



CH7. TREES

CSED233 Data Structure

Prof. Hwanjo Yu

POSTECH

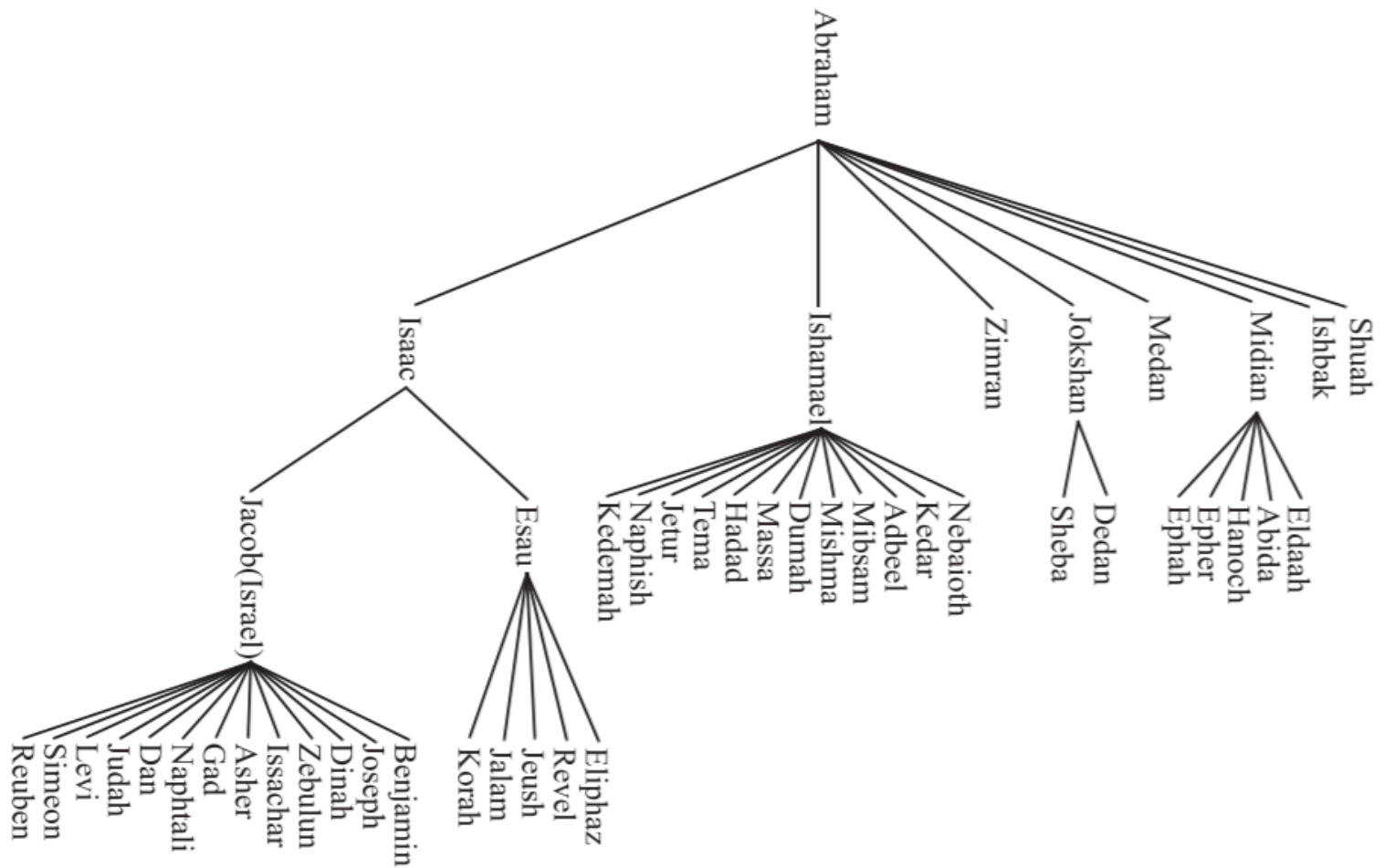
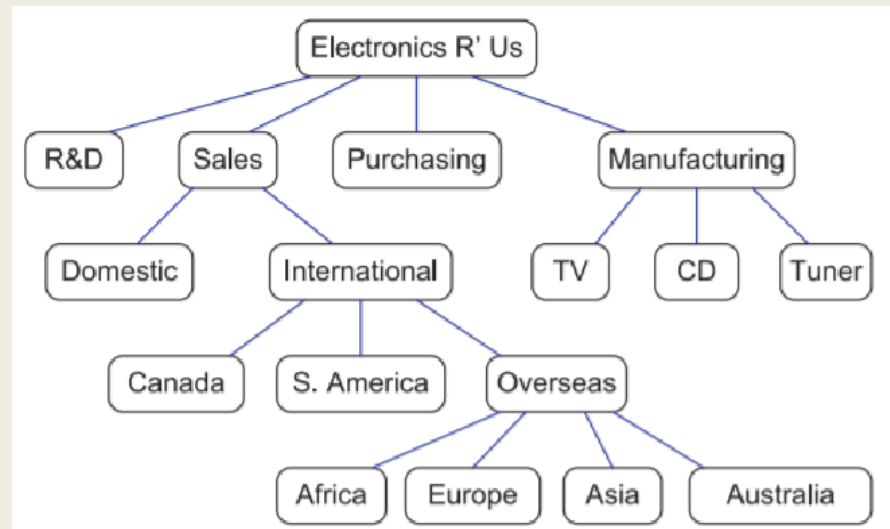


Figure 7.1: A family tree showing some descendants of Abraham, as recorded in Genesis, chapters 25–36.

Tree Definitions and Properties

■ Tree

- *Parent*
- *Children*
- *Root*
- *Siblings*
- *External nodes (leaves)*
- *Internal nodes*
- *Ancestor*
- *Descendent*
- *Subtree*
- *Edge and path*



■ Position

- *p.parent()*
- *p.children(): returns a position list*
- *root(): returns a position*
- *positions(): returns a position list of all the nodes*

C++ Tree Interface

```
template <typename E>           // base element type
class Position<E> {             // a node position
public:
    E& operator*();              // get element
    Position parent() const;      // get parent
    PositionList children() const; // get node's children
    bool isRoot() const;          // root node?
    bool isExternal() const;      // external node?
};
```

Code Fragment 7.1: An informal interface for a position in a tree (not a complete C++ class).

```
template <typename E>           // base element type
class Tree<E> {
public:                           // public types
    class Position;               // a node position
    class PositionList;           // a list of positions
public:                           // public functions
    int size() const;             // number of nodes
    bool empty() const;           // is tree empty?
    Position root() const;        // get the root
    PositionList positions() const; // get positions of all nodes
};
```

Code Fragment 7.2: An informal interface for the tree ADT (not a complete class).

- PositionList
 - *An STL list of Position*
 - “*std::list<Position>*”

A Linked Structure for General Trees

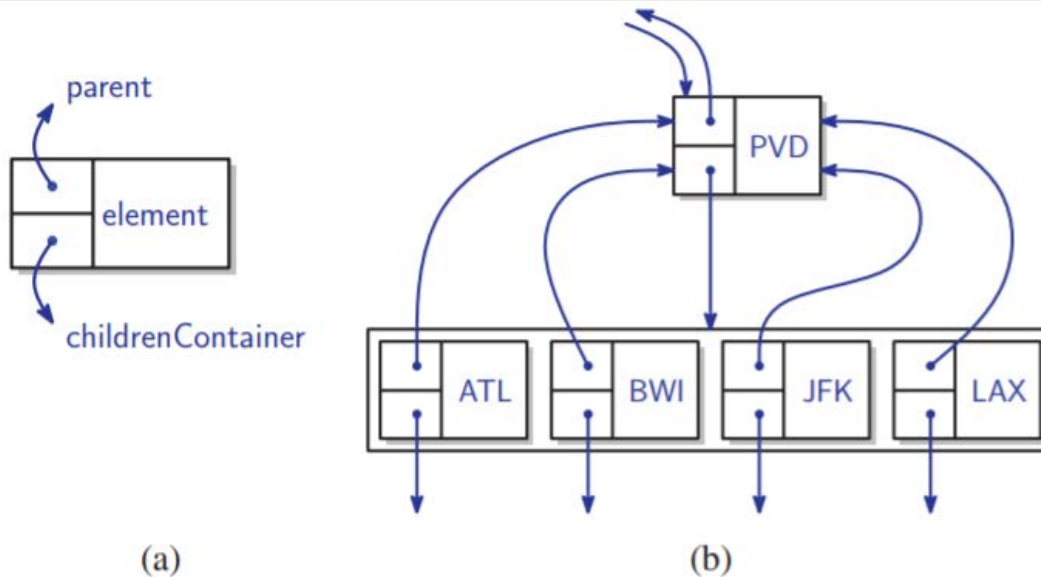


Figure 7.5: The linked structure for a general tree: (a) the node structure; (b) the portion of the data structure associated with a node and its children.

<i>Operation</i>	<i>Time</i>
isRoot, isExternal	$O(1)$
parent	$O(1)$
children(p)	$O(c_p)$
size, empty	$O(1)$
root	$O(1)$
positions	$O(n)$

Depth and Height

```
int depth(const Tree& T, const Position& p) {  
    if (p.isRoot())  
        return 0;                // root has depth 0  
    else  
        return 1 + depth(T, p.parent());    // 1 + (depth of parent)  
}
```

```
int height1(const Tree& T) {  
    int h = 0;  
    PositionList nodes = T.positions();    // list of all nodes  
    for (Iterator q = nodes.begin(); q != nodes.end(); ++q) {  
        if (q->isExternal())  
            h = max(h, depth(T, *q));    // get max depth among leaves  
    }  
    return h;  
}
```

```
int height2(const Tree& T, const Position& p) {  
    if (p.isExternal()) return 0;    // leaf has height 0  
    int h = 0;  
    PositionList ch = p.children();    // list of children  
    for (Iterator q = ch.begin(); q != ch.end(); ++q)  
        h = max(h, height2(T, *q));  
    return 1 + h;    // 1 + max height of children  
}
```

Preorder Traversal

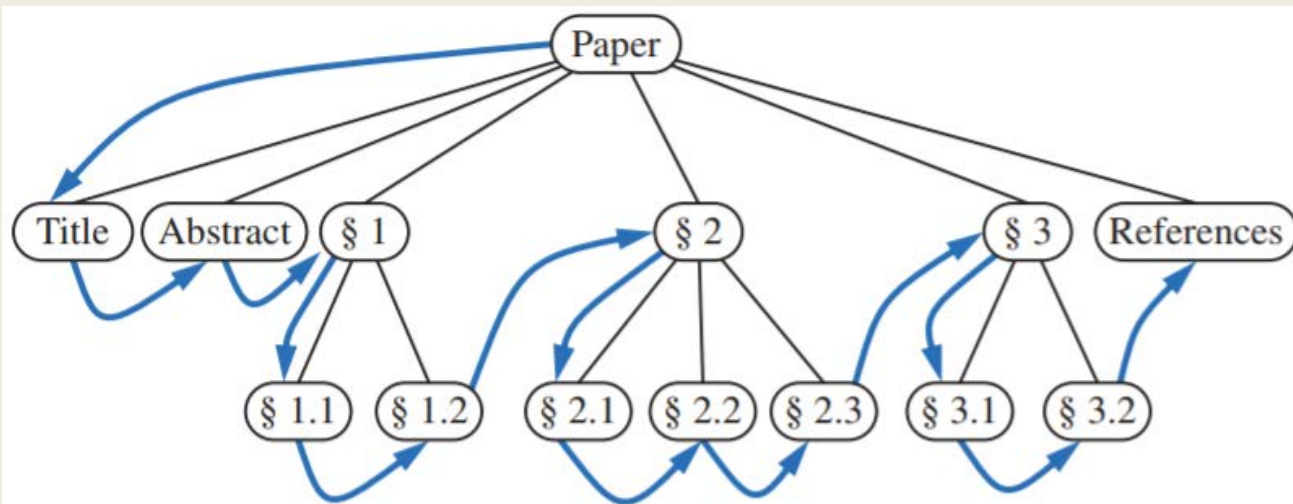


Figure 7.6: Preorder traversal of an ordered tree, where the children of each node are ordered from left to right.

```
void preorderPrint(const Tree& T, const Position& p) {  
    cout << *p;                                // print element  
    PositionList ch = p.children();              // list of children  
    for (Iterator q = ch.begin(); q != ch.end(); ++q) {  
        cout << " ";  
        preorderPrint(T, *q);  
    }  
}
```

Code Fragment 7.10: Method `preorderPrint(T, p)` that performs a preorder printing of the elements in the subtree associated with position p of T .

Postorder Traversal

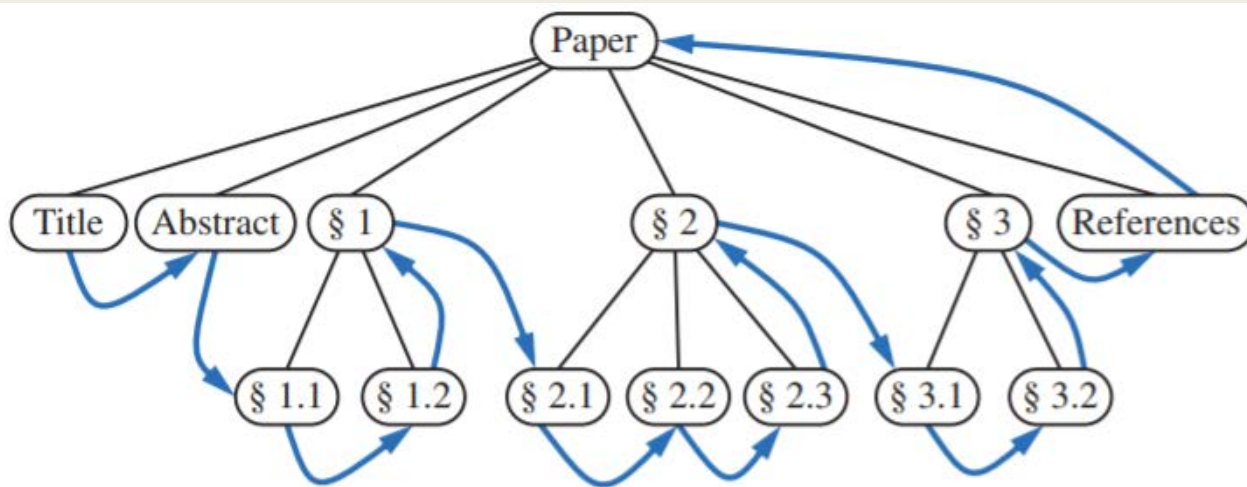


Figure 7.8: Postorder traversal of the ordered tree of Figure 7.6.

```
void postorderPrint(const Tree& T, const Position& p) {  
    PositionList ch = p.children();           // list of children  
    for (Iterator q = ch.begin(); q != ch.end(); ++q) {  
        postorderPrint(T, *q);  
        cout << " ";  
    }  
    cout << *p;                             // print element  
}
```

Code Fragment 7.13: The function `postorderPrint(T, p)`, which prints the elements of the subtree of position p of T .

Postorder Traversal

```
int diskSpace(const Tree& T, const Position& p) {  
    int s = size(p);           // start with size of p  
    if (!p.isExternal()) {    // if p is internal  
        PositionList ch = p.children(); // list of p's children  
        for (Iterator q = ch.begin(); q != ch.end(); ++q)  
            s += diskSpace(T, *q); // sum the space of subtrees  
        cout << name(p) << ": " << s << endl; // print summary  
    }  
    return s;  
}
```

Code Fragment 7.14: The function `diskSpace`, which prints the name and disk space used by the directory associated with p , for each internal node p of a file-system tree T . This function calls the auxiliary functions `name` and `size`, which should be defined to return the name and size of the file/directory associated with a node.

Other Traversal

■ Depth-First Traversal

- *Preorder: me first and children later*
- *Postorder: children first and me later*
- *Use Stack (or recursive function)*

■ Breadth-First Traversal

- *Use Queue*

Binary Trees (§ 7.3)

■ Binary trees

- Every node has at most two children
- Left child and right child
- A binary tree is **proper** if each node has either zero or two children (**full** binary tree)

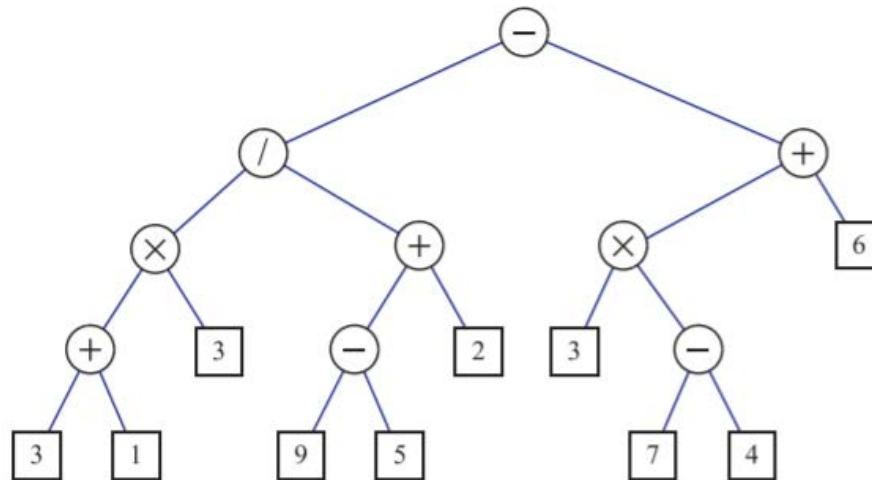
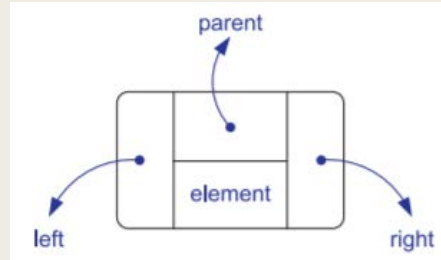


Figure 7.11: A binary tree representing an arithmetic expression. This tree represents the expression $(((((3+1) \times 3)/((9-5)+2)) - ((3 \times (7-4)) + 6)))$. The value associated with the internal node labeled “/” is 2.

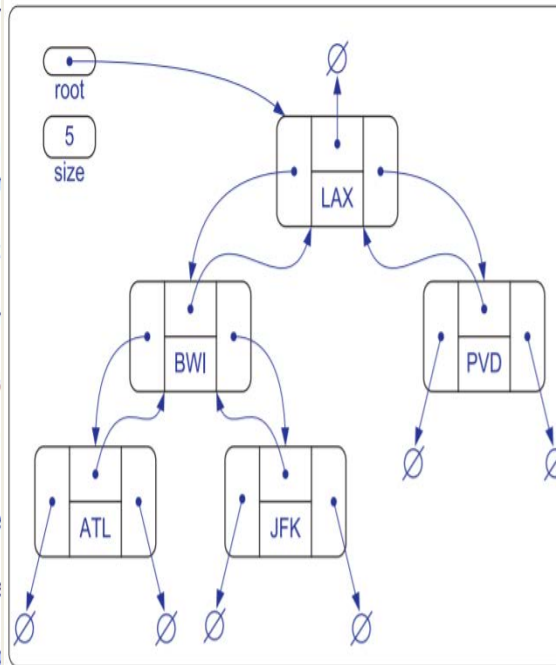
The Binary Tree ADT

```
struct Node {
    Elem elt;
    Node* par;
    Node* left;
    Node* right;
    Node() : elt(), par(NULL), left(NULL), right(NULL) { }
};
```



```
class Position {
private:
    Node* v;
public:
    Position(Node* _v = NULL) : v(_v) { }
    Elem& operator*() const { return v->elt; }
    Position left() const { return Position(v->left); }
    Position right() const { return Position(v->right); }
    Position parent() const { return Position(v->par); }
    bool isRoot() const { return v->par == NULL; }
    bool isExternal() const { return v->left == NULL && v->right == NULL; }
    friend class LinkedBinaryTree;
};

typedef std::list<Position> PositionList;
```



```
typedef int Elem;
class LinkedBinaryTree {
protected:
    // insert Node declaration here...
public:
    // insert Position declaration here...
public:
    LinkedBinaryTree();
    int size() const;
    bool empty() const;
    Position root() const;
    PositionList positions() const;
    void addRoot();
    void expandExternal(const Position& p);
    void removeAboveExternal(const Position& p);
    // housekeeping functions omitted...
protected:
    void preorder(Node* v, PositionList& pl) const;
private:
    Node* _root;
    int n;
};
```

Binary Tree Update Functions

expandExternal(p): Transform p from an external node into an internal node by creating two new external nodes and making them the left and right children of p , respectively; an error condition occurs if p is an internal node.

removeAboveExternal(p): Remove the external node p together with its parent q , replacing q with the sibling of p (see Figure 7.15, where p 's node is w and q 's node is v); an error condition occurs if p is an internal node or p is the root.

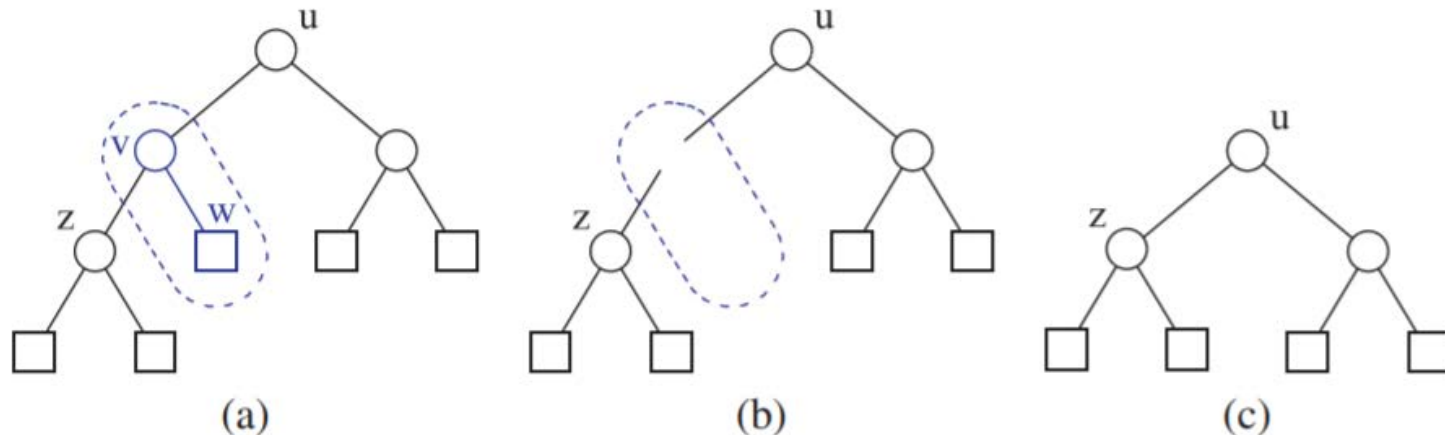


Figure 7.15: Operation `removeAboveExternal(p)`, which removes the external node w to which p refers and its parent node v .

Binary Tree Update Functions

```
void LinkedBinaryTree::expandExternal(const Position& p) {  
    Node* v = p.v;                // p's node  
    v->left = new Node;             // add a new left child  
    v->left->par = v;               // v is its parent  
    v->right = new Node;           // and a new right child  
    v->right->par = v;             // v is its parent  
    n += 2;                       // two more nodes  
}
```

```
LinkedBinaryTree::Position // remove p and parent  
LinkedBinaryTree::removeAboveExternal(const Position& p) {  
    Node* w = p.v; Node* v = w->par; // get p's node and parent  
    Node* sib = (w == v->left ? v->right : v->left);  
    if (v == _root) { // child of root?  
        _root = sib; // ...make sibling root  
        sib->par = NULL;  
    }  
    else {  
        Node* gpar = v->par; // w's grandparent  
        if (v == gpar->left) gpar->left = sib; // replace parent by sib  
        else gpar->right = sib;  
        sib->par = gpar;  
    }  
    delete w; delete v; // delete removed nodes  
    n -= 2; // two fewer nodes  
    return Position(sib);  
}
```


Binary Tree Traversals

```
// list of all nodes
LinkedList::PositionList LinkedList::positions() const {
    PositionList pl;
    preorder(_root, pl);
    return PositionList(pl);
}

// preorder traversal
void LinkedList::preorder(Node* v, PositionList& pl) const {
    pl.push_back(Position(v));
    if (v->left != NULL)
        preorder(v->left, pl);
    if (v->right != NULL)
        preorder(v->right, pl);
}
```

Algorithm $\text{inorder}(T, p)$:

if p is an internal node **then**

$\text{inorder}(T, p.\text{left}())$ {recursively traverse left subtree}

perform the “visit” action for node p

if p is an internal node **then**

$\text{inorder}(T, p.\text{right}())$ {recursively traverse right subtree}

Code Fragment 7.27: Algorithm inorder for performing the inorder traversal of the subtree of a binary tree T rooted at a node p .

Binary Search Trees

■ Binary search trees

- *Internal node p stores an element $x(p)$*
- *$x(p_{left}) \leq x(p) \leq x(p_{right})$*
- *No elements in external nodes*
- *Inorder traversal visits the elements in nondecreasing order*

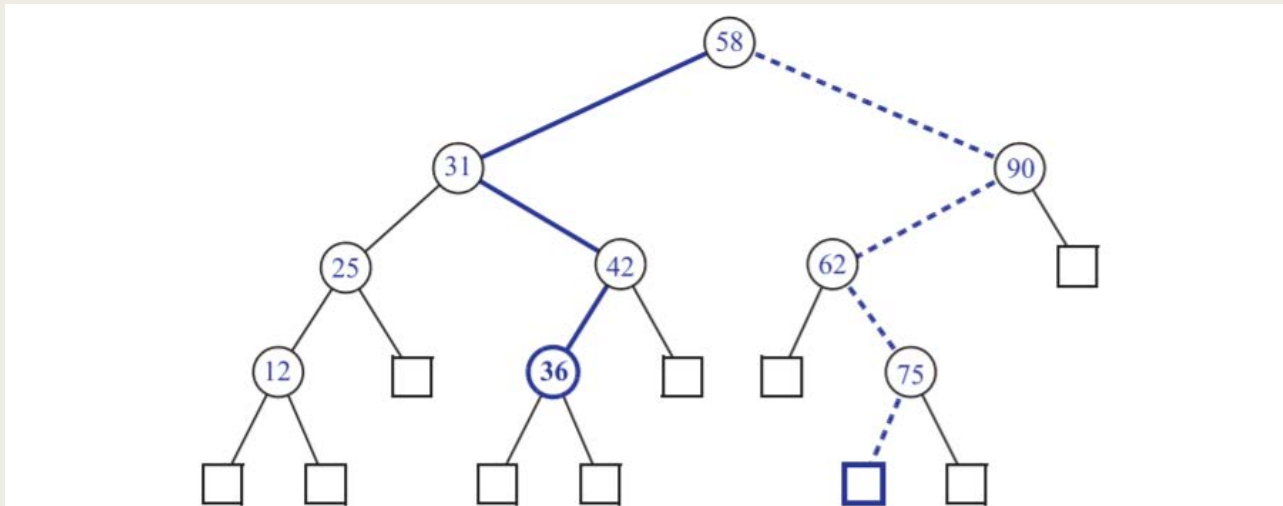


Figure 7.19: A binary search tree storing integers. The blue solid path is traversed when searching (successfully) for 36. The blue dashed path is traversed when searching (unsuccessfully) for 70.