

# Introduction to Computer Organization

**DIS 1A – Week 9**

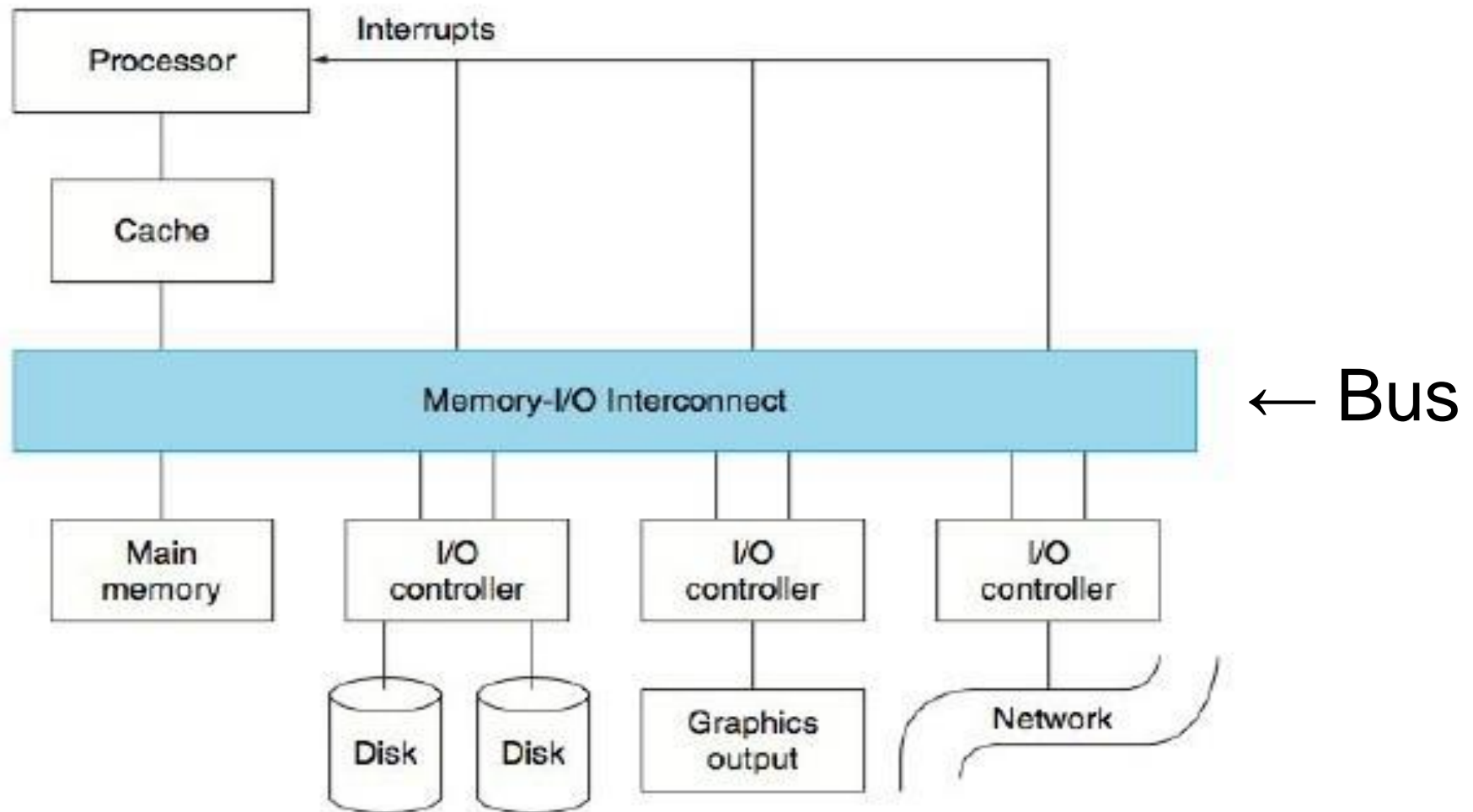
Slides modified from Eric Kim

# Agenda

- I/O
- Virtual Memory
- Linking

# The more hardware-ish viewpoint

- A hypothetical logical interconnection:



# I/O

- Things to note:
- Despite the variety of components (CPU, memory, devices), most things are linked together via a “bus”.
- A bus is essentially a collection of wires that can be used to transfer data.
- In this example the processor is not connected to the cache via the bus. Generally, we want at least the L1 cache to be as close to the processor as possible.

# I/O

- Things to note:
- Devices are not directly connected to the bus. They are connected via an I/O controller.
- What are the trade-offs of having everything connected via a single bus?

# I/O

- What are the trade-offs of having everything connected via a single bus?
- Pros:
  - Simple from a hardware standpoint. Requires few components/little space.
  - Transparency between devices. Each device can snoop on the bus and know exactly what's going on. This is a very nice property if you have multiple processors sharing memory via a bus.
- Cons?

# I/O

- What are the trade-offs of having everything connected via a single bus?
- Cons:
  - You could potentially have many devices competing for a single resource. The bus becomes a huge bottleneck.
  - Bus arbitration logic. If a device wants to use a bus, it needs to fight the other devices for the right to use the bus. There is only one winner.

# I/O

- Things to note:
- The wires of the bus fall into several categories and serve different purposes (data, address, control).
- Through the bus, each of the controllers can communicate with the other controllers (depending on the complexity of the controller)



# I/O

- Computer architecture and interconnection is not standardized because different goals require different interconnections.
- There are, however, common features that you should be aware of so that you will be able to understand more practical/realistic arrangements.

# Communication with I/O Devices

- At the processor, how are commands given to I/O devices?
- Memory Mapped I/O: Portions of the address space are assigned to represent an I/O device.
  - `movl (0x1234), %eax`
  - The address and operation are sent over the bus. The memory system recognizes that the address corresponds to an I/O device and doesn't respond.
- Special I/O assembly instructions.

# Communication with I/O Devices

- Now that the processor has issued a request to a device, how does the I/O device respond back to the processor?
  - Polling
  - Interrupt driven I/O
  - Direct Memory Access

# Communication with I/O Devices

- Polling
  - When the I/O device has a result ready for the CPU, it indicates it or puts the result in a register.
  - When the CPU expects a result, it must manually go and check the registers to see if it has a delivery. If there is, the CPU goes and gets the result.
  - If the CPU must wait before continuing, it can issue a request and do nothing other than continually poll the register until a result is received.
  - What about if a CPU isn't explicitly waiting for something (like a mouse/keyboard action)?

# Communication with I/O Devices

- Polling
  - What about if a CPU isn't explicitly waiting for something (like a mouse/keyboard action)?
  - The CPU will have to spend a lot of time checking the status register to make sure there isn't some result that it has to handle.
  - This is a waste of time.

# Communication with I/O Devices

- Interrupt Driven:
  - When an I/O device has a result. It will modify a status and cause register and inform the CPU by explicitly sending an interrupt.
  - Once the currently running instruction completes, the CPU will handle the exception and read the registers if necessary to decide how to handle the I/O.

# Communication with I/O Devices

- Both interrupt-driven and polling simply inform the CPU of when it can fetch data and the CPU is ultimately responsible for getting the data.
- If the CPU is spending time fetching data from I/O devices, it's not running the program that it's supposed to be running. Program execution is halted.
- As a result, these methods work fine for small data transfers but don't work very well for large and slow data transfers (like reading from disk).

# Communication with I/O Devices

- When the processor reads to disk, the processor will be copying from disk to RAM.
- What a bore.
- If only the CPU could spend it's time running the program and the “disk controller” could access memory... directly.



# Communication with I/O Devices

- Direct Memory Access (DMA)
- Turns the I/O controllers into small CPUs, each of which can access the bus and do work such as transferring data.
  - 1.Processor issues request informing the DMA controller what to do.
  - 2.Processor goes back to doing it's job. Meanwhile the DMA controller arbitrates for the bus and attempts to do the data transfer to memory.
  - 3.When the DMA is done, it informs the CPU via an interrupt.

# Communication with I/O Devices

- In this way, the processor can do the haughty processor work without having to sully itself with the petty matters of the proletariat (I/O devices).

# What this means for you

- When it comes to applications, how can they make use of this I/O structure?

# What this means for you

- Initiate the low level interactions by simply calling syscalls:
- `open()`
- `read()`
- `write()`
- `close()`

# Memory

- Last week, we covered caches and why it was necessary to have them.
- Recap: We need DRAM/Main Memory since we need some “large memory” in order to adequately contain our program's addressable space.
- Unfortunately, this large memory is too slow to be our primary source of satisfying memory accesses.
- Cache to the rescue.

# Memory

- We now have an adequate model for describing how a program is executed.
- Instruction addresses are fed into the processor and memory accesses generally must be satisfied by the cache.
- Memory addresses range from 32, 48, and 64 (?) bits. If we consider the 32 bit case, this implies that our memory must have a capacity of  $2^{32}$  bytes.

# Memory

- That suggests that main memory must be at least  $2^{32}$  or approximately 4 GB.
- But that can't be right, computers can function just fine with less memory than that.
- ...for that matter even if you had 4 GB of memory, how could you run multiple processes if each process expects to have 4 GB of personal memory space.
- What if a computer was running 100 processes?

# Virtual Memory: Basics

- Addresses that are known to a program are actually virtual addresses in a scheme known as virtual memory.
- Each process expects to be the sole owner of  $2^{32}$  bytes of memory, but it would be impractical to have actually that much DRAM
- Instead, we can simply allow each process to believe that they own the entire addressable space.



# Virtual Memory: Basics

- In reality, the physical memory must be shared between all of the processes.
- The actual contents of each process' memory must actually be stored on the much larger (but much slower) disk.
- Main memory thus becomes a “cache” for the virtual memory on disk.

# Virtual Memory: Basics

- Memory (both virtual and physical) is split up into a number of “pages”.
- Each page is just a contiguous chunk of memory of a set size.
- When a process accesses memory, it uses a virtual address. If the physical memory contains the “page” that the virtual address belongs to, get the value from memory.
- If not, page fault, you'll have to find the page on disk, then copy it to physical memory.

# Virtual Memory: Basics

- Wait... so each process expects ~4 GB of memory which is stored on disk instead. That means if I have 100 processes, I need ~400 GB of disk space, just to store the memory spaces of all of the programs?

# Virtual Memory: Basics

- Not all pages are actually “allocated”. This means they don't exist anywhere. This allows processes to only take up as much space as they need.
- For example, if pages are 4KB and the program has not defined any use for memory address range 0x01000000 to 0x01001000, then there's no need to have that page allocated in memory.

# Virtual Memory: Basics

- If physical memory is a “cache” for the virtual memory on disk, where in physical memory is each physical page assigned?
- IE: Consider the page that spans virtual addresses:
- $0x0000 \rightarrow 0x1000$
- Where in physical address should that belong to?

# Virtual Memory: Basics

- Physical memory is like a “fully set associative” cache. This means that any page that belongs to virtual memory can be located anywhere in physical memory.
- As a result, a real view of physical memory would show that it's a big mess, interleaved with scattered pages from various processes.

# Virtual Memory: Basics

- Like a cache, if main memory is full and you need to bring a different page from disk into main memory, some page is going to have to be a victim.
- Keep this in mind for later.
- If the virtual page can be anywhere in physical memory, how do we find it?
- It would be obnoxious to have to search every page in physical memory as we would with a set associative cache.

# Virtual Memory: Page Table

- When we need to look through main memory for a virtual page, we don't want to have to manually search every page.
- Instead, we maintain a Page Table which maps virtual addresses to physical addresses.
- We will use (part of) the virtual address to index into the table. Each entry in the page table will contain (part of) the physical address that it maps to.



# Virtual Memory: Page Table

- Consider a page size of ~4 KB or  $2^{12}$  bytes. If the addressable space is 32 bits. How many pages could there possibly be in the virtual address space?

# Virtual Memory: Page Table

- Consider a page size of ~4 KB or  $2^{12}$  bytes. If the addressable space is 32 bits. How many pages could there possibly be in the virtual address space?
- $2^{32} \text{ bytes} * 1/2^{12} \text{ pages/byte} = 2^{32}/2^{12} = 2^{20} \text{ pages}$
- Each page is of size  $2^{12}$  bytes.

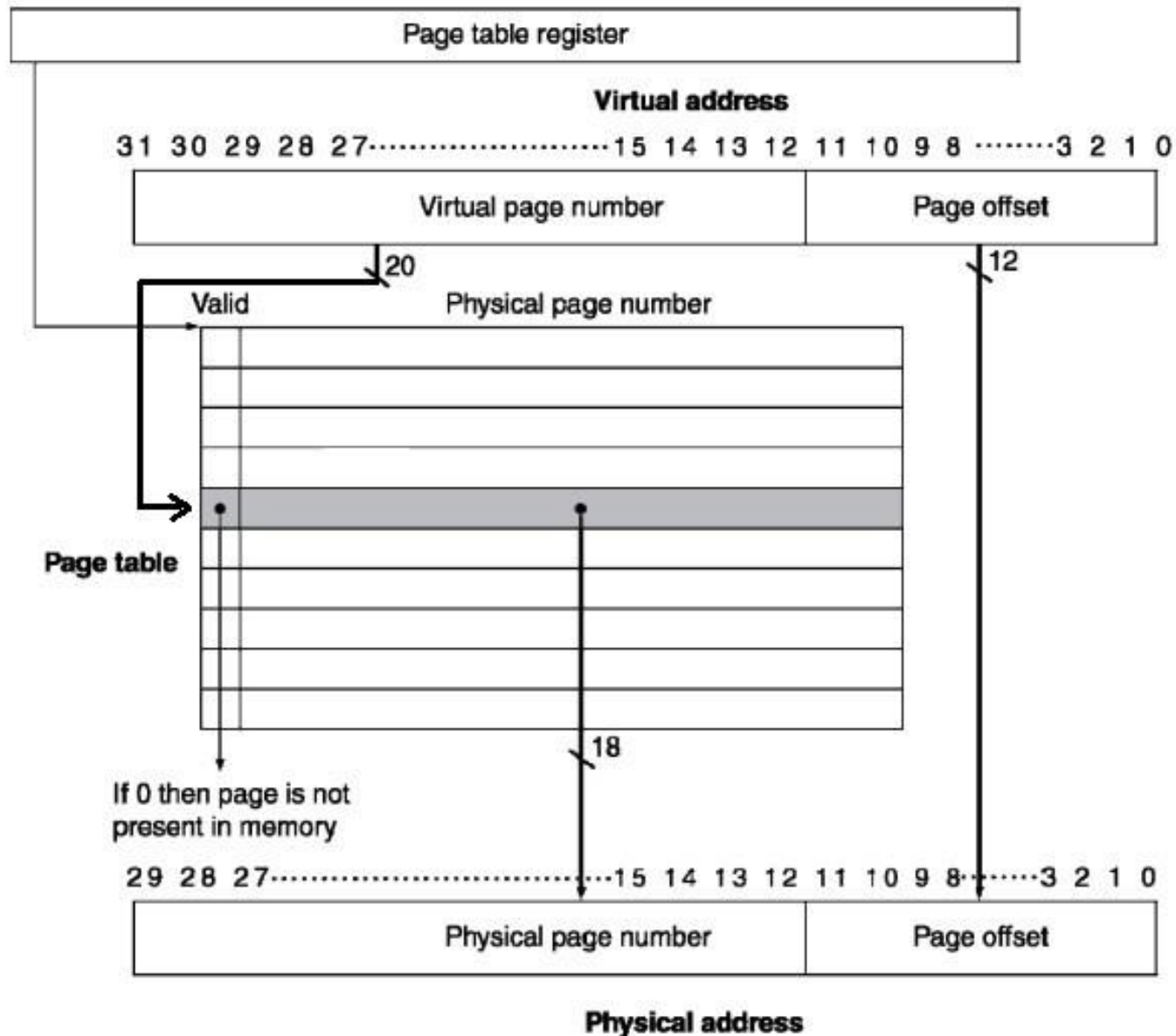
# Virtual Memory: Page Table

- Virtual Address decomposition.
- [          VPN          ][ VPO    ]
- VPN: Virtual Page Number
  - The index into the page table
- VPO: Virtual Page Offset
  - The byte offset into the page
- Index into the page table with the VPN. The value stored in the page table is the PPN or physical page number.

# Virtual Memory: Page Table

- Virtual Address decomposition.
- $[ \quad \text{VPN} \quad ][ \text{VPO} ]$
- Physical Address decomposition.
- $[ \quad \text{PPN} \quad ][ \text{PPO} ]$
- The VPO and PPO are same since page size are consistent in both virtual and physical address space.

# Virtual Memory: Page Table



# Virtual Memory: Page Table

- Ex: Consider a 14-bit virtual address space and a 12-bit physical address space.
- Each page is 256 bytes.
- How is the Virtual Address split in order to index into the Page Table?

# Virtual Memory: Page Table

- Ex.
- How is the Virtual Address split in order to index into the Page Table?
- Each page has  $256 = 2^8$  bytes. This means we need 8 bits to represent the page offset (VPO and PPO).
- This means the VPN is 6-bits and the PPN is 4-bits.

# Virtual Memory: Page Table

- Ex.
- Suppose that you're given the following virtual address:
- 011001 00101000
- How many entries in the page table? (note: this is the same as asking how many pages there are in the memory space)



# Virtual Memory: Page Table

- Ex.
- Suppose that you're given the following virtual address:
- 011001 00101000
- There are  $2^6$  different pages in the memory space ( $2^6 = 2^{14} / 2^8$ )
- This particular address will access the page table with index 25 (011001).

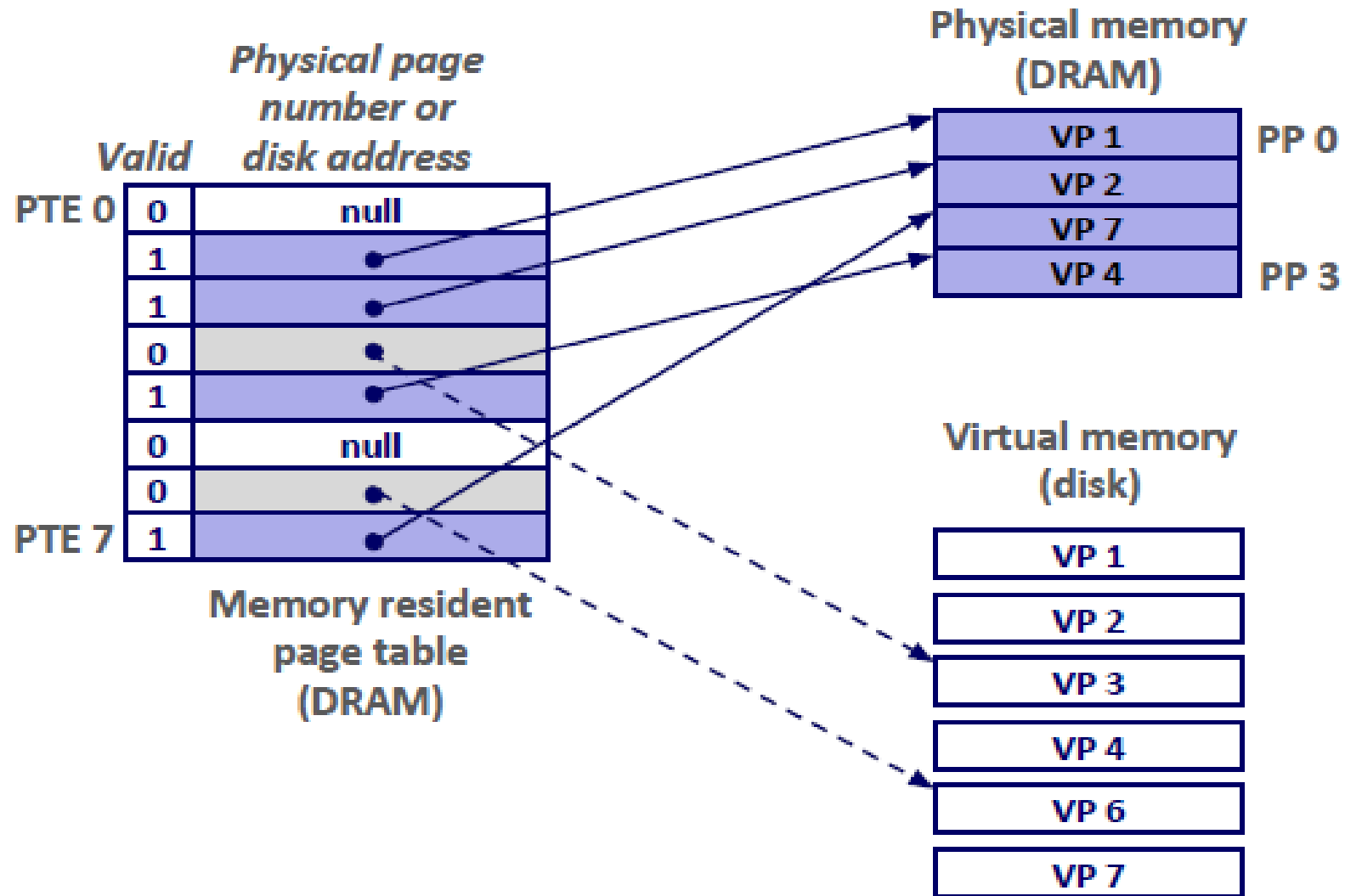
# Virtual Memory: Page Table

- Ex.
- Say the entry at the page table entry 25 has the following as the PPN:
  - 0110.
- The reconstructed physical address is:
- [PPN]:[VPO] = 0110 00101000

# Virtual Memory: Page Table

- Consider 8 bit virtual addresses with a page size of  $2^5$  bytes. This mean 5 bits for the virtual page offset and 3 bits for the virtual page number.
- There are  $2^3$  pages in this addressable space and thus, the there are 8 page table entries indexed from 0 (000) to 7 (111).
- Each page table entry would contain the mapping to the physical address (PPN).

# Virtual Memory: Page Table



# Virtual Memory: Page Table

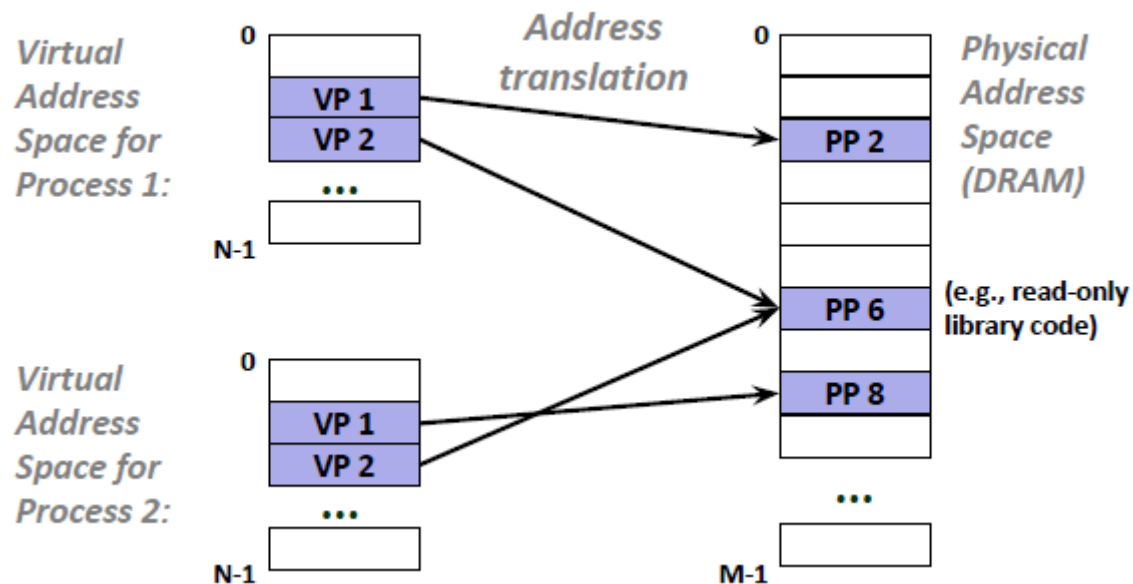
- Some notes:
- The Page Table is an entity stored in memory, it's not hardware.
- The physical address of the current process' page table is stored in a register (which is backed up in the context switch).
- **Each process has its own page table.**
- A page table entry will either indicate:
  - Virtual page is in memory at location [PPN : VPO]
  - or Virtual page is not in memory (valid bit = 0). Go to disk
    - The page is either allocated in disk or unallocated.

# Virtual Memory: Page Table

- More notes:
- The page table look-up process inherently provides one of the other great benefits of virtual memory: isolation between processes.
- Processes can't see the memory of any other process by virtue of the fact that all processes have the same virtual address space.
- Ex. Process 1 has a variable at address 0x10. For process 2, address 0x10 refers to something completely different.

# Virtual Memory: Page Table

- More notes:
- Virtual memory paging, however, also allows for simple explicit memory sharing.
- If you want two processes to share some value of memory, have their page tables point to the same physical address.



# Virtual Memory: Page Table

More notes:

If a virtual page isn't in main memory, when the page is pulled in from disk, the page table of the process is updated.

However, consider the case when we need to evict a page. The OS can choose to throw out any page belonging to any process.

This means that evicting a page potentially means updating multiple or all page tables, whoever had a reference to that page.



# Virtual Memory: Page Table

- The fact that the page table is stored in memory should be a red flag.
- For every memory access, we actually need to make two memory accesses?!
  - One to access page table to find where the memory is actually located.
  - One to actually access memory.
- Well actually...

# Virtual Memory: Page Table

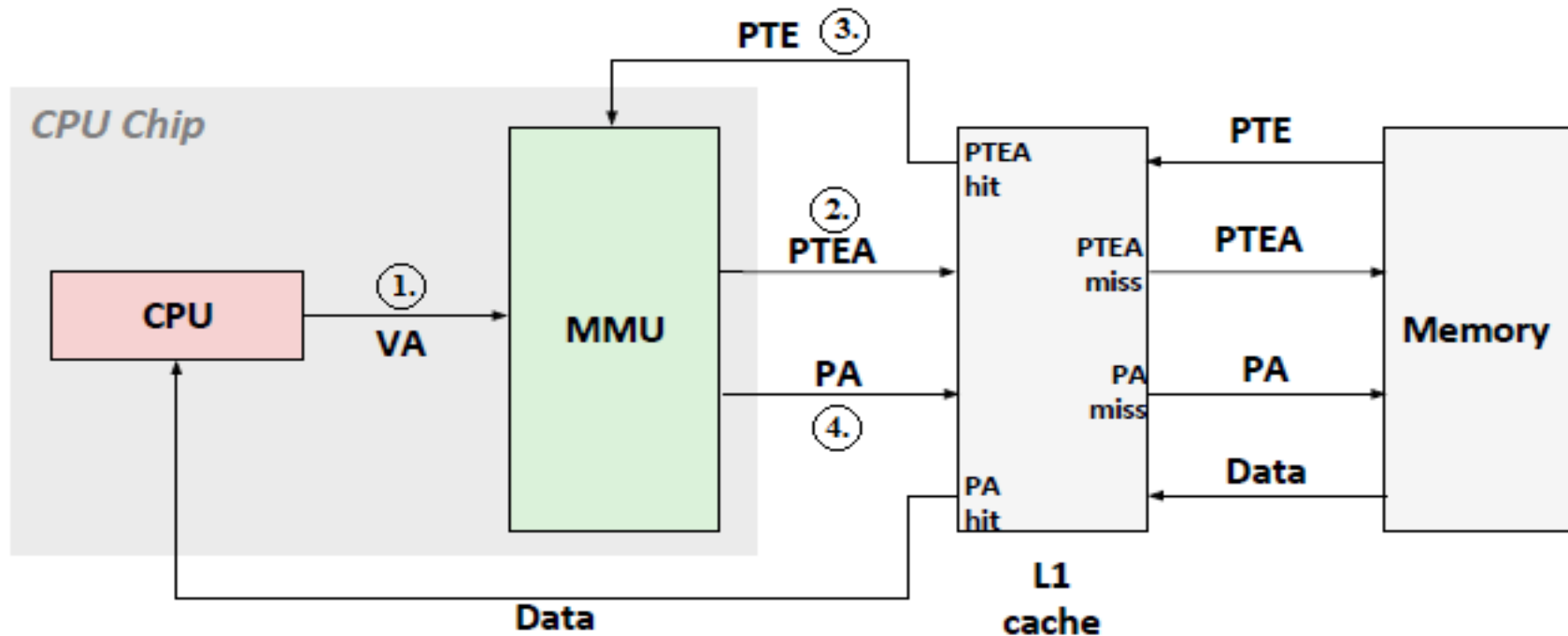
- Because the page table is simply a data structure in memory, it can be cached just like anything else, sharing the instruction or data cache.
- How does this entire process look?

# Virtual Memory: Page Table

- An overview:
  - The CPU wants to access memory. It issues a memory address to the Memory Management Unit (MMU). This address is a *virtual address*.
  - The MMU takes the virtual address and using the address of the page table, attempts to find the Page Table Entry. This means issuing a request to memory.
  - If the MMU receives a valid PTE, then the Physical Address is extracted and the Physical Address is forwarded to the cache + memory etc.
  - If the MMU receives an invalid PTE, it means that the data that corresponds to the virtual address is not in RAM. An exception is thrown to get the data from disk into RAM.

# Virtual Memory: Page Table

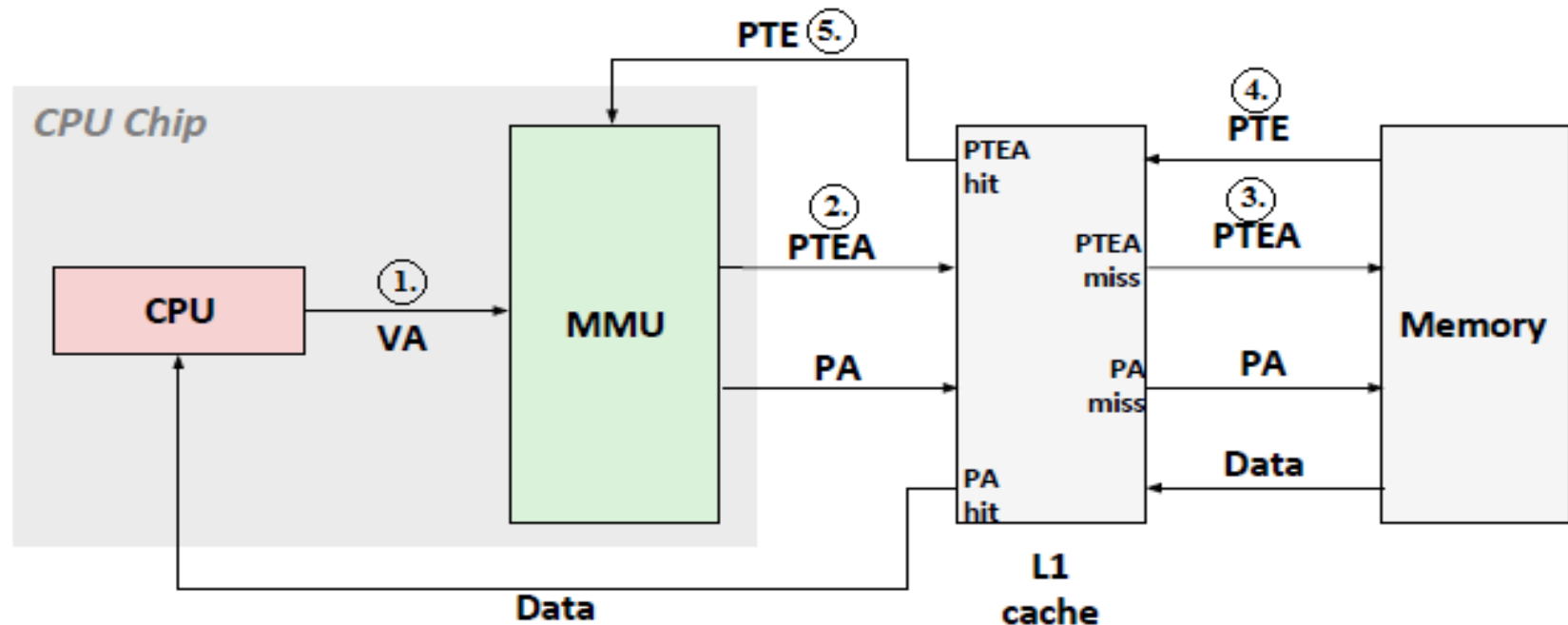
- Page Table Entry in cache



1. CPU issues virtual address to memory management unit.
2. MMU issues address of relevant page table entry to cache.
3. L1 cache return the page table entry to MMU.
4. MMU constructs physical address and sends it to cache

# Virtual Memory: Page Table

- Page Table Entry **not** in cache

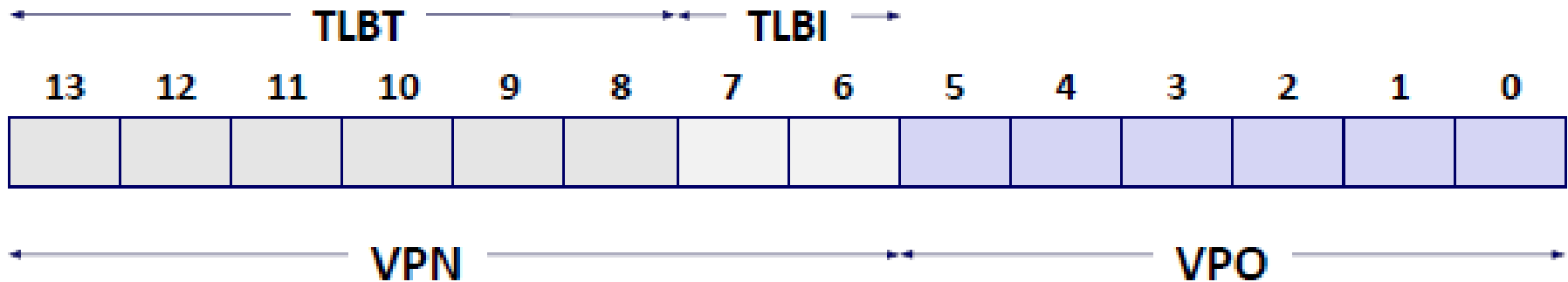


1. CPU issues virtual address to memory management unit.
2. MMU issues address of relevant page table entry to cache.
3. Page table entry not in cache. Cache passes page table entry address to memory.
4. Memory sends page table entry to cache. PTE is cached in... cache.
5. Cache sends page table entry to MMU... and so on.

# Virtual Memory: TLB

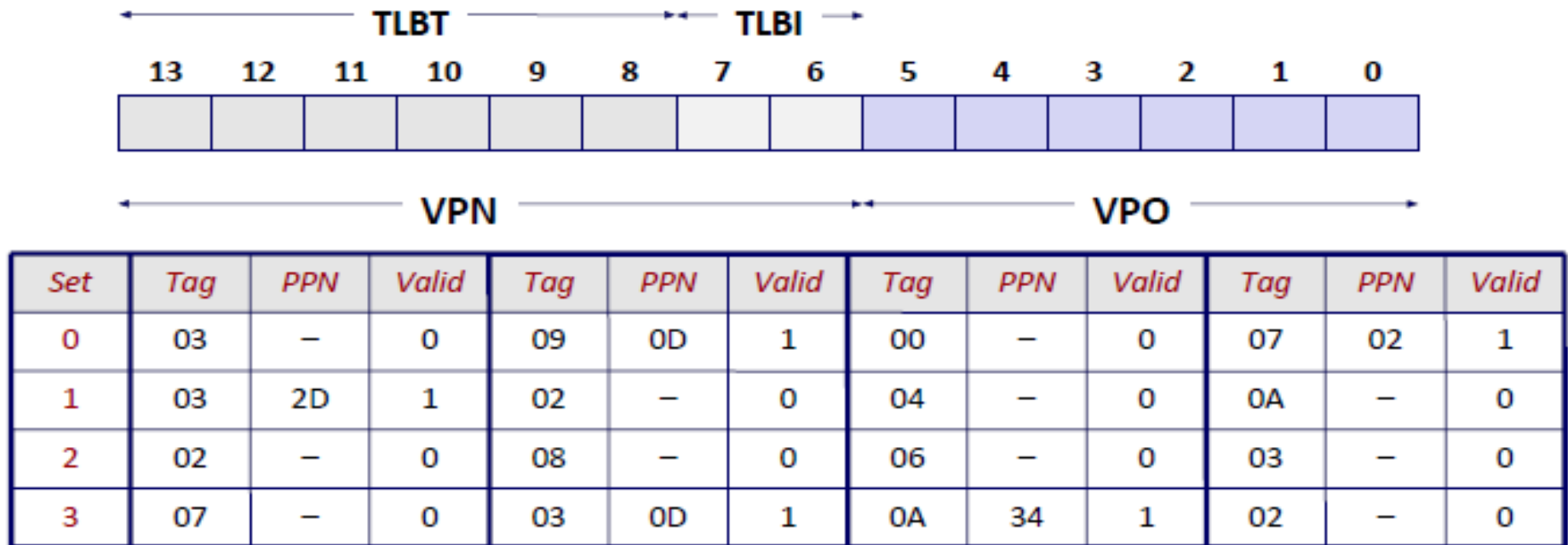
- Despite being able to cache the page table, we really want to ensure that we don't have to go to RAM in order to get the page table entry.
- As a result, we would like a specialized cache that will only hold page table entries.
- Enter... the translation lookaside buffer.
- Instead of having to go to the cache and then memory to get the page table, lets have a special cache for just the page table.

# Virtual Memory: TLB



- Accessing the TLB is the same as accessing a cache; the (virtual) address is split into three components Tag (TLBT), Index (TLBI), and Offset (VPO).
- Instead of memory data, the TLB simply contains the page table entry corresponding to that virtual address.

# Virtual Memory: TLB



- Each entry contains the tag, a valid bit, and a PPN.
- At a high level, how does this look?

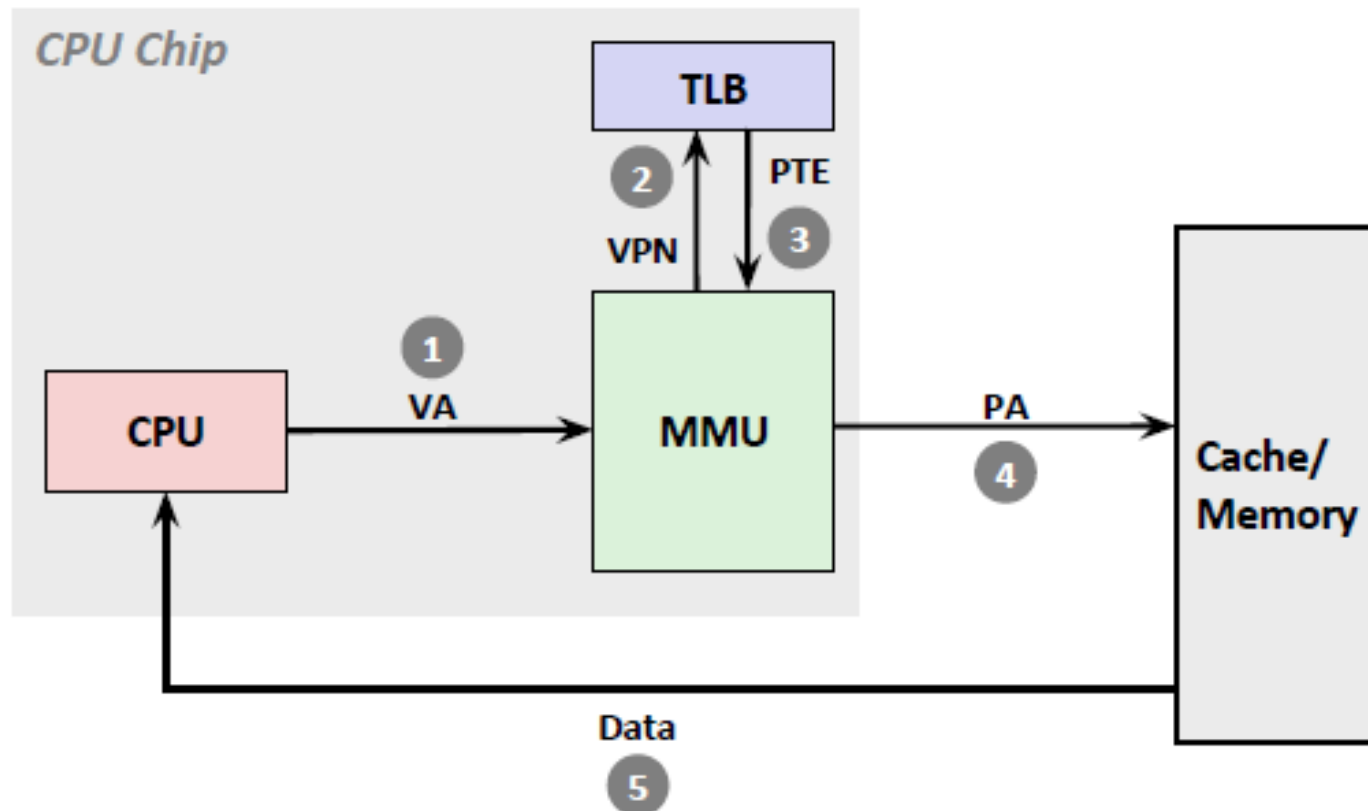


# Virtual Memory: TLB

- Index of abbreviations:
  - VA: Virtual Address
  - VPN: Virtual Page Number (ie the index into the page table)
  - PTE: Page Table Entry (the actual data within a page table entry)
  - PA: Physical Address
  - PTEA: Page Table Entry Address (the address of a particular page table entry)

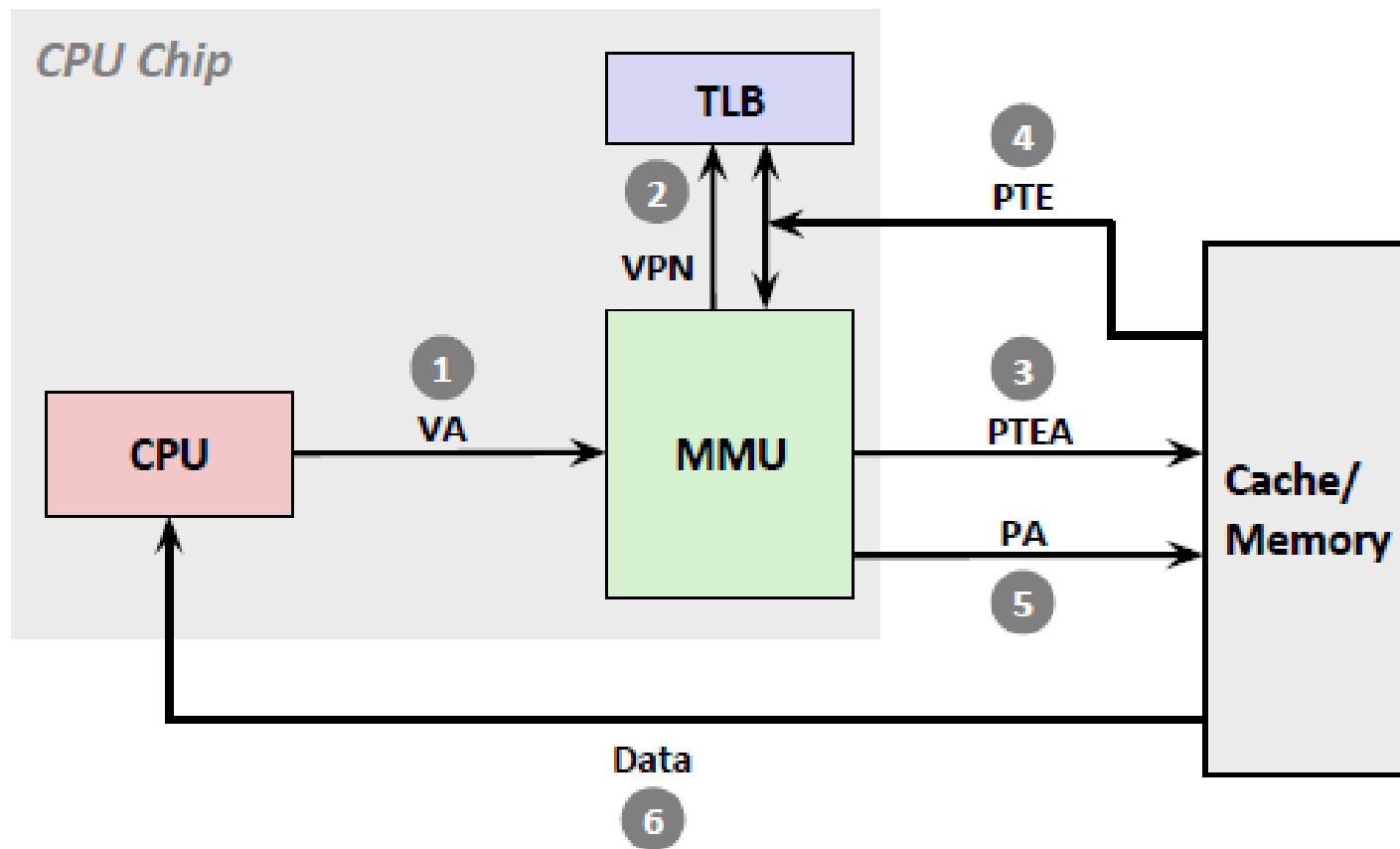
# Virtual Memory: TLB

- TLB Hit (the page table is in the TLB)



# Virtual Memory: TLB

- TLB Miss (the page table is not in the TLB)



# Virtual Memory: Hierarchical Page Tables

- The page tables take up a pretty hefty chunk of memory.
- Additionally, the page table pretty much needs to be in memory at all times.
- However, the entire page table corresponds to the entire virtual addressable space. Most programs don't use up that much of the addressable space. As a result, most programs don't need to use most of the Page Table.

# Virtual Memory: Hierarchical Page Tables

- The solution is to use a table structure that allows for only part of the table to be allocated at any given time.
- In the original case, the virtual address was split up as follows:
  - [          VPN          ][ VPO    ]
- Now we split it up like this:
- [ VPN1 ][ VPN2 ][ VPO    ]

# Virtual Memory: Hierarchical Page Tables

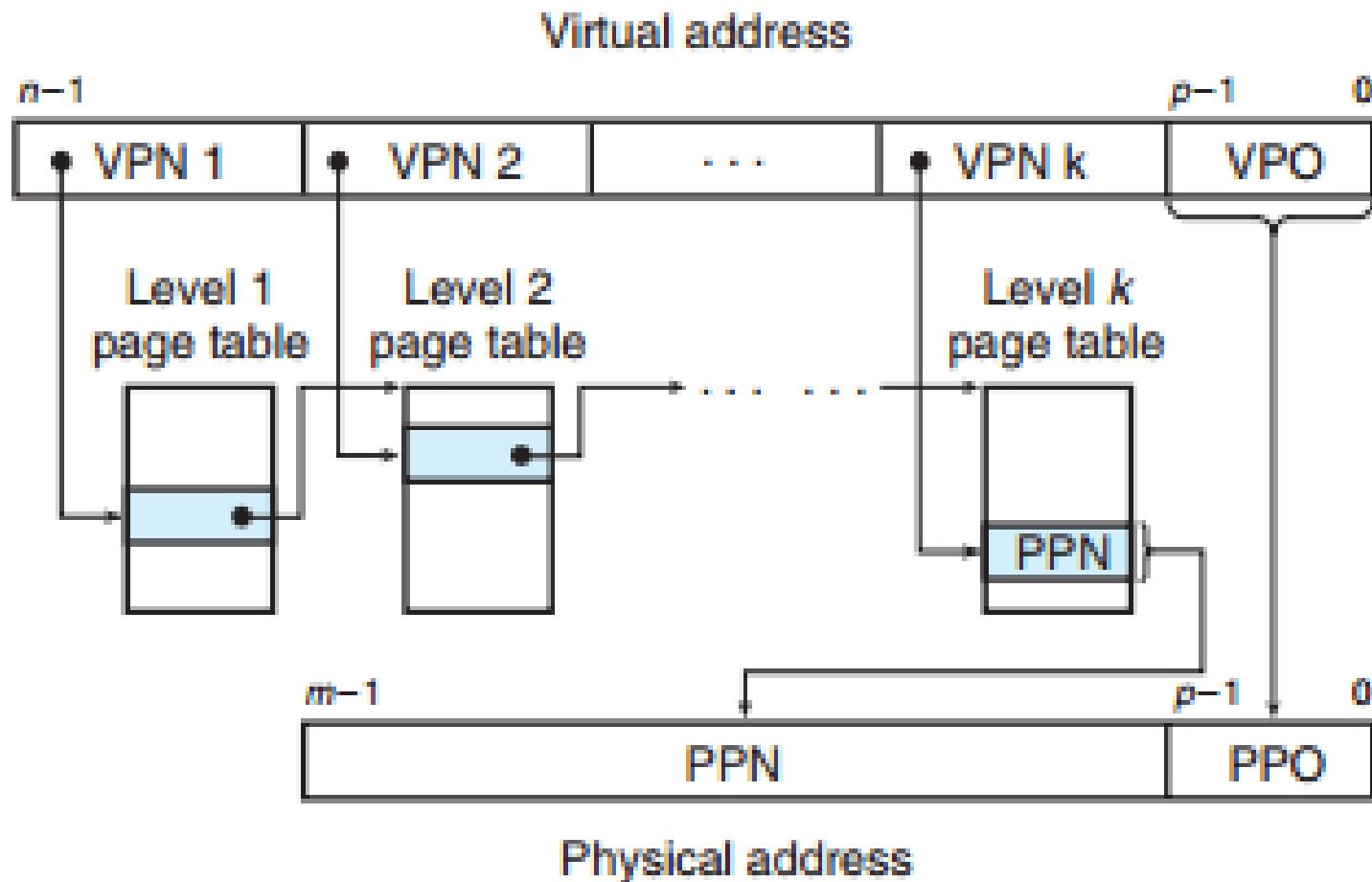
- [ VPN1 ][ VPN2 ][ VPO ]
- This system requires a two-level page table hierarchy.
- As with the traditional case, there is a register that points to the page table except now this register points to the first level page table.
- As before, VPN1 is an index into the L1 Page Table (the use of “L1” here is just a short-hand and not actually a notation that is used).

# Virtual Memory: Hierarchical Page Tables

- Now however, instead of the L1 Page Table containing the physical address that corresponds to virtual address, it contains a physical address to an L2 Page Table.
- VPN2 is used to index into the L2 Page Table. Now, the entry in the L2 Page Table will have the PPN.
- Let's see this in action.

# Virtual Memory: Hierarchical Page Tables

- The sky is the limit.





# Virtual Memory: Hierarchical Page Tables

- Consider the following:
  - 32-bit physical addresses
  - 10-bit virtual addresses (yes, it's a weird example)
  - [ 3-bit VPN1 ][ 2-bit VPN2 ][ 5-bit VPO ]
- L1 Page Table located at address 0x10.
- We are issued the address:
- 010 01 00100
- We consult the L1 Page Table.
- How many entries are in the L1 Page Table?

# Virtual Memory: Hierarchical Page Tables

- Consider this example of an L1 page table.
- Because we index into the L1 page table with a 3-bit value, there are  $2^3 = 8$  entries. Each entry is 4 bytes long because they contain an address to another page table in physical memory.
- $\text{VPN1} = 010 = 2$
- This means we're accessing the entry at address  $0x10$  (base address of table) +  $2(\text{VPN1}) * 4$  (sizeof each table entry)

Addr	Entry
0x10	0x1230
0x14	0x1240
0x18	0x1250
0x1c	0x1260
0x20	0x1270
0x24	0x1280
0x28	0x1290
0x2c	0x12a0

# Virtual Memory: Hierarchical Page Tables

- Thus, the L2 page table is at 0x1250. Now we use the VPN2. Because we index into the L2 page table with 2 bits, there are  $2^2 = 4$  entries.

- VPN2 = 01 = 1

- L2 Page Table:

Addr	Entry
0x1250	-
0x1254	0xAB
0x1258	-
0x125c	0xCD

- The corresponding PPN is 0xAB

# Virtual Memory: Hierarchical Page Tables

- How does this help the problem of page tables taking too much memory?
- In the non-hierarchical case, the 5-bit VPN would result in a  $2^5 = 32$  entry table.
- In this example, the L1 page table had addresses for each of its 8 entries, but perhaps only entry 2 is valid.
- This means, we only need to allocate space for one L2 page table to correspond to entry 2.

# Virtual Memory: Hierarchical Page Tables

- This means in order to store this hierarchy, we only need  $2^3$  entries (1 L1 page table) +  $1 * 2^2$  (1 L2 page table) = 12 entries total, instead 32.
- Note however, if every page table was allocated, we'd need  $2^3 + 8 * 2^2 = 40$  entries.
- This only helps if we're not using up ALL of our page table entries... which is most of the time.
- Also note, the entries of the L1 Page Table will contain different data from the L2 Page table, which may mean different entry sizes.

# Compilation Pipeline

```
cpp code.c code.i // C Preprocessor -> code.i
gcc -S code.i      // Compile C -> code.s
gcc -c code.s      // Assemble code.s -> code.o
gcc code.o         // Link objfile to make executable
```

# Object Files

```
$ gcc -c code.c    // Compile: outputs objfile code.o
```

Aka "Relocatable Object Files".

On unix systems, .o files are in ELF format ("Executable and Linkable Format").

Are binary objects that contain several sections:

header, text, rodata, data, bss, symtable, rel\_text, rel\_data, debug, line, strtab, footer

# Linking

```
gcc code.o          // Link objfile to make executable
```

Generates an executable. Two main steps:

(1) Symbol resolution

(2) Relocation



# Linking and header files (.h)

```
// file1.c
#include <stdio.h>
#include "mything.h"

int main() {
    float r=fn(3, PI_);
    printf("%f\n",r);
    return 0;
}
```

**Question:** How to  
create executable?

```
// mything.h
double PI_;
float fn(int,double);
```

```
// mything.c
double PI_ = 3.1415;
float fn(int x, double y) {
    return x + 2*y;
}
```

**Answer:**

```
$ gcc -c file1.c
$ gcc -c mything.c
$ gcc -o file1 file1.o mything.o
```

# Linking and header files (.h)

```
// file1.c
#include <stdio.h>
#include "mything.h"

int main() {
    float r=fn(3, PI_);
    printf("%f\n",r);
    return 0;
}
```

**Question:** Why did we not have to mention mything.h?

```
// mything.h
double PI_;
float fn(int,double);
```

```
// mything.c
double PI_ = 3.1415;
float fn(int x, double y) {
    return x + 2*y;
}
```

**Answer:** C preprocessor copied body of mything.h into file1.c, ie check out:  
\$ cpp file1.c file1.i

# Static Linking

Specify object file at compilation time. Ex: Here, mything.o is statically linked to file1:

```
$ gcc file1.o mything.o
```

For larger projects:

```
$ gcc -static vlc.o libpng.a libmpg.a libmp4.a  
libmp3.a ...
```

# Static Linking: Pros/Cons

## Pros

- Consistent behavior across systems.
  - Simple!

## Cons

- Larger executable size
- If a library has an update, then we have to re-link the project to include the updated library.
- For common libs, each process has a copy in memory.  
Wasteful!
- Can't share libraries with other processes

# Dynamic Linking

**Static:** Load all libraries into executable during compile time.

**Dynamic:** Load library(s) into executable while loading program!

Has a number of benefits.

# Shared Libraries: .so and .dll

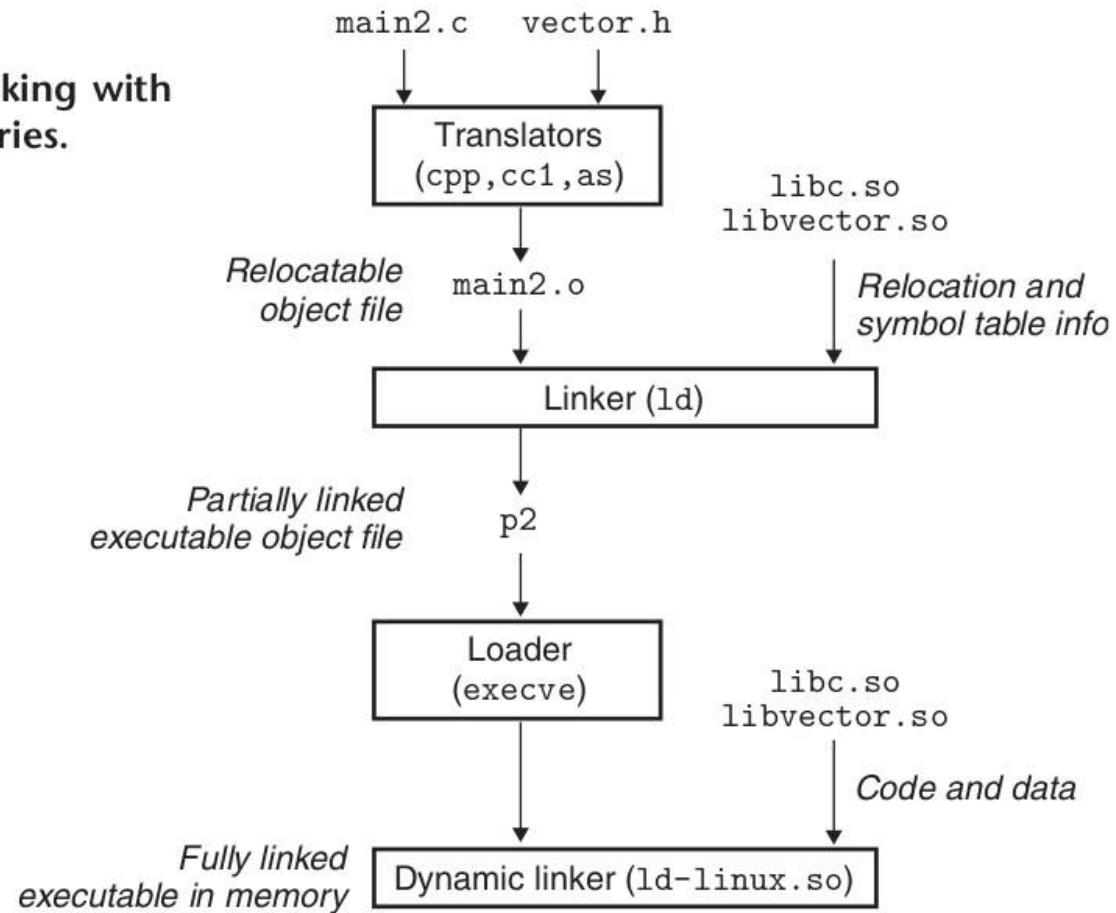
By design, shared (ie dynamic) libraries are loaded during runtime, when OS loads program into memory.

.so: "Shared Object" [unix]

.dll: "Dynamic Link Library" [windows]

(In unix, can create shared libraries with gcc!)

**Figure 7.15**  
**Dynamic linking with**  
**shared libraries.**



# "DLL Hell"

Shared libs are now decoupled from executable.

**Scenario:** I download VLC 2.1.0, which assumed libmpeg2 (v1.1). Then, I upgrade libmpeg2 to v1.2, because 1.2 is much faster and less buggy.

**Problem:** VLC might now be broken!

**DLL Hell!**



# Dynamic Linking: Pros/Cons

## **Pros**

- Smaller executable.

- Processes can share libraries, save memory!

## **Cons**

- Possible instabilities ("DLL Hell")

- More complicated behavior during load time (due to dynlinker).

# Object File (Contents)

(We only consider x86 ELF format)

Contains several sections in binary format.

```
$ gcc -c -o myobjfile.o main.c
```



(relocatable) object file! Not an  
executable yet!

# Object File (Contents)

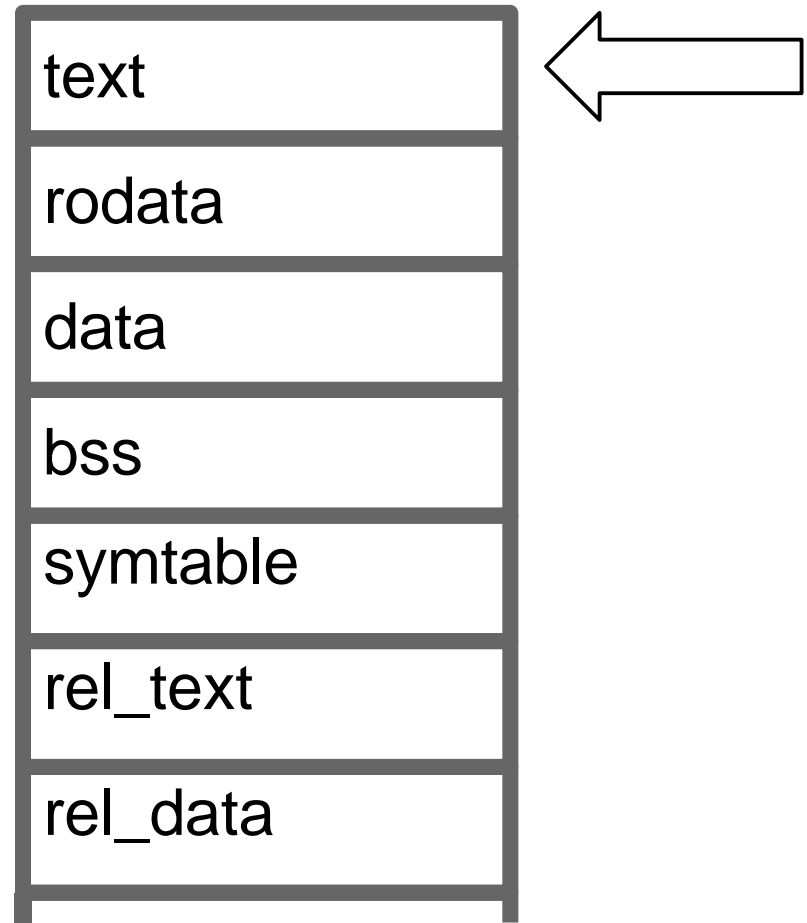
Is actually  
empty!



text
rodata
data
bss
symtable
rel_text
rel_data
debug
line
strtab

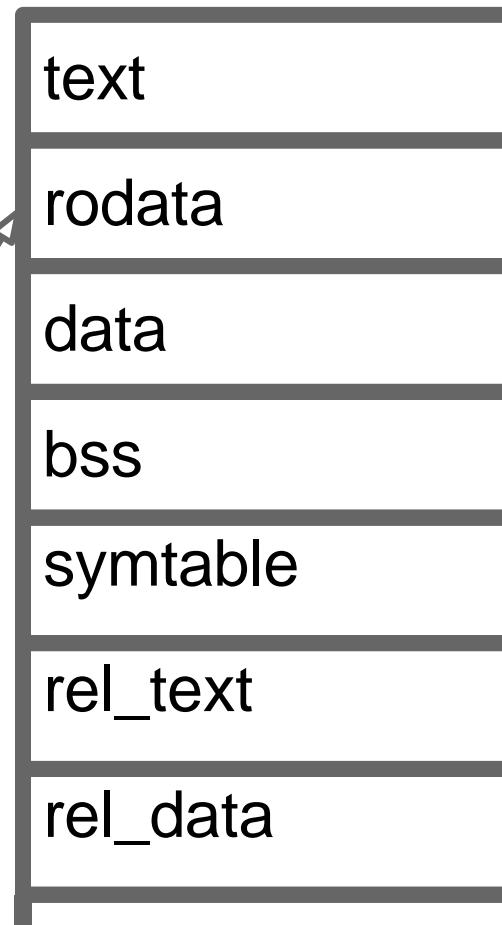
(Not shown: Header and Footer)

text: instructions for \*this\* module, ie any functions defined in this file.



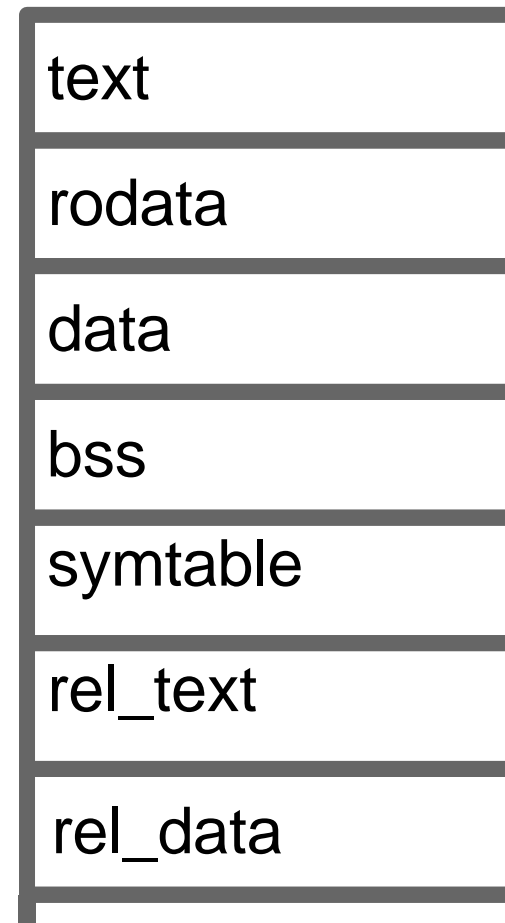
rodata: Read-only data.  
Example: constant strings  
declared in your  
programs.

```
int main() {  
    char* msg = "Hello!\n";  
    printf(msg);  
    return 0;  
}
```



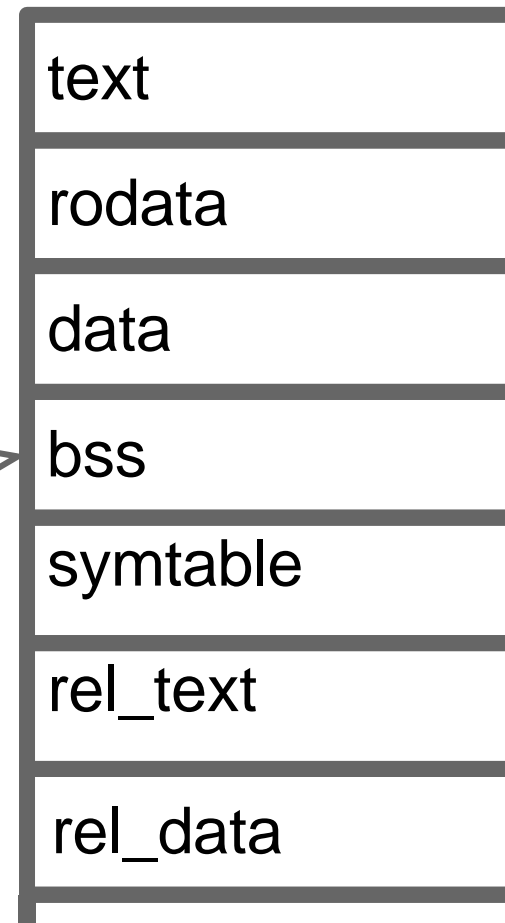
data: Read/write data that is initialized by user.  
Example: static initialized variables (ie file-level).

```
// code.c
int PI_APPROX = 3.1415
int answer;
...
int main() {
    ...
}
```



bss: Read/write data that is uninitialized by user.  
Example: static uninitialized variables.

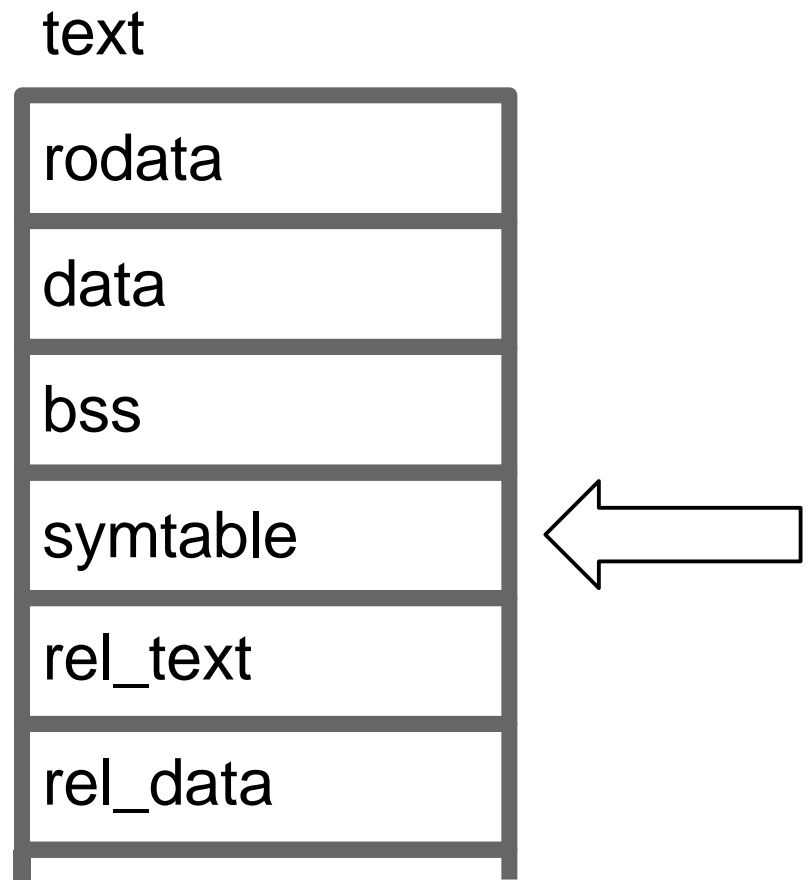
```
// code.c
int PI_APPROX = 3.1415
int answer;
...
int main() {
    ...
}
```



"empty" ←

symtable: Information about  
symbols:

- (1) What symbols I define
- (2) What symbols are undefined





# symtable

```
// file1.c
#include <stdio.h>
extern float PI;
```

```
void main() {
    printf("pi=%f\n",PI);
}
```

```
// file2.c
float PI = 3.1415;
```

**Question:** What do the symtables look like for both file1.o and file2.o?

# symtable

**Ndx:** The section index. # can have diff meaning for different objfiles! 1: text

```
$ readelf -s file1.o
```

```
Symbol table '.symtab' contains 12 entries:
```



Num:	Value	Size	Type	Bind	Vis	Ndx	Name
0:	0000000000000000	0	NOTYPE	LOCAL	DEFAULT	UND	
1:	0000000000000000	0	FILE	LOCAL	DEFAULT	ABS	file1.c
...							
9:	0000000000000000	38	FUNC	GLOBAL	DEFAULT	1	main
10:	0000000000000000	0	NOTYPE	GLOBAL	DEFAULT	UND	PI
11:	0000000000000000	0	NOTYPE	GLOBAL	DEFAULT	UND	printf

# symtable


**Ndx:** The section index.

1: text 2: data 3: bss

```
$ readelf -s file2.o
```

Symbol table '.symtab' contains 8 entries:

Num:	Value	Size	Type	Bind	Vis	Ndx	Name
0:	0000000000000000	0	NOTYPE	LOCAL	DEFAULT	UND	
1:	0000000000000000	0	FILE	LOCAL	DEFAULT	ABS	file2.c
...							
7:	0000000000000000	4	OBJECT	GLOBAL	DEFAULT	2	PI



rel\_text: Locations in .text that must be relocated.

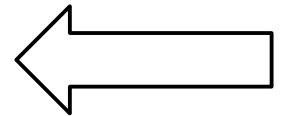
Ex: Any inst that calls an externally-defined function.

data

bss

symtable

rel_text
rel_data
debug
line
strtab



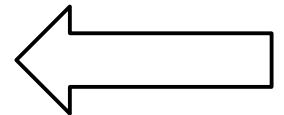
rel\_data: Locations in .data that must be relocated.  
Ex: Any initialized global variable whose initial value is the addr of a global variable or externally-defined function.

data

bss

symtable

rel_text
rel_data
debug
line
strtab



debug: Contains information for debugger.

line: Maps btwn machine code insts and C source code lines.

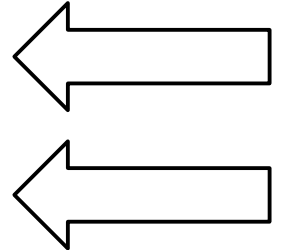
For both debug+line, must use -g compiler option.

data

bss

symtable

rel_text
rel_data
debug
line
strtab



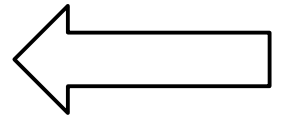
strtab: String table. Contains the human-readable string for each symbol in symtable and debug.

data

bss

symtable

rel_text
rel_data
debug
line
strtab



# Symbol Resolution, Relocation

During compilation, need to know

- (1) What symbols are defined (and where)
- (2) What run-time addresses to assign to each symbol

**Key:** Need to handle multiple files, each referring to each other.



# Quick Example

```
// file1.c
#include <stdio.h>
extern int counter, var;
float PI = 3.1415;
int fn(x){ return x + var; }
int main() {
    printf("%f\n", fn(counter)+PI);
    return 0;
}
```

**Question:** Which symbols are completely resolved during symbol resolution (\$ gcc -c file1.c)? Which symbols are declared as UNDEF?

**Answer:**

Resolved: PI, fn, main.

Undefined: counter, var