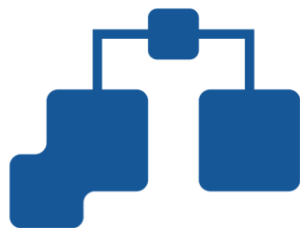


ForneyLab.jl

a Julia Toolbox for Factor Graph-based Probabilistic Programming

JuliaCon 2018



BIASLAB



Thijs van de Laar
TU/e

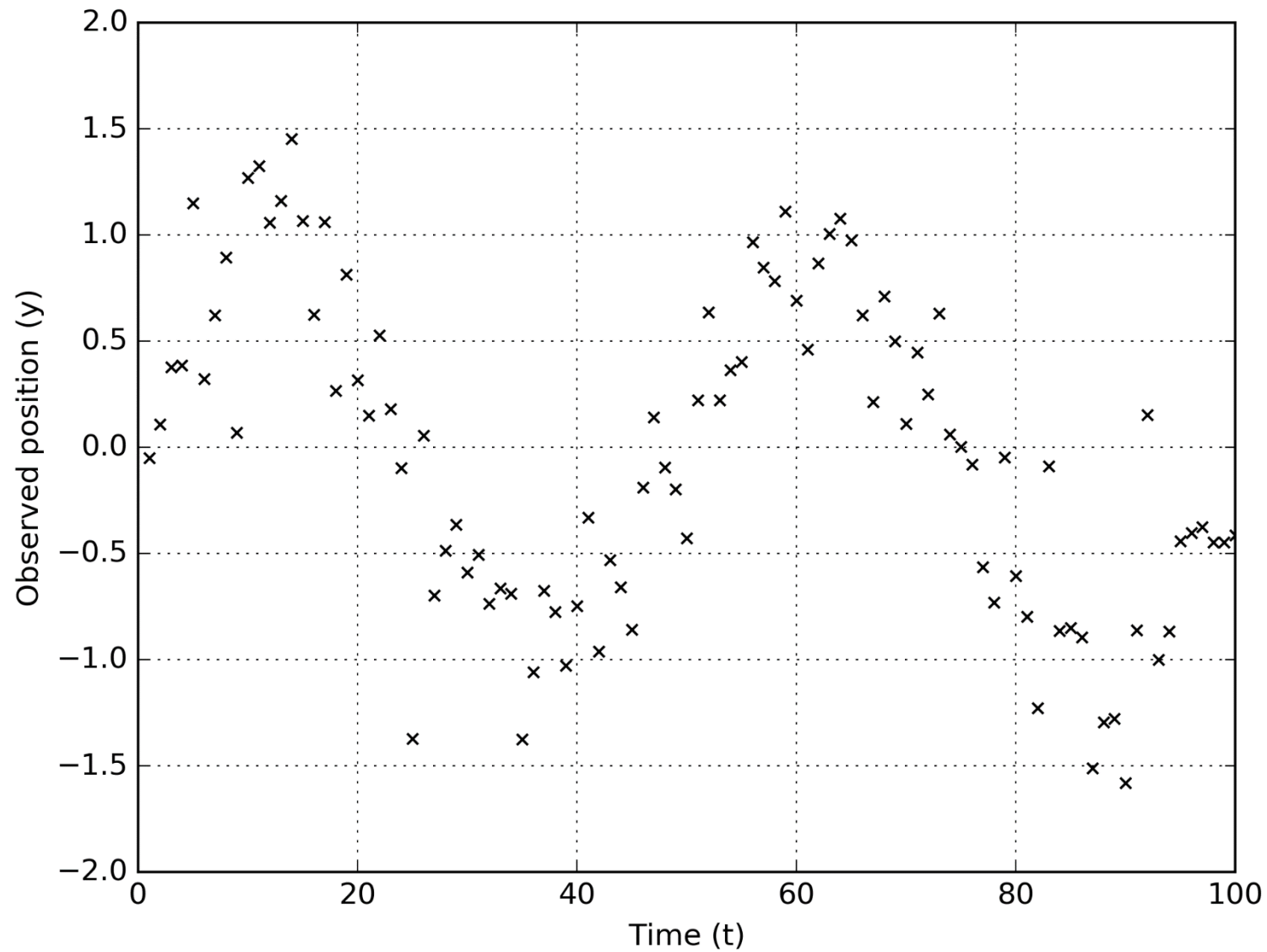


Marco Cox
TU/e

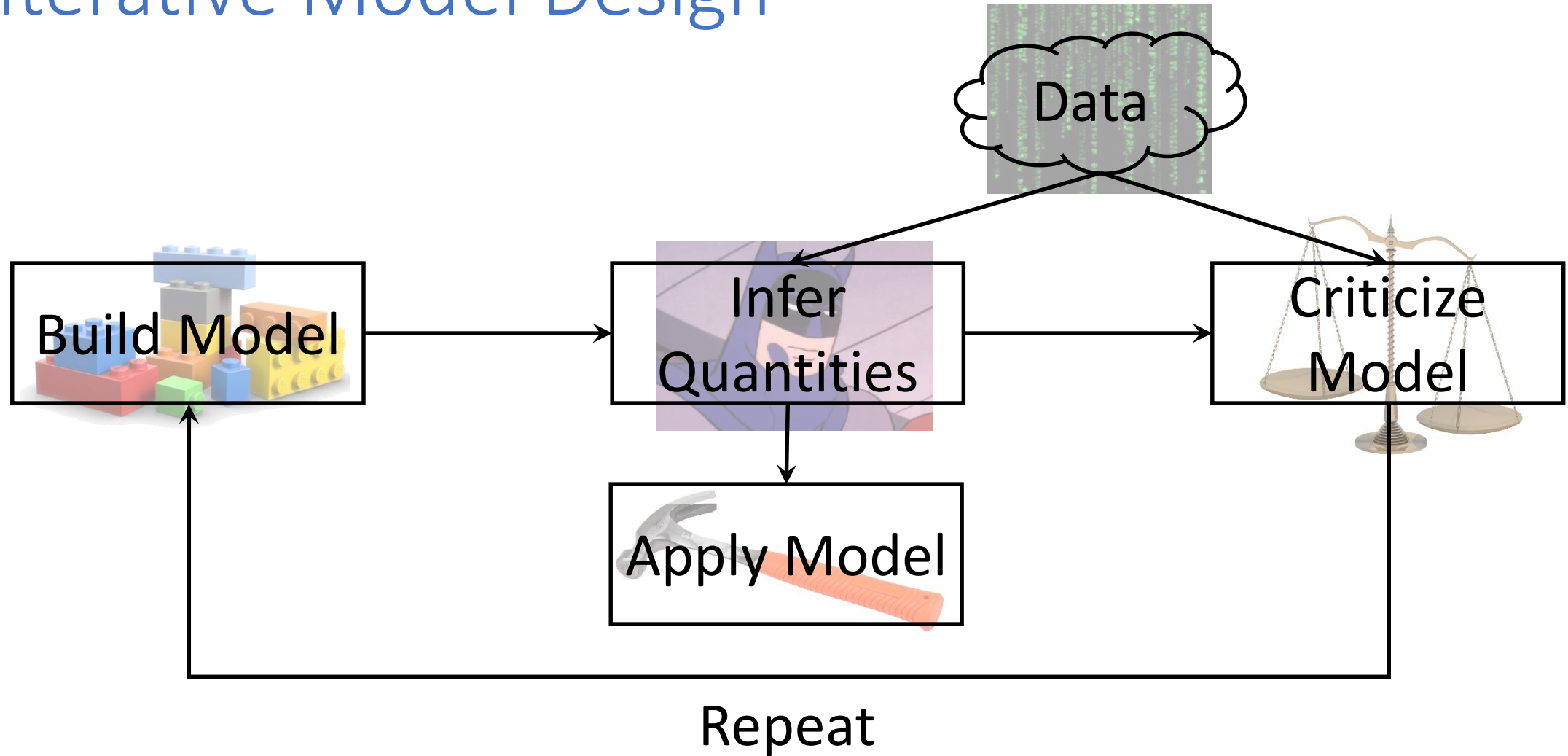


Bert de Vries
TU/e GN Hearing

Example Dataset

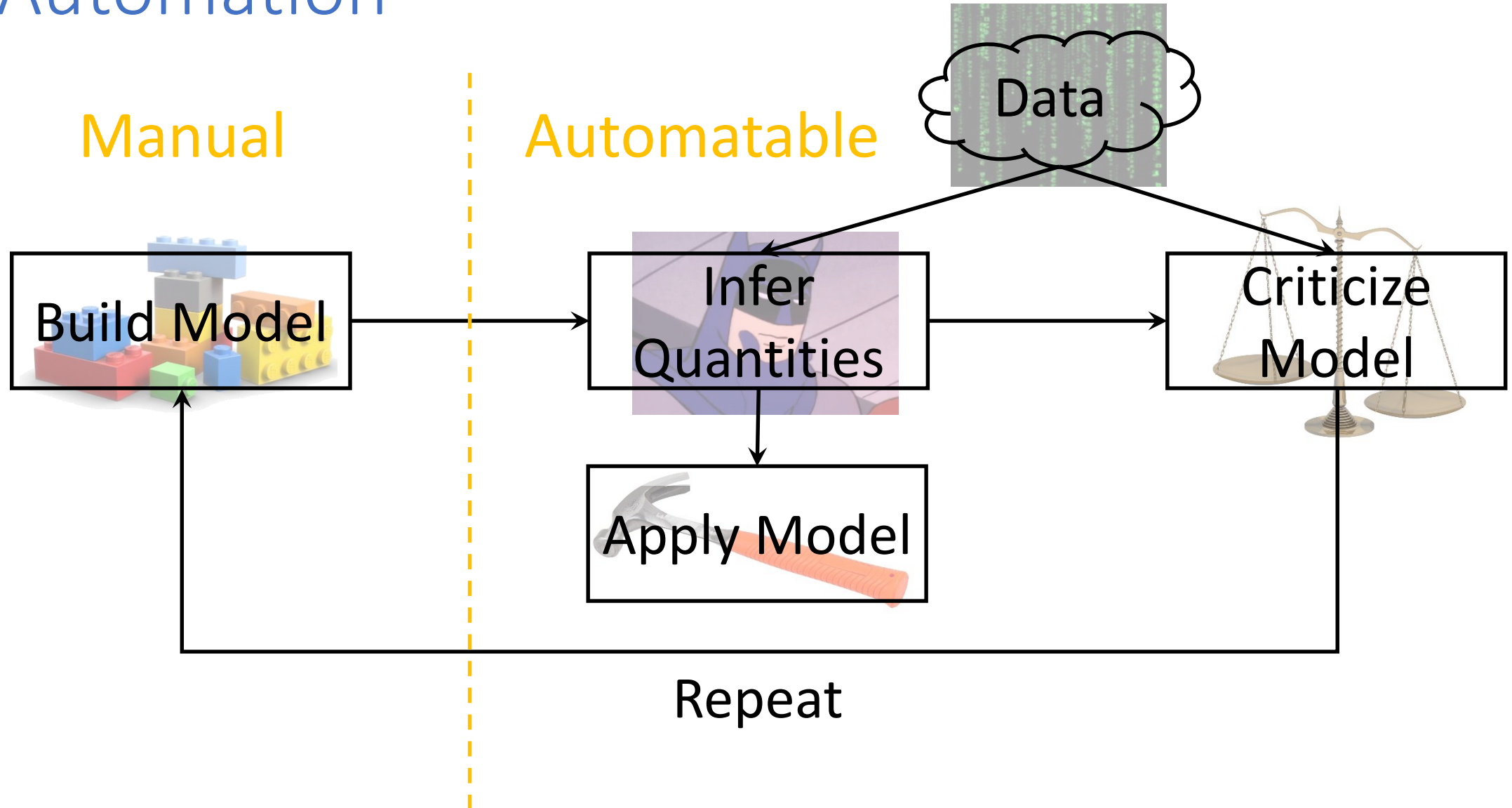


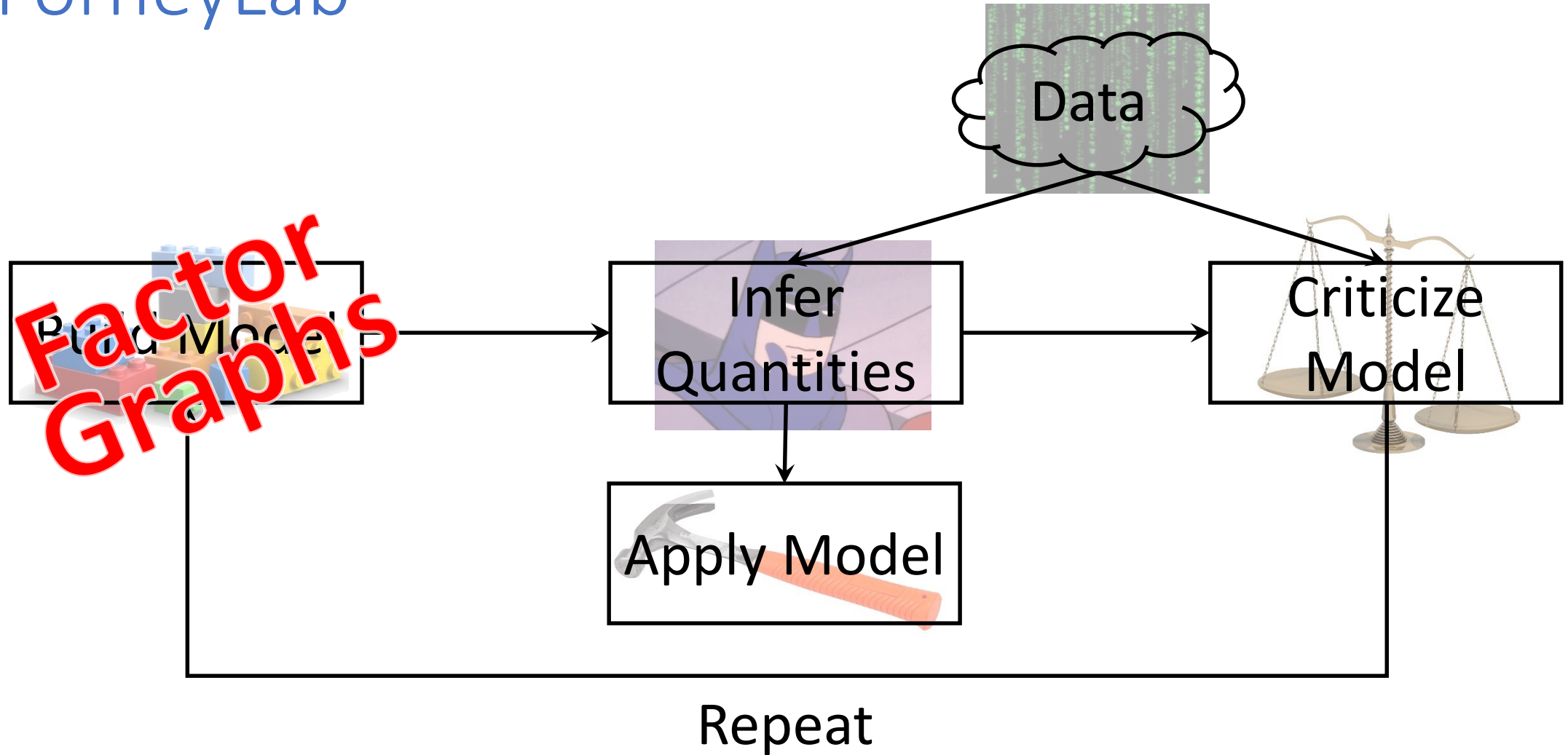
Iterative Model Design

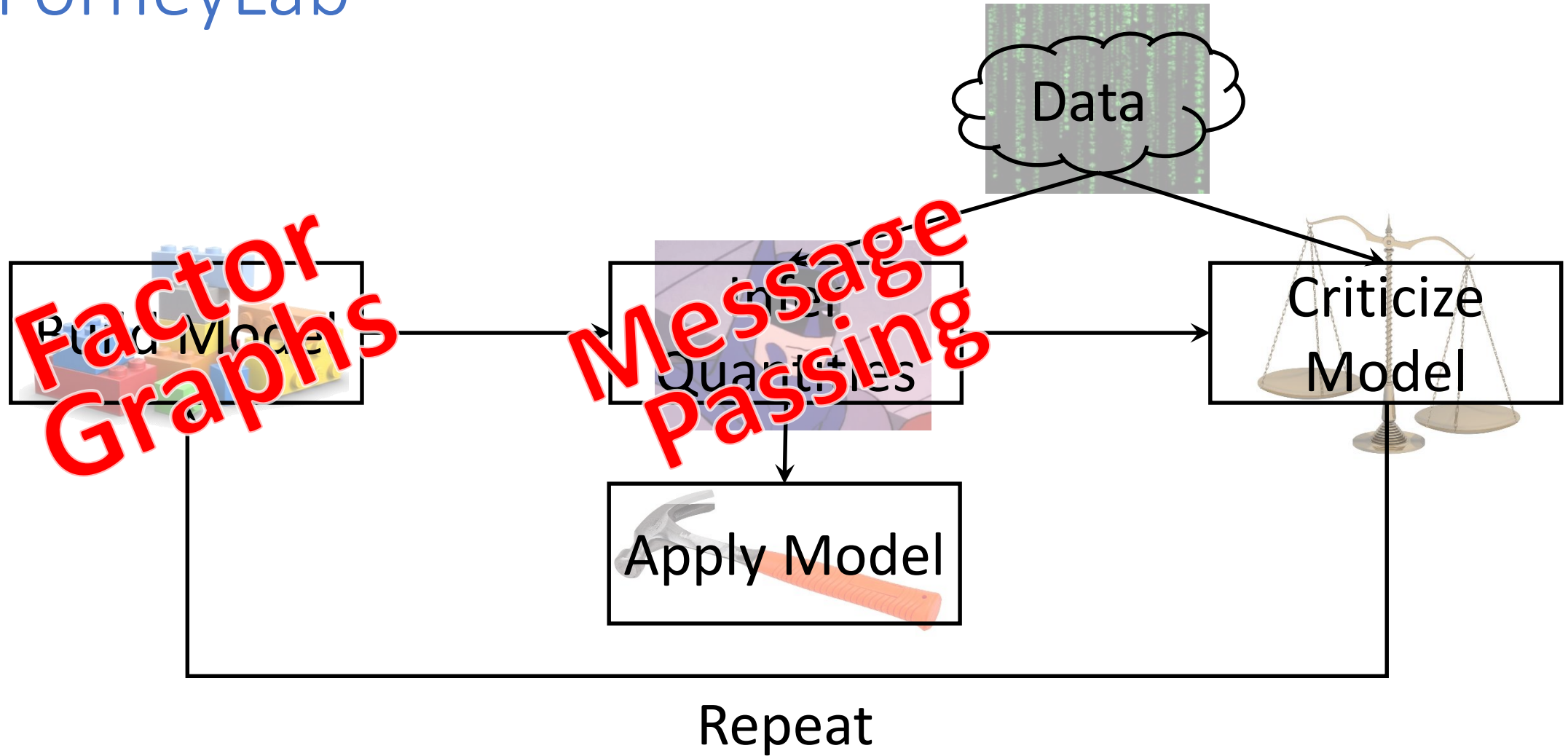


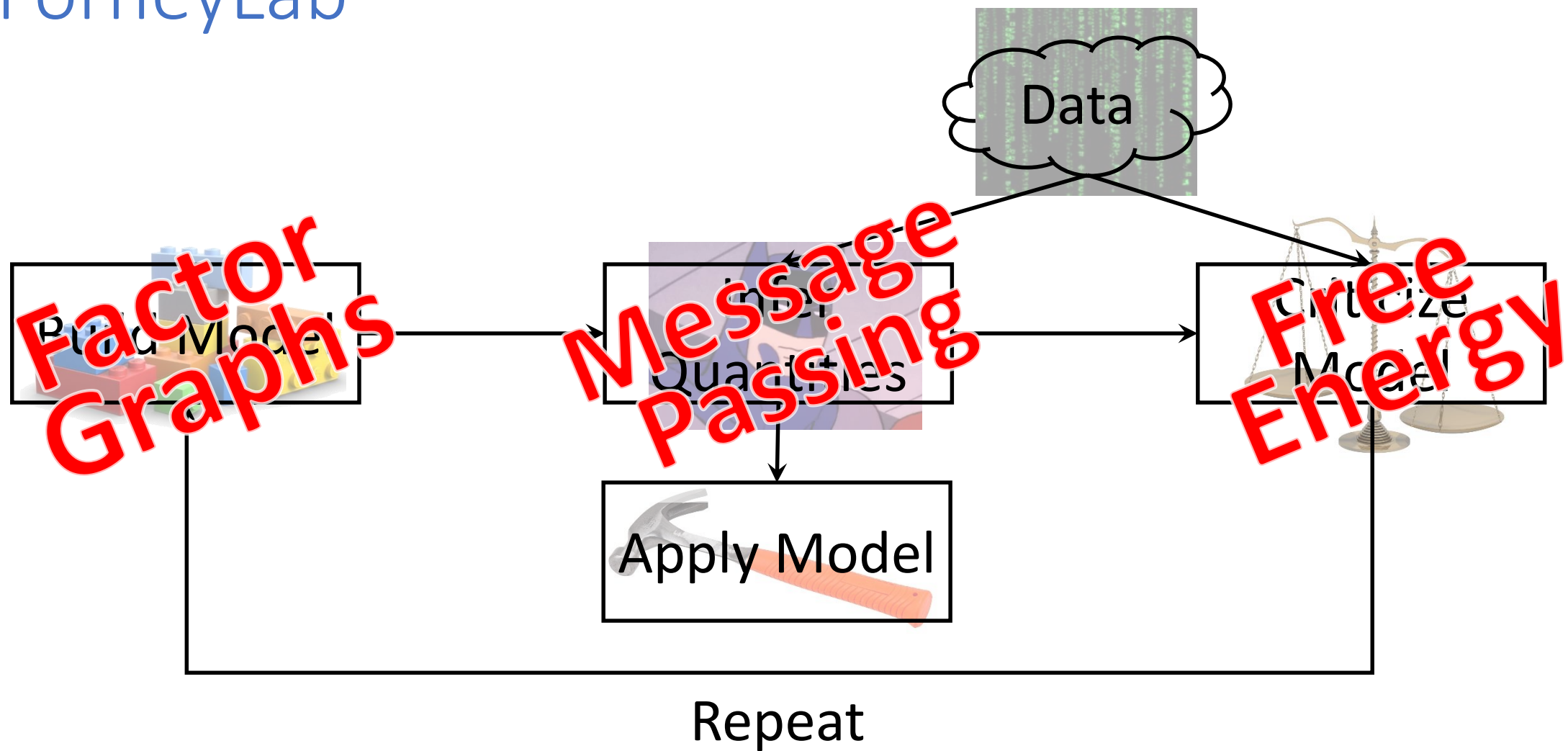
Blei, D. M. (2014). Build, compute, critique, repeat: Data analysis with latent variable models. *Annual Review of Statistics and Its Application*, 1, 203-232.

Automation










ForneyLab

 biaslab / ForneyLab.jl

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4


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 Code

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Julia package for automatically generating Bayesian inference algorithms through message passing on Forney-style factor graphs.

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ThijsvdLaar Merge pull request #313 from biaslab/readme_update ...

Latest commit 42c9e7c a day ago

 demo

fix equation rendering

a day ago

 src

Merge pull request #312 from biaslab/demo_review

a day ago

 test

Merge pull request #307 from biaslab/explicit_gaussians

8 days ago

 .gitignore

Renamed getOrCreate*!() to ensure*!(). ensureMessage!() now sets vagu...

3 years ago

 CONTRIB.md

remove doc folder, bump version, update readme and contrib

6 months ago

<https://github.com/biaslab/ForneyLab.jl>

Model Specification



Prior: $x_0 \sim \mathcal{N}_p(0, 0.04)$

State transition model: $x_t \sim \mathcal{N}_p(x_{t-1}, 100)$

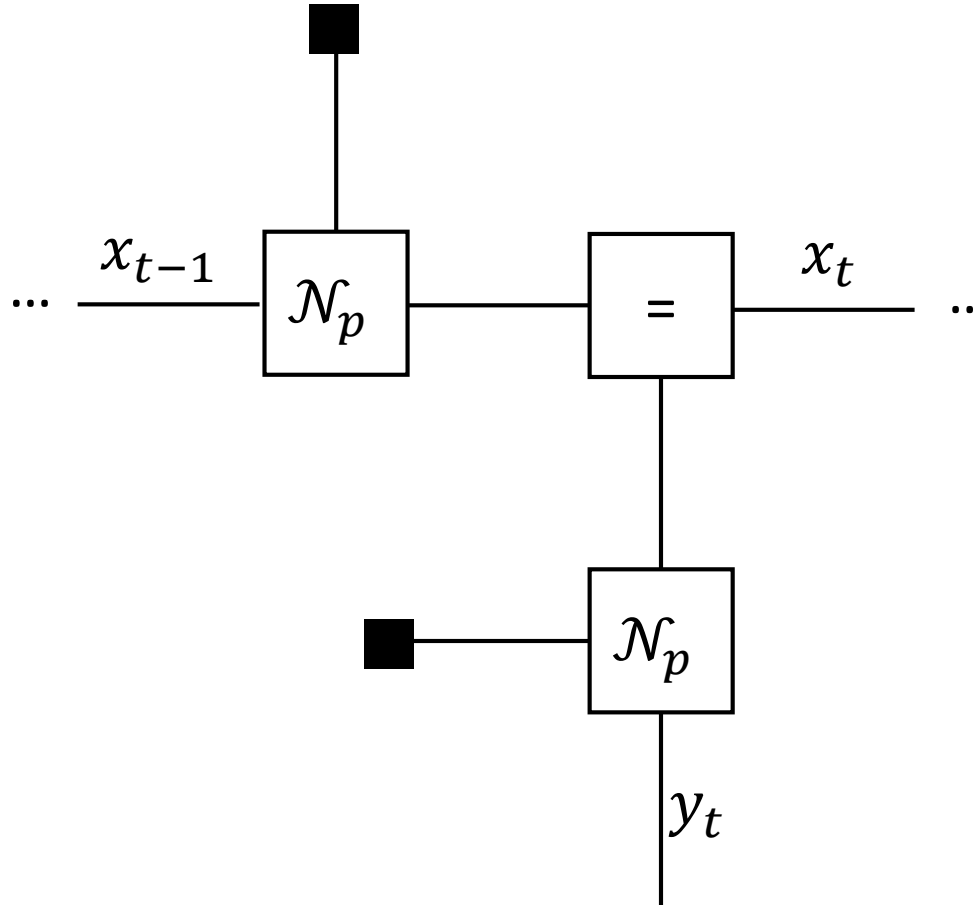
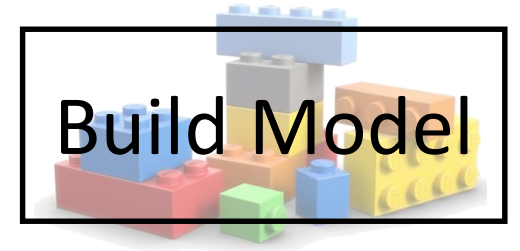
Observation model: $y_t \sim \mathcal{N}_p(x_t, 10)$

```
@RV x_0 ~ GaussianMeanPrecision(0.0, 0.04) # State prior

x_t_min = x_0
for t=1:T
    @RV x[t] ~ GaussianMeanPrecision(x_t_min, 100.0) # State transition model
    @RV y[t] ~ GaussianMeanPrecision(x[t], 10.0) # Observation model
    placeholder(y[t], :y, index=t) # Placeholder for data

    x_t_min = x[t] # Reset state for next section
end
```

Factor Graph Representation



Forney, G. D. (2001). Codes on graphs: Normal realizations. *IEEE Transactions on Information Theory*, 47(2), 520-548.

Loeliger, H. A. (2004). An introduction to factor graphs. *IEEE Signal Processing Magazine*, 21(1), 28-41.

Inference Specification

A small image of Batman's face in the background of the 'Infer Quantities' text box.

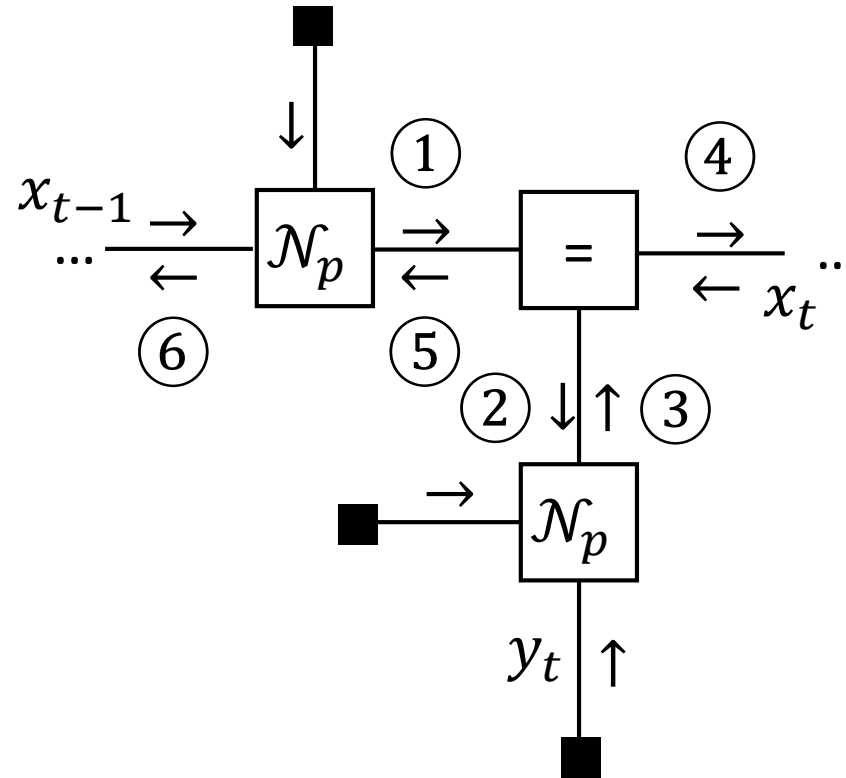
Infer
Quantities

```
q = RecognitionFactorization([x_0; x], ...) # Specify a recognition distribution  
algo = variationalAlgorithm(q) # Construct the inference algorithm
```

Variational Message Passing

Infer
Quantities

```
q = RecognitionFactorization([x_0; x], ...) # Specify a recognition distribution
algo = variationalAlgorithm(q) # Construct the inference algorithm
```



Automated Algorithm Generation

Infer
Quantities

```
q = RecognitionFactorization([x_0; x], ...) # Specify a recognition distribution
algo = variationalAlgorithm(q) # Construct the inference algorithm
```

```
function step!(data::Dict, marginals::Dict=Dict(),
messages::Vector{Message}=Array{Message}(499))
```

```
    messages[1] = ruleVBGaussianMeanPrecisionM(ProbabilityDistribution(Univariate,
PointMass, m=data[:y][50]), nothing, ProbabilityDistribution(Univariate,
PointMass, m=10.0))
```

```
    ...
```

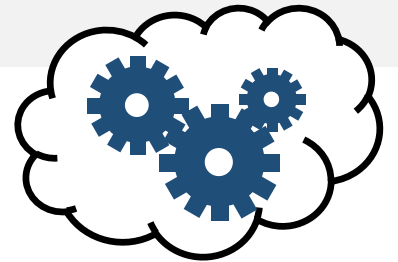
```
    messages[499] = ruleSVBGaussianMeanPrecisionMGVD(messages[498], nothing,
ProbabilityDistribution(Univariate, PointMass, m=100.0))
```

```
    marginals[:x_0] = messages[3].dist * messages[499].dist
```

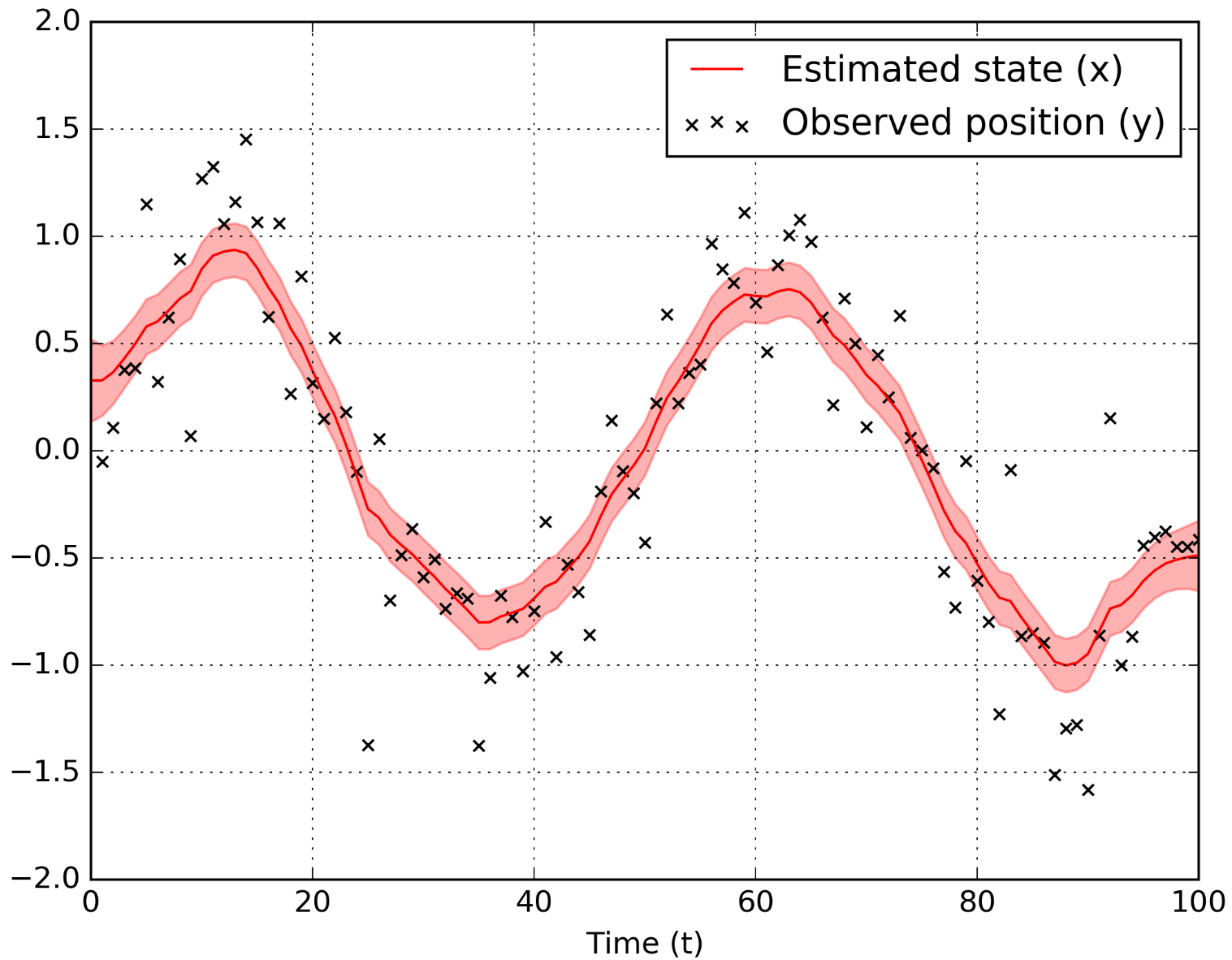
```
    ...
```

```
    return marginals
```

```
end
```



Inference Results



Model Performance



Criticize
Model

```
algo_F = freeEnergyAlgorithm(q) # Construct a performance evaluation metric
```

Attias, H. (2000). A variational bayesian framework for graphical models. In *Advances in neural information processing systems* (pp. 209-215).

Automated Performance Evaluation



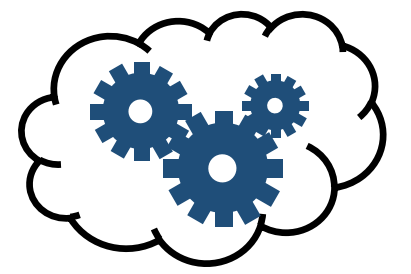
Criticize
Model

```
algo_F = freeEnergyAlgorithm(q) # Construct a performance evaluation metric
```

```
function freeEnergy(data::Dict, marginals::Dict)
    F = 0.0

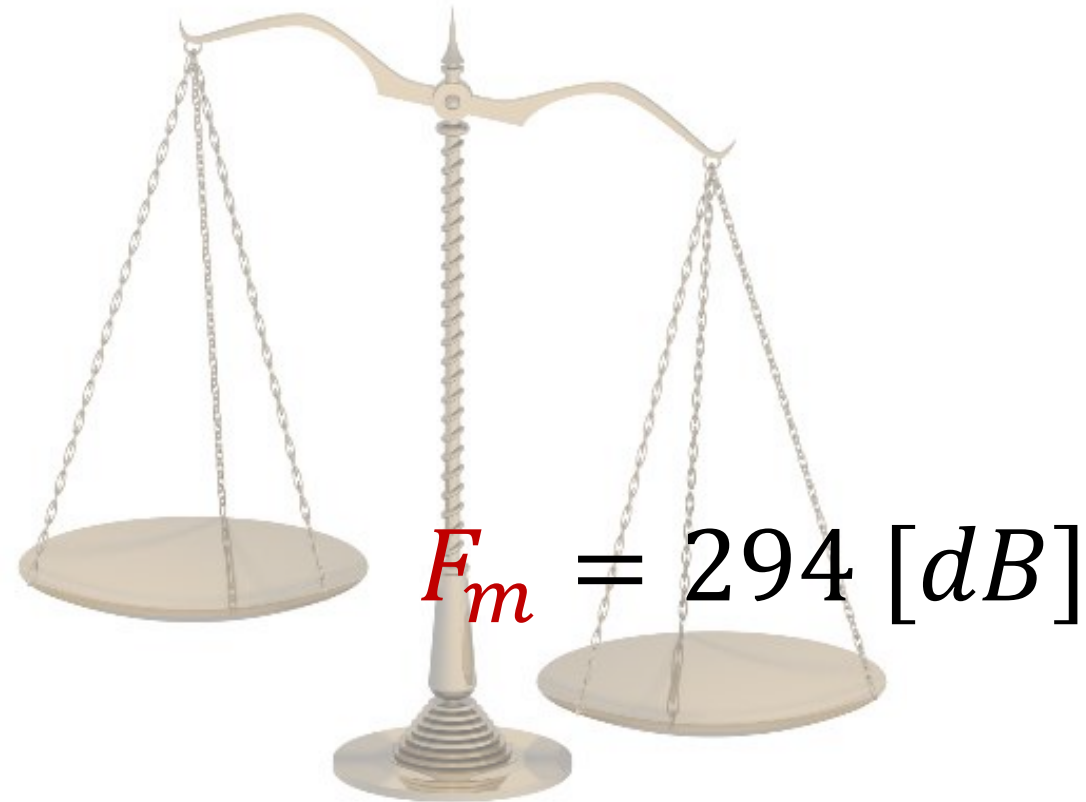
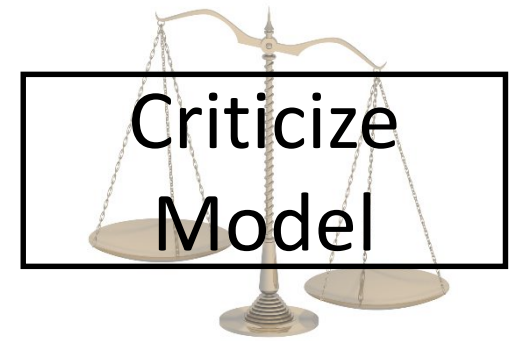
    F += averageEnergy(GaussianMeanPrecision, marginals[:x_1_x_0],
        ProbabilityDistribution(Univariate, PointMass, m=100.0))
    F += averageEnergy(GaussianMeanPrecision, ProbabilityDistribution(Univariate,
        PointMass, m=data[:y][44]), marginals[:x_44],
        ProbabilityDistribution(Univariate, PointMass, m=10.0))
    ...
    F -= differentialEntropy(marginals[:x_0])

return F
end
```

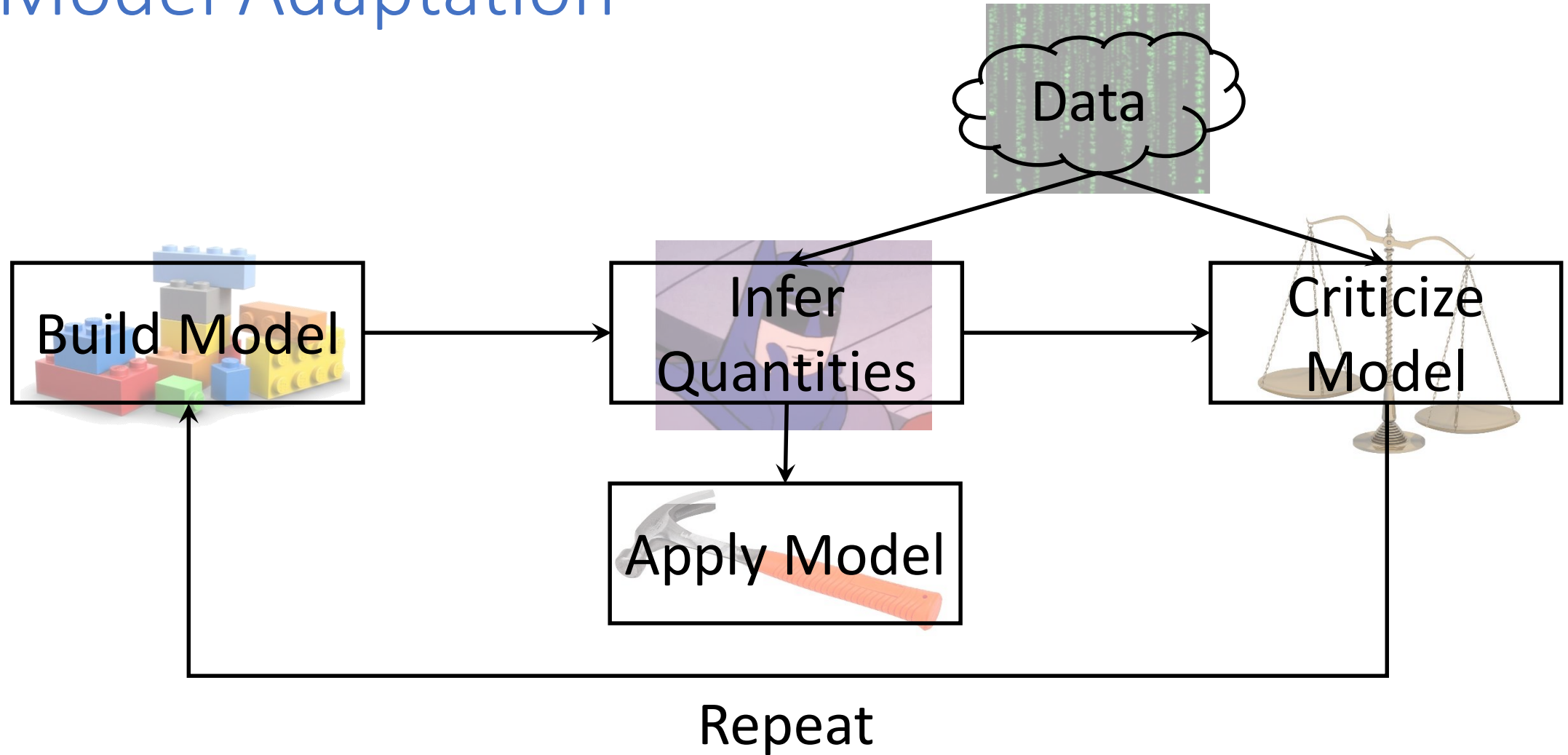


Model Comparison

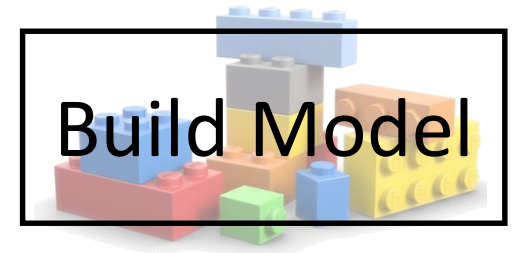
Evaluate free energy (less is better)



Model Adaptation



Model Adaptation



Prior: $x_0 \sim \mathcal{N}_p(0, 0.04)$

State transition model: $x_t \sim \mathcal{N}_p(\textcolor{red}{A}x_{t-1}, 100)$

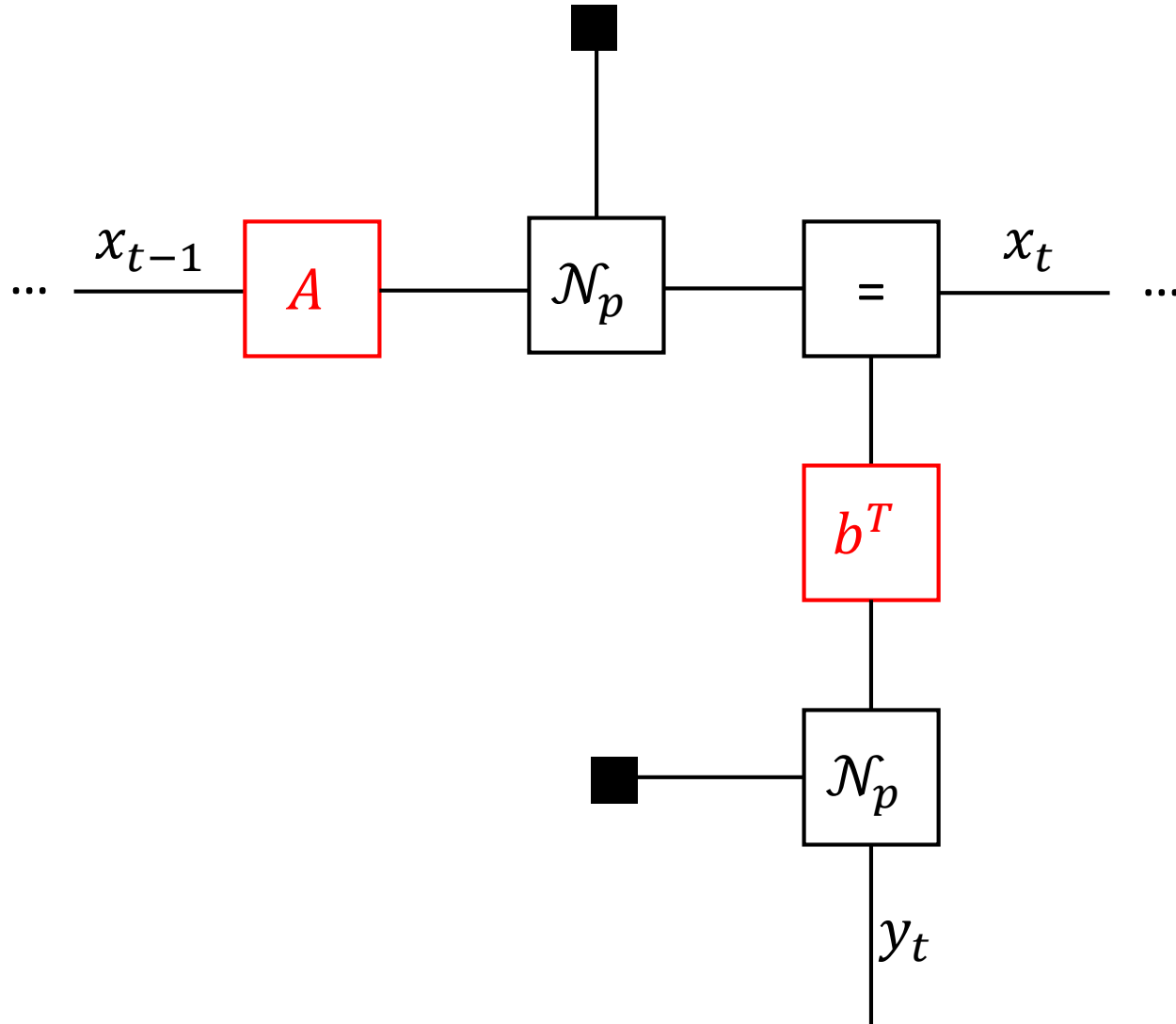
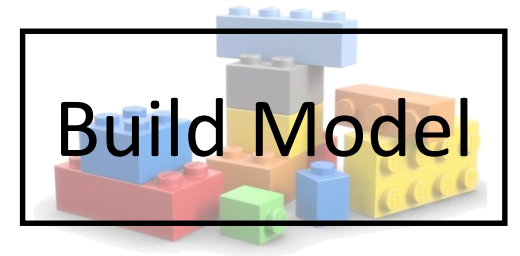
Observation model: $y_t \sim \mathcal{N}_p(\textcolor{red}{b}^T x_t, 10)$

```
@RV x_0 ~ GaussianMeanPrecision(zeros(2), 0.04*eye(2)) # State prior

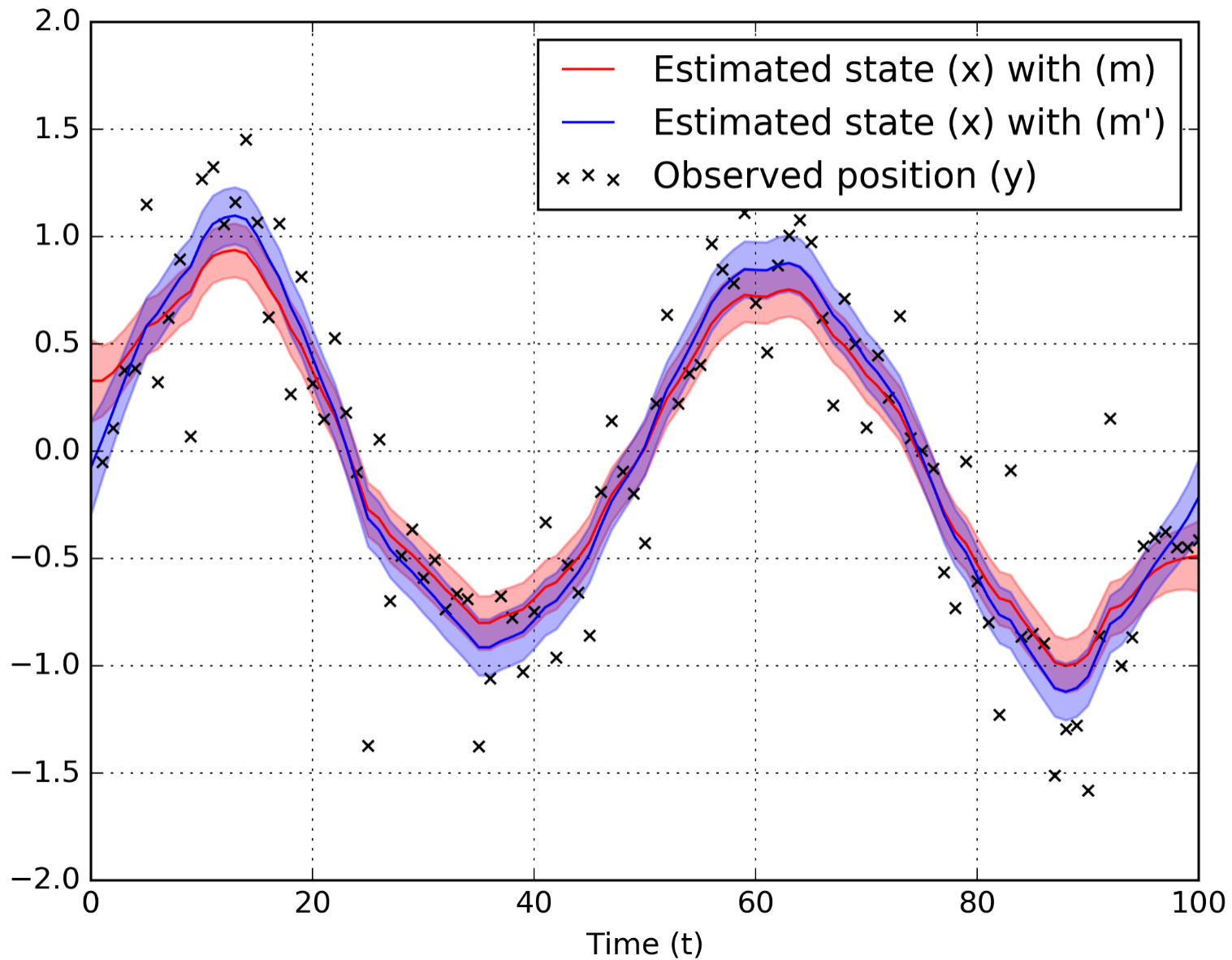
x_t_min = x_0
for t=1:T
    @RV x[t] ~ GaussianMeanPrecision(A*x_t_min, 100.0*eye(2)) # Transition model
    @RV y[t] ~ GaussianMeanPrecision(dot(b, x[t]), 10.0*eye(2)) # Obs. model
    placeholder(y[t], :y, index=t) # Placeholder for data

    x_t_min = x[t] # Reset state for next section
end
```

Model Adaptation

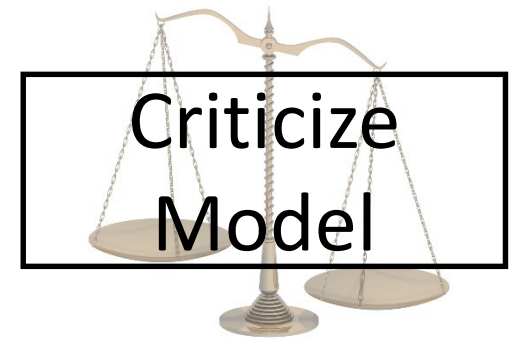


Inference Results



Model Comparison

Evaluate free energy (less is better)

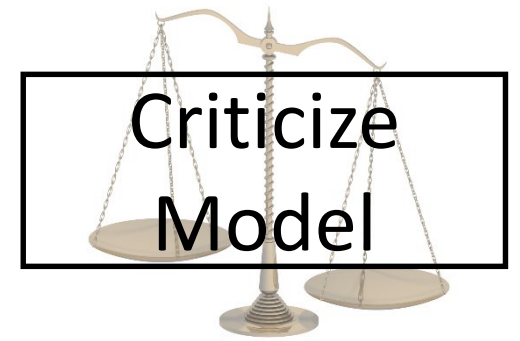



$$F_{m'} = 205 [dB]$$

$$F_m = 294 [dB]$$

Model Comparison

Evaluate free energy (less is better)



A large balance scale is shown. The left pan, which is higher, contains a gold trophy. The right pan is lower and empty. The trophy has a small plaque that says "PROPERTY OF THE UNIVERSITY OF CHICAGO".
$$F_{m'} = 205 [dB]$$

$$F_m = 294 [dB]$$

ForneyLab

- Enhances the probabilistic model design cycle
- Is a Julia program that writes Julia programs
- Is available on GitHub

Thanks

Ivan Bocharov

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