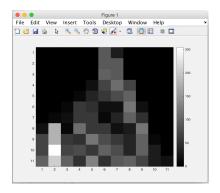
CS 532: Homework Assignment 7

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1 Part b

For spin images, I'm computing $\beta = dot(n, p_j - p)$ and $\alpha = \sqrt{||p_j - p||^2 - \beta^2}$, where p is the point chosen, p_j are the point cloud points, n is the normal of the point chosen. Then we need to find to which bin allocate the current point, for that I divide α and β by the bin size (first normalizing β so that I can consider above and below the point chosen). Below I show a one spin image generated for each $apple_1$ and $banana_1$.



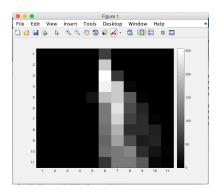


Figure 1: Apple1 Spin Image

Figure 2: Banana1 Spin Image

2 Part c

For the KNN classifier, I'm getting an average of 56.99% accuracy on 15 runs with different training and test set. I didn't understand the last part that you say to keep track of correctness of spin image classification. Here is an example of the confusion matrix that I generated when accuracy is 57.77%:

$$confmat = \begin{bmatrix} 9 & 19 & 32 \\ 3 & 54 & 3 \\ 3 & 14 & 43 \end{bmatrix}$$

Where "C(i,j) is a count of observations known to be in group i but predicted to be in group j" (from Mathworks).

So we can see that Apple spin images were misclassified most of the time, frequently classified as lemons. And this does not happen in the other way around. Lemons have a reasonable classification accuracy. On the other hand, the algorithm performs really well with Bananas.

3 Matlab code

```
function normals = estimateNormals(obj, sig, k)
    den = 2 * sig^2;
    pts = obj.vertices;
    [idx, dist] = knnsearch(pts, pts, 'k', k);
    normals = [];
    for i = 1:length(pts)
        \% compute centroid
        centr = mean(pts(idx(i,:),:));
        % init weights
        w = \exp(-\operatorname{dist.^2}./\operatorname{den});
        cc = zeros(3,3);
        for j = 1:k
             xj = pts(idx(i,j),:);
             cc = cc + (xj - centr)' * (xj - centr) .* w(i,j);
        C = cc./sum(w(i,:));
        [V, \tilde{\ }] = eig(C);
        normals(i,:) = V(:,1)';
    end
    flip = sign(dot(normals',-pts'))';
    normals = [flip flip flip].*normals;
end
function spin = computeSpinImage(obj, ptidx, nbins, binsize)
    if ptidx = 0
        r1 = 1; r2 = length(obj.vertices);
        ptidx = round((r2-r1)*rand+r1);
%
           disp(['point\ idx\ is:\ 'num2str(ptidx)]);
    end
    spin = zeros(nbins, nbins);
    norml = obj.normals(ptidx,:);
    for pt = 1:length(obj.vertices)
        xp = obj.vertices(pt,:) - obj.vertices(ptidx,:);
```

```
\mathbf{beta} = \mathbf{sum}(\operatorname{norml.*xp}, 2);
         alpha = \mathbf{sqrt}(\mathbf{sum}(xp.*xp,2) - \mathbf{beta}.^2);
         % back to zero
         beta = beta - nbins*binsize/2;
         b = floor(-beta/binsize) + 1;
         a = floor(alpha/binsize) + 1;
         \mathbf{if} \ \mathbf{a} > 0 && \mathbf{b} > 0 && \mathbf{a} <= \mathbf{nbins} && \mathbf{b} <= \mathbf{nbins}
              spin(a,b) = spin(a,b) + 1;
         end
    end
    spin = spin(:);
end
clear all;
% clc;
k = 50;
sig = 20;
knn = 30;
ap1 = readply('hw7/apple_1.ply');
ap2 = readply('hw7/apple_2.ply');
ap3 = readply('hw7/apple_3.ply');
ap4 = readply('hw7/apple_4.ply');
ban1 = readply('hw7/banana_1.ply');
ban2 = readply('hw7/banana_2.ply');
ban3 = readply('hw7/banana_3.ply');
ban4 = readply('hw7/banana_4.ply');
lem1 = readply('hw7/lemon_1.ply');
lem2 = readply('hw7/lemon_2.ply');
lem3 = readply('hw7/lemon_3.ply');
lem4 = readply('hw7/lemon_4.ply');
ap1.normals = estimateNormals(ap1, sig, k);
ap2.normals = estimateNormals(ap2, sig, k);
ap3.normals = estimateNormals(ap3, sig, k);
ap4.normals = estimateNormals(ap4, sig, k);
ban1.normals = estimateNormals(ban1, sig, k);
```

```
ban2.normals = estimateNormals(ban2, sig, k);
ban3.normals = estimateNormals(ban3, sig, k);
ban4.normals = estimateNormals(ban4, sig, k);
lem1.normals = estimateNormals(lem1, sig, k);
lem2.normals = estimateNormals(lem2, sig, k);
lem3.normals = estimateNormals(lem3, sig, k);
lem4.normals = estimateNormals(lem4, sig, k);
train = [];
test = [];
cnt = 1;
for i = 1:30
   train(cnt, :) = [1 computeSpinImage(ap1, 0, 11, 3)];
   train(cnt+1, :) = [1 computeSpinImage(ap2, 0, 11, 3)];
   train(cnt+2, :) = [2 computeSpinImage(ban1, 0, 11, 3)];
   train(cnt+3, :) = [2 computeSpinImage(ban2, 0, 11, 3)];
   train(cnt+4, :) = [3 computeSpinImage(lem1, 0, 11, 3)];
   train(cnt+5, :) = [3 computeSpinImage(lem2, 0, 11, 3)];
   test(cnt, :) = [1 computeSpinImage(ap3, 0, 11, 3)];
   test(cnt+1, :) = [1 computeSpinImage(ap4, 0, 11, 3)];
   test(cnt+2, :) = [2 computeSpinImage(ban3, 0, 11, 3)];
   test(cnt+3, :) = [2 computeSpinImage(ban4, 0, 11, 3)];
   test(cnt+4, :) = [3 computeSpinImage(lem3, 0, 11, 3)];
   test(cnt+5, :) = [3 computeSpinImage(lem4, 0, 11, 3)];
   cnt = cnt + 6;
end
train_lbl = train(:,1);
train_data = train(:, 2:end);
test_lbl = test(:,1);
test_data = test(:, 2:end);
correct = 0;
for i = 1: size(test, 1)
    sample = test_data(i,:);
    idx = knnsearch(train_data, sample, 'K', knn);
    votes = zeros(3,1);
    for j = 1:knn
```

```
votes(train_lbl(idx(j))) = votes(train_lbl(idx(j))) + 1;
     \mathbf{end}
        [\tilde{\ }, lbl] = max(votes);
%
%
        if lbl == test_lbl(i)
%
             correct = correct + 1;
%
        end
     [vv, labels] = sort(votes, 'descend');
     if all (vv=vv(1)) % all the same
          if labels(1) = test_lbl(i)
                correct = correct + 0.33;
          end
     elseif vv(1) = = vv(2)
          if labels(1) = test_lbl(i)
                correct = correct + 0.5;
          end
     _{
m else}
          if labels(1) = test_lbl(i)
                correct = correct + 1;
          end
     end
     knnout(i) = labels(1);
end
\mathbf{disp}\left(\left[\begin{array}{c} \mathsf{'accuracy:\_'} & \mathbf{num2str}(\left.\mathsf{correct/size}\left(\left.\mathsf{test\_data}\right.,1\right)\right)\right]\right)
confmat = confusionmat(test_lbl,knnout')
```