



# LAB 3

i8086

16 bits para registros  $\Rightarrow$  64K

can access to 1MB  $\Rightarrow 2^{20}$  memory size dividiendo en trozos de 64K

El programa debe saber 2 cosas

data y code segment address

**BaseRegister x 10h + offset**

tengo DS, XXXX

lo multiplico por 10h

XXXX0

se sumo el offser YYYYYY

me da como resultado

ZZZZZ

## Segment registers are:

- CS: code segment register
- DS: data segment register
- SS: stack segment register
- ES: extra segment (data) register

Addressing modes		µP 8086/88	Examples
Immediate		Immediate	MOV AX,15h
Direct	To register	Register	MOV AX,BX
	To memory	(with segmentation)	
	To page	Direct	MOV CX,ETIQUETA
Relative	To program counter	(for jumps only)	
	To register	Relative to base register	MOV [BX]+ARTÍCULO,AL
	To index register	Relative to index register	MOV DL,VECTOR[SI]
		Relative to index and base registers	MOV AH,[BX][SI]+ARRAY
	To stack	(relative to stack)	
Indirect		(it doesn't exist)	
Implicit		Some instructions only	

- Relative addressing modes: ejemplos

- ADD DX, [BX]
- MOV DL, [SI]
- SUB AX, [BP][SI]
- XOR red[BX][DI], DX
- AND AL, [BP+8]

- shift instructions

## ShiftInstruction target, times

times si es 1 lo puedo poner directamente pero si son mas, lo tengo que poner en CL

- SAL



- SAR



- SHL



- SHR



- ROL

- ROR



- RCL



- RCRA



## Operaciones

- AND target, source  
AND ax,bx  
AND ax,8000h  
AND ax,1
- OR
- XOR
- NOT

## DOSSEG

**.MODEL** SMALL

**.STACK** 100h

**.DATA**

numeros **DB** 1,2,3,4,5,6 ; String numbers

**.CODE**

Inicio:

**MOV** AX, @DATA

**MOV** DS, AX

**LEA** BX, numeros ; DS:BX string address

**MOV** CX, 6 ; Number of times

Bucle:

**MOV** DL, [BX] ; Memory position is  
; stored on DL

**ADD** DL, 7 ; We add 7 to it

**MOV** [BX], DL ; Store new value on  
; current memory  
; position

**INC** BX ; BX is incremented by 1

**LOOP** Bucle

**MOV** AH, 4Ch ; program end  
service

**INT** 21h ; requested

**DOSSEG**

**.MODEL** SMALL

**.STACK** 100h

**.DATA**

numeros **DB** 1,2,3,4,5,6; String numbers

**.CODE**

Inicio:

**MOV** AX, @DATA

**MOV** DS, AX

**MOV** SI, 0 ; SI is initialized to 0

**MOV** CX, 6 ; Number of times

Bucle:

**ADD** numeros[SI], 7

**INC** SI

**LOOP** Bucle

**MOV** AH, 4Ch ; Program end service

**INT** 21h ; requested

**END** Inicio