

Automated Verification of Safety Properties of Declarative Networking Programs

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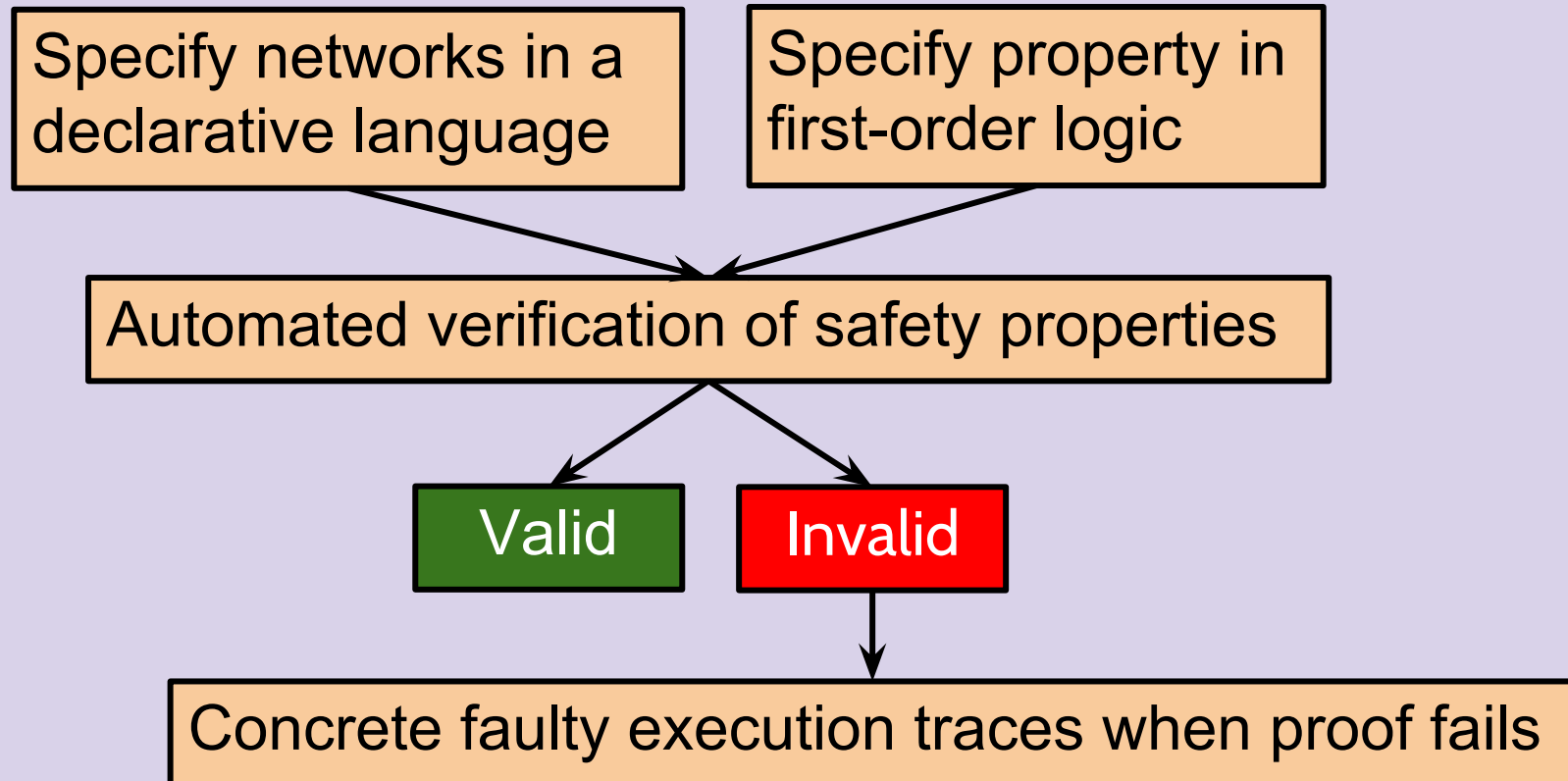
INTRODUCTION

Motivation

- Networks are complex systems that unfortunately are ridden with errors
- Such errors can lead to disruption of services with grave consequences

Our Solution

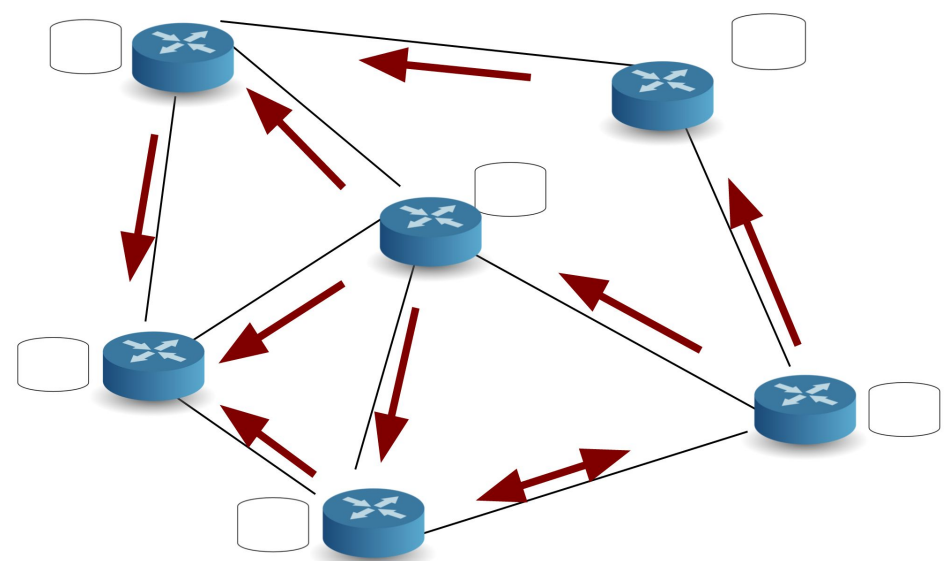
- Network Verification



Formal specification of networks in a declarative language

- Encode the network protocol in Network Datalog (NDLog), a distributed variant of Datalog
- Recursive query language over network states

Rule Head :- Body₁, Body₂, ..., Body_n, Constraint
 @: Location specifier



DGraph

Dependency Graph

NDLog Program

Vertices

Tuple nodes
Rule nodes

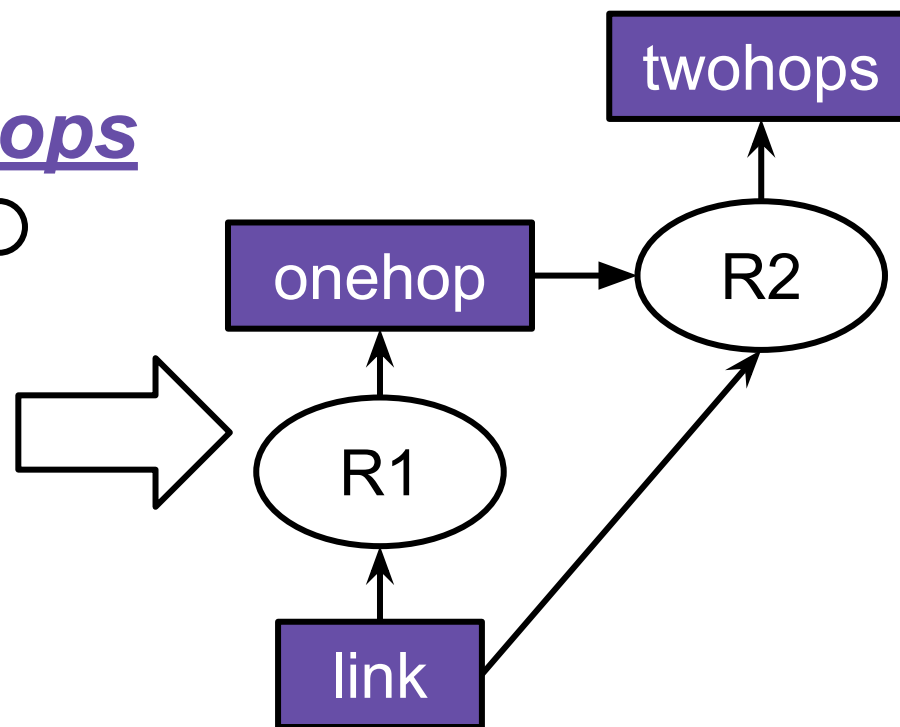
Edges

[Rule node → Head tuple node]
[Body tuple node → Rule node]

Example dependency graph for Twohops

Twohops

R1 onehop(@z,x,c2) :- link(@z,x,c2)
 R2 twohops(@x,y,c) :-
 link(@z,y,c1), onehop(@z,x,c2), c=c1+c2



GenDPool

Derivation pool construction

- Each entry in the derivation pool maps to a distinct tuple in the NDLog program
- Consists of list of possible derivations and their corresponding constraints

Specify safety property in first-order logic

Safety property Something bad never happens

Restricted property format “◆” Indicates the temporal operation “past”

$$\forall x_1.p_1(x_1) \wedge \forall x_2.p_2(x_2) \wedge \dots \wedge \forall x_n.p_n(x_n) \wedge c_q(x_1, \dots, x_n) \supset \exists y_1. \text{◆} q_1(y_1) \wedge \exists y_2. \text{◆} q_2(y_2) \wedge \dots \wedge \exists y_m. \text{◆} q_m(y_m) \wedge c_q(x_1, \dots, x_n, y_1, \dots, y_m)$$

Example invalid safety property for Twohops

If the cost of traversing a **onehop** tuple is greater than zero, then there exists a link tuple, such that the cost of traversing that **link** tuple is less than zero

$$\forall x_1, x_2, x_3. \text{onehop}(x_1, x_2, x_3) \wedge (x_3 > 0) \supset \exists y_1, y_2, y_3. \text{◆} \text{link}(y_1, y_2, y_3) \wedge (y_3 < 0)$$

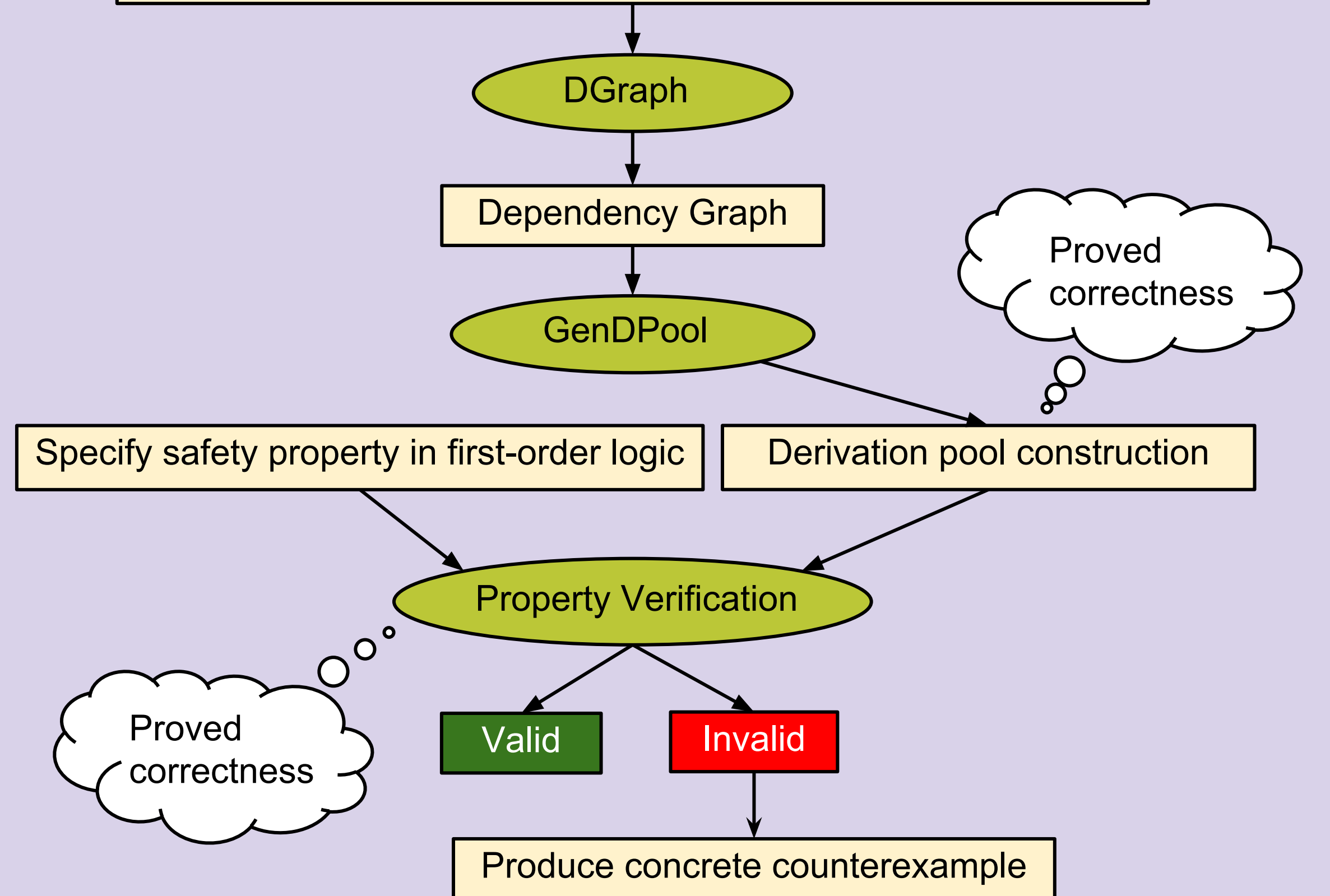
COMPLEXITY

Theoretical Given an NDLog program with R rules where each rule has at most W body tuples, and a property where n = #predicates in the antecedent, m = #predicates in consequent, then the time complexity is $O((R^{nW \wedge R})n^m W^{Rn})$.

Experimental We tested our tool on four network applications: ethernet source learning, load balancer, firewall, and address resolution protocol. Each case study ran to completion within 1 second.

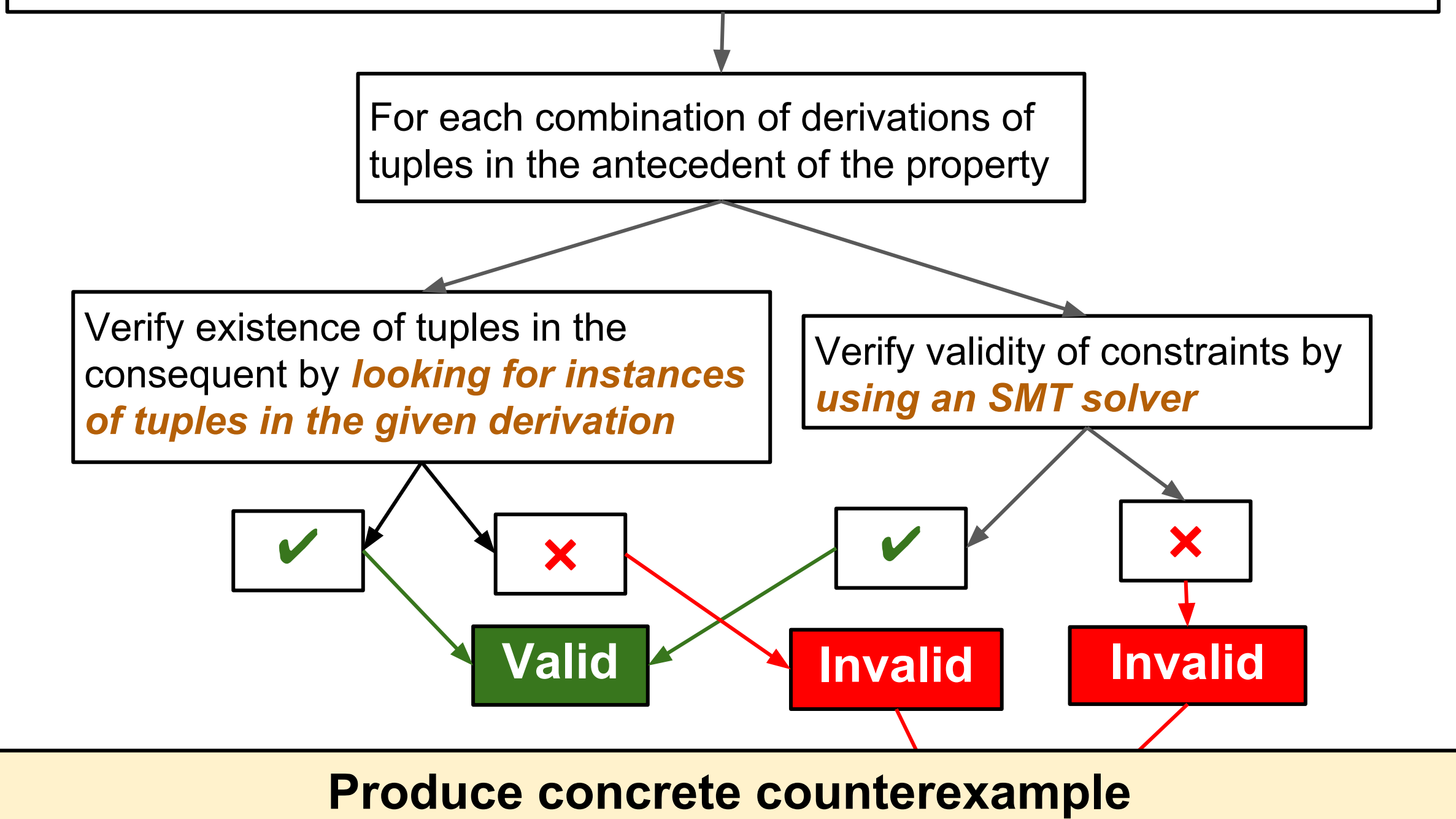
METHODOLOGY OUTLINE

Formal specification of networks in a declarative language



Property Verification

Verify the property holds for all possible derivations by **enumerating all derivations for the tuples in the antecedent of the property**



Produce concrete counterexample

Find a satisfying substitution for the negation of the constraints to generate a concrete counterexample

Example counterexample construction for Twohops

$$\forall x_1, x_2, x_3. \text{onehop}(x_1, x_2, x_3) \wedge (x_3 > 0) \supset \exists y_1, y_2, y_3. \text{◆} \text{link}(y_1, y_2, y_3) \wedge (y_3 < 0)$$

Verify the property holds for all possible derivations of tuples in the antecedent
 Tuple **onehop** in the antecedent has only one possible derivation

