

Paradigms of Programming

Course Outline

Imperative : A set of statements / commands / instructions each of which changes the current state of system.

Eg: C, Pascal, Fortran, Basic, Assembly, Machine Code

Recursion ↓ ↳ Scientific (w/o recursion) Fortran, HLL
 type-safe

D Why C?

01-08-2017 Imperative paradigm has the concept of time. At any time, the machine is in some state s_t . Any instruction changes the state.

$$s_{t-1} \xrightarrow{\text{It}} s_t$$

15 C language was first used to write the UNIX OS. It was useful because it helps to optimize code which is very essential while developing OS.

Eg: `while (i++ > 2) > (j++ < 2);`
2 times slower than Assembly.

Object orientation

20 Classes introduce data types. Data & their associated functions are clubbed together to form "objects".

Eg: C++, Objective C, C++, Java.

Pure Object Oriented : Only objects & messages b/w them - Eg. Java, Objective C

Functional

No notion of time or state $O = f(I)$
(output) (input)

Typically recursion. Eg. LISP (developed in 1959) : List Processing, Python, Haskell, Matlab.

30 5-10 times slower than C.

Logic Programming

Specify a set of rules. Eg. PROLOG.
2 times slower than functional

Imperative Paradigm

Assignment statement :-

$x \leftarrow e$ expression.
 variable assignment

int x; → variable declaration

A data type defines the storage of variables of that type and the associated operations that can be performed on data of this type.

Inbuilt data type : int, long, short, float, double, char

User defined data type : class, complex{float r, float i}

Eg - complex operator + (complex a, complex b)
 {
 complex c;
 c.r = a.r + b.r;
 c.i = a.i + b.i;
 return c;
 }

complex a = {1.0, 2.0}, b = {1.5, 2.5}

complex c = a+b; polymorphism helps it to detect to perform
+(a,b)

Alternative Statement

if (boolean expression) → { statements }.

General: if $B_1 \rightarrow S_1$

$B_2 \rightarrow S_2$

\vdots
 $B_n \rightarrow S_n$

fi // conclusion

Loops / Iterative Statement

do

$B_1 \rightarrow S_1$

$B_2 \rightarrow S_2$

\vdots
 $B_n \rightarrow S_n$

od.

for $i \leftarrow 1$ to 10 step 2. do { S }

↳ used for a fixed number of iterations for a given set of values of an iterator.

while:

while B

→ repeat

do S

flag = 0

if (flag = 0 & $\neg B$)

break;

else flag = 1

$S; S$
until ($\neg B$)
while ($\neg B$)
 $S;$

Repeat-until:

repeat S

→ until ($\neg B$)
while ($\neg B$)
 $S;$

until B

7-08-2017

Monday

We cannot write a program to generate another program. Because the no. of options available at each step are many (exponential) indefiniteness

Functions

Global declarations (type declarations & variable declarations)

function1() { }

function2() { }

:

main() { }

Scope: int x = 2;

f1() {

int x = 3;

print(x); // prints 3 nested scope

}

Pascal:

Global declaration {
 square()
 { square(2); }
}

f1() {
 nested func. square() {
 }
 square(2);
 }
}

Recursion :-

- (i) $f_1 \rightarrow f_1$
- (ii) $f_1 \rightarrow f_2 \rightarrow f_1$
- (iii) $f_1 \rightarrow f_2 \rightarrow f_3 \rightarrow f_1$

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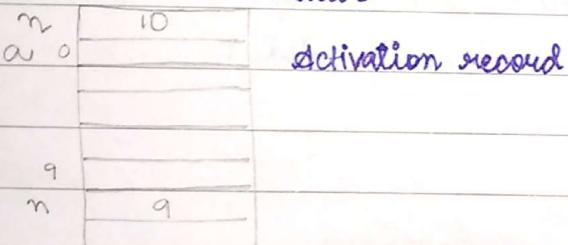
In recursion, at a given point of time, only one version of the function is active. In FORTRAN at compile time only, the fns, global & local variables are statically allocated. Hence it cannot support recursion - Very fast execution.

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Recursion in C is implemented using a "call stack".

2 types of memory in C: heap memory & stack memory
 call stack malloc \rightarrow fn variables.

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```
int fact (int n) {
```

```
    int a[10];
```

```
    if (n==0) return 1;
```

```
    else return (n * fact (n-1));
```

// returning a here would give

} If we want to return array error because activation record
 we could do: int * fact (int n) { is popped from stack once fn returns
 $\text{int } *a = \text{malloc } 1;$

return a;

activation record.

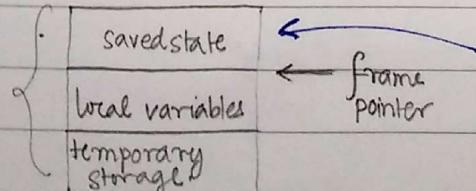
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for restarting computation of previous fn.
 (registers/instruction counter).



8-08-2017

Tuesday

Dynamic Scope

```

int x = 1;
f1() {
    int x = 2;
    f2();
}
f2() {
    print(x);
}

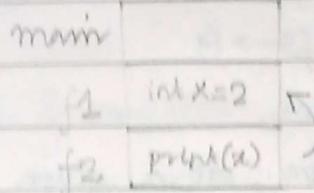
```

main() {

f1();

}

// prints 2.

Call Sequence

Early implementation of LISP had dynamic scope.

Static / Lexical scope can be determined at compile time.Most modern languages ^(including C) follow static scope.

In previous code, it would've printed 1.

Function parameter passing mechanismCall-by-value

```

f1(int x, float y)
{
    x = 2;
    y = 3.0f;
}

```

```

main() {
    int x = 1;
    float y = 2.0f;
    f1(x, y);
    print(x, y); // prints 1, 2.0
}

```

Call by reference

prints 3, 3.0.

f1(int &x, int &y)

Call by value- result Copy while calling & returning.
Code prints 2, 80.

Slower than call by reference.

call by name.

(Textual substitution). - Typically used for macros

Eg - swap (int x, int y) {

 int temp = ~~xy~~;

~~xy~~ = ~~zw~~;

~~zw~~ = temp;

main
swap (int x, int y) {

 int ~~temp~~ x = 1, y = 2;

 swap (w, z); w acquires value of x, z → y. Then swapped

 print (w, z); // prints 2, 1

}

Functions

Multiple occurrences of code segments can be put into a function:

- Modularity
- Libraries
- Recursion

C program :-

25 Global declarations {

 f1() {

 }

 f2() {

 }

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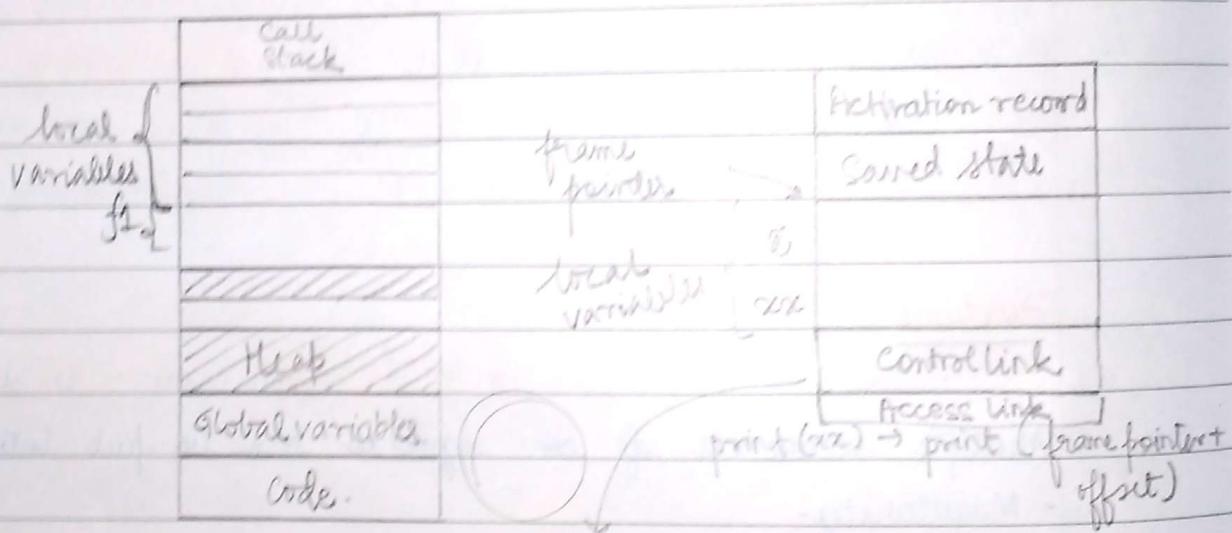
```

int x = 1;
f1() {
    int x = 2;
    {
        int x = 3;
        print(x);
    }
}
    
```

↔ int y = 3;
 print(y)

C has only 2 levels
 of scope.
 New scope is created
 only in function
 declaration.

C memory allocation



PASCAL :

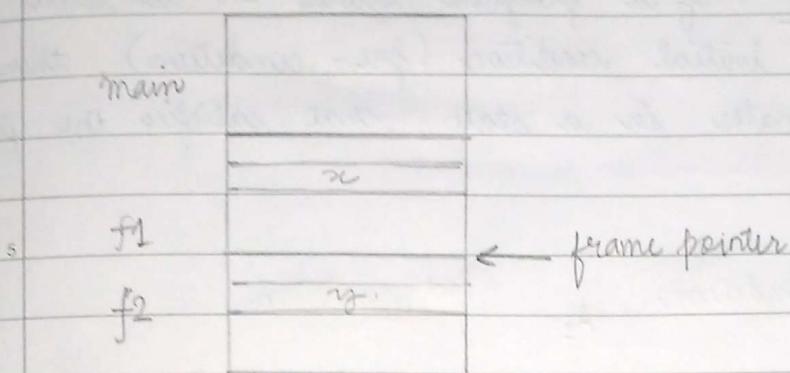
```

function f1()
{
    int x=2;
}

function f2()
{
    int y=3;
    print(x,y);
}

f2();
    
```

→ frame pointer + fixed offset



say another f_n inside f_1 is declared as follows:-

10 $f_3() \{$
 int $x = 4;$
 $f_2();$
 }

same
access
link

& we call f_3 inside f_1 .

15 Main $\rightarrow f_1 \rightarrow f_3 \rightarrow f_2$ dynamic (control) links

Main $\rightarrow f_1 \rightarrow f_3 \rightarrow f_2$ access (static) links

14-08-2017

Monday

Eg. 1.

Analyzing Imperative Programs

Precondition: $\{x * x = x * x, \text{MININT} \leq x * x \leq \text{MAXINT}\}$

$$y \leftarrow x * x.$$

Postcondition: $\{(y = x * x) \wedge (\text{MININT} \leq y \leq \text{MAXINT})\}$

Eg. 2.
swap

Precondition: $\{x = X, y = Y\}$

$$\{x = X, y = Y\} \xrightarrow{t \leftarrow x;} t \leftarrow x;$$

$$\{y = Y, t = X\} \xrightarrow{x \leftarrow y;} x \leftarrow y;$$

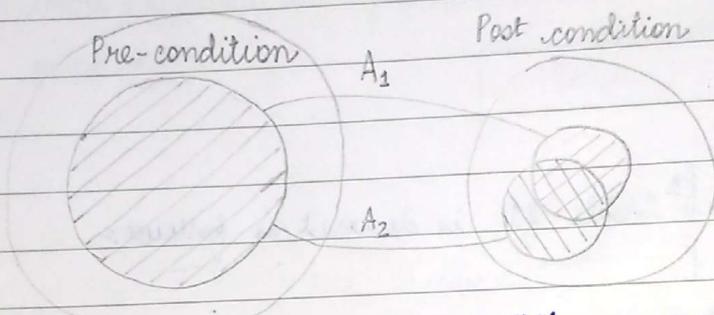
$$\{x = Y, t = X\} \xrightarrow{y \leftarrow t;} y \leftarrow t;$$

Postcondition: $\{x = Y, y = X\}$

work w/
the
preconditions
in reverse
order

Program correctness : If a program starts in a state satisfying the initial condition (pre-condition), then the program terminates in a state that satisfies the post-condition.

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Even if states satisfying pre-condition are mapped to a subset of post condition, it's a valid program. Eg. MST
The program should work for a condition weaker than pre-condition & condition stronger or equal to post condition.

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Weakest Pre-condition (wp) : $wp(S, R) = P$

Weakest pre-condition such that execution of S in any of the states satisfying S will result in state satisfying R

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$$wp(x \in e, R) = \text{domain}(e) \text{ cond } \underbrace{R^x_e}_{\text{conditional and}} \quad \text{replace } x \text{ with } e \text{ in } R.$$

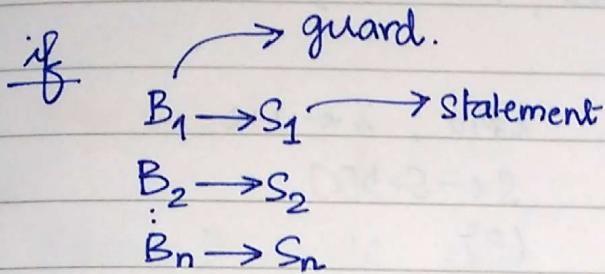
$$Q \Rightarrow wp(S, R)$$

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$$wp("x \leftarrow e", R) = \text{domain}(e) \text{ cond } \underbrace{R^x_e}_e$$

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Conditional Statements.



fi

$$WP(IF, R) = \begin{array}{l} \text{domain (BB) cond. BB} \wedge \\ B_1 \Rightarrow WP(S_1, R) \wedge \\ B_2 \Rightarrow WP(S_2, R) \wedge \\ \vdots \\ B_n \Rightarrow WP(S_n, R) \end{array}$$

BB $\Rightarrow B_1 \vee B_2 \vee \dots \vee B_n$.

{P} \rightarrow Loop invariant

do

$$\begin{array}{l} B_1 \rightarrow S_1 \\ B_2 \rightarrow S_2 \\ \vdots \\ B_n \rightarrow S_n \end{array}$$

do

$$\begin{array}{l} BB \rightarrow \\ \text{if } B_1 \rightarrow S_1 \\ B_2 \rightarrow S_2 \\ \vdots \\ B_n \rightarrow S_n \end{array}$$

od.

{R}

fi
od.

Find a predicate P called the loop invariant that satisfies ① P is true before the loop.

② $\{P \wedge B_i\} \leq i \leq \{P\} \quad \# 1 \leq i \leq n$

(or) $P \wedge B_i \Rightarrow WP(S_i, R^P)$

③ $P \wedge BB \Rightarrow R$

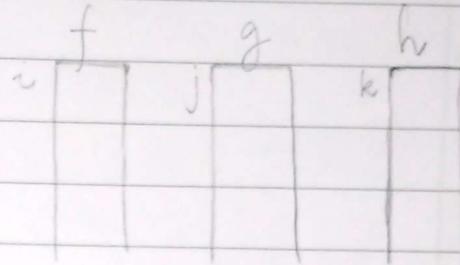
④ $P \wedge BB \Rightarrow t > 0$

⑤ $\{P \wedge B_i\} \quad t_1 \leq t; \forall i \quad t < t_2 \# \quad 1 \leq i \leq n$

{R: $Z = a * b$ }

Welfare Crook.

Given: 3 sorted lists



Problem: Find the first common entry in the 3 lists.

$i \leftarrow 0, j \leftarrow 0, k \leftarrow 0$

do

$$\begin{array}{lll} f[i] < g[j] & \vee & f[i] < h[k] \\ g[j] < f[i] & \vee & g[j] < h[k] \\ h[k] < f[i] & \vee & h[k] > g[j] \end{array} \quad \begin{array}{l} i \leftarrow i+1; \\ j \leftarrow j+1; \\ k \leftarrow k+1; \end{array}$$

end

{R: $f[i] = g[j] = h[k]$ }

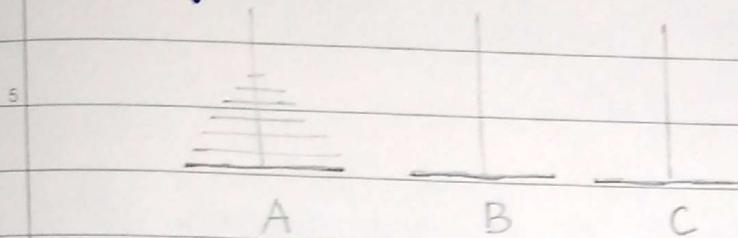
$P \wedge \neg BB = R$

\hookrightarrow vague.

$$\begin{array}{ll} f(i) \geq g(j) & \wedge \quad f(i) \geq h(k) \\ \wedge \quad g(j) \geq f(i) & \wedge \quad g[j] \geq h(k) \\ \wedge \quad h[k] \geq f[i] & \wedge \quad h[k] \geq g[j] \end{array}$$

Recursive vs Iterative

Tower of Hanoi



$\text{TOH}(n, A, B, C)$: Move n disks from A to C using B as spare.

{

$\text{TOH}(n-1, A, C, B);$

move a disk from A to C;

$\text{TOH}(n-1, B, A, C);$

}

Recursive is tough in this case. (or use stack overflow)

Mergesort

$\text{mergesort}(\text{list})$

{

mid $\leftarrow \text{size}(\text{list}) / 2;$

leftlist $\leftarrow \text{sublist}(\text{list}[: \text{mid}]);$

rightlist $\leftarrow \text{sublist}(\text{list}[\text{mid} + 1:]);$

merge(mergesort(leftlist), mergesort(rightlist));

}

Iterative :

set $s \leftarrow \text{split the list into } n \text{ singleton lists}$

while ($\text{size}(s) > 1$) {

pick any two lists from s & merge. Put it back into s .

}

Note: set works because ordering doesn't matter

Most efficient merge: Always pick the 2 smallest sets & merge

P: All lists in S are sorted, union of all lists = original list
 t: size(S).

Quicksort

```
quicksort (b[], i, j) {
    if (j - i + 1 > 1) {
        k ← partition (b, i, j);
        quicksort (b, i, k - 1);
        quicksort (b, k + 1, j);
    }
}
```

Iterative:

```
s ← {(2, 7)}
```

```
while (size(s) > 0)
```

{

pull out any interval $(\underline{m}, \underline{n}) \in s$;

$\leftarrow k \leftarrow \text{partition}(b, i, j);$

\leftarrow put back $(i, k - 1)$ into s : $s = s \cup \{(i, k - 1), (k + 1, j)\}$

P: Those elements not included in any interval are correctly placed

t: sum of interval lengths

Developing loops

Initialization statements

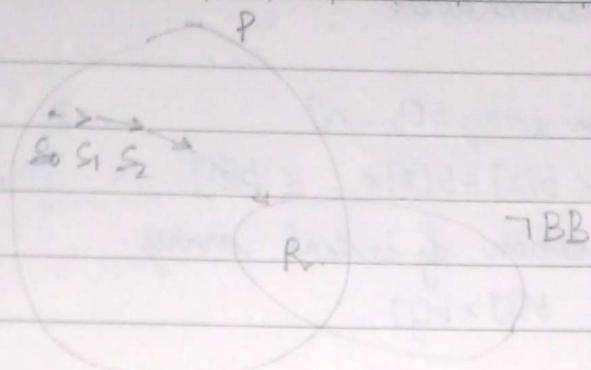
{P}

do

$B \rightarrow S$

od

{R}



P is obtained from R by weakening R .

Eg: $R: z = a * b$

By introducing variables, $\stackrel{P}{z} + x * y = a * b$. $x, y \geq 0$.

① Develop the guard first (By looking at which condition P reduces to R).

Eg-1 do

$$y \neq 0 \rightarrow \stackrel{z \leftarrow z+x}{y \leftarrow y-1}$$

$$\text{od. } \begin{cases} y > 0 \\ y \text{ even} \end{cases} \quad \text{or } y \leftarrow y/2$$

$$wp(y \leftarrow y-1, z+x+y = ab).$$

$$= z + x(y-1) = ab.$$

$$= z + xy - x = ab.$$

$$wp(z \leftarrow z+x, z-x+xy = ab).$$

$$= z + xy = ab.$$

$$wp(y \leftarrow y/2, z+x+y = ab)$$

$$= z + x(y/2) = ab.$$

$$wp(x \leftarrow x+z, z + z(y/2) = ab)$$

$$= z + 2y = ab \quad \wedge \quad \begin{matrix} y \text{ is even} \\ \nearrow \\ y > 0 \end{matrix}$$

$$P \quad \wedge \quad Bi$$

② Write guarded statements to
make progress towards termination
Eg 2. Bubble Sort

Precondition Q: Given an array $b[1, \dots, n]$

Post condition R: $b[1] \leq b[2] \leq b[3] \leq \dots \leq b[n]$ ^ final array is
permutation of initial array.

5 Bound function: $\sum_{\substack{(i,j) \\ i < j}} b[i] > b[j]$

Start by making progress towards termination.
 $b[i] > b[j] \rightarrow \text{swap}(b[i], b[j])$