6.01

Variational Methods

consider the following integral:

Allows us to construct the following integral:

TT [u]:=
$$\int_{2}^{1} EA(u_{1x})^{2} dx - \int_{3}^{1} eAdx - tA \cdot u(L)$$

The strain of work done work done by traction.

Where u belongs to S ($u \in S = \{u \mid u(o) = u_{o}\}$)

and $f_{1}t$ & constitutive relation $\sigma = Eu_{1x}$

are given.

TT[u]: Gibbs free energy (for purely mechanical problems)

- also called the potential energy in mechanical problems.

a point value of the

AT[u] is not a function.

A function g(x): R+R

a mappin

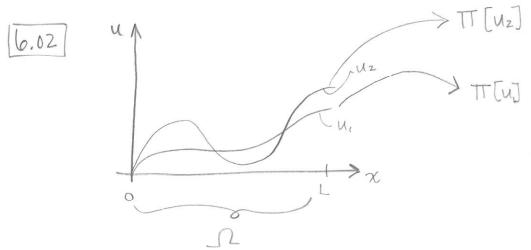
from R to

a point value of the cargnement and returns another point value.

How is TIEU] different?

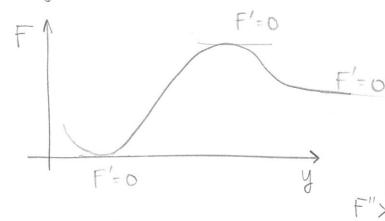
TITUI is a mapping of a field, u(x) to the real numbers.

 $tT[u]: S \longmapsto \mathbb{R}$



TI[u] is a functional. (integrals & derivatives are functionals.) & Gibbs free energy functional &

Extrema of free energies characterize states of equilibria of Systems.



Extrema occur where

These are points of equilibrium (either Stable, unstable cr neutrally stable) F"(0 F"=0

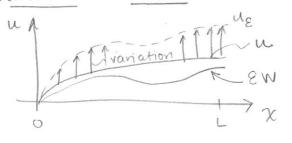
Can we find extrema of T[u]?

What is an appropriate notion of a derivative of TI wit u?

- Differentiation wit a field, u.

6.03

A variational method



Consider a variation W such that the "varied" or perturbed field is

Uz = u+ EW where EER W is also a field

WEV= {W/W(0)=0} NOTE: W (0) = 0. W vanishes at the Dirichlet boundary. So that us Satisfies the Dirichlet B.C.

Consider the perturbed functional IT [UE]

dTT[UE]: the amount of variation in TT for variation in U - having chosen the "form" of the variation w.

d TT[ue] : variation in TT wrt u, at u.

8=0 — Functional derivative.

Extremization of TCuJ: 6.04)

$$\Rightarrow \frac{d}{d\epsilon} \left[\left(\frac{1}{2} EA \left(u + \epsilon w \right)_{,\chi} \right)^2 d\chi - \int_{\Omega} f(u + \epsilon w) A d\chi - tA \cdot (u + \epsilon w) \right] = 0.$$

$$\Rightarrow \left[\int_{2}^{1} \frac{1}{z} \left[\frac{1}{z$$

$$=) \int_{\Omega} W_{,x} \cdot \xi A \cdot U_{,x} dx - \int_{\Omega} w f A dx - w(L) \cdot tA = 0$$

When an extremized principle is available Remarks: (extremum of the free energy functional) the weak form can be obtained using variational calculus.

A Variational principle exists.

A This derivation is not appropriate for the physics of heat conduction of mass diffusion. The mathematics does work... but a physical principle doesn't exist.

Variational Principles Exist for:

- Elasticity @ Steady State - Schrödinger equation @ Steady State.

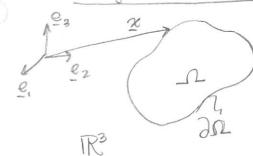
7.01 Linear, elliptic PDE's in 3-D, with scalar unknown.

- Steady State heat conduction

- Steady State mass diffusion.

Strong Form of the Problem

I unit length



 $\{e_i, e_j = S_i\}$ the knowledger pelta.

I: open in R3 & DI: the boundary of I.

Find u, given f(x), ug, jn, and the constitutive relation ji=-Kij (i, j = 1, 2, 3)such that - ji; = f in sz

B.C.s: N= Ug on 2Du - Dirichlet b.c.

-j·n=jn on 2D + Neuman b.c.

2Du () 2D; = Ø empty set.

