

## 1 Vectors in $\mathbb{R}^n$

$\mathbb{R}^n$  is the collection of all lists (**ordered**  $n$ -tuples) of all numbers.

**Note:** the zero vector  $\vec{0} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$

### Algebraic Properties of Vectors

1.  $\vec{u} + \vec{v} = \vec{v} + \vec{u}$
2.  $(\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w})$
3.  $\vec{u} + \vec{0} = \vec{0} + \vec{u} = \vec{u}$
4.  $\vec{u} + (-\vec{u}) = \vec{0}$
5.  $c(\vec{u} + \vec{v}) = c\vec{u} + c\vec{v}$
6.  $(c + d)\vec{v} = c\vec{v} + d\vec{v}$
7.  $c(d\vec{v}) = (cd)\vec{v}$
8.  $1\vec{u} = \vec{u}$

## 2 Linear Combination

**Definition 1** given vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$  in  $\mathbb{R}^n$  and scalars  $c_i \in \mathbb{R}$ , the vector  $\vec{y}$  defined by

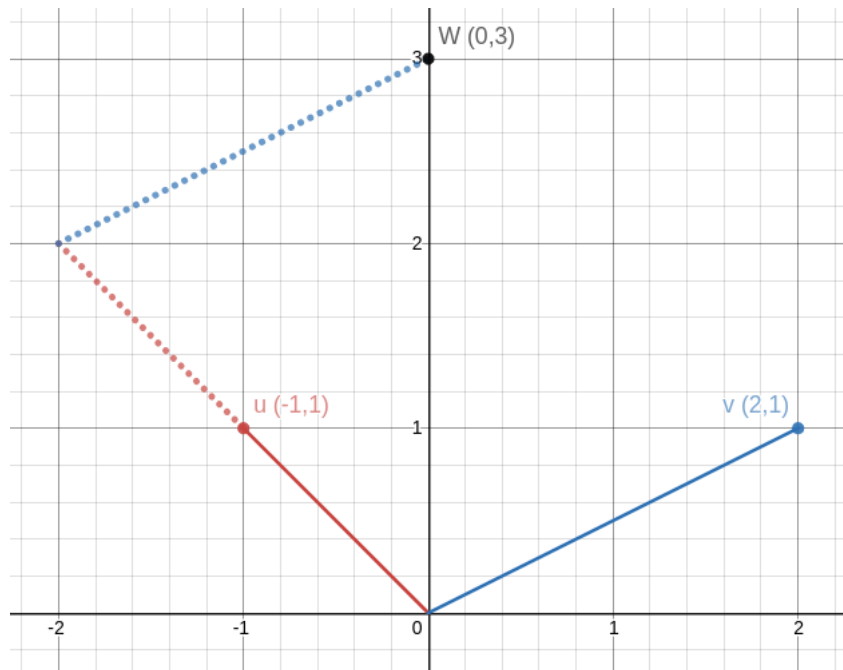
$$\vec{y} = c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_p\vec{v}_p$$

is called a **linear combination** of  $\vec{v}_1, \dots, \vec{v}_p$  with weights  $c_1, \dots, c_p$ .

**Example**

Let  $\vec{u} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ ,  $\vec{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

The point  $\vec{w} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$  can be represented as a linear combination of these two vectors.

**Example (3D)**

Let  $\vec{a}_1 = \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix}$ ,  $\vec{a}_2 = \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix}$ ,  $\vec{b} = \begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix}$

Can we write  $\vec{b}$  as a linear combination of  $\vec{a}_1$  and  $\vec{a}_2$ , so that

$$x_1 \vec{a}_1 + x_2 \vec{a}_2 = \vec{b}$$

$$x_1 \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix}$$

$$\begin{cases} x_1 + 2x_2 = 7 \\ -2x_1 + 5x_2 = 4 \\ -5x_1 + 6x_2 = -3 \end{cases}$$

We can convert this system to an augmented matrix and solve for a solution. I'll omit a few steps, see previous notes for solving linear systems.

$$\begin{bmatrix} 1 & 2 & 7 \\ -2 & 5 & 4 \\ -5 & 6 & -3 \end{bmatrix} \xrightarrow{\substack{+2 \cdot eq.1 \\ +5 \cdot eq.1}} \begin{bmatrix} 1 & 2 & 7 \\ 0 & 9 & 18 \\ 0 & 16 & 32 \end{bmatrix} \xrightarrow{\cdot \frac{1}{9}} \begin{bmatrix} 1 & 2 & 7 \\ 0 & 1 & 2 \\ 0 & 16 & 32 \end{bmatrix} \xrightarrow{\substack{-2 \cdot eq.2 \\ -16 \cdot eq.2}} \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

It may seem like there are infinite solutions ( $0 = 0$  implies a free variable), but remember there are only 2 unknowns. This system tells us that we have a single solution,  $x_1 = 3$ ,  $x_2 = 2$ .

$$\text{So, } 3 \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix} + 2 \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix}$$

**Definition 2** a vector equation  $x_1 \vec{a}_1 + \cdots + x_n \vec{a}_n = \vec{b}$  has the same solution set as the linear system whose augmented matrix is

$$[\vec{a}_1 \quad \vec{a}_2 \quad \cdots \quad \vec{a}_n \quad \vec{b}]$$

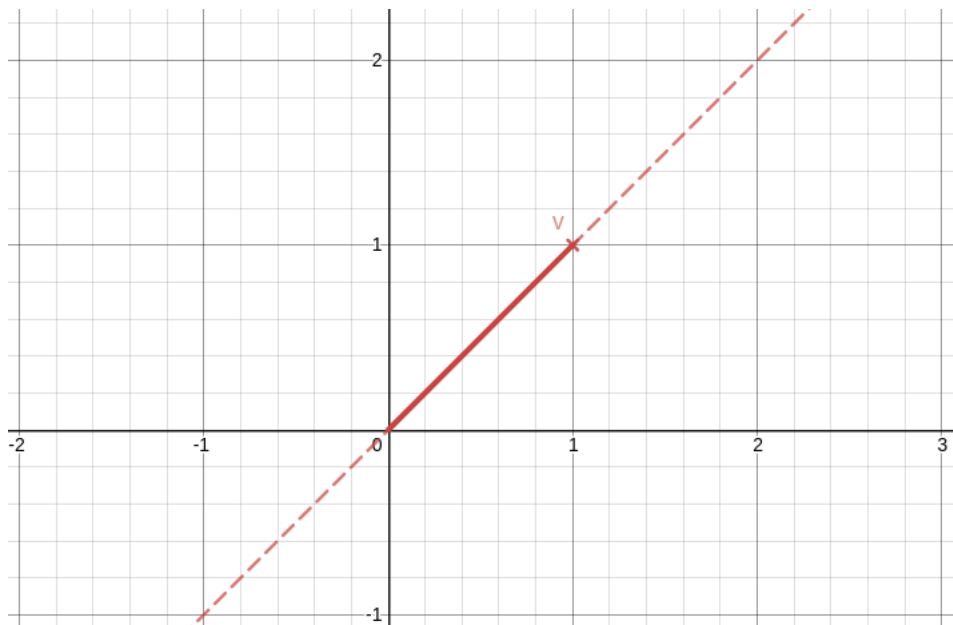
**Definition 3** if  $\vec{v}_1, \cdots, \vec{v}_p$  are in  $\mathbb{R}^n$ , then the set of all linear combinations of the vectors is denoted by  $\text{Span}\{\vec{v}_1, \cdots, \vec{v}_p\}$  and is called the subset of  $\mathbb{R}^n$  spanned by  $\vec{v}_1, \cdots, \vec{v}_p$ .

$\text{Span}\{\vec{v}_1, \cdots, \vec{v}_p\}$  is the collection of all vectors that can be written in the form

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \cdots + c_n \vec{v}_n$$

## 2.1 Geometric Description of $\text{Span}\{\vec{v}\}$ and $\text{Span}\{\vec{u}, \vec{v}\}$

For  $\text{Span}\{\vec{v}\}$ , the span is all vectors formed by scaling  $\vec{v}$  by any scalar. That's all we can do. This is one dimension.



For  $\text{Span}\{\vec{u}, \vec{v}\}$ , the span contains every point in  $\mathbb{R}^2$  space. Here's two vectors and an example of them combining to reach a third arbitrary point.

