Draft1 - Waypoint

I - Definition

We call a **waypoint** a location reached by a drone during a mission. It should be linked to a mission and could be linked to a goal.

II - Attributes

II.1 - Definitions

A waypoint can have the following attributes:

- battery_level, the battery level (in percent) when the drone arrives at the waypoint.
- comments, comments about the mission.
- waypoint_location, the GPS coordinates of the waypoint.
- end_pose_time; for some reasons (like collecting data in a interesting point or try to send videos to the base on the ground), the drone may want to stay a few seconds on the waypoint. When he leaves the waypoint to continue the mission, we store the time in the end_pose_time attribute.
- arrival_time, when the drone arrives at the waypoint (or pass through the waypoint).
- temperature, the temperature at the waypoint.
- wind_direction, the direction of the wind (in degree relative to the north, clockwise).
- wind_strength, the strength of the wind (in km/h)

II.2 - Description

II.2.1 - Graphical representation

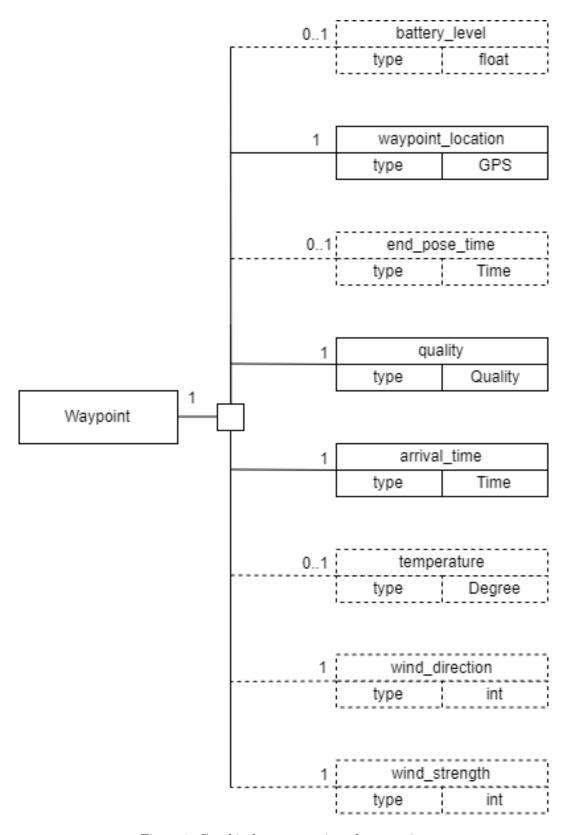


Figure 1: Graphical representation of a waypoint

II.2.2 - Description table

Name	Type	Expected length	Optional	Significant
$battery_level$	float	-	Yes	2
$way point_location$	GPS	-	No	1
end_pose_time	Time	-	No	1
$arrival_time$	Time	-	No	1
temperature	float	-	Yes	3
$wind_direction$	float	-	Yes	3
$wind_strength$	int	-	Yes	3

Table 1: Description table

III - Examples

```
"battery level" : 80.5,
 4
     "waypoint_location" : {"altitude" : 15.321,
5
                          "latitude" : 048.452666,
 6
                          "longitude" : -001.6406852},
7
      "end_pose_time" : "2019-05-02T17:05:32,854+02:00",
8
     "quality" : 2,
9
     "arrival_time" : "2019-05-02T17:05:24,413+02:00",
10
     "temperature" : 14.3,
11
12
      "wind direction" : 320.4,
      "wind strength" : 25}
13
```

Figure 2: Example of a waypoint in json