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In [1]:
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import numpy as np
import cv2
In [2]:
def onChange(pos): # 트랙바 핸들러
    global img
     r = cv2.getTrackbarPos('R','img')
    g = cv2.getTrackbarPos('G','img')
    b = cv2.getTrackbarPos('B', 'img')
     img[:] = (b, g, r)
     cv2.imshow('img', img)
In [3]:
img = np.zeros((512, 512, 3), np.uint8) # black
cv2.imshow('img',img)
# 트랙바 생성
cv2.createTrackbar('R', 'img', 0, 255, onChange)
cv2.createTrackbar('G', 'img', 0, 255, onChange) cv2.createTrackbar('B', 'img', 0, 255, onChange)
# 트랙바 위치 초기화
cv2.setTrackbarPos('R', 'img', 0) cv2.setTrackbarPos('G', 'img', 0) cv2.setTrackbarPos('B', 'img', 255)
cv2.waitKey()
cv2.destroyAllWindows()
In [ ]:
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