LABORATORIO DI INGEGNERIA DEI SISTEMI SOFTWARE

Introduction

Requirements

Req1 : percorrere (una volta) il bordo perimetrale della stanza rappresentata nella scena di WEnv

Requirement analysis

Problem analysis

The client can interact with WEnv using both **synchronous** and **asynchronous** communication protocols.

HTTP POST	WEBSOCKET
 application layer messages sent on port 8090 request/response protocol easier for testing 	 messages sent on port 8091 bidirectional: the server sends a message with the outcome of the command use of annotations

After discussion with the client, it was agreed to use **HTTP** as communication protocol.

Test plans

Project

To cover the boundary of the room, the robot must

- move forward along the wall
- when reaching the end, the robot must turn left

for **4 times**. The boundary is entirely covered when the robot has travelled along the four walls: wallUp, wallRight, wallDown, wallLeft.

Testing

- A possible testing solution is to have the robot colliding with the opposite wall, followed by a 90 degree rotation to the left.
 In this way, the robot will walk the boundary counterclockwise since its home is located in the top-left corner.
- If the **size of the room** and the **speed of the robot** are known, I can check how long it takes for the robot to **reach the opposite wall without colliding** with it.

 After walking a wall, the robot must rotate only once.
- At the end, the robot must be in the **HOME** position and it must have collided with the 4 walls

Deployment

Maintenance

- By Letizia Mancini
- email: letizia.mancini3@studio.unibo.it
- GIT repo: https://github.com/llevtizia/issLab23-ManciniLetizia
- matricola: 0000926656

