

Let $Y_t(\mathbf{s})$, where $\{\mathbf{s} \in \mathbb{R}^d, t \in \mathbb{Z}\}$, denote the spatio-temporal random process. We assume that the random process is spatially and temporally second order stationary, i. e.

$$\begin{aligned} E[Y_t(\mathbf{s})] &= \mu, \\ Var[Y_t(\mathbf{s})] &= \sigma_Y^2 < \infty, \\ Cov[Y_t(\mathbf{s}), Y_{t+u}(\mathbf{s} + \mathbf{h})] &= c(\mathbf{h}, u), \quad \mathbf{h} \in \mathbb{R}^d, u \in \mathbb{Z}. \end{aligned}$$

We note that $c(\mathbf{h}, 0)$ and $c(\mathbf{0}, u)$ correspond to the purely spatial and purely temporal covariances of the process respectively. A further common stronger assumption that is often made is that the process is isotropic. The assumption of isotropy is a stronger assumption. The process is said to be isotropic if

$$c(\mathbf{h}, u) = c(\|\mathbf{h}\|, u), \quad \|\mathbf{h}\| \geq 0, u \in \mathbb{Z},$$

where $\|\mathbf{h}\|$ is the Euclidean distance. Without loss of generality, we set μ equal to zero. As in the case of spatial process, one can define the spatio-temporal variogram for $\{Y_t(\mathbf{s})\}$ as

$$2\gamma(\mathbf{h}, u) = Var[Y_{t+u}(\mathbf{s} + \mathbf{h}) - Y_t(\mathbf{s})]. \quad (1)$$

If the random process $\{Y_t(\mathbf{s})\}$ is spatially and temporally stationary, then we can rewrite the above as

$$2\gamma(\mathbf{h}, u) = 2[c(\mathbf{0}, 0) - c(\mathbf{h}, u)], \quad (2)$$

and for an isotropic process, $\gamma(\mathbf{h}, u) = \gamma(\|\mathbf{h}\|, u)$. We note that $\gamma(\mathbf{h}, u)$ is defined as the semi-variogram.

In view of our assumption that the zero mean random process $\{Y_t(\mathbf{s})\}$ is second order spatially and temporally stationary, we have the spectral representation

$$Y_t(\mathbf{s}) = \int_{-\infty}^{\infty} \int_{-\pi}^{\pi} e^{i(\mathbf{s} \cdot \underline{\lambda} + t\omega)} dZ_Y(\underline{\lambda}, \omega), \quad (3)$$

where $\mathbf{s} \cdot \underline{\lambda} = \sum_{i=1}^d \mathbf{s}_i \lambda_i$ and $\int_{-\infty}^{\infty}$ represents d -fold multiple integral. We note that $Z_Y(\underline{\lambda}, \omega)$ is a zero mean complex valued random process with orthogonal increments with

$$\begin{aligned} E[dZ_Y(\underline{\lambda}, \omega)] &= 0, \\ E|dZ_Y(\underline{\lambda}, \omega)|^2 &= dF_Y(\underline{\lambda}, \omega), \end{aligned} \quad (4)$$

where $dF_Y(\underline{\lambda}, \omega)$ is a spectral measure. If we assume further that $dF(\underline{\lambda}, \omega)$ is absolutely continuous with respect to In view of the orthogonality of the function $Z_Y(\underline{\lambda}, \omega)$, we can show that the positive definite covariance function $c(\mathbf{h}, u)$ has the representation

$$c(\mathbf{h}, u) = \int_{-\infty}^{\infty} \int_{-\pi}^{\pi} e^{i(\mathbf{h} \cdot \underline{\lambda} + u\omega)} f(\underline{\lambda}, \omega) d\underline{\lambda} d\omega, \quad (5)$$

and by Fourier inversion, we have

$$f(\underline{\lambda}, \omega) = \frac{1}{(2\pi)^{d+1}} \sum_u \int_{-\infty}^{\infty} e^{-i(\mathbf{h} \cdot \underline{\lambda} + u\omega)} c(\mathbf{h}, u) d\mathbf{h}, \quad (6)$$

where $d\mathbf{h} = \prod_{i=1}^d dh_i$. From equation (5) we obtain

$$\begin{aligned} c(0, u) &= \int_{-\infty}^{\infty} \int_{-\pi}^{\pi} e^{iu\omega} f(\underline{\lambda}, \omega) d\underline{\lambda} d\omega = \int_{-\pi}^{\pi} e^{iu\omega} g_0(\omega) d\omega, \\ c(\|\mathbf{h}\|, u) &= \int_{-\pi}^{\pi} e^{iu\omega} \int_{-\infty}^{\infty} e^{i\mathbf{h} \cdot \underline{\lambda}} f(\underline{\lambda}, \omega) d\underline{\lambda} d\omega \\ &= \int_{-\pi}^{\pi} e^{iu\omega} g_{\|\mathbf{h}\|}(\omega) d\omega \end{aligned}$$

DFT, Discrete Fourier Transform

$$J_{\mathbf{s}_i}(\omega_k) = \frac{1}{\sqrt{2\pi n}} \sum_{t=1}^n Y_t(\mathbf{s}_i) e^{-it\omega_k}, \quad (7)$$

Let

$$\begin{aligned} g_{\|\mathbf{h}\|}(\omega) &= Cov(J_{\mathbf{s}}(\omega), J_{\mathbf{s}+\mathbf{h}}(\omega)) \\ &= \int_{-\infty}^{\infty} e^{i(\mathbf{h} \cdot \underline{\lambda} + u\omega)} f(\underline{\lambda}, \omega) d\underline{\lambda} d\omega \end{aligned}$$

be the covariance/spectrum function and, for example, let $g_{\|\mathbf{h}\|}(\omega)$ be of the form given by (??). Assume the function $g_{\|\mathbf{h}\|}(\omega)$ is characterized by the parameter vector ϑ . For convenience, we denote this covariance function by $g_{\|\mathbf{h}\|}(\omega, \vartheta)$.

Let us consider the case $\nu = 1$. Then from the equation (??) we have

$$g_{\|\mathbf{h}\|}(\omega) = \frac{\sigma_e^2}{(2\pi)^2} \left(\frac{\|\mathbf{h}\|}{2|c(\omega)|} \right) K_1(|c(\omega)| \|\mathbf{h}\|), \quad (8)$$

and from the equation (??) we have

$$g_0(\omega) = \frac{\sigma_e^2}{2(2\pi)^2 |c(\omega)|^2}, \quad (9)$$

which implies that $|c(\omega)|^2$ is proportional to $g_0^{-1}(\omega)$, which is defined as the inverse second order spectral density function of the process.

we can also obtain an expression for the auto-correlation function. We have the auto-correlation function when $d = 2$, and for all $\nu > 0$,

$$\begin{aligned}\rho(\|\mathbf{h}\|, \omega) &= \frac{g_{\|\mathbf{h}\|}(\omega)}{g_0(\omega)} \\ &= \frac{(\|\mathbf{h}\| |c(\omega)|)^{2\nu-1}}{2^{2\nu-2}\Gamma(2\nu-1)} K_{2\nu-1}(|c(\omega)| \|\mathbf{h}\|). \end{aligned} \quad (10)$$

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$$\begin{aligned}\rho(\|\mathbf{h}\|, \omega) &= \frac{g_{\|\mathbf{h}\|}(\omega)}{g_0(\omega)} \\ &= \frac{(\|\mathbf{h}\| |c(\omega)|)^{2\nu-1}}{2^{2\nu-2}\Gamma(2\nu-1)} K_{2\nu-1}(|c(\omega)| \|\mathbf{h}\|). \end{aligned} \quad (11)$$

It is interesting to note that $\rho(\|\mathbf{h}\|, \omega)$ is in fact the coherency coefficient between two Discrete Fourier Transforms separated by the spatial distance $\|\mathbf{h}\|$ at the frequency ω .

1 Spatio-temporal Prediction

Our object in this section is to obtain an optimal predictor for $\{Y_t(\mathbf{s}); t = 1, 2, \dots, n\}$ at the location \mathbf{s}_0 given the m spatial time series $\{Y_t(\mathbf{s}_i) | i = 1, 2, \dots, m; t = 1, 2, \dots, n\}$ from a spatio-temporal stationary, isotropic process $\{Y_t(\mathbf{s})\}$. In other words, we are predicting the entire data set at the location \mathbf{s}_0 . Using the predicted data at the location \mathbf{s}_0 , we can obtain the optimal predictors for the future values $\{Y_t(\mathbf{s}); t = n + \nu, \nu \geq 0\}$ at the location \mathbf{s}_0 . As in the case of the observed data $\{Y_t(\mathbf{s}_i)\}$, we define the discrete Fourier transform $J_{\mathbf{s}_0}(\omega)$ of $\{Y_t(\mathbf{s}_0)\}$, and predict the Fourier transform $J_{\mathbf{s}_0}(\omega)$ for all ω . Using the inverse Fourier Transform, we compute the predicted values of $Y_t(\mathbf{s}_0)$ for all $1 \leq t \leq n$. We pointed out earlier that there is a one to one correspondence between the discrete Fourier Transforms and the data. We have shown that if

$$J_{\mathbf{s}_0}(\omega) = \frac{1}{\sqrt{(2\pi n)}} \sum_{t=1}^n Y_t(\mathbf{s}_0) e^{-it\omega}, \quad (12)$$

then we have

$$Y_t(\mathbf{s}_0) = \sqrt{\frac{n}{2\pi}} \int_{-\pi}^{\pi} J_{\mathbf{s}_0}(\omega) e^{it\omega} d\omega. \quad (13)$$

Consider the vector of the discrete Fourier transforms obtained from all m locations at the frequency ω ,

$$\underline{J}'_m(\omega) = [J_{\mathbf{s}_1}(\omega), J_{\mathbf{s}_2}(\omega), \dots, J_{\mathbf{s}_m}(\omega)].$$

We note that

$$\begin{aligned} E[\underline{J}_m(\omega)] &= 0, \\ E[\underline{J}_m(\omega) \underline{J}_m^*(\omega)] &= F_m(\omega), \end{aligned} \quad (14)$$

where the real, $m \times m$ dimensional symmetric, positive definite square matrix $F_m(\omega) = (g_{\|s_i - s_j\|}(\omega); i, j = 1, 2, \dots, m)$, and each element $g_{\|s_i - s_j\|}(\omega)$ of the matrix $F_m(\omega)$ is given by (??). The complex random vector $\underline{J}_m(\omega)$ has a multivariate complex Gaussian distribution with mean zero and variance covariance matrix $F_m(\omega)$. Consider now the $(m+1)$ dimensional complex valued random vector,

$$\underline{J}'_{m+1}(\omega) = [J_{s_0}(\omega), \underline{J}'_m(\omega)].$$

It can be shown that the mean of the vector is zero, and the variance covariance matrix is given by

$$\begin{aligned} E[\underline{J}_{m+1}(\omega) \underline{J}_{m+1}^*(\omega)] &= \begin{bmatrix} E(J_{s_0}(\omega) J_{s_0}^*(\omega)) & E(J_{s_0}(\omega) \underline{J}_m^{*'}(\omega)) \\ E(\underline{J}_m(\omega) J_{s_0}^*(\omega)) & E(\underline{J}_m(\omega) \underline{J}_m^{*'}(\omega)) \end{bmatrix} \\ &= \begin{bmatrix} g_0(\omega) & \underline{G}'_0(\omega) \\ \underline{G}_0(\omega) & F_m(\omega) \end{bmatrix}, \end{aligned}$$

where $g_0(\omega)$ is the second order spectral density function of the spatial process $\{Y_t(\mathbf{s}_0)\}$ and the row vector $\underline{G}'_0(\omega)$ is given by

$$\begin{aligned} \underline{G}'_0(\omega) &= E[J_{s_0}(\omega) \underline{J}_m^{*'}(\omega)] \\ &= [g_{\|s_0 - s_1\|}(\omega), g_{\|s_0 - s_2\|}(\omega), \dots, g_{\|s_0 - s_n\|}(\omega)], \end{aligned}$$

and $F_m(\omega)$ is defined above. Therefore, the optimal linear least squares predictor of $J_{s_0}(\omega)$ given the vector $\underline{J}_m(\omega)$, is given by the conditional expectation

$$E[J_{s_0}(\omega) | \underline{J}_m(\omega)] = \underline{G}'_0(\omega) F_m^{-1}(\omega) \underline{J}_m(\omega), \quad (15)$$

and the minimum mean square prediction error is given by

$$\sigma_m^2(\omega) = g_0(\omega) - \underline{G}'_0(\omega) F_m^{-1}(\omega) \underline{G}_0(\omega). \quad (16)$$

To predict the data $Y_t(\mathbf{s}_0)$ for all t , we use the inverse transform (13). In computing the predictor of $J_{s_0}(\omega)$ using the expression (15) one usually replaces the elements of the matrices $\underline{G}_0(\omega)$ and $F_m(\omega)$ by their corresponding estimates and obtain

$$\hat{Y}_t(\mathbf{s}_0) = \sqrt{\frac{n}{2\pi}} \int_{-\pi}^{\pi} e^{it\omega} \hat{\underline{G}}'_0(\omega) \hat{F}_m^{-1}(\omega) \underline{J}_m(\omega) d\omega. \quad (17)$$

It is interesting to compare the formulae (15) and (16) with the corresponding expressions obtained using the time domain approach (see [CW11], equations 6.49 and 6.50; [BCG14], equations 11.21 and 11.22). They are similar, but it is important to note that for evaluating the expressions given in [CW11],

[BCG14], one requires the inversion of matrices of order $mn \times mn$, where as the evaluation of (ref:eq.5.3) given above only requires the inversion of $m \times m$ order matrices.

We note $E(Y_t(\mathbf{s}_0)) = 0$ and $Var(Y_t(\mathbf{s}_0)) \simeq \int_{-\pi}^{\pi} G'_0(\omega) F_m^{-1}(\omega) G_0(\omega) d\omega$.

We can show by an application of Parseval's Theorem

$$\begin{aligned} E \left(Y_t(\mathbf{s}_0) - \hat{Y}_t(\mathbf{s}_0) \right)^2 &= E \left| \mathcal{F}^{-1} \left(J_{\mathbf{s}_0}(\omega) - \hat{J}_{\mathbf{s}_0}(\omega) \right) \right|^2 \\ &= \int_{-\pi}^{\pi} \sigma_m^2(\omega) d\omega. \end{aligned} \quad (18)$$

In practice, the above integrals are approximated by finite sums of the form

$$\hat{Y}_t(\mathbf{s}_0) = \sqrt{\frac{2\pi}{n}} \sum_{j=0}^{n-1} e^{it\omega_j} \hat{\underline{G}}'_0(\omega_j) \hat{F}_m^{-1}(\omega_j) \underline{J}_m(\omega_j). \quad (19)$$

for all $t = 1, 2, \dots, n$, where the estimates $\hat{\underline{G}}_0(\omega_j)$ and $\hat{F}_m(\omega)$ are substituted for $\underline{G}_0(\omega)$ and $F_m(\omega)$ respectively. As noted earlier, the vector $\underline{G}_0(\omega)$ and the matrix $F_m(\omega)$ have covariance functions $g_{\|\mathbf{s}_i - \mathbf{s}_j\|}(\omega)$ as their elements.

1.1 Estimation of the Parameters of the Covariance function $g_{\|\mathbf{h}\|}(\omega, \vartheta)$ by Frequency Variogram (FV) Method.

Here we discuss briefly the FV methodology, The method here is based on the differences of DFTs.

We define a new spatio-temporal random process based on differences of the observed process $\{Y_t(\mathbf{s})\}$. Calculate the differences

$$X_{ij}(t) = Y_t(\mathbf{s}_i) - Y_t(\mathbf{s}_j), \quad \text{for each } t = 1, 2, \dots, n$$

and for all locations $\mathbf{s}_i, \mathbf{s}_j$ where \mathbf{s}_i and \mathbf{s}_j , ($i \neq j$) are the pairs that belong to the set $N(\mathbf{h}_l) = \{\mathbf{s}_i, \mathbf{s}_j \mid \|\mathbf{s}_i - \mathbf{s}_j\| = \|\mathbf{h}_l\|, l = 1, 2, \dots, L\}$. Define the Finite Fourier transform of the new time series $\{X_{ij}(t) \mid i \neq j\}$ at the frequencies $\omega_k = 2\pi s_k/n, k = 1, \dots, K$, where $s_k, k = 1, 2, \dots, K$ are set of integers and $\omega_j \pm \omega_k \neq 0 \pmod{2\pi}$ for $1 \leq j < k \leq K$ (see [Bri01], [GKS12]). Let

$$J_{X_{ij}}(\omega_k(n)) = \frac{1}{\sqrt{(2\pi n)}} \sum_{t=1}^n X_{ij}(t) e^{-it\omega_k} = J_{\mathbf{s}_i}(\omega_k) - J_{\mathbf{s}_j}(\omega_k).$$

Let $I_{X_{ij}}(\omega_k)$ be the second order periodogram of the time series $\{X_{ij}(t)\}$ given by

$$I_{X_{ij}}(\omega_k) = |J_{X_{ij}}(\omega_k)|^2. \quad (20)$$

Let $G_{X_{ij}}(\omega_k(n), \vartheta) = E(I_{X_{ij}}(\omega_k))$. The function $G_{X_{ij}}(\omega_k, \vartheta)$ is defined as the Frequency Variogram by [SRDB14]. It is very similar to the classical

definition of spatio-temporal variogram $2\gamma(\mathbf{h}, u)$ defined in section 2 (set $u = 0$) in (1). The usefulness of FV as a measure of dissimilarity between two spatial processes and its further properties were discussed in a recent paper by the authors ([ST16])

From (20), we obtain

$$\begin{aligned} E[I_{X_{ij}}(\omega_k)] &= G_{X_{ij}}(\omega_k, \vartheta) \\ &= E[I_{\mathbf{s}_i}(\omega_k)] + E[I_{\mathbf{s}_j}(\omega_k)] - 2\operatorname{Re} E[I_{\mathbf{s}_i\mathbf{s}_j}(\omega_k)], \end{aligned} \quad (21)$$

where $I_{\mathbf{s}_i\mathbf{s}_j}(\omega_k(n))$ is the cross periodogram between the processes $\{Y_t(\mathbf{s}_i)\}$ and $\{Y_t(\mathbf{s}_j)\}$ and $I_{\mathbf{s}_i}(\omega_k)$ is the periodogram of the series $Y_t(\mathbf{s}_i)$. For large n , it can be shown that for a stationary process $E[I_{\mathbf{s}_i}(\omega_k)] = E[I_{\mathbf{s}_j}(\omega_k)] = g_0(\omega_k; \underline{\vartheta})$ and for a stationary and an isotropic process $E[I_{\mathbf{s}_i\mathbf{s}_j}(\omega_k)] = g_{\|\mathbf{s}_i - \mathbf{s}_j\|}(\omega_k; \underline{\vartheta})$ which is real. Therefore, the expectation of (21) is given by

$$G_{(s_i, s_j)}(\omega_k; \underline{\vartheta}) = 2[g_0(\omega_k; \underline{\vartheta}) - g_{\|\mathbf{s}_i - \mathbf{s}_j\|}(\omega_k; \underline{\vartheta})], \quad (22)$$

It is interesting to compare $G_{(s_i, s_j)}(\omega_k; \underline{\vartheta})$ with spatio-temporal variogram $2\gamma(\mathbf{h}, u)$ given by equation (2). The similarity between these two functions shows that one can use the Frequency variogram which is a frequency domain version of spatio-temporal variogram for estimating the effective range $\|\mathbf{h}\|$, and also the parameters etc.

Now for the estimation of the parameter vector $\underline{\vartheta}$ we proceed as in [SRDB14]. Consider the K -dimensional complex valued random vector,

$$\underline{F}_{\|\mathbf{s}_i - \mathbf{s}_j\|}(\omega) = [J_{X_{ij}}(\omega_1), J_{X_{ij}}(\omega_2), \dots, J_{X_{ij}}(\omega_K)],$$

which is distributed asymptotically as complex normal with mean zero and with variance covariance matrix with diagonal elements $[g_{\|\mathbf{h}\|}(\omega_1, \vartheta), g_{\|\mathbf{h}\|}(\omega_2, \vartheta), \dots, g_{\|\mathbf{h}\|}(\omega_K, \vartheta)]$, where $\|\mathbf{h}\| = \|\mathbf{s}_i - \mathbf{s}_j\|$. We note that because of asymptotic independence of Fourier transforms at distinct frequencies chosen above, the off diagonal elements of the variance covariance matrix of the complex Gaussian random vector $\underline{X}_{\|\mathbf{h}\|}(\omega)$ are zero. Therefore, the minus of log likelihood function can be shown to be proportional to

$$Q_{n, N(\mathbf{h})}(\underline{\vartheta}) = \frac{1}{|N(\mathbf{h})|} \sum_{(\mathbf{s}_i, \mathbf{s}_j) \in N(\mathbf{h})} \sum_{k=1}^K \left[\ln G_{(\mathbf{s}_i, \mathbf{s}_j)}(\omega_k; \underline{\vartheta}) + \frac{I_{X_{ij}}(\omega_k(n))}{G_{(\mathbf{s}_i, \mathbf{s}_j)}(\omega_k; \underline{\vartheta})} \right]. \quad (23)$$

Here $|N(\mathbf{h})|$ is the total number of all distinct pairs \mathbf{s}_i and \mathbf{s}_j such that $N(\mathbf{h}) = \{(\mathbf{s}_i, \mathbf{s}_j) \mid \|\mathbf{s}_i - \mathbf{s}_j\| = \|\mathbf{h}\|\}$. The above criterion (23) is defined only for one distance $\|\mathbf{h}\|$. Suppose we now define L spatial distances from the observed data. We can now define an over all criterion for the minimization

$$Q_n(\vartheta) = \frac{1}{L} \sum_{l=1}^L Q_{n, N(\mathbf{h}_l)}(\underline{\vartheta}), \quad (24)$$

We minimize (24) with respect to $\underline{\vartheta}$ (for details refer to [SRDB14]). The asymptotic normality of the estimator $\underline{\vartheta}$ obtained by minimizing (24) has been proved in Theorem 2 of the paper of [SRDB14]. To avoid repetition, we refer to their paper for details. We state the asymptotic distribution of the estimates. It has been shown in [SRDB14] that under certain conditions, and for large n ,

$$\sqrt{n}(\underline{\vartheta}_n - \vartheta_0) \xrightarrow{D} N\left(\underline{0}, (\nabla^2 Q_n(\underline{\vartheta}_0))^{-1} V(\nabla^2 Q_n(\underline{\vartheta}_0))\right),$$

where $V = \lim_{n \rightarrow \infty} \text{Var} \left[\frac{1}{\sqrt{n}} \nabla Q_n(\vartheta_0) \right]$, $\nabla Q_n(\vartheta_0)$ is a vector of first order partial derivatives, $\nabla^2 Q_n(\vartheta_0)$ is a matrix of second order partial derivatives.

2 Algorithm

p=1 (16 előfordulás 24-ből)
q=0 (12/24) vagy q=1(11/24)
P=3 (18/24)
Q=0 (24/24)
d=0 (24/24)
D=1 (24/24)

Polynomials, AR, MA moving average polynomial is

$$\begin{aligned}\phi(z) &= 1 - \varphi_1 z - \varphi_2 z^2 - \dots - \varphi_p z^p, \\ \theta(z) &= 1 + \vartheta_1 z + \vartheta_2 z^2 + \dots + \vartheta_q z^q,\end{aligned}$$

where z complex, $|z| = 1$ is the unit circle, i.e. $z = e^{i\omega}$.
no common factors of $\varphi(z)$ and $\vartheta(z)$

$$\begin{aligned}\Phi(z) &= 1 - \Phi_1 u - \Phi_2 u^2 - \dots - \Phi_P u^P, \\ \Theta(z) &= 1 + \Theta_1 u + \Theta_2 u^2 + \dots + \Theta_Q u^Q,\end{aligned}$$

$$u = z^S = e^{iS\omega}$$

no common factors of $\Phi(z)$ and $\Theta(z)$

We are given a time series $\tilde{Y}_t(\mathbf{s}_i)$ for each location \mathbf{s}_i .

1. First step, for each time series $\tilde{Y}_t(\mathbf{s}_i)$ according to location $\mathbf{s}_i, i = 1, 2, \dots, m$, use SARIMA model and estimate the order $(p, d, q, P, D, Q, S)_i$. Find the common order: (p, d, q, P, D, Q, S) .
In our case $(p = 1, d = 0, q = 0, P = 3, D = 1, Q = 0)$

2. Apply the operator $(1 - B)^d (1 - B^S)^D$ on $\tilde{Y}_t(\mathbf{s}_i)$, i.e.

$$(1 - B)^d (1 - B^S)^D \tilde{Y}_t(\mathbf{s}_i) = Y_t(\mathbf{s}_i),$$

in case a trend/drift would be included, substruct the mean.

In our case, use seasonal difference $D = 1$, $lag = 12$, $\text{diff}(x, lag = 12)$, keep the first values for later inversion. Note the the drift will be eliminated since the later difference.

3. Use the above (p, q, P, Q, S) , estimate the *common* parameters by Whittle likelihood.

In our case, $(p, q, P, Q, S) = (p = 1, q = 0, P = 3, Q = 0)$

- (a) Calculate the distances between locations $\mathbf{s}_i, \mathbf{s}_j$ where $i < j$, they are denoted as length of differences $\|\mathbf{h}_{ij}\| = \|\mathbf{s}_i - \mathbf{s}_j\|$.
- (b) Calculate the differences

$$X_{ij}(t) = Y_t(\mathbf{s}_i) - Y_t(\mathbf{s}_j), \quad \text{for each } t = 1, 2, \dots, n$$

and for all locations $\mathbf{s}_i, \mathbf{s}_j$ where $i < j$. Collect pairs \mathbf{s}_i and \mathbf{s}_j , ($i \neq j$) that belong to the set $N(\mathbf{h}_l) = \{\mathbf{s}_i, \mathbf{s}_j \mid \|\mathbf{s}_i - \mathbf{s}_j\| = \|\mathbf{h}_l\|, l = 1, 2, \dots, L\}$. Note, the size of the matrix $[X_{ij}(t)]$, where $t = 1, 2, \dots, n$, and $i < j$, is $n \times (m-1)m/2$.

In our case each location forms an individual set.

- (c) Finite Fourier transform of $\{X_{ij}(t) \mid i < j\}$ at the frequencies $\omega_k = 2\pi k/n_0$, $k = 0, 1, \dots, n_0 - 1$, (see [Bri01], [GKS12]):

$$J_{X_{ij}\omega_k} = \frac{1}{\sqrt{(2\pi n)}} \sum_{t=1}^n X_{ij}(t) e^{-it\omega_k}.$$

Calculate the smoothed periodogram. Let $I_{X_{ij}}(\omega_k)$ be the second order periodogram of the time series $\{X_{ij}(t)\}$ given by

$$I_{X_{ij}}(\omega_k) = |J_{X_{ij}}(\omega_k)|^2. \quad (25)$$

In our case

- (d) For given SARMA (p, q, P, Q, S) i.e. given $(\varphi_1, \varphi_2, \dots, \varphi_p)$, $(\vartheta_1, \vartheta_2, \dots, \vartheta_q)$, $(\Phi_1, \Phi_2, \dots, \Phi_P)$, and $(\Theta_1, \Theta_2, \dots, \Theta_Q)$

$$\phi(B)\Phi(B^s)Y_t = \theta(B)\Theta(B^s)W_t,$$

Calculate $|c(\omega)|^2$

$$|c(\omega)|^2 = \left| \frac{\theta(z)\Theta(z^s)}{\phi(z)\Phi(z^s)} \right|^2$$

$z = e^{i\omega}$, at the same frequencies as the periodogram.

- (e) Calculate $g_0(\omega_k; \underline{\vartheta})$ and $g_{\|\mathbf{s}_i - \mathbf{s}_j\|}(\omega_k; \underline{\vartheta})$ and

$$\begin{aligned} G_{(s_i, s_j)}(\omega_k; \underline{\vartheta}) &= 2 [g_0(\omega_k; \underline{\vartheta}) - g_{\|\mathbf{s}_i - \mathbf{s}_j\|}(\omega_k; \underline{\vartheta})] \\ &= 2 \left[\frac{\sigma_e^2}{2(2\pi)^2 |c(\omega)|^2} - \frac{\sigma_e^2}{(2\pi)^2} \left(\frac{\|\mathbf{h}_{ij}\|}{2|c(\omega)|} \right) K_1(|c(\omega)| \|\mathbf{h}_{ij}\|) \right] \\ &= \frac{\sigma_e^2}{(2\pi)^2 |c(\omega)|^2} [1 - \|\mathbf{h}_{ij}\| |c(\omega)| K_1(|c(\omega)| \|\mathbf{h}_{ij}\|)] \end{aligned}$$

where $\mathbf{h}_{ij} = \mathbf{s}_i - \mathbf{s}_j$

(f) The exponent of the Whittle likelihood

$$Q_{n,N(\mathbf{h})}(\underline{\vartheta}) = \frac{1}{|N(\mathbf{h})|} \sum_{(\mathbf{s}_i, \mathbf{s}_j) \in N(\mathbf{h})} \sum_{k=1}^K \left[\ln G_{(\mathbf{s}_i, \mathbf{s}_j)}(\omega_k; \underline{\vartheta}) + \frac{I_{Xij}(\omega_k(n))}{G_{(\mathbf{s}_i, \mathbf{s}_j)}(\omega_k; \underline{\vartheta})} \right]$$

$$Q_n(\vartheta) = \frac{1}{L} \sum_{l=1}^L Q_{n,N(\mathbf{h}_l)}(\underline{\vartheta}),$$

Whittle estimator for ϑ

$$\arg \min Q_n(\vartheta).$$

4. Prediction

References

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