 $X_1, X_2$ 为端点的线段上的任意一点可表示为

$$X = X_1 + t(X_2 - X_1), 0 \leq t \leq 1.$$

考虑一元函数 $g(t) = f(X_1 + t(X_2 - X_1))$ ,

有 $g'(t) = \langle \nabla f(X_1 + t(X_2 - X_1)), X_2 - X_1 \rangle$ . 由一元函数的微分中值定理, 存在 $t_0 \in (0, 1)$ 使得

$$\begin{aligned} f(X_2) - f(X_1) &= g(1) - g(0) = g'(t_0) \\ &= \langle \nabla f(X_1 + t_0(X_2 - X_1)), X_2 - X_1 \rangle. \end{aligned}$$

因此取 $\xi = X_1 + t_0(X_2 - X_1)$ 即可.

设 $D$ 是 $\mathbb{R}^n$ 中的凸区域,  $F : D \rightarrow \mathbb{R}^m$ 可微, 对于 $X_1, X_2 \in D$ , 求证: 存在 $\theta \in (0, 1)$ , 使得

$$|F(X_2) - F(X_1)| \leq |J_F(X_1 + \theta(X_2 - X_1))| |X_2 - X_1|.$$

Proof. 可考虑

$$G(t) = \langle F(X_1 + t(X_2 - X_1)) - F(X_1), F(X_2) - F(X_1) \rangle, \quad t \in [0, 1].$$

## Corollary

若定义在区域  $D \subseteq \mathbb{R}^n$  内的函数  $f(X)$  的偏导数恒为零, 则  $f$  为常值函数.

**证明**  $D$  是道路连通的, 只须证  $f(X_1) = f(X_2), \forall X_1, X_2 \in D$ . 取连续道路  $\gamma: [0, 1] \rightarrow D$  满足  $\gamma(0) = X_1, \gamma(1) = X_2$ .  $[0, 1]$  紧  $\Rightarrow \gamma([0, 1])$  紧. 对于任意  $X \in \gamma([0, 1])$ , 存在  $r = r(X) > 0$ , 使得  $B_r(X) \subseteq D$ , 则  $\gamma([0, 1]) \subseteq \{B_r(X) \mid X \in \gamma([0, 1])\}$  开覆盖, 故存在有限子覆盖:

$$\gamma([0, 1]) \subseteq \bigcup_{i=1}^k B_{r_i}(X_i) \subseteq D.$$

而每个  $B_{r_i}(X_i)$  均为凸区域, 故  $f(X)$  在每个  $B_{r_i}(X_i)$  均为常数, 特别地,  $f(X)$  沿  $\gamma([0, 1])$  取常值, 故有  $f(X_1) = f(X_2)$ .

任取一个点  $X_0 \in D$ , 令

$$U = \{X \in D \mid f(X) = f(X_0)\}.$$

只须证  $U$  是  $D$  的非空相对开且相对闭子集, 由  $D$  的连通性, 即得  $U = D$ .

(1) 非空. 由于  $X_0 \in U$ .

(2) 相对闭. 若  $X_m \in U$  且  $X_m \rightarrow X^* \in D$ ,

则  $f(X^*) = \lim_{m \rightarrow \infty} f(X_m) = f(X_0)$ , 即  $X^* \in U$ , 从而  $U$  是  $D$  相对闭.

(3) 相对开. 若  $Y \in U$ , 由于  $D$  开, 从而存在  $\delta > 0$ , 使  $B_\delta(Y) \subseteq D$ . 由于  $B_\delta(Y)$  凸, 对任意  $X \in B_\delta(Y)$ , 有

$$f(X) - f(Y) = \langle \nabla f(\xi), X - Y \rangle = 0.$$

故  $B_\delta(Y) \subseteq U$ , 则  $U$  是  $D$  的相对开集.

注: 由 $g(t)$ 是一元凸函数, 则

$$\varphi(t) = \frac{g(t) - g(t_0)}{t - t_0}, \quad t \neq t_0$$

是增函数, 由单调有界原理,  $g'_+(t_0)$ 与 $g'_-(t_0)$ 都存在, 并且有

$$g'_+(t_0) \geq g'_-(t_0).$$



## 凸函数的方向导数存在

(1) 设  $f(X)$  是  $\mathbb{R}^n$  上的凸函数, 任取  $X_0 \in \mathbb{R}^n$  和单位方向向量  $\vec{l}$ , 则  $\frac{\partial f}{\partial \vec{l}}(X_0)$  存在. 记  $\frac{\partial f}{\partial \vec{l}}(X_0)$  表示  $f$  在  $X_0$  沿  $\vec{l}$  的方向导数, 则

$$\frac{\partial f}{\partial \vec{l}}(X_0) \geq -\frac{\partial f}{\partial \vec{l}^-}(X_0).$$

证明

令  $g(t) = f(X_0 + t \vec{l}), t \in \mathbb{R}$ . 则  $g(t)$  是  $\mathbb{R}$  上的凸函数.

且有  $\frac{\partial f}{\partial \vec{l}}(X_0) = g'_+(0), \frac{\partial f}{\partial \vec{l}^-}(X_0) = -g'_-(0).$

偏导数存在  $\xrightarrow{\text{凸}}$  可微

(2) 设  $f(X)$  是  $\mathbb{R}^n$  上的凸函数, 若在  $X_0$  点所有偏导数存在, 则  $f(X)$  在  $X_0$  可微.

**证明** 不妨设  $X_0 = O$ . 函数  $f(tX)$  关于  $t$  是凸的, 从而

$$\varphi(t) = \frac{f(tX) - f(O)}{t}, \quad t \neq 0$$

是增函数.

$\forall X = (x_1, \dots, x_n) \in \mathbb{R}^n$ , 取  $\mathbb{R}^n$  的标准正交基  $\{e_i\}$ ,

$$\begin{aligned} f(X) - f(O) &= \varphi(1) \geq \lim_{t \rightarrow 0^+} \varphi(t) \geq \lim_{t \rightarrow 0^-} \varphi(t) \\ &= \lim_{t \rightarrow 0^-} \frac{f(O) - f(tX)}{-t} \\ &= \lim_{t \rightarrow 0^-} \frac{\sum_{i=1}^n (f(O) - f(ntx_i e_i))}{-nt} \\ (tX = \frac{\sum_{i=1}^n ntx_i e_i}{n} \text{ 和 } f \text{ 凸}) &\geq \lim_{t \rightarrow 0^-} \frac{\sum_{i=1}^n (f(O) - f(ntx_i e_i))}{-nt} \\ &= \sum_{i=1}^n x_i \frac{\partial f}{\partial x_i}(O), \\ f(X) - f(O) &\geq \sum_{i=1}^n \frac{\partial f}{\partial x_i}(O) x_i. \end{aligned}$$

注:  $f(X) - f(O) \geq \langle \nabla f(O), X \rangle$ .

另一方面, 由 $f$ 的凸性可得

$$\begin{aligned} f(X) - f(O) &\leq \frac{1}{n} \sum_{i=1}^n \left[ f(nx_i \vec{e}_i) - f(O) \right] \\ &= \sum_{i=1}^n \frac{1}{n} [f(0, \dots, nx_i, \dots, 0) - f(0, \dots, 0)] \\ &= \sum_{i=1}^n \frac{\partial f}{\partial x_i}(O) x_i + \frac{1}{n} \sum_{i=1}^n \rho_i |x_i|, \end{aligned}$$

由柯西不等式可得

$$\left| \sum_{i=1}^n \rho_i |x_i| \right| \leq \sqrt{\rho_1^2 + \dots + \rho_n^2} |X| = o(|X|)$$

综上所述可知

$$f(X) - f(O) = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(O) x_i + o(|X|).$$