That's No Moon: New Analysis Shows No Evidence for Lunar Companion Orbiting Kepler-1625b

LAURA KREIDBERG, 1,2 RODRIGO LUGER, AND MEGAN BEDELL

¹Harvard Society of Fellows, 78 Mount Auburn Street, Cambridge, MA 02138 ²Harvard-Smithsonian Center for Astrophysics, 60 Garden Street, Cambridge, MA 02138

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ABSTRACT

The planet Kepler-1625b was recently suggested to have an EXOMOON. We present here a reanalysis of the HST/WFC3 observations of the Kepler-1625 system. We find that the data are well fit with a single transit model. We also do a moon model, and it is not favored. Upper limit on moon. Instrument systematics? Focus searches for exomoons on alternative targets.

Keywords: planets and satellites: individual (Kepler-1625b)

1. INTRODUCTION

Moons are abundant in the Solar System, and provide clues to the formation history, evolution, and even habitability of the planets they orbit. The great scientific potential of moons has prompted extensive search for lunar companions in exoplanetary systems (exomoons), and creative development of new search techniques (e.g. Kipping 2009a,b; Kipping et al. 2013; Simon et al. 2010; Peters & Turner 2013; Heller et al. 2014; Noyola et al. 2014; Hippke 2015; Agol et al. 2015; Sengupta & Marley 2016; Vanderburg et al. 2018).

Recently, a potential exomoon candidate was identified in the Kepler-1625 system (Teachey et al. 2018). The host planet, Kepler-1625b, is fairly long-period large world, with a radius consistent with that of Jupiter and an orbital period of 287 days. long period makes it ideal for stability of moon!

It was discovered in the Analysis of the four-year Kepler mission (Teachey & Kipping 2018).

Of the FIXME transits observed by *Kepler* FIXME what did they show.

Recently, analysis by FIXME of *Kepler* observations of FIXME suggested a moon. Follow-up happened.

(?) found moon was model dependent

2. OBSERVATIONS AND DATA REDUCTION

The Kepler-1625 system was observed with 26 continuous *HST* orbits on 28 - 29 October, 2017 (Program GO 15149: PI: A. Teachey). The observations used the Wide Field Camera 3 (WFC3) G141 grism in staring mode, which fixed the spectrum in a constant position on the detector. At the beginning of the visit, there was a sin-

gle exposure taken with the F130N filter, which is used to determine the position of the spectral trace. The following exposures used the G141 grism with the SPARS25, NSAMP=15 readout pattern (exposure time of 290.8 seconds; 9 exposures per orbit). For additional description of the observation design, see Teachey & Kipping (2018).

We reduced the HST data using custom software developed in Kreidberg et al. (2014). We used the flt data product provided by STScI, which is corrected for dark current, bias, and nonlinearity. The flt files are also flatfielded, and cosmic rays are rejected based on a fit to the up-the-ramp samples. To begin the data reduction, we fit the centroid of the direct image with a two-dimensional Gaussian. The centroid position determines the position of the spectral trace, which we calculated using the coefficients provided in the configuration file from STScI: G141.F130N.V4.32.conf¹. We then created an extraction box centered on the spectral trace. We varied the height and width of the box in 1-pixel increments to find the window that minimized the root-mean-square (rms) deviation from the best fit to the transit light curve. The best was FIXME.

Using this window, we reduced the grism exposures with the optimal extraction routine of (Horne 1986), which minimizes background noise in the extracted spectrum by weighting pixels that are dominated by the target spectrum more heavily than pixels dominated by the background. The inputs for the optimal extraction are the background-subtracted data array, the error ar-

 $^{^1}$ available at http://www.stsci.edu/hst/wfc3/analysis/grism-obs/calibrations/wfc3_g141.html

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ray (including photon noise read noise, and uncertainty due to background subtraction), an initial guess for the spectrum and its uncertainty, and a mask array for bad pixels. For the error array, we used a quadrature sum of the photon noise (the square root of the pixel counts), the read noise (12 electrons for flt files, according to the WFC3 data handbook), and the error due to background subtraction (described in 2.1). We initially masked pixels with the data quality flag 4 or 512 (dead pixels or blobs). For the initial guess of the spectrum and its uncertainty, we did a simple box extraction (sum over all rows in the extraction window), and assumed the variance was equal to the box-extracted spectrum (expected for photon noise limit). See 2.1 for further detail on background subtraction.

In brief, optimal extraction is an iterative procedure with the following steps. First, we create a smoothed image by median-filtering each row of the data with a 9-pixel-wide window. We then normalize the smoothed image by dividing each column by its sum, and multiply it by the best guess spectrum. We compare the smoothed image to the real data and mask outliers in the data that are greater than a threshold $\sigma_{\rm cut}$. We then recompute the best guess spectrum with the new mask and the optimal weights from Horne (1986). The process is iterated until no outliers greater than the threshold remain. This procedure masks any cosmic rays or bad pixels that were missed by the initial flt calibration. We tested a range of thresholds $(4 < \sigma_{\rm cut} < 15)$ and found that different $\sigma_{\rm cut}$ choices did not significantly change the final transit light curve. The data reported in this work use $\sigma_{\rm cut} = 15$.

2.1. Background Subtraction

The star Kepler-1625 is faint (H mag = 14.0) relative to most other exoplanet host stars observed with WFC3, which makes accurate background subtraction especially important for this target. Moreover, the host star is in a crowded field, so the pixels used to estimate the background must be chosen carefully to avoid contamination from other stars. We identified several uncontaminated regions by eye: 130 < X < 215 and 6 < Y < 24; 220 < X < 250 and 110 < X < 155; 6 < X < 47and 127 < Y < 141, where X and Y are pixel numbers in the spectral and spatial direction, respectively (numbering from zero). To estimate the background and its uncertainty for each exposure, we took the median and median absolute deviation (MAD) of the pixel counts in these three regions. The per pixel uncertainty due to background subtraction is 1.4826 times the MAD.

2.2. Pointing Drift Measurement

The position of the spectrum on the detector shifts slightly over time ($\sim 0.1 \text{ pixel/day}$) due to the spacecraft's pointing drift. This drift can change the flux measured for the target star: if the spectrum moves onto less sensitive pixels, fewer photoelectrons are recorded. To enable a correction for this effect, we measured the position of the spectrum over time. To measure shifts in the spatial direction, we first summed each flt image over all columns (which we dub the "column sum"). We used the first exposure in the visit as a template, and for each subsequent exposure, we used least-squares minimization to calculate the shift in pixels that minimized the difference between its column sum and the template. The shifts are a fraction of a pixel, so we used the NumPy interproutine to do linear interpolation on a sub-pixel scale. The WFC3 point spread function is undersampled, so we convolved each column sum with a 4-pixel-wide Gaussian before the interpolation (following Deming et al. 2013).

To measure the spectral shifts, we repeated this procedure with two differences: (1) we used the optimally extracted spectrum rather than the column sum; and (2) in addition to calculating the best fit shift, we also calculated a best fit normalization factor (a scalar multiple for the whole spectrum), to ensure that our results are not biased by the varying brightness of the host star during the planet's transit.

Figure 1 shows the best fit shifts. Over the entire 26-orbit visit, the maximum shift is less than 0.2 pixel in the spatial direction and 0.3 pixel in the spectral direction. The largest shift occurs after orbit 14, when the telescope reacquired the guide stars.

3. ANALYSIS

We fit the light curves with the planetplanet package Host star parameters were estimated using the Gaia DR2 parallax (Gaia Collaboration et al. 2016, 2018) along with UBV photometry from Everett et al. (2012) and JHK photometry from 2MASS (Skrutskie et al. 2006). We employed the isochrone python package (?) with the Dartmouth isochrone grid (Dotter et al. 2008) to obtain posterior constraints on the stellar parameters. The resulting parameters indicate that Kepler-1625 has stellar mass $1.37^{+0.13}_{-0.16}~{\rm M}_{\odot}$, radius $1.81^{+0.18}_{-0.16}~{\rm R}_{\odot}$, and age $2.8^{+1.6}_{-1.2}~{\rm Gyr}$.

4. COMPARISON WITH TEACHEY & KIPPING (2018)

5. DISCUSSION

We did not find evidence for the exomoon. Why are we different from Teachey and Kipping?

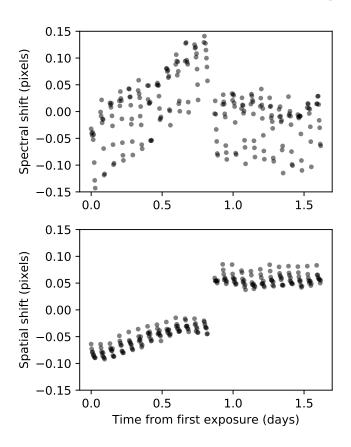


Figure 1. Shift (in pixels) relative to the mean position of the spectrum in the spectral direction (top) and spatial direction (bottom). The largest shift occurs after orbit 14 due to a guide star reacquisition.

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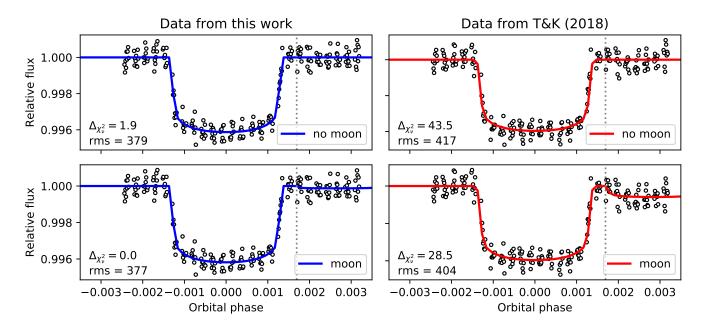


Figure 2. Best fit models compared to transit light curves from this work (left) and from TK18 (right). The top panel shows the best fit no-moon model (blue), and the bottom shows the best fit moon model (red). The lower left of each panel indicates the fit rms (in ppm) and the Δ_{χ_2} relative to the overall best fit (data reduction from this work, moon model). The dotted gray line marks the possible moon ingress identified by TK18.

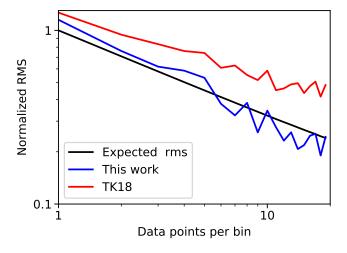


Figure 3. Light curve rms versus bin size for the best fit no-moon model. The fit to data from this work (blue line) agrees well with the expected photon-limited, \sqrt{N} decrease in rms with bin size (black line). The TK18 rms (red line) ranges from $1.3-2\times$ the photon limit for bin sizes of 1 to 20 data points. The increase in relative rms for larger bin sizes indicates that time-correlated noise is present in the TK18 data.

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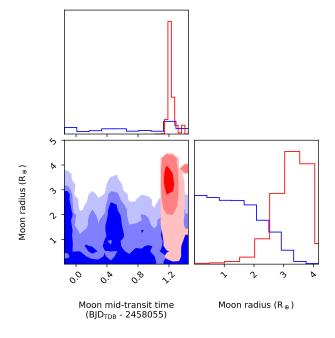


Figure 4. Posterior distributions

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