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## Cuckoo Search Algorithm

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### 9.1 Introduction

The original cuckoo search (CS) was first developed by Xin-She Yang and Suash Deb in 2009 [1], which was inspired by the brooding parasitism of some cuckoo species. CS has been used for engineering optimization [2], and has been extended to multiobjective optimization [3], and structural optimization problems [4]. In fact, the literature is rapidly expanding with a diverse range of applications [5]. One of the main advantages of cuckoo search is that it uses Lévy flights [6] that consist of a fraction of long-distance, non-local moves in addition to many local moves, which makes the algorithm much more efficient in exploring the sparse search space [5, 6]. Other variants have been developed, including the quantum-inspired CS [7], modified cuckoo search [8], random-key discrete cuckoo search [9] and others [10]. Recently, CS has been extended to a new variant of multi-species cuckoo search [11]. For a more comprehensive

review of the cuckoo search, its variants and applications, please refer to more advanced literature [5, 10].

The rest of this chapter will first introduce the main steps of the original cuckoo search, and explain in detail how to carry out Lévy flights and implementations, followed by the introduction of the demo codes in both Matlab and C++.

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## 9.2 Original cuckoo search

Many cuckoo species engage in aggressive reproduction strategies by laying eggs in the nests of host species so as to let host species to raise their young chicks. From the evolutionary point of view, this maximizes the reproductivity probability of the cuckoo species. However, host species can also fight back by abandoning such eggs or nests with contaminated alien eggs. Thus, there is an ongoing arms race between cuckoo species and host species. Cuckoo search has been developed, based on the inspiration of such cuckoo-host characteristics.

### 9.2.1 Description of the cuckoo search

In essence, the main characteristics for the cuckoo search with a population of  $n$  cuckoos can be summarized as

- Each cuckoo lays one egg and dumps it into a randomly chosen host nest. An egg can be considered as a solution vector  $\mathbf{x}$  to an optimization problem.
- The best eggs in nests will be passed on to the next generation. This means the best solutions are retained.
- The number of available nests is fixed, and each egg laid by a cuckoo may be discovered and abandoned with a probability  $p_a$ . This is equivalent to that a fraction  $p_a$  of the total population will be modified at each iteration  $t$ .

In the real-world, each nest of a host bird typically has 3 or 4 or more eggs, and each cuckoo can attack quite a few nests by laying its eggs in such nests. For simplicity, we assume that each cuckoo can only lay one egg and affect one host nest, which means that the number of eggs is equal to the number of nests and cuckoos. Thus, we can encode the location of an egg as a solution vector to an optimization problem. This way, there is no need to distinguish eggs, cuckoos and nests. Thus, we have ‘egg=cuckoo=nest’.

In the original CS, there are two main equations for two different actions. One equation is

$$\mathbf{x}_i^{t+1} = \mathbf{x}_i^t + \alpha s \otimes H(p_a - \epsilon) \otimes (\mathbf{x}_j^t - \mathbf{x}_k^t), \quad (9.1)$$

where  $\mathbf{x}_j^t$  and  $\mathbf{x}_k^t$  are two different solution vectors, randomly selected from the population for  $i = 1, 2, \dots, n$ . The switching condition with a probability  $p_a$  is realized by a Heaviside function (or a step function) by comparing  $p_a$  with a random number  $\epsilon$  drawn from a uniform distribution in  $[0, 1]$ . In addition,  $s$  is a step size by random permutation of solution differences, and this is scaled by a scaling factor  $\alpha$ . Furthermore, the product of two vectors is an entry-wise multiplication using  $\otimes$ .

The other equation is mainly for non-local random walks by Lévy flights

$$\mathbf{x}_i^{t+1} = \mathbf{x}_i^t + \alpha L(s, \beta), \quad (9.2)$$

where the step sizes are drawn from the Lévy distribution

$$L(s, \beta) \sim \frac{\beta \Gamma(\beta) \sin(\pi\beta/2)}{\pi} \frac{1}{s^{1+\beta}}, \quad (9.3)$$

which is an approximation to a Lévy distribution with an exponent  $0 \leq \beta \leq 2$ . The gamma function is defined by

$$\Gamma(q) = \int_0^\infty z^{q-1} e^{-z} dz. \quad (9.4)$$

The notation ‘ $\sim$ ’ highlights the fact that this is a pseudo-random number to be drawn from the probability distribution on the right-hand side of the above equation. Strictly speaking, the Lévy step sizes should be given by the inverse integral form of the following Fourier transform [6]

$$L(s, \beta) = \frac{1}{\pi} \int_0^\infty \cos(ks) \exp[-w|k|^\beta] dk, \quad (9.5)$$

where  $w$  is a scaling parameter.

However, the realization of this integral is difficult, so we will use an efficient but simplified algorithm, called Mantegna’s algorithm, in the implementation below.

### 9.2.2 Pseudo-code of CS

Based on the above descriptions, the main steps of the CS consist of initialization, the iteration loop, modifications of solutions by two different ways. The pseudo-code is shown in Algorithm 8.

### 9.2.3 Parameters in the cuckoo search

Comparing with other swarm optimization algorithms, CS has a relatively low number of parameters, which makes it easier to tune the algorithm. The three parameters are population size  $n$ , switching probability  $p_a$  and the Lévy exponent  $\beta$ . In our implementation here, we have used  $n = 25$ ,  $p_a = 0.25$  and  $\beta = 1.5$ .

**Algorithm 8** Pseudo-code of the cuckoo search algorithm.

---

```

1: Define the objective function  $f(\mathbf{x})$ 
2: Initialize all the parameters
3: Generate an initial population of  $n$  nests  $\mathbf{x}_i$  ( $i = 1, 2, \dots, n$ )
4: for t=1:MaxGeneration do
5:   Get a cuckoo/solution randomly
6:   Generate a solution by Lévy flights [Eq. (9.3)]
7:   Evaluate the new solution  $\mathbf{x}_i$  and its fitness  $f_i$ 
8:   Choose a nest (say,  $j$ ) among  $n$  nests randomly
9:   if  $f_i < f_j$  then
10:    Replace  $\mathbf{x}_j$  by  $\mathbf{x}_i$ 
11:   end if
12:   A fraction ( $p_a$ ) of the worse nests are abandoned
13:   New nests/solutions are generated by Eq. (9.1)
14:   Update the best solution if a better solution is found
15: end for
16: Output results

```

---

### 9.3 Source code of the cuckoo search in Matlab

The implementation of the cuckoo search algorithm is straightforward using Matlab, though care should be taken when generating Lévy flights in terms of drawing random numbers.

For simplicity and to be consistent with other tutorial chapters such as the tutorial on the firefly algorithm, we use the same function benchmark  $f(\mathbf{x})$

$$\text{minimize } f(\mathbf{x}) = (x_1 - 1)^2 + (x_2 - 1)^2 + \dots + (x_D - 1)^2, \quad x_i \in \mathbb{R}, \quad (9.6)$$

which has a global minimum of  $\mathbf{x}_* = (1, 1, \dots, 1)$ . We also apply the following lower bound ( $Lb$ ) and upper bound ( $Ub$ ):

$$Lb = [-5, -5, \dots, -5], \quad Ub = [+5, +5, \dots, +5]. \quad (9.7)$$

The Matlab code for the cuckoo search algorithm here consists of five parts: initialization, the main loop, Lévy flights, simple bounds, and the objective function. The whole codes should consist of all the lines of codes in a sequential order. For ease of description, we discuss each part in sequential order.

The first part is mainly initialization of parameter values such as the population size  $n = 25$  and the switching probability  $pa = 0.25$ . All the solutions of 25 nests or cuckoos in the initial population are evaluated so as to obtain the initial best solution. As mentioned earlier, we do not distinguish among an egg, a nest or a cuckoo and we have used here ‘an egg=a cuckoo=a nest=a solution vector’.

```

1 function [bestnest ,fmin]=cuckoo_search_demo
2 %% Initialization of parameters
3 n=25;           % Number of nests (or population size)
4 pa=0.25;        % Discovery rate of alien eggs/solutions
5 nd=15;          % Number of dimensions
6 Lb=-5*ones(1,nd); % Lower bounds
7 Ub=5*ones(1,nd); % Upper bounds
8 N_IterTotal=1000; % Increase it to get better results
9
10 % Random initial solutions for the population with n cuckoos
11 for i=1:n,
12     nest(i,:) = Lb + (Ub-Lb).*rand(size(Lb));
13 end
14 % Get the best solution among the initial population
15 fitness=10^10*ones(n,1);
16 [fmin, bestnest, nest, fitness]=get_best_nest(nest, nest, fitness);

```

### Listing 9.1

CS demo initialization.

The second part is the main part, consisting of a loop over the whole cuckoo population at each iteration. New cuckoos or solutions are generated by `get_cuckoos()` or `empty_nests()` subroutines, which will be explained below.

```

1 %% Starting iterations
2 for iter=1:N_IterTotal,
3     % Generate new solutions (but keep the current best)
4     new_nest=get_cuckoos(nest, bestnest, Lb, Ub);
5     [fnew, best, nest, fitness]=get_best_nest(nest, new_nest, fitness);
6     % Discovery and randomization
7     new_nest=empty_nests(nest, Lb, Ub, pa);
8
9     % Evaluate this set of solutions
10    [fnew, best, nest, fitness]=get_best_nest(nest, new_nest, fitness);
11    % Find the best objective so far
12    if fnew < fmin,
13        fmin=fnew;
14        bestnest=best;
15    end
16 end %% End of iterations
17 %% Display all the nests
18 disp(strcat('Best solution=', num2str(bestnest)));
19 disp(strcat('Best objective=', num2str(fmin)));

```

### Listing 9.2

Main part for the cuckoo search algorithm.

The third part is about the Lévy flights and the selection of the best solution. The generation of pseudo-random numbers obeying the Lévy distribution is carried out by Mantegna's algorithm [12]

$$s = \frac{u}{|v|^{1/\beta}}, \quad (9.8)$$

where  $u$  and  $v$  are drawn from normal distributions

$$u \sim N(0, \sigma_u^2), \quad v \sim N(0, 1). \quad (9.9)$$

Here,  $\sigma^2$  should be calculated by

$$\sigma = \left\{ \frac{\Gamma(1+\beta) \sin(\pi\beta/2)}{\beta \Gamma[(1+\beta)/2] 2^{(\beta-1)/2}} \right\}^{1/\beta}, \quad (9.10)$$

where  $\Gamma$  is the standard gamma function. In practice, it is easier to use a fixed  $\sigma$  value, together with scaling factor such as 0.01. Thus, the Lévy flight step is replaced by

$$u \sim N(0, \sigma^2), \quad v \sim N(0, 1), \quad (9.11)$$

and

$$s = \frac{u}{|v|^{1/\beta}}, \quad \beta = 3/2, \quad (9.12)$$

which gives stepsizes for modifying  $\mathbf{x}_i$  as

$$\text{stepsize} = 0.01(\mathbf{x}_i - \mathbf{x}_{\text{best}}) \cdot \frac{u}{|v|^{1/\beta}}. \quad (9.13)$$

```

1 %% Get cuckoos by random walk
2 function nest=get_cuckoos(nest, best, Lb, Ub)
3 % Carry out Levy flights
4 n=size(nest,1);
5 beta=3/2;
6 sigma=(gamma(1+beta)*sin(pi*beta/2)/(gamma((1+beta)/2)*beta*2^((beta
   -1)/2)))^(1/beta);
7
8 for j=1:n,
9     s=nest(j,:);
10    %% Levy flights by Mantegna's algorithm
11    u=randn(size(s))*sigma;
12    v=randn(size(s));
13    step=u./abs(v).^(1/beta);
14    stepsize=0.01*step.*(s-best);
15    s=s+stepsize.*randn(size(s));
16    %% Apply simple bounds/limits
17    nest(j,:)=simplebounds(s,Lb,Ub);
18 end
19
20 %% Find the current best nest
21 function [fmin,best,nest,fitness]=get_best_nest(nest,newnest,fitness)
22 % Evaluating all new solutions
23 for j=1:size(nest,1),
24     fnew=fobj(newnest(j,:));
25     if fnew<=fitness(j),
26         fitness(j)=fnew;
27         nest(j,:)=newnest(j,:);
28     end
29 end
30 % Find the current best solution
31 [fmin,K]=min(fitness);
32 best=nest(K,:);
33
34 %% Replace some nests by constructing new solutions/nests
35 function new_nest=empty_nests(nest,Lb,Ub,pa)
36 % A fraction of worse nests are discovered with a probability pa
37 n=size(nest,1);
38 % Discovered or not — a status vector
39 K=rand(size(nest))>pa;
40 %% Generate new solutions by biased/selective random walks
41 stepsize=rand*(nest(randperm(n),:)-nest(randperm(n),:));
42 new_nest=nest+stepsize.*K;
43 for j=1:size(new_nest,1)
44     s=new_nest(j,:);
45     new_nest(j,:)=simplebounds(s,Lb,Ub);
46 end

```

### Listing 9.3

Lévy flights and selection of the best.

The fourth part applies the simple lower and upper bounds. This will ensure the new solution vector should be within the regular bounds.

```

1 % Application of simple bounds
2 function s=simplebounds(s,Lb,Ub)
3   % Apply the lower bound
4   ns_tmp=s;
5   I=ns_tmp<Lb;
6   ns_tmp(I)=Lb(I);
7
8   % Apply the upper bounds
9   J=ns_tmp>Ub;
10  ns_tmp(J)=Ub(J);
11  % Update this new move
12  s=ns_tmp;

```

#### Listing 9.4

Simple bounds are verified for new solutions.

The fifth part is the objective function. New solutions can be evaluated by calling the objective or cost function.

```

1 %% Cost or objective function
2 function z=cost(x)
3 z=sum((x-1).^2); % Solutions should be (1,1,...,1)

```

#### Listing 9.5

The objective function.

If we run this code with a maximum number of 1000 iterations, we can get the best minimum value as  $f_{\text{best}} = 3.5 \times 10^{-12}$  for 15 decision variables. If we use  $D = 5$  (five variables), we can easily get about  $2.7 \times 10^{-31}$ .

Since such algorithms contain randomness, multiple runs are needed to get some proper statistics and statistical measures.

---

## 9.4 Source code in C++

For the CS, we have also implemented it in C++. However, as there is no standard library for Lévy flights, we have also implemented the Lévy flights in C++ code below.

```

1 #include <iostream>
2 #include <time.h>
3 #include <cmath>
4 #include <random>
5 #include <algorithm>
6 using namespace std;
7 float simplebounds(float s, float Lb, float Ub)
8 {if (s>Ub) {s=Ub;} if (s<Lb) {s=Lb;} return s;}
9 //A very simple approximation of gamma function
10 float gamma(float x)
11 {return sqrt(2.0*M_PI/x)*pow(x/M_E, x);}
12 //Definition of the objective function OF(.)
13 float fobj(float x[], int size_array)
14 {float t=0;
15 for(int i=0; i<size_array; i++){t=t+(x[i]-1)*(x[i]-1);}

```

```

16 return t;}
17 //Generate pseudo random numbers in the range [0, 1)
18 float ra() {return (float)rand()/RAND_MAX;}
19 int main()
20 { //Normal distribution generator
21 std::default_random_engine generator;
22 std::normal_distribution<double> distribution(0,1.0);
23 srand(time(NULL));
24 int n=25; //Number of nests (or population size)
25 float pa=0.25; //Discovery rate of alien eggs/solutions
26 int nd=15; //Number of dimensions
27 float Lb[nd]; //Lower bounds
28 float Ub[nd]; //Upper bounds
29 float fitness[n]; //Fitness values
30 float beta=3/2, sigma, fmin, best[nd], bestnest[nd];
31 int K, r1, r2, r, randperm1[n], randperm2[n];
32 for(int i=0; i<nd; i++){Lb[i]=-5; Ub[i]=5;}
33 int N_IterTotal=1000; //Increase it get better results
34 //Random initial solutions for the population with n cuckoos
35 float nest[n][nd], new_nest[n][nd];
36 for(int i=0; i<n; i++){
37     for(int j=0; j<nd; j++){
38         nest[i][j]=Lb[j]+(Ub[j]-Lb[j])*ra();}}
39 for(int i=0; i<n; i++){
40     fitness[i]=fobj(nest[i],nd);
41     randperm1[i]=i; randperm2[i]=i;}
42 K=0; fmin=fitness[K];
43 for(int i=1; i<n; i++){
44     if (fitness[i]<=fmin){
45         fmin=fitness[i];
46         K=i;}}
47 for(int j=0; j<nd; j++){
48     best[j]=nest[K][j];}
49 //Starting iterations
50 float s, u, v, step, stepsize, fnew;
51 for(int iter=0; iter<N_IterTotal; iter++)
52 {
53     //Generate new solutions (but keep the current best)
54     sigma=pow(gamma(1+beta)*sin(M_PI*beta/2)/(gamma((1+beta)/2)*beta*pow
55         (2,(beta-1)/2))),(1/beta));
56     for(int i=0; i<n; i++){
57         for(int j=0; j<nd; j++){
58             s=nest[i][j];
59             //Levy flights by Mantegna's algorithm
60             u=distribution(generator)*sigma;
61             v=distribution(generator);
62             step=u/pow(abs(v),(1/beta));
63             stepsize=0.01*step*(s-best[j]);
64             s=s+stepsize*distribution(generator);
65             //Apply simple bounds/limits
66             new_nest[i][j]=simplebounds(s, Lb[j], Ub[j]);}
67         fnew=fobj(new_nest[i], nd);
68         if (fnew<=fitness[i]){fitness[i]=fnew;
69             for(int j=0; j<nd; j++){
70                 nest[i][j]=new_nest[i][j];}}}
71 //Get the best nest
72 K=min_element(fitness, fitness+nd)-fitness;
73 fmin=fitness[K];
74 for(int j=0; j<nd; j++){best[j]=nest[K][j];}
75 //Carry out random permutation
76 for(int i=0; i<n; i++){r1=rand()%n; r2=rand()%n;
77     if (r1!=r2){r=randperm1[r1]; randperm1[r1]=randperm1[r2];
78         randperm1[r2]=r;
79         r1=rand()%n; r2=rand()%n;
80         if (r1!=r2){r=randperm2[r1]; randperm2[r1]=randperm2[r2];
81             randperm2[r2]=r;}}
82 }

```



```

80 //Discovery and randomization
81 for(int i=0; i<n; i++)
82 {
83     for(int j=0; j<nd; j++)
84     {
85         stepsize=ra()*(nest[randperm1[i]][j]-nest[randperm2[i]][j]);
86         if(ra()>pa)
87         {
88             new_nest[i][j]=nest[i][j]+stepsize;
89         }
90         else
91         {
92             new_nest[i][j]=nest[i][j];
93         }
94         new_nest[i][j]=simplebounds(new_nest[i][j], Lb[j], Ub[j]);
95     }
96 }
97 //Evaluate the new set of solutions
98 for(int i=0; i<n; i++)
99 {
100     fnew=fobj(new_nest[i], nd);
101     if (fnew<=fitness[i])
102     { fitness[i]=fnew;
103       for(int j=0; j<nd; j++)
104         { nest[i][j]=new_nest[i][j]; } }
105 //Get the best nest
106 K=min_element(fitness, fitness+nd)-fitness;
107 fmin=fitness[K];
108 for(int j=0; j<nd; j++){ best[j]=nest[K][j]; }
109 //Find the best objective so far
110 if (fnew<fmin)
111     { fmin=fnew;
112       for(int j=0; j<nd; j++)
113         { bestnest[j]=best[j]; } }
114 //Output the best solution
115 cout<<"Best solution = [ ";
116 for(int i=0; i<nd; i++) { cout<<bestnest[i]<<" "; }
117 cout<<" ] "<<endl;
118 cout<<"Best objective = "<<fmin<<endl;
119 getchar();
120 return 0;
121 }

```

### Listing 9.6

Cuckoo search in C++.

## 9.5 A worked example

Let us use the cuckoo search algorithm to find the minimum of

$$f(\mathbf{x}) = (x_1 - 1)^2 + (x_2 - 1)^2 + (x_3 - 1)^2 + (x_4 - 1)^2 + (x_5 - 1)^2, \quad (9.14)$$

in the simple ranges of  $-5 \leq x_i \leq 5$ . This simple 5-variable problem has the global minimum solution  $\mathbf{x}_{\text{best}} = [1, 1, 1, 1, 1]$ .

For the purpose of algorithm demonstration, we only use  $n = 3$  cuckoos. Suppose the initial population is randomly initialized and their objective

(fitness) values are as follows:

$$\left\{ \begin{array}{l} \mathbf{x}_1 = (5.00 \quad -1.00 \quad 5.00 \quad 2.00 \quad 3.00), \\ \mathbf{x}_2 = (3.00 \quad 2.00 \quad 4.00 \quad 5.00 \quad -5.00), \\ \mathbf{x}_3 = (3.00 \quad -4.00 \quad 2.00 \quad 0.00 \quad -2.00), \end{array} \right. \quad \begin{array}{l} f_1 = f(\mathbf{x}_1) = 41.00, \\ f_2 = f(\mathbf{x}_2) = 66.00, \\ f_3 = f(\mathbf{x}_3) = 40.00, \end{array} \quad (9.15)$$

where we have only used two decimal places for simplicity. Obviously, the actual random numbers generated for the initial population can be any numbers in the simple bounds, but here we have used the numbers that are rounded up as the initialization; this is purely for simplicity and clarity.

Obviously, the best solution with the lowest (or best) value of the objective function is  $\mathbf{x}_3$  with  $f_3 = 40.00$  for this population at  $t = 0$ . Thus, we have

$$\mathbf{x}_{\text{best}} = [3.00, -4.00, 2.00, 0.00, -2.00]. \quad (9.16)$$

At the first iteration, let us suggest that we randomly pick solution  $\mathbf{x}_2$  for modifying it by Lévy flights. If we generate two random number vectors  $u$  and  $v$ , then suppose we get

$$\text{stepsize} = \Delta \mathbf{x} = [0.50, -0.90, -1.40, -0.70, 2.30], \quad (9.17)$$

then the new modified solution will be

$$\mathbf{x}_2^1 = \mathbf{x}_2^0 + \Delta \mathbf{x} = [3.50, 1.10, 2.60, 4.30, -2.70], \quad (9.18)$$

which gives  $f(\mathbf{x}_2^1) = 33.40$ . This solution is better than the previous solution  $\mathbf{x}_2$  and all the previous solutions. Thus, the next call to get the best solution will give the new best solution  $f_{\min} = 33.40$  with

$$\mathbf{x}_{\text{best}} = [3.50, 1.10, 2.60, 4.30, -2.70]. \quad (9.19)$$

After this Lévy flight modification, we randomly select another solution, say  $\mathbf{x}_3$  via emptying a nest. We first generate a random number and compare it with  $p_a$  to decide if we should update this solution. Suppose the result is to update the solution. Now we have to do this by random permutation of the population, and also generate a random number (say  $r = 0.42$ ). We can get the modification step size as

$$\Delta \mathbf{x}_3 = 0.42 \times (\mathbf{x}_2^1 - \mathbf{x}_1) = [-0.630, 0.882, -1.008, 0.966, -2.394], \quad (9.20)$$

which gives the new solution

$$\mathbf{x}_3^1 = \mathbf{x}_3 + \Delta \mathbf{x}_3 = [2.370, -3.118, 0.992, 0.966, -4.394]. \quad (9.21)$$

Thus, the new objective value  $f(\mathbf{x}_3^1) = 47.93$ , which is no better than any of the solutions in the current population, so we will not update  $f_{\min}$ . However, we still replace  $\mathbf{x}_3$  by the new solution for population diversity.

Once the above modifications over the whole population and updates are done, we move on to the next generation  $t = 2$  of iterations.

Cuckoo search is very efficient, even with a small population. For example, if we use  $n = 5$  (cuckoos), we can get  $f_{\text{best}} = 1.34 \times 10^{-17}$  after 1000 iterations for the above example. Even for  $D = 15$  and  $n = 25$ , we can typically get  $f_{\text{best}} = 2.50 \times 10^{-12}$  after 1000 iterations.

Obviously, due to the stochastic nature, performance evaluations should be based on the statistical measures of results of multiple runs with proper parametric studies.

---

## 9.6 Conclusion

The cuckoo search algorithm can be very efficient and flexible. However, the implementation is slightly more complicated than the implementations of other algorithms due to its use of Lévy flights. The demo codes presented in this chapter provide a simple implementation to focus on the core ideas of the algorithm. It is hoped that this can form a basis for further improvements and modifications so as to solve a wide range of optimization problems in applications.

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