

## Problem 2 - Assignment 9

LPT model for  $t=0, \dots, T-1$

$$P_{t+1} = P_t e^{Z_t}$$

$$X_{t+1} = \rho X_t + \eta_t$$

$$Q_t = P_t (1 - bN_t - \theta X_t)$$

Let  $R_t$  be the remaining stocks at time  $t$

and  $N_t$  be the number of shares sold at time  $t$ ,

such that  $R_t = R_{t-1} - N_t$ ,  $R_0 = N$ ,  $R_T = 0$

where  $N$  is the total number of shares to be sold.

The goal is to maximize:  $E\left[\sum_{t=0}^{T-1} N_t Q_t\right]$

The Optimal Value Function satisfies the Bellman Equation:

$$V_t^*(P_t, R_t, X_t) = \max_{N_t} \left[ E[N_t Q_t + V_{t+1}^*(P_{t+1}, R_{t+1}, X_{t+1})] \right]$$

Starting from  $t=T-1$  and then recursively moving backwards, we obtain:

$$\bullet V_{T-1}^*(P_{T-1}, R_{T-1}, X_{T-1}) = \max_{N_{T-1}} \left[ E[N_{T-1} Q_{T-1}] \right] = E[R_{T-1} Q_{T-1}] = R_{T-1} P_{T-1} (1 - bR_{T-1} - \theta X_{T-1})$$

$$\bullet V_{T-2}^*(P_{T-2}, R_{T-2}, X_{T-2}) = \max_{N_{T-2}} \left[ E[N_{T-2} Q_{T-2} + V_{T-1}^*(P_{T-1}, R_{T-1}, X_{T-1})] \right]$$

$$= \max_{N_{T-2}} \left[ E \left[ N_{T-2} P_{T-2} (1 - bN_{T-2} - \theta X_{T-2}) + P_{T-1} (R_{T-2} - N_{T-2}) (1 - \theta X_{T-1} - b(R_{T-2} - N_{T-2})) \right] \right]$$

$$= \max_{N_{T-2}} \left[ N_{T-2} P_{T-2} (1 - bN_{T-2} - \theta X_{T-2}) + P_{T-2} E[e^{Z_{T-1}}] (R_{T-2} - N_{T-2}) (1 - \theta \rho X_{T-2} - b(R_{T-2} - N_{T-2})) \right]$$

Let  $q = E[e^{Z_{T-1}}] = e^{\mu_2 + \frac{\sigma_2^2}{2}}$ , then:

$$V_{T-2}^* = \max_{N_{T-2}} \left[ N_{T-2} P_{T-2} (1 - bN_{T-2} - \theta X_{T-2}) + q P_{T-2} (R_{T-2} - N_{T-2}) (1 - \theta \rho X_{T-2} - b(R_{T-2} - N_{T-2})) \right]$$

The above is a function of  $N_{T-2}$  and it's concave<sup>(\*)</sup>, so by taking its derivative and setting it to 0, we can find  $N_{T-2}^*$ :

(\*) The coefficient of  $N_{T-2}^2$  is negative:  $-b(1+q)P_{T-2} < 0$

$$N_{T-2}^* = C_{T-2}^{(1)} + C_{T-2}^{(2)} R_{T-2} + G_{T-2}^{(3)} X_{T-2}$$

where

$$C_{T-2}^{(1)} = \frac{q-1}{-2b(q+1)}, \quad C_{T-2}^{(2)} = \frac{q}{q+1}, \quad C_{T-2}^{(3)} = \frac{\theta(q\theta-1)}{2b(q+1)}$$

Substituting  $N_{T-2}^*$  back in  $V_{T-2}^*$ , we obtain the following:

$$V_{T-2}^*(P_{T-2}, R_{T-2}, X_{T-2}) = qP_{T-2} \left[ C_{T-2}^{(4)} + C_{T-2}^{(5)} R_{T-2} + C_{T-2}^{(6)} X_{T-2} + C_{T-2}^{(7)} R_{T-2}^2 + C_{T-2}^{(8)} X_{T-2}^2 + C_{T-2}^{(9)} R_{T-2} X_{T-2} \right]$$

where

$$C_{T-2}^{(4)} = C_{T-2}^{(1)} (1 - bC_{T-2}^{(1)}) - qC_{T-2}^{(1)} (1 + bC_{T-2}^{(1)})$$

$$C_{T-2}^{(5)} = 2C_{T-2}^{(2)}$$

$$C_{T-2}^{(6)} = (1-q)C_{T-2}^{(3)}$$

$$C_{T-2}^{(7)} = -bC_{T-2}^{(2)}$$

$$C_{T-2}^{(8)} = C_{T-2}^{(3)} (-bC_{T-2}^{(1)} - \theta) - qC_{T-2}^{(3)} (\theta + bC_{T-2}^{(1)})$$

$$C_{T-2}^{(9)} = -\theta(1+q)C_{T-2}^{(2)}$$

Continuing backwards in time in this manner gives:

$$V_{T-3}^*(P_{T-3}, R_{T-3}, X_{T-3}) = \max_{N_{T-3}} \left[ E \left[ N_{T-3} Q_{T-3} + V_{T-2}^*(P_{T-2}, R_{T-2}, X_{T-2}) \right] \right]$$

$$\begin{aligned} &= \max_{N_{T-3}} \left[ N_{T-3} P_{T-3} (1 - bN_{T-3} - \theta N_{T-3}) + qP_{T-3} (C_{T-2}^{(4)} + C_{T-2}^{(5)} R_{T-2} + C_{T-2}^{(6)} X_{T-2} + C_{T-2}^{(7)} R_{T-2}^2 + C_{T-2}^{(8)} X_{T-2}^2 + C_{T-2}^{(9)} R_{T-2} X_{T-2}) \right] \\ &= \max_{N_{T-3}} \left[ N_{T-3} P_{T-3} (1 - bN_{T-3} - \theta N_{T-3}) + q^2 P_{T-3} (C_{T-2}^{(4)} + C_{T-2}^{(5)} (R_{T-3} - N_{T-3}) + C_{T-2}^{(6)} p X_{T-3} + C_{T-2}^{(7)} (R_{T-3} - N_{T-3})^2 \right. \\ &\quad \left. + C_{T-2}^{(8)} p^2 X_{T-3}^2 + C_{T-2}^{(9)} p X_{T-3} (R_{T-3} - N_{T-3})) \right] \end{aligned}$$

Taking its derivative and setting it to 0, yields the following after many messy calculations:

$$N_{T-3}^* = C_{T-3}^{(1)} + C_{T-3}^{(2)} R_{T-3} + C_{T-3}^{(3)} X_{T-3}$$

where

$$C_{T-3}^{(1)} = \frac{qC_{T-2}^{(1)} - 1}{2(-b + qC_{T-2}^{(1)})}$$

$$C_{T-3}^{(2)} = \frac{qC_{T-2}^{(2)}}{-b + qC_{T-2}^{(1)}}$$

$$C_{T-3}^{(3)} = \frac{qpC_{T-2}^{(3)} + \theta}{2(-b + qC_{T-2}^{(1)})}$$



Substituting  $N_{t-3}^*$  back in  $V_{t-3}^*$ , we obtain the following:

$$V_{t-3}^*(P_{t-3}, R_{t-3}, X_{t-3}) = q P_{t-3} \left[ C_{t-3}^{(4)} + C_{t-3}^{(5)} R_{t-3} + C_{t-3}^{(6)} X_{t-3} + C_{t-3}^{(7)} R_{t-3}^2 + C_{t-3}^{(8)} X_{t-3}^2 + C_{t-3}^{(9)} R_{t-3} X_{t-3} \right]$$

where

$$C_{t-3}^{(4)} = C_{t-3}^{(1)} (1 - b C_{t-3}^{(1)}) + q (C_{t-2}^{(4)} + \sigma_{\eta}^2 C_{t-2}^{(8)}) - q C_{t-3}^{(1)} (C_{t-2}^{(5)} - C_{t-3}^{(1)} C_{t-2}^{(7)})$$

$$C_{t-3}^{(5)} = C_{t-3}^{(2)} + q (1 - C_{t-3}^{(1)}) C_{t-2}^{(5)}$$

$$C_{t-3}^{(6)} = q p C_{t-2}^{(6)} - C_{t-3}^{(3)} (q C_{t-2}^{(5)} - 1)$$

$$C_{t-3}^{(7)} = -b C_{t-3}^{(2)}$$

$$C_{t-3}^{(8)} = C_{t-3}^{(3)} (-b C_{t-3}^{(2)} - \theta) + q p C_{t-2}^{(8)} - q C_{t-3}^{(3)} (p C_{t-2}^{(9)} - C_{t-3}^{(2)} C_{t-2}^{(7)})$$

$$C_{t-3}^{(9)} = -\theta C_{t-3}^{(2)} + q p C_{t-2}^{(9)} (1 - C_{t-3}^{(2)})$$

Continuing in this fashion, we obtain the following

$$\bullet N_t^* = C_t^{(1)} + C_t^{(2)} R_t + C_t^{(3)} X_t$$

where

$$C_t^{(1)} = \frac{q C_{t+1}^{(5)} - 1}{2(-b + q C_{t+1}^{(9)})}, \quad C_t^{(2)} = \frac{q C_{t+1}^{(7)}}{-b + q C_{t+1}^{(9)}}, \quad C_t^{(3)} = \frac{q p C_{t+1}^{(9)} + \theta}{2(-b + q C_{t+1}^{(9)})}$$

$$\bullet V_t^*(P_t, R_t, X_t) = q P_t (C_t^{(4)} + C_t^{(5)} R_t + C_t^{(6)} X_t + C_t^{(7)} R_t^2 + C_t^{(8)} X_t^2 + C_t^{(9)} R_t X_t)$$

where

$$C_t^{(4)} = C_t^{(1)} (1 - b C_t^{(1)}) + q (C_{t+1}^{(4)} + \sigma_{\eta}^2 C_{t+1}^{(8)}) - q C_t^{(1)} (C_{t+1}^{(5)} - C_t^{(1)} C_{t+1}^{(7)})$$

$$C_t^{(5)} = C_t^{(2)} + q (1 - C_t^{(1)}) C_{t+1}^{(5)}$$

$$C_t^{(6)} = q p C_{t+1}^{(6)} - C_t^{(3)} (q C_{t+1}^{(5)} - 1)$$

$$C_t^{(7)} = -b C_t^{(2)}$$

$$C_t^{(8)} = C_t^{(3)} (-b C_t^{(2)} - \theta) + q p C_{t+1}^{(8)} - q C_t^{(3)} (p C_{t+1}^{(9)} - C_t^{(2)} C_{t+1}^{(7)})$$

$$C_t^{(9)} = -\theta C_t^{(2)} + q p C_{t+1}^{(9)} (1 - C_t^{(2)})$$

$$\text{where } q = e^{\frac{1}{2} + \frac{\sigma_{\epsilon}^2}{2}}$$