

$$\rho \frac{\partial^2 \vec{u}}{\partial t^2} - (\lambda + 2\mu) \vec{\nabla}(\vec{\nabla} \cdot \vec{u}) + \mu \vec{\nabla} \times (\vec{\nabla} \times \vec{u}) = \vec{F} \quad (1)$$

usando  $\vec{\nabla}^2 \vec{A} - \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) = -\vec{\nabla} \times (\vec{\nabla} \times \vec{A})$

$$\begin{aligned} \rho \frac{\partial^2 \vec{u}}{\partial t^2} - (\lambda + 2\mu) \vec{\nabla}(\vec{\nabla} \cdot \vec{u}) + \mu(\vec{\nabla}(\vec{\nabla} \cdot \vec{u}) - \vec{\nabla}^2 \vec{u}) &= \vec{F} \\ \rho \frac{\partial^2 \vec{u}}{\partial t^2} &= (\lambda + \mu) \vec{\nabla}(\vec{\nabla} \cdot \vec{u}) + \mu \vec{\nabla}^2 \vec{u} + \vec{F} \end{aligned}$$

Tensorialmente

$$\boxed{\rho \frac{\partial^2 u_i}{\partial t^2} = (\lambda + \mu) \frac{\partial}{\partial x_i} \frac{\partial u_j}{\partial x_j} + \mu \frac{\partial^2 u_i}{\partial x_j \partial x_j} + F_i}$$

Si  $F_i = \delta_{ij} \delta(t) \delta(x)$  se obtiene que la solución es  $u_i = G_{ij}$ . Buscamos una solución ortogonal con simetría esférica. Para ello descompondremos el problema con 2 operadores ortogonales ( $M^p$  y  $M^s$ ).

Si  $\vec{v}$  es un vector arbitrario  $\vec{v} = \vec{v}(\vec{x}, t)$

$$\begin{aligned} M^p \vec{v} &= \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) \\ M^s \vec{v} &= \vec{\nabla}^2 \vec{v} - \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) = -\vec{\nabla} \times (\vec{\nabla} \times \vec{v}) \end{aligned}$$

donde

$$\begin{aligned} M^p(M^s \vec{v}) &= M^s(M^p \vec{v}) = 0 \quad (\text{ortogonalidad}) \\ M^p(M^p \vec{v}) &= M^p(\vec{\nabla}^2 \vec{v}) \\ M^s(M^s \vec{v}) &= M^s(\vec{\nabla}^2 \vec{v}) \end{aligned}$$

Reescribiendo (1) con  $\boxed{\alpha^2 = \frac{\lambda + 2\mu}{\rho} \quad \text{y} \quad \beta^2 = \frac{\mu}{\rho}}$

$$\rho \frac{\partial^2 \vec{u}}{\partial t^2} - (\lambda + 2\mu) M^p \vec{u} - \mu M^s \vec{u} = \vec{F}$$

$$\frac{\partial^2 \vec{u}}{\partial t^2} = \frac{\vec{F}}{\rho} + \alpha^2 M^p \vec{u} + \beta^2 M^s \vec{u} \quad (2)$$

Podemos escribir  $\vec{u}(\vec{x}, t) = M^p \vec{A}^p(\vec{x}, t) + M^s \vec{A}^s(\vec{x}, t)$

donde al reemplazar en (2) y como  $M^p$  y  $M^s$  no dependen de t

$$\left( M^p \frac{\partial^2 \vec{A}^p}{\partial t^2} + M^s \frac{\partial^2 \vec{A}^s}{\partial t^2} \right) = \frac{\vec{F}}{\rho} + \alpha^2 M^p (M^p \vec{A}^p + M^s \vec{A}^s) + \beta^2 M^s (M^p \vec{A}^p + M^s \vec{A}^s)$$

como

$$\begin{aligned} M^k(M^k \vec{A}^k) &= M^k(\vec{\nabla}^2 \vec{A}^k) \quad \text{con} \quad k = \{s, p\} \\ M^p(M^s \vec{A}) &= M^s(M^p \vec{A}) = 0 \end{aligned}$$

$$\begin{aligned} \left( M^p \frac{\partial^2 \vec{A}^p}{\partial t^2} + M^s \frac{\partial^2 \vec{A}^s}{\partial t^2} \right) &= \frac{\vec{F}}{\rho} + \alpha^2 M^p (\vec{\nabla}^2 \vec{A}^p) + \beta^2 M^s (\vec{\nabla}^2 \vec{A}^s) \\ M^p \left( \alpha^2 \vec{\nabla}^2 \vec{A}^p - \frac{\partial^2 \vec{A}^p}{\partial t^2} \right) + M^s \left( \beta^2 \vec{\nabla}^2 \vec{A}^s - \frac{\partial^2 \vec{A}^s}{\partial t^2} \right) + \frac{\vec{F}}{\rho} &= 0 \end{aligned}$$

Además,  $\vec{F} = \vec{f}(t)\delta(x)$ ; usando la relación  $\nabla^2 \left( \frac{-1}{4\pi r} \right) = \delta(x)$  donde  $r = |\vec{x}| = \sqrt{x^2 + y^2 + z^2}$ ,  $\vec{F} = \vec{f}(t)\vec{\nabla}^2 \left( \frac{-1}{4\pi r} \right) = \vec{\nabla}^2 \left( \frac{-\vec{f}(t)}{4\pi r} \right)$ .

Así

$$M^p \left( \alpha^2 \vec{\nabla}^2 \vec{A}^p - \frac{\partial^2 \vec{A}^p}{\partial t^2} \right) + M^s \left( \beta^2 \vec{\nabla}^2 \vec{A}^s - \frac{\partial^2 \vec{A}^s}{\partial t^2} \right) = \frac{\vec{\nabla}^2}{\rho} \left( \frac{\vec{f}(t)}{4\pi r} \right)$$

como

$$\begin{aligned} M^p \vec{v} + M^s \vec{v} &= \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) + \nabla^2 \vec{v} - \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) \\ (M^p + M^s) \vec{v} &= \nabla^2 \vec{v} \end{aligned}$$

$$\rho M^p \left( \alpha^2 \vec{\nabla}^2 \vec{A}^p - \frac{\partial^2 \vec{A}^p}{\partial t^2} \right) + \rho M^s \left( \beta^2 \vec{\nabla}^2 \vec{A}^s - \frac{\partial^2 \vec{A}^s}{\partial t^2} \right) = M^p \left( \frac{\vec{f}(t)}{4\pi r} \right) + M^s \left( \frac{\vec{f}(t)}{4\pi r} \right)$$

Así, resolviendo para  $\vec{A}$  que es análogo a  $\vec{A}^s$  y  $\vec{A}^p$  con  $c^2 = \{\alpha^2, \beta^2\}$ .

$$c^2 \vec{\nabla}^2 \vec{A} - \frac{\partial^2 \vec{A}}{\partial t^2} = \frac{\vec{f}(t)}{4\pi r \rho} \cdot r$$

Asumiendo simetría esférica para  $\vec{A} = \vec{A}(r, t)$

$$\begin{aligned} \vec{\nabla}^2 \vec{A} &= \frac{1}{r} \frac{\partial^2}{\partial r^2} (r \vec{A}) \rightarrow r \vec{\nabla}^2 \vec{A} = \frac{\partial^2}{\partial r^2} (r \vec{A}) \\ c^2 \frac{\partial^2}{\partial r^2} (r \vec{A}) - r \frac{\partial^2 \vec{A}}{\partial t^2} &= \frac{\vec{f}(t)}{4\pi \rho}; \quad (\vec{f}(t) = \ddot{\vec{p}}(t)) \\ c^2 \frac{\partial^2}{\partial r^2} (r \vec{A}) - \frac{\partial^2}{\partial t^2} (r \vec{A}) &= \frac{\vec{f}(t)}{4\pi \rho} = \frac{\ddot{\vec{p}}(t)}{4\pi \rho} \end{aligned}$$

Ec. de onda inhomogénea para  $r \vec{A}$

$$r \vec{A} = \underbrace{\vec{U}_1 \left( t - \frac{r}{c} \right) + \vec{U}_2 \left( t + \frac{r}{c} \right)}_{\text{Sol. Homogénea}} - \underbrace{\frac{\vec{p}(t)}{4\pi \rho}}_{\text{Sol. Particular}}$$

$\vec{U}_2 = \vec{0}$  pues las ondas salen desde el origen!  
y para evitar singularidades en  $r \rightarrow 0$

$$\begin{aligned} 0 \cdot \vec{A} = \vec{0} &= \vec{U}_1(t) = \frac{\vec{p}(t)}{4\pi \rho} \rightarrow \vec{U}_1 \left( t - \frac{r}{c} \right) = \frac{\vec{p}\left(t - \frac{r}{c}\right)}{4\pi \rho} \\ \text{Así, } \vec{A}(r, t) &= \frac{\vec{p}\left(t - \frac{r}{c}\right) - \vec{p}(t)}{4\pi \rho r} \\ \vec{A}^p &= \frac{\vec{p}\left(t - \frac{r}{\alpha}\right) - \vec{p}(t)}{4\pi \rho r}; \quad \vec{A}^s = \frac{\vec{p}\left(t - \frac{r}{\beta}\right) - \vec{p}(t)}{4\pi \rho r} \end{aligned}$$

$$\begin{aligned}
&\text{donde } \vec{u} = M^p \vec{A}^p + M^s \vec{A}^s \\
&M^p \vec{v} = \vec{\nabla}(\vec{\nabla} \cdot \vec{v}); M^s \vec{v} = \vec{\nabla}^2 \vec{v} - \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) \\
&\vec{u} = \vec{\nabla} \left( \vec{\nabla} \cdot \left( \frac{\vec{p}(t-\frac{r}{\alpha}) - \vec{p}(t)}{4\pi\rho r} \right) \right) + \vec{\nabla}^2 \left( \frac{\vec{p}(t-\frac{r}{\beta}) - \vec{p}(t)}{4\pi\rho r} \right) - \vec{\nabla} \left( \vec{\nabla} \cdot \left( \frac{\vec{p}(t-\frac{r}{\beta}) - \vec{p}(t)}{4\pi\rho r} \right) \right) \\
&\vec{u} = -\vec{\nabla}^2 \left( \frac{\vec{p}(t)}{4\pi\rho r} \right) + (\vec{\nabla}^2 - \vec{\nabla}(\vec{\nabla} \cdot)) \left( \frac{\vec{p}(t-\frac{r}{\beta})}{4\pi\rho r} \right) - \vec{\nabla} \left( \vec{\nabla} \cdot \left( \frac{\vec{p}(t-\frac{r}{\alpha})}{4\pi\rho r} \right) \right)
\end{aligned}$$

donde recordamos  $r = |\vec{x}| = \sqrt{x^2 + y^2 + z^2}$ .

Reescribiendo en forma tensorial

$$\begin{aligned}
u_i &= -\delta_{ij} \nabla^2 \left( \frac{P_j(t)}{4\pi\rho r} \right) + \left( \delta_{ij} \nabla^2 - \frac{\partial^2}{\partial x_i \partial x_j} \right) \left( \frac{P_j(t-\frac{r}{\beta})}{4\pi\rho r} \right) + \frac{\partial^2}{\partial x_i \partial x_j} \left( \frac{P_j(t-\frac{r}{\alpha})}{4\pi\rho r} \right) \\
\text{Donde } \delta_{ij} \nabla^2 \left( \frac{P_j(t)}{4\pi\rho r} \right) &= P_j(t) \frac{\partial^2}{\partial x_j \partial x_j} \left( \frac{1}{4\pi\rho r} \right) \\
&= \frac{P_j(t)}{4\pi\rho} \left( \frac{\partial^2}{\partial x_j \partial x_j} \left( \frac{1}{r} \right) \right) \\
&= \frac{P_j(t)}{4\pi\rho} \left( \frac{3\gamma_j \gamma_j - \delta_{jj}}{r^3} \right) = 0 \quad ; \quad r > 0
\end{aligned}$$

$$\begin{aligned}
&\text{donde } \gamma_j \gamma_j = 1 = \gamma_x^2 + \gamma_y^2 + \gamma_z^2 = \frac{x^2 + y^2 + z^2}{r^2} \\
&\delta_{jj} = 1 + 1 + 1 \quad (\text{convenio de Einstein})
\end{aligned}$$

$$\begin{aligned}
\text{Así, } u_i &= \left( \delta_{ij} \nabla^2 - \frac{\partial^2}{\partial x_i \partial x_j} \right) \left( \frac{P_j(t-\frac{r}{\beta})}{4\pi\rho r} \right) + \frac{\partial^2}{\partial x_i \partial x_j} \left( \frac{P_j(t-\frac{r}{\alpha})}{4\pi\rho r} \right) \\
u_i &= (\delta_{ij} - \gamma_i \gamma_j) \frac{\ddot{P}_j(t-\frac{r}{\beta})}{4\pi\rho\beta^2 r} + \frac{\gamma_i \gamma_j}{4\pi\rho\alpha^2} \ddot{P}_j(t-\frac{r}{\alpha}) + \frac{P_j(t-\frac{r}{\alpha}) - P_j(t-\frac{r}{\beta})}{4\pi\rho} \frac{\partial^2}{\partial x_i \partial x_j} \left( \frac{1}{r} \right)
\end{aligned}$$

$$\text{donde } \frac{\partial^2}{\partial x_i \partial x_j} \left( \frac{1}{r} \right) = \frac{\partial}{\partial x_i} \left( -\frac{1}{r^2} \frac{\partial r}{\partial x_j} \right)$$

$$\begin{aligned}
&= \frac{2}{r^3} \frac{\partial r}{\partial x_i} \frac{\partial r}{\partial x_j} - \frac{1}{r^2} \frac{\partial}{\partial x_i} \left( \frac{\partial r}{\partial x_j} \right) \\
&= \frac{2}{r^3} \gamma_i \gamma_j - \frac{1}{r^2} \left( \frac{\partial}{\partial x_i} \left( \frac{x_j}{r} \right) \right) \\
&= \frac{2}{r^3} \gamma_i \gamma_j - \frac{1}{r^2} \left( \frac{\partial x_j}{\partial x_i} \left( \frac{1}{r} \right) - \frac{x_j}{r^2} \frac{\partial r}{\partial x_i} \right) \\
&= \frac{2}{r^3} \gamma_i \gamma_j - \frac{1}{r^3} \delta_{ij} + \frac{1}{r^3} \gamma_j \gamma_i \\
&= \frac{3\gamma_i \gamma_j - \delta_{ij}}{r^3} \\
u_i &= (\delta_{ij} - \gamma_i \gamma_j) \frac{1}{4\pi\rho\beta^2 r} \ddot{P}_j \left( t - \frac{r}{\beta} \right) + \frac{\gamma_i \gamma_j}{4\pi\rho\alpha^2 r} \ddot{P}_j \left( t - \frac{r}{\alpha} \right) + \left( \frac{3\gamma_i \gamma_j - \delta_{ij}}{4\pi\rho r^3} \right) \left( P_j \left( t - \frac{r}{\alpha} \right) - P_j \left( t - \frac{r}{\beta} \right) \right) \\
&\text{Para hallar } G_{ij} \text{ basta considerar}
\end{aligned}$$

$$\begin{aligned}
u_i = G_{ij} &\leftrightarrow f_i = \delta_{ij} \delta(t) \delta(\vec{r}) \\
&f_i = \delta_{ij} \delta(t)
\end{aligned}$$

$$\text{Así } P_i(t) = \delta_{ij}R(t)$$

$$R(t) = \begin{cases} t & ; \quad t > 0 \\ 0 & ; \quad t < 0 \end{cases} \rightarrow \ddot{P}_i(t) = \delta(t)$$

Finalmente tenemos lo siguiente,

$$G_{ij} = -\frac{(-\delta_{ij} + \gamma_i \gamma_j)}{4\pi\rho\beta^2 r} \delta\left(t - \frac{r}{\beta}\right) + \frac{\gamma_i \gamma_j}{4\pi\rho\alpha^2 r} \delta\left(t - \frac{r}{\alpha}\right) +$$

$$\left(\frac{3\gamma_i \gamma_j - \delta_{ij}}{4\pi\rho r^3}\right) \underbrace{\int_{\frac{r}{\alpha}}^{\frac{r}{\beta}} \tau \delta(1 - \tau) d\tau}_t \rightarrow$$

Usando la  
representación  
integral de  $R(t)$