Import relevant packages here.

```
In [3]:
        import matplotlib.pyplot as plt
        import numpy as np
```

Load the data and verify it is loaded correctly.

• Print it (head, tail, or specific rows, choose a sensible number of rows).

0.262078]

-0.61244]]

• Compare it to the source file.

```
In [4]: data = np.loadtxt('cf data.csv', dtype=np.float64, delimiter=',', skiprows=1)
        print(data)
        [[-0.74324 53.5427]
                                1.24257 ]
         [-0.55723 53.612
                                1.77792 ]
         [-0.454769 53.6541
                                0.544107]
         [ 5.13764 115.118
                                0.232283]
```

In the ensuing, you will use numpy.

[5.15348 114.599

[5.25868 113.112

Let's create a grid for the values to plot. But first create **two arrays named dv and s** using numpy.linspace that hold the grid values at the relevant indices in their respective dimension of the grid.

Create a **grid named a** with zeros using numpy zeros in to which calculated acceleration values can be stored.

Let the grid span:

- Speed difference dv [m/s]
 - From -10 till 10
 - With 41 evenly spaced values
- Headway s [m]
 - From 0 till 200

With 21 evenly spaced values

```
In [5]: dv = np.linspace(-10, 10, 41)
        s = np.linspace(0, 200, 21)
        a = np.zeros([dv.size, s.size])
```

Create from the imported data 3 separate numpy arrays for each column dv, s and a. (We do this for speed reasons later.)

- Make sure to name them differently from the arrays that belong to the grid as above. • You can access the data of each column in a DataFrame using data.xxx where xxx is the column name (not as a string).
- Use the method to_numpy() to convert a column to a numpy array.

```
In [6]: DV = data[:, 0]
        S = data[:, 1]
        A = data[:, 2]
```

the lecture. At each grid point, it calculates a weighted mean of all measurements. The weights are given by an exponential function, based on the 'distance' between the grid point, and the measurement values of dv and s. To get you started, how many for -loops do you need?

Create an algorithm that calculates all the acceleration values and stores them in the grid. The algorithm is described visually in the last part of

For this you will need math.

• Print a line for each iteration of the outer-most for -loop that shows you the progress.

Warning: This calculation may take some time. So:

Use an *upsilon* of 1.5m/s and a *sigma* of 30m.

- Test you code by running it only on the first 50 measurements of the data.

```
In [45]: import time
         upsilon = 1.5
         sigma = 30
         def filter_a(dv, s):
             dv_grid, s_grid = np.meshgrid(dv, s)
             # timer, progress
             start = time.time()
             progress, total = 0, np.size(dv_grid)
             def one_step_filter(dv_item, s_item):
                 nonlocal progress
                 # main body
                 omega = lambda DV_item, S_item: np.exp(- np.abs(dv_item - DV_item)/upsilon - np.abs(s_item - S_item)/sigma)
                 smooth_A_item = np.sum(omega(DV, S) * A) / np.sum(omega(DV, S))
                 # print progress
                 progress += 1
                 if progress % 1e2 == 0:
                      print("progress now: %.2f %%" % (progress / total * 1e2), ", time elapsed %.2f s" % (time.time() - start))
                 return smooth A item
             one step filter = np.vectorize(one step filter)
             return one step filter(dv grid, s grid)
         a = filter_a(dv, s)
         print("complete!")
         print("a shape:", a.shape)
         progress now: 11.61 % , time elapsed 0.23 s
         progress now: 23.23 % , time elapsed 0.41 s
         progress now: 34.84 % , time elapsed 0.60 s
         progress now: 46.46 % , time elapsed 0.77 s
         progress now: 58.07 % , time elapsed 0.94 s
         progress now: 69.69 % , time elapsed 1.13 s
         progress now: 81.30 % , time elapsed 1.30 s
         progress now: 92.92 % , time elapsed 1.47 s
         complete!
         a shape: (21, 41)
In [41]: # test case
         a_test = filter_a(dv[:25], s[:2])
```

```
0.43853545 0.42333708 0.41087822 0.39771161 0.3804174
                                                           0.35928689
 0.32570546 0.28687769 0.24632719 0.20100141 0.14857471 0.09012394
 0.02700055 - 0.04124758 - 0.11562593 - 0.19879562 - 0.28130451 - 0.35755138
-0.42593754]
[ 0.53152837  0.52472414  0.51473605  0.49722638  0.47772383  0.4593541
 0.44141404 0.42624089 0.41381434 0.40068399 0.38342171 0.3623419
 0.32881282 0.29005594 0.24939012 0.2039263 0.15133874 0.09271452
 0.0295022 -0.03888711 -0.11350169 -0.19686542 -0.27981293 -0.3564541
```

 $[[0.52879029 \quad 0.52197296 \quad 0.51196083 \quad 0.49443067 \quad 0.47489727 \quad 0.4564993]$

Negative (slower than leader) and positive (faster than leader) speed differences?

The following code will plot the data for you. Does it make sense when considering:

- Small and large headways?
- In [42]: X, Y = np.meshgrid(dv, s)

print(a_test)

-0.42518631]]

```
axs = plt.axes()
p = axs.pcolor(X, Y, a, shading='nearest')
axs.set_title('Acceleration [m/s/s]')
axs.set_xlabel('Speed difference [m/s]')
axs.set ylabel('Headway [m]')
axs.figure.colorbar(p)
axs.figure.set_size_inches(10, 7)
```

