



DEEP  
LEARNING  
INSTITUTE

# Computer Vision (3주차)

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# DEEP LEARNING INSTITUTE

## DLI Mission

Helping people solve challenging problems using AI and deep learning.

- Developers, data scientists and engineers
- Self-driving cars, healthcare and robotics
- Training, optimizing, and deploying deep neural networks

# TOPICS

- Week 2 Review
- Object Detection

# WEEK 2 REVIEW

# OBJECT DETECTION

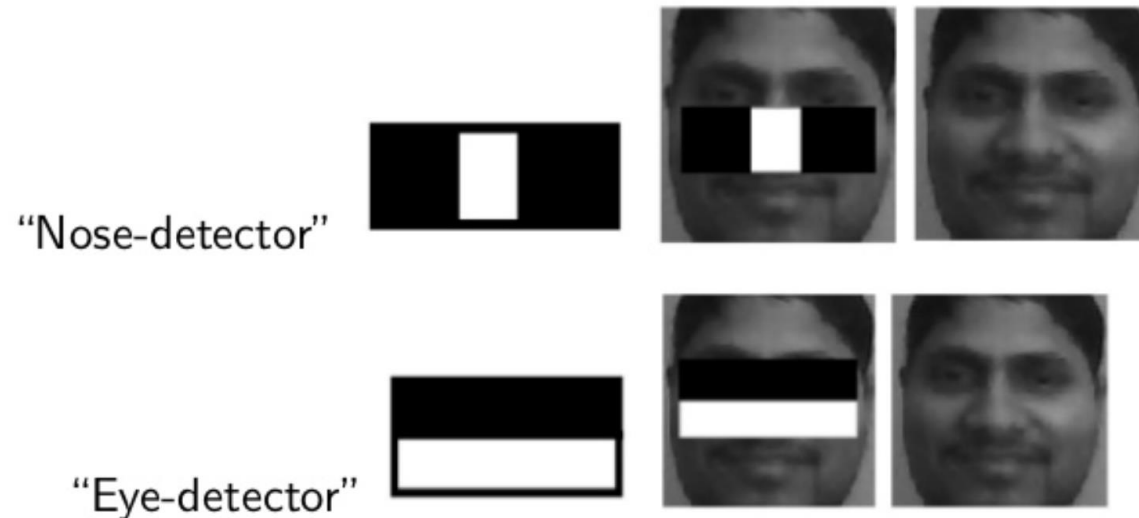
# OBJECT DETECTION

- Object detection in the natural image
  - **History**
    - 초기 object detection 기법은 handcraft feature를 기준으로 함
    - **Sliding window classifier**



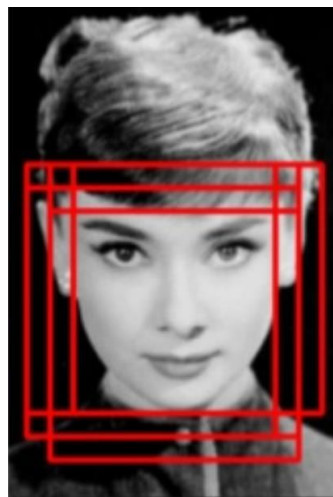
# OBJECT DETECTION

- Object detection in the natural image
  - **History**
    - Boosted classifier
    - **Haar-like features (Viola and Jones, 2001.)**

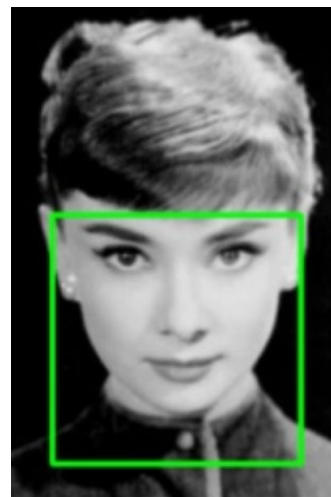


# OBJECT DETECTION

- Object detection in the natural image
  - History
    - Sliding window classifier는 너무 많은 corrected detection을 만듦  
→ Non-Maximum Suppression (NMS)



Before NMS

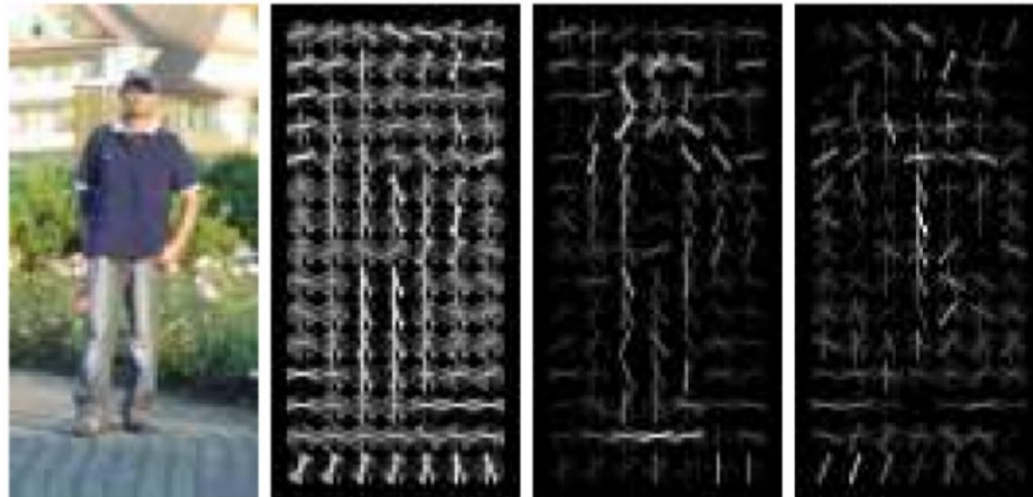


After NMS



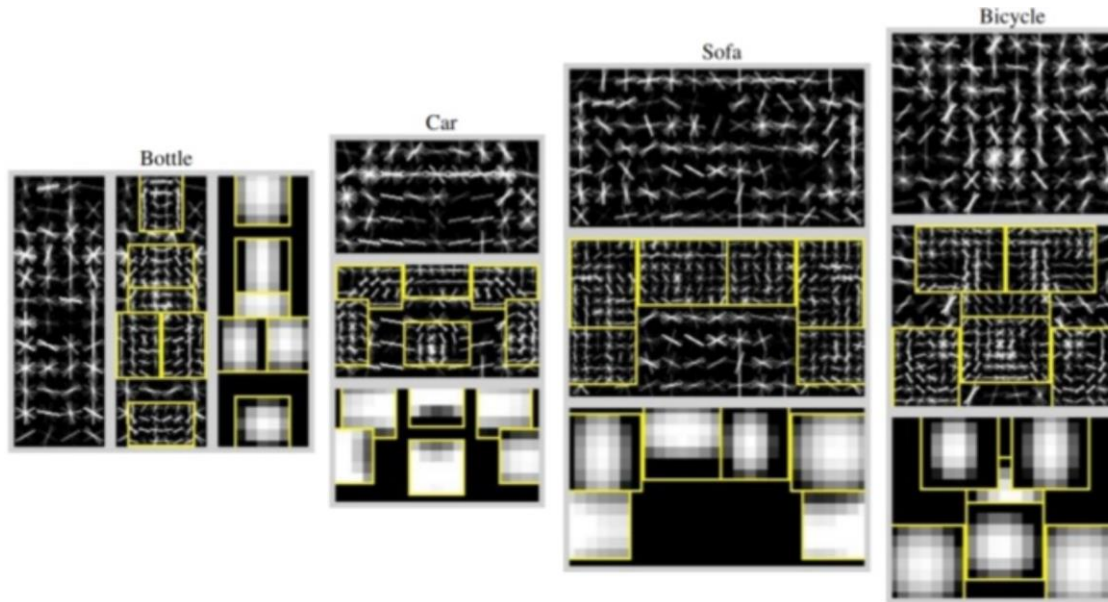
# OBJECT DETECTION

- Object detection in the natural image
  - **History**
    - Computes histogram of gradient orientation over sub-image blocks
    - **Histograms of Oriented Gradients (HOG) (Dalal and Triggs, 2005.)**



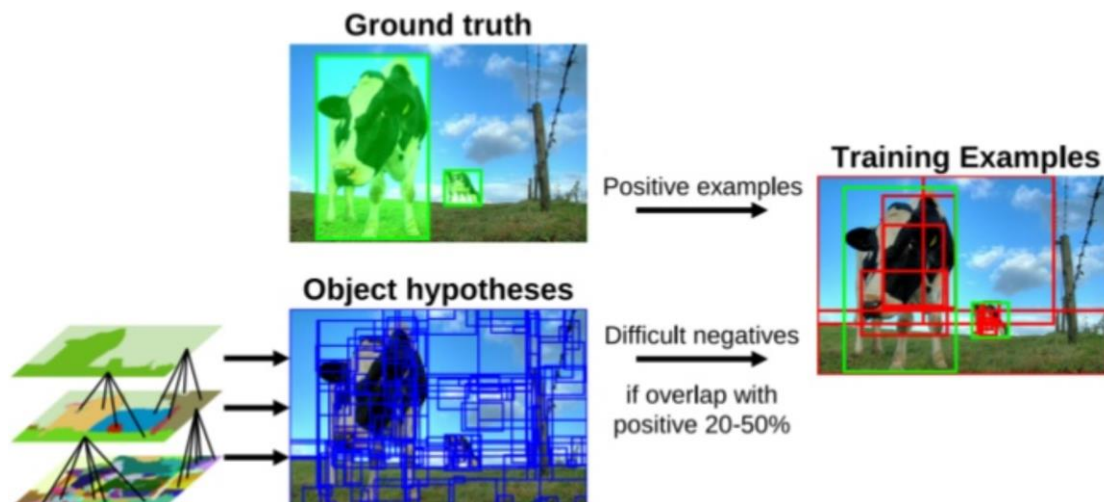
# OBJECT DETECTION

- Object detection in the natural image
  - History
    - Learn the relationships between HOG features of object parts via a latent SVM
    - **Deformable Part Models (DPM)** (Felzenszwalb et al., 2008.)



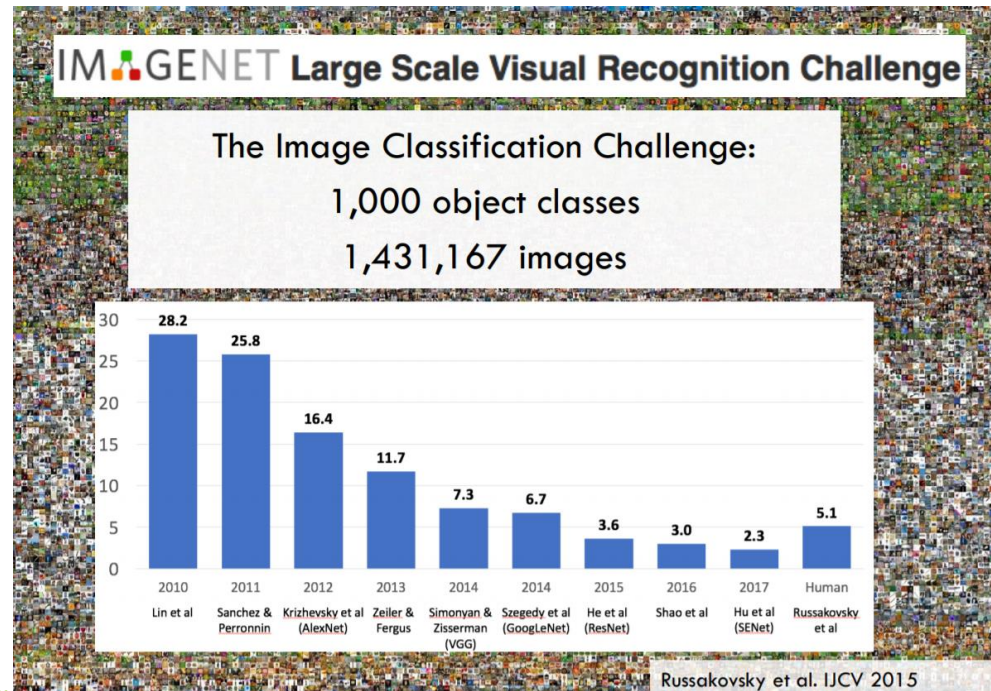
# OBJECT DETECTION

- Object detection in the natural image
  - **History**
    - Propose regions that have high “objectness”
    - Oversegment image and merge regions
    - **Selective Search (Uijlings et al., 2013.)**



# OBJECT DETECTION

- Object detection in the natural image
  - Competition
    - ImageNet Large Scale Visual Recognition Challenge (ILSVRC, ImageNet)



# OBJECT DETECTION

- Object detection in the natural image
  - **Competition**
    - **Visual Object Classes Challenge 2012 (PASCAL VOC 2012)**
      - Classification, Detection, Segmentation
      - # of classes : 20

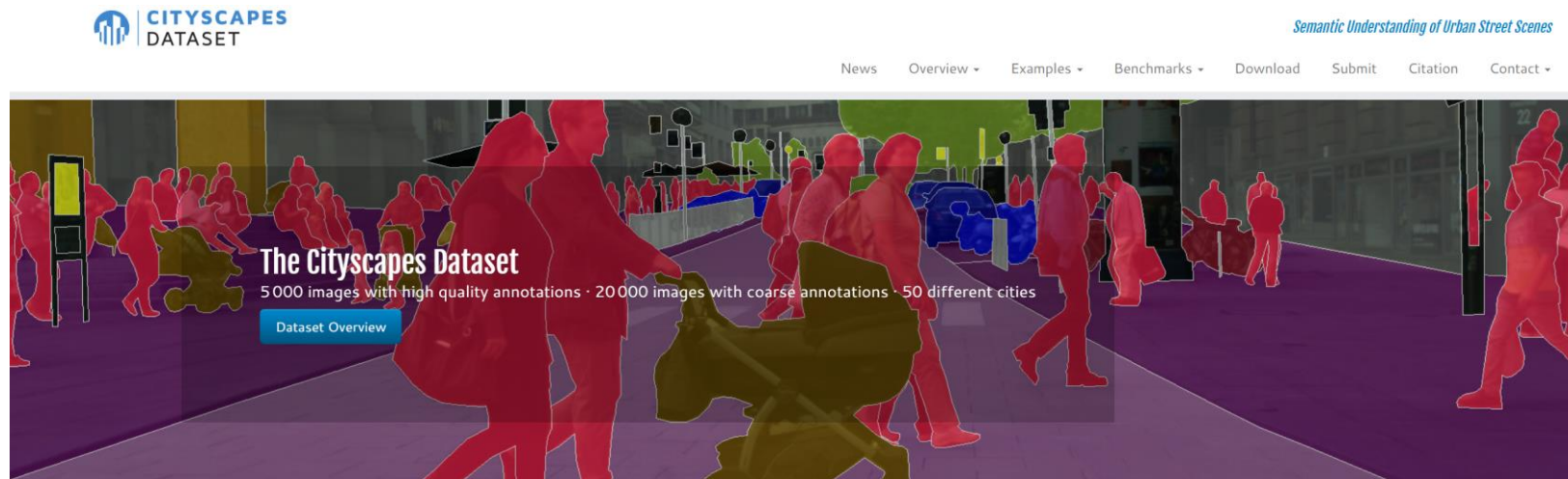






# OBJECT DETECTION

- Object detection in the natural image
  - Competition
    - Cityscapes Dataset
      - Semantic, Instance, Panoptic Segmentation
      - # of images : 5,000 (fine annotations) / 20,000 (coarse annotations)

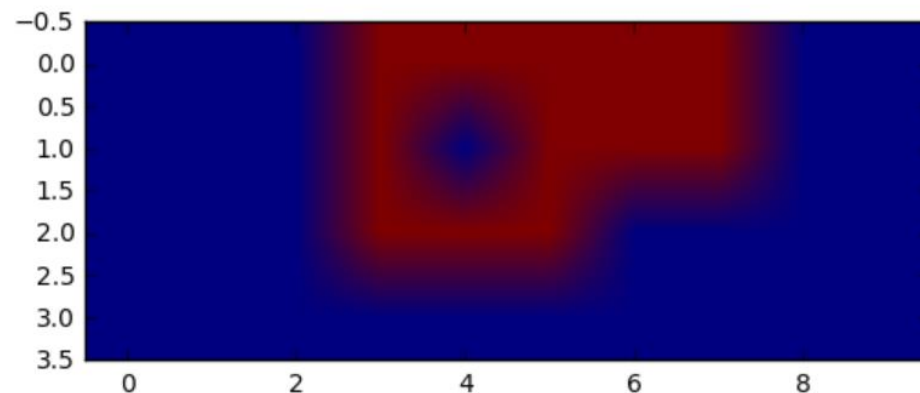


# OBJECT DETECTION

- Object detection using sliding window
  - Technique
    - Build a dog / 'not dog' classifier
    - Sliding window python application runs classifier on each 256x256 segment



Total inference time: 2.67519593239 seconds





# OBJECT DETECTION

- Architecture
  - **Two-stage detector**
    - R-CNN
    - SPPNet
    - Fast R-CNN
    - **Faster R-CNN**
    - **Feature Pyramid Networks (FPN)**
    - ...
  - **One-stage detector**
    - YOLO
    - Single Shot MultiBox Detector (SSD)
    - **RetinaNet**
    - ...

# OBJECT DETECTION

- Architecture
  - Two-stage detector
    - Faster R-CNN (S. Ren et al., TPAMI 2017.)
      - 대표적인 two-stage region proposal network

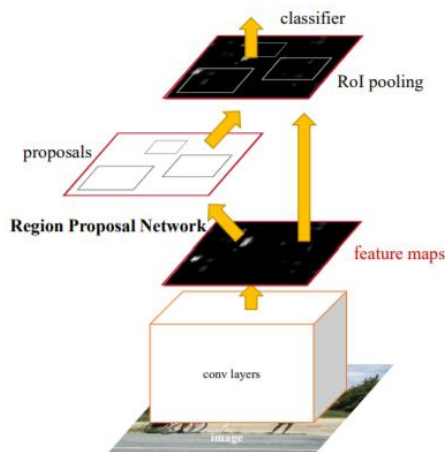


Figure 2: Faster R-CNN is a single, unified network for object detection. The RPN module serves as the 'attention' of this unified network.

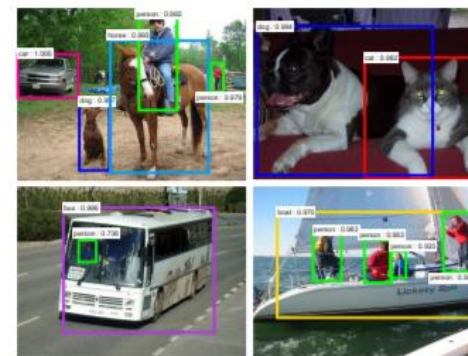
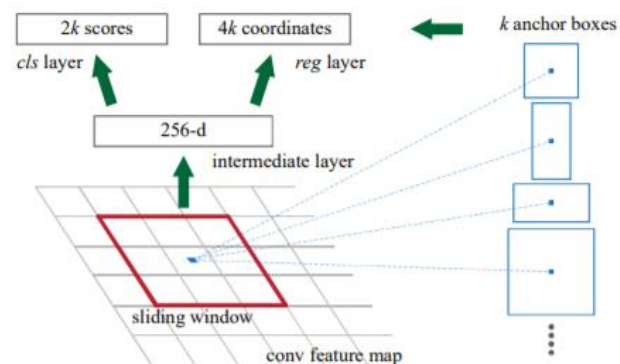


Figure 3: **Left:** Region Proposal Network (RPN). **Right:** Example detections using RPN proposals on PASCAL VOC 2007 test. Our method detects objects in a wide range of scales and aspect ratios.

# OBJECT DETECTION

- Architecture
  - Two-stage detector
    - Feature Pyramid Networks (T.-Y. Lin et al., CVPR 2017.)
      - Faster R-CNN 기반 Feature Pyramid Network 제안

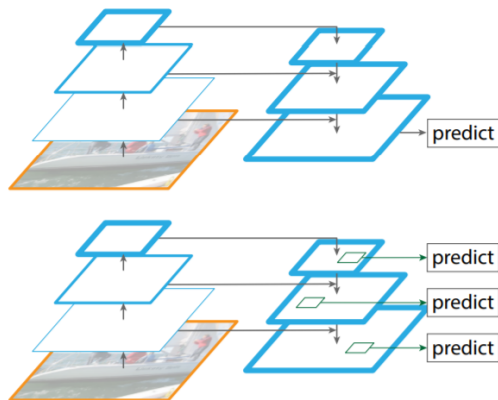
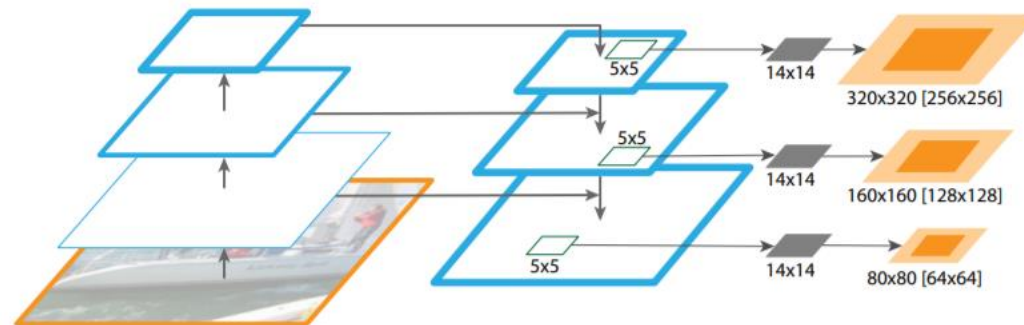


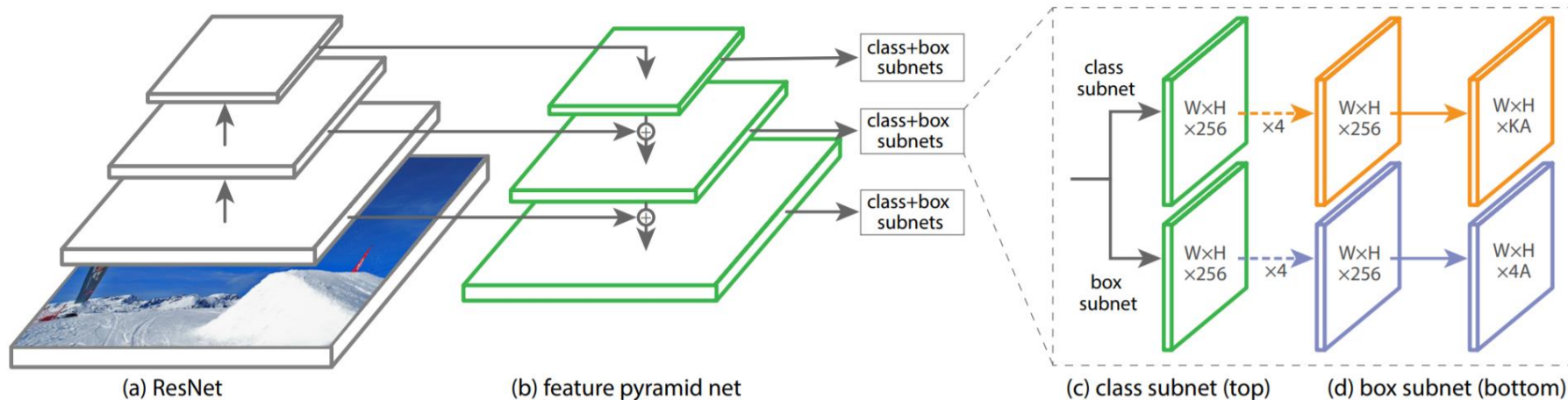
Figure 2. Top: a top-down architecture with skip connections, where predictions are made on the finest level (e.g., [28]). Bottom: our model that has a similar structure but leverages it as a *feature pyramid*, with predictions made independently at all levels.





# OBJECT DETECTION

- Architecture
  - One-stage detector
    - RetinaNet (T.-Yi. Lin et al., ICCV 2018.)
      - Feature Pyramid Network를 one-stage detector로 변화



# Reference

- <https://www.slideshare.net/pfi/a-brief-history-of-object-detection-tommi-kerola>
- <http://image-net.org/index>
- [http://cs231n.stanford.edu/slides/2019/cs231n\\_2019\\_lecture01.pdf](http://cs231n.stanford.edu/slides/2019/cs231n_2019_lecture01.pdf)
- <http://host.robots.ox.ac.uk/pascal/VOC/voc2012/>
- <http://cocodataset.org/#home>
- <https://www.cityscapes-dataset.com/>
- <https://arxiv.org/pdf/1905.05055.pdf>
- Faster R-CNN : <https://arxiv.org/pdf/1506.01497.pdf>
- Feature Pyramid Networks : <https://arxiv.org/pdf/1612.03144.pdf>
- YOLO : <https://arxiv.org/pdf/1506.02640.pdf>
- RetinaNet : <https://arxiv.org/pdf/1708.02002.pdf>





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