

The background of the slide is a dark, blurred image filled with various snippets of code in different colors (blue, green, yellow, red, white). The code appears to be JavaScript or a similar language, with visible keywords like 'function', 'use_array', 'for', 'var', 'return', 'else', and 'length'.

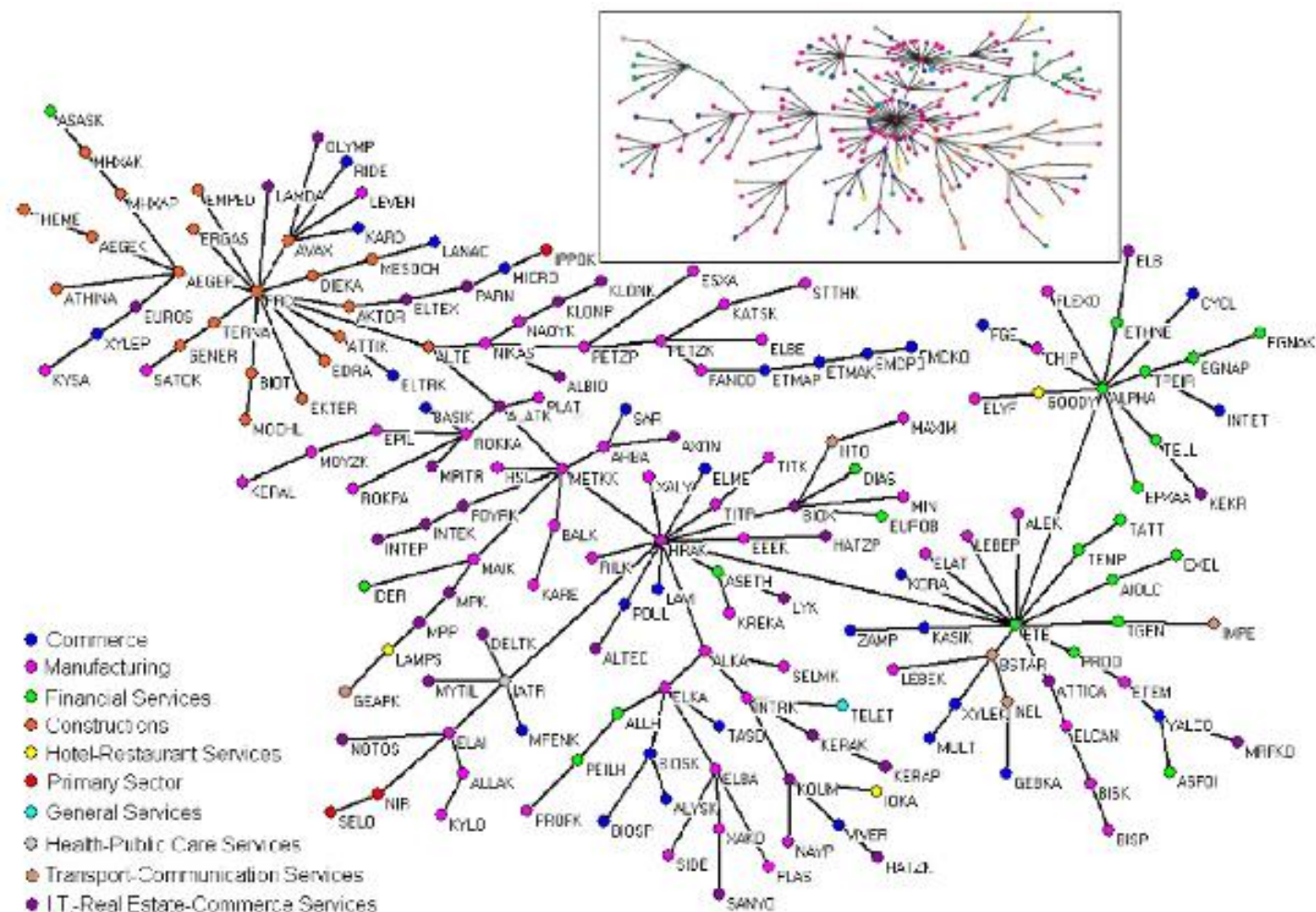
Minimum Spanning Tree

Computer Network Topology

Leonardo Batista - Dezembro 2017

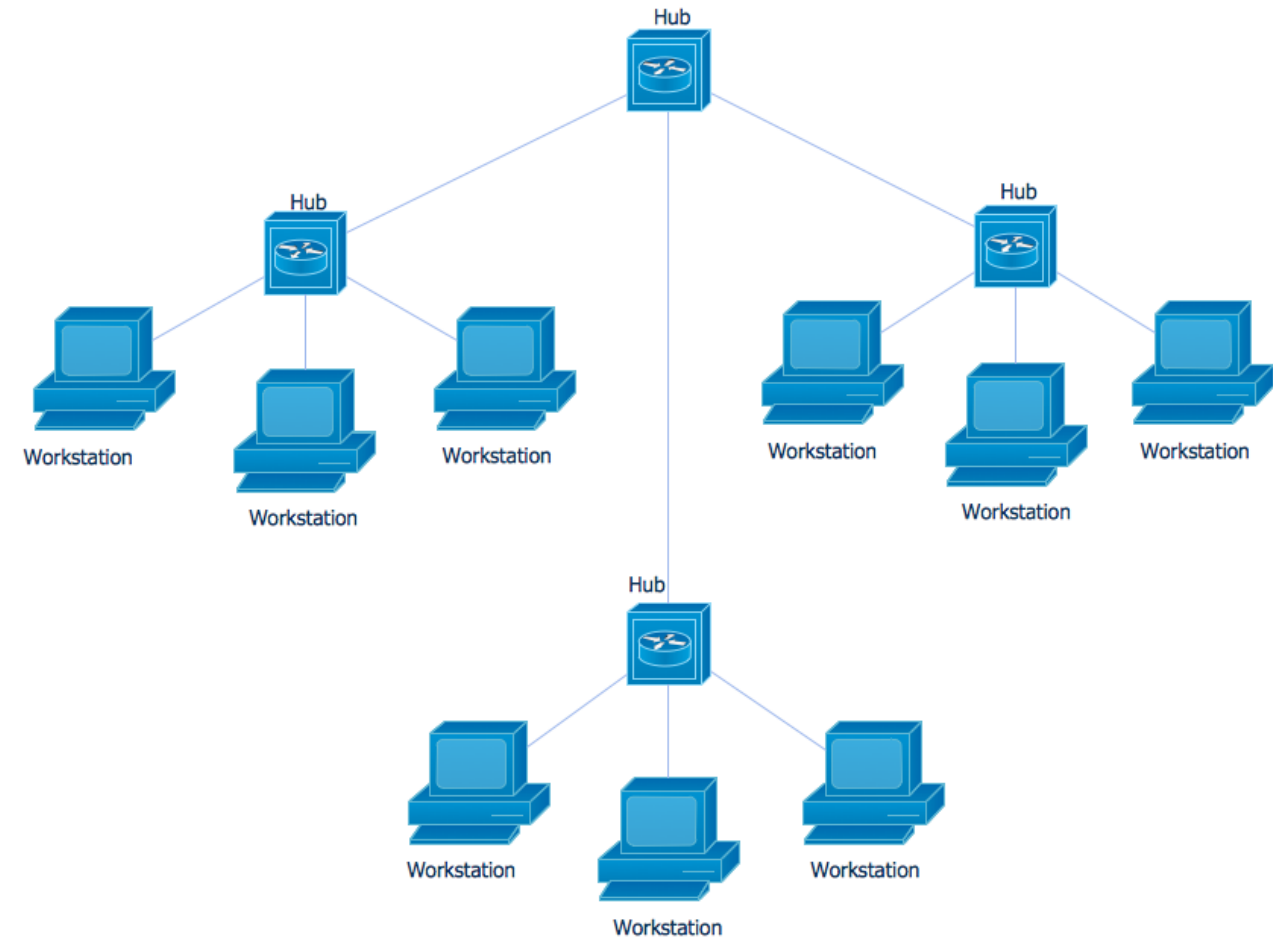
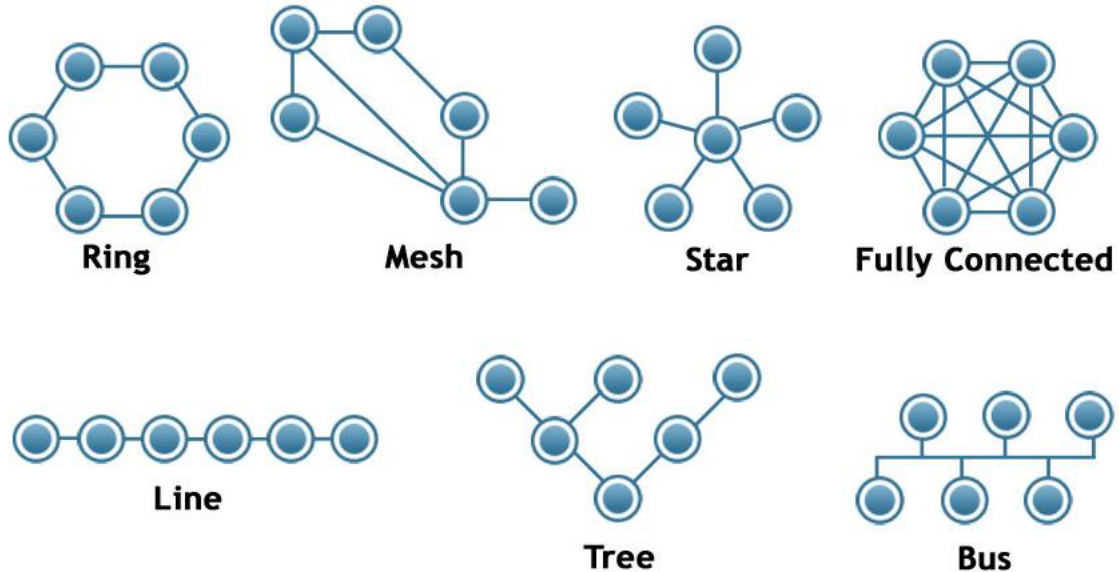
Resumo sobre MST

- Grafo --> Árvore
- $G=\{V,E\} \rightarrow T=\{V,V-1\}$

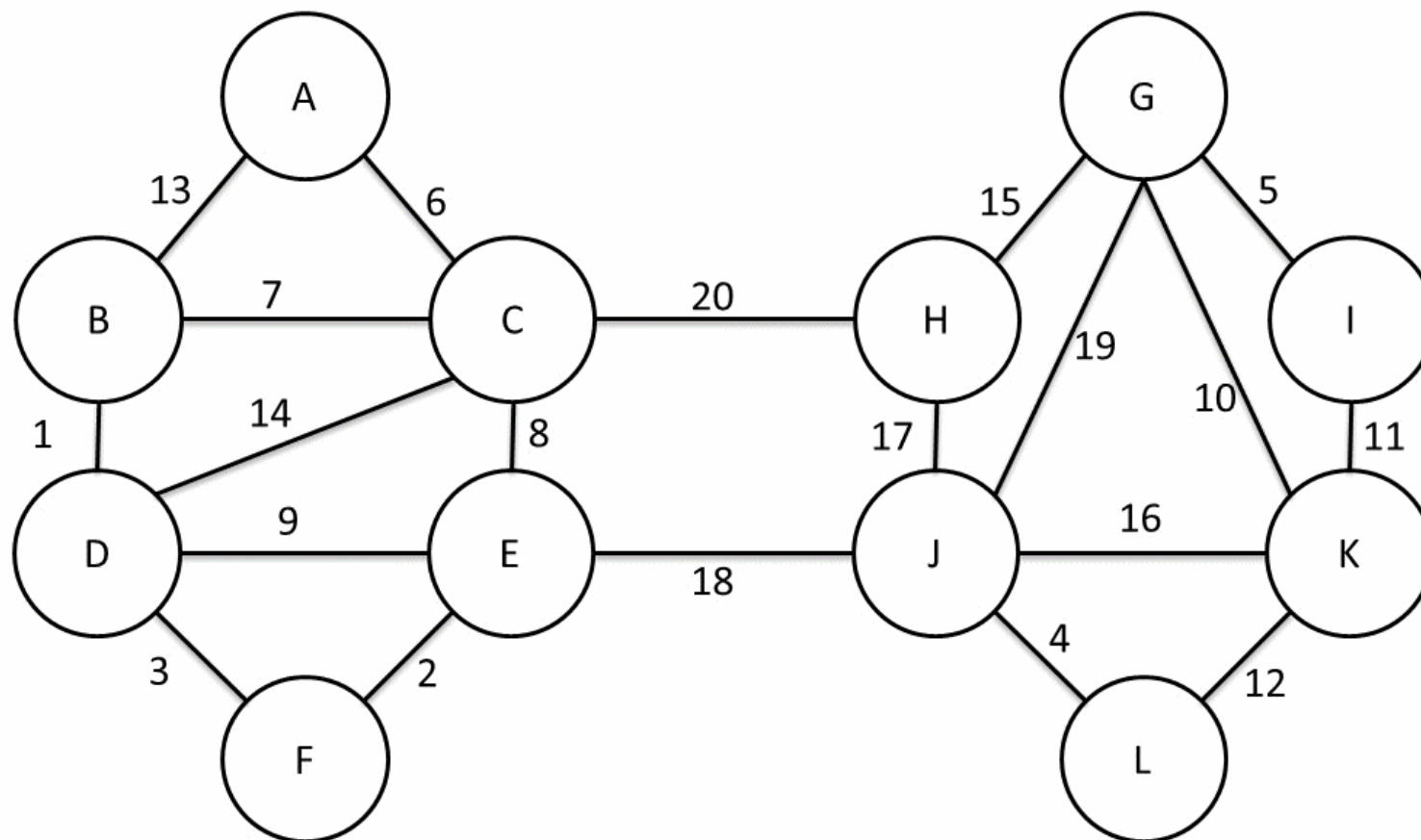


Topologia de Computadores

- *Multiple Spanning Tree Protocol* (IEEE 802.1s)
- IP, MAC, Gateway, Name



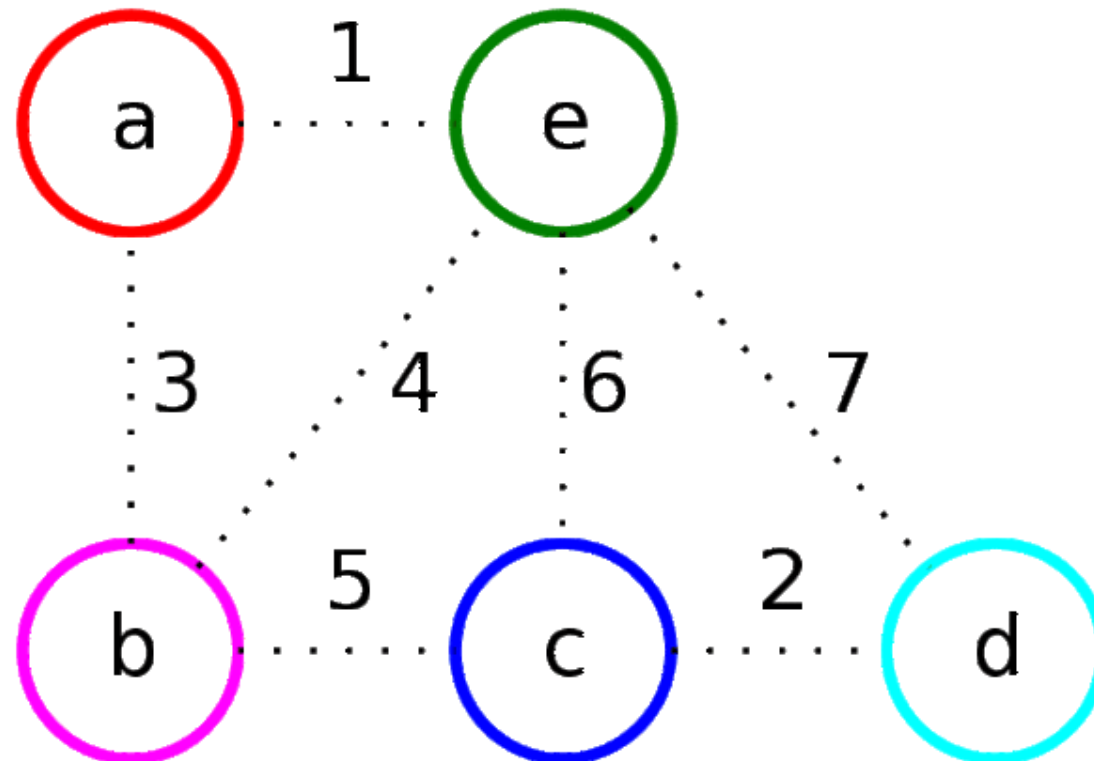
Algoritmo de Borůvka's (1926)



Conceito de Floresta

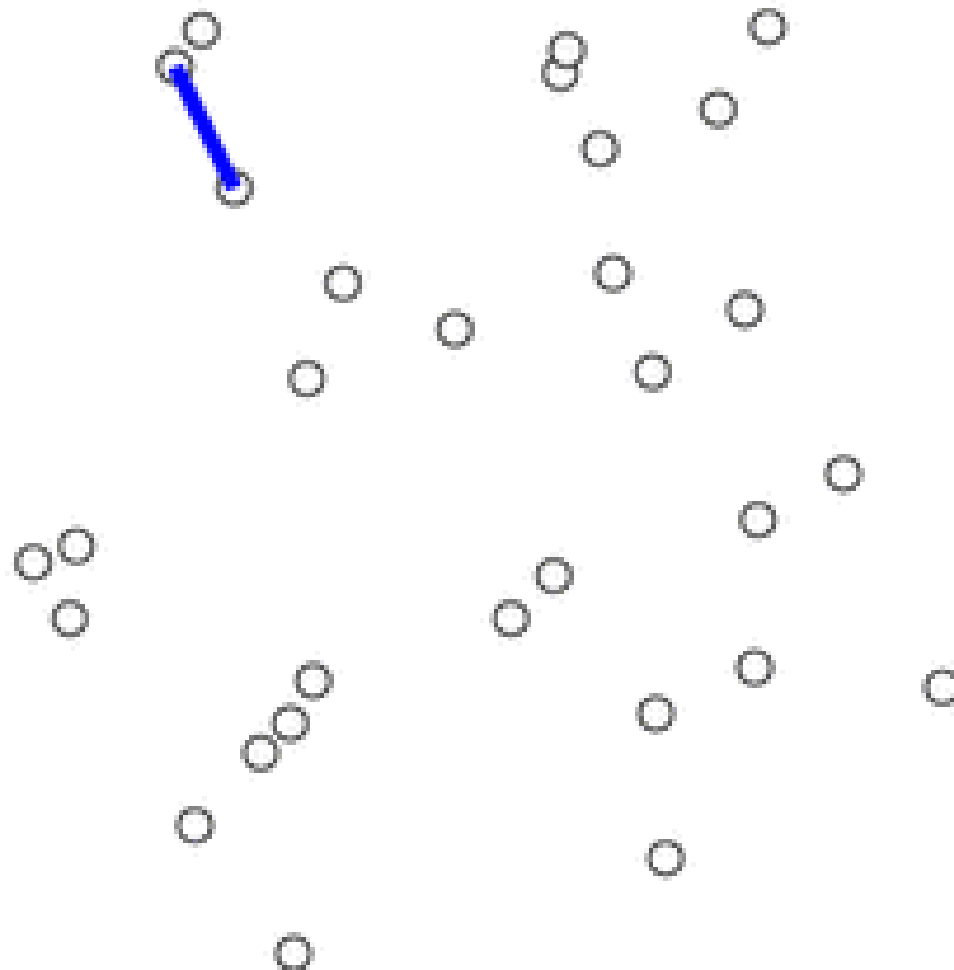
Algoritmo de Kruskal's (1956)

Edge	ab	ae	bc	be	cd	ed	ec
Weight	3	1	5	4	2	7	6



Conceito de menor custo

Algoritmo de Prim's (1957)



Conceito de centralização

```

void prims(grafo_t *g, int v){
    int i, j;
    //aresta_t **matriz_adj;

    if (g == NULL){
        perror("prims");
        exit(EXIT_FAILURE);
    }

    if (v > g->n_vertices){
        perror("prims vertices");
        exit(EXIT_FAILURE);
    }

    int k=0;
    while(k != g->n_vertices-1){
        uint8_t w, id, menor = 0xFF;
        for (i=0; i < g->n_vertices; i++){

            w = g->matriz_adj[v][i].weight;

            #ifdef DEBUG
                printf("v:%d, i:%d\n", v, i);
                printf("Peso: %d; Flag: %d\n", w, g->matriz_adj[v][i].flag);
            #endif // DEBUG

            if ((adjacente(g,v,i)) && (!g->matriz_adj[v][i].flag) && (!g->vertices[i].flag)){ //
                if(w <= menor){// condição de definição do menor
                    menor = w;
                    id = i; // vertice adjacente com o menor peso na aresta
                }
                if (menor == w){
                    /*nothing*/
                }else{
                    //printf("Removido: (%d, %d)\n", v, i);
                    rem_adjacencia(g, v, i); // remove a adjacencia atual por que o peso é maior
                }
            }
        }
    }
}

```

```

        //printf("Removido: (%d, %d)\n", v, i);
        rem_adjacencia(g, v, i); // remove a adjacencia atual por que o
    }
}

g->matriz_adj[v][id].flag = TRUE;
g->matriz_adj[id][v].flag = TRUE;
g->vertices[v].flag = TRUE;
g->vertices[id].flag = TRUE;
v = id; // próximo vertice
k++;
}

for (i=0; i < g->n_vertices; i++){
    for (j=0; j < g->n_vertices; j++){
        g->matriz_adj[i][j].adj = FALSE;
        if(g->matriz_adj[i][j].flag){
            g->matriz_adj[i][j].adj = TRUE;
        }
        //printf("Flag[%d][%d]: %d\n", i, j, g->matriz_adj[i][j].flag);
    }
}

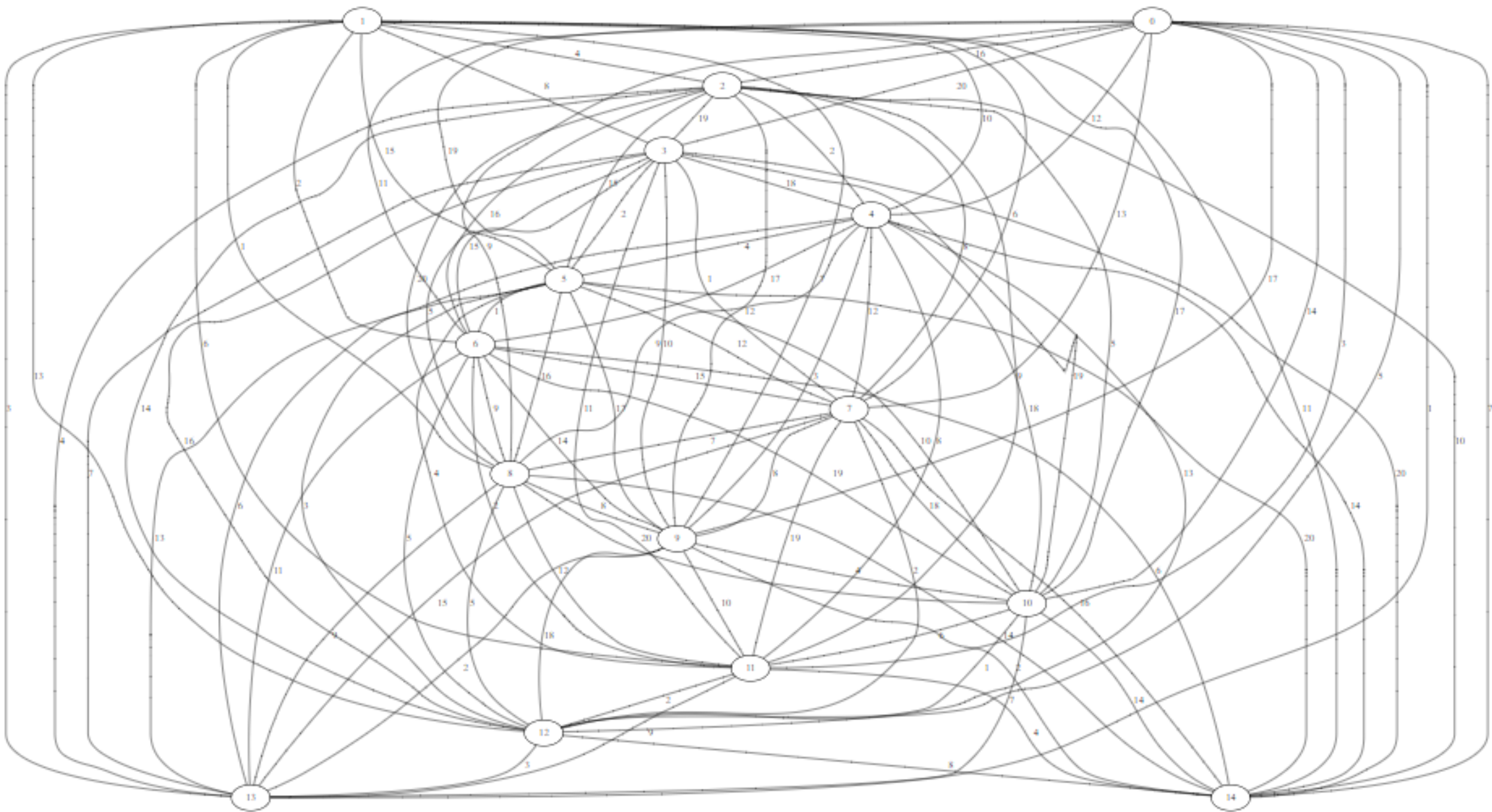
void kruskal(grafo_t *g){
    if (g == NULL){

```

graph {

0 -- 2 [label = 16];	1 -- 12 [label = 13];	3 -- 12 [label = 16];	6 -- 8 [label = 9];	9 -- 13 [label = 2];
0 -- 3 [label = 20];	1 -- 13 [label = 3];	3 -- 13 [label = 7];	6 -- 9 [label = 14];	9 -- 14 [label = 2];
0 -- 4 [label = 12];	1 -- 14 [label = 11];	3 -- 14 [label = 20];	6 -- 10 [label = 19];	10 -- 11 [label = 6];
0 -- 5 [label = 19];	2 -- 3 [label = 19];	4 -- 5 [label = 4];	6 -- 11 [label = 2];	10 -- 12 [label = 1];
0 -- 6 [label = 11];	2 -- 4 [label = 2];	4 -- 6 [label = 17];	6 -- 12 [label = 5];	10 -- 13 [label = 7];
0 -- 7 [label = 13];	2 -- 5 [label = 15];	4 -- 7 [label = 12];	6 -- 13 [label = 11];	10 -- 14 [label = 14];
0 -- 8 [label = 9];	2 -- 6 [label = 16];	4 -- 8 [label = 9];	6 -- 14 [label = 6];	11 -- 12 [label = 2];
0 -- 9 [label = 17];	2 -- 7 [label = 8];	4 -- 9 [label = 3];	7 -- 8 [label = 7];	11 -- 13 [label = 9];
0 -- 10 [label = 14];	2 -- 8 [label = 20];	4 -- 10 [label = 18];	7 -- 9 [label = 8];	11 -- 14 [label = 4];
0 -- 11 [label = 3];	2 -- 9 [label = 12];	4 -- 11 [label = 8];	7 -- 10 [label = 18];	12 -- 13 [label = 3];
0 -- 12 [label = 5];	2 -- 10 [label = 5];	4 -- 12 [label = 13];	7 -- 11 [label = 19];	12 -- 14 [label = 8];
0 -- 13 [label = 1];	2 -- 11 [label = 9];	4 -- 13 [label = 6];	7 -- 12 [label = 2];	}
0 -- 14 [label = 7];	2 -- 12 [label = 14];	4 -- 14 [label = 14];	7 -- 13 [label = 15];	
1 -- 2 [label = 4];	2 -- 13 [label = 4];	5 -- 6 [label = 1];	7 -- 14 [label = 16];	
1 -- 3 [label = 8];	2 -- 14 [label = 10];	5 -- 7 [label = 12];	8 -- 9 [label = 8];	
1 -- 4 [label = 10];	3 -- 4 [label = 18];	5 -- 8 [label = 16];	8 -- 10 [label = 20];	
1 -- 5 [label = 15];	3 -- 5 [label = 2];	5 -- 9 [label = 17];	8 -- 11 [label = 12];	
1 -- 6 [label = 2];	3 -- 6 [label = 15];	5 -- 10 [label = 10];	8 -- 12 [label = 5];	
1 -- 7 [label = 6];	3 -- 7 [label = 1];	5 -- 11 [label = 4];	8 -- 13 [label = 9];	
1 -- 8 [label = 1];	3 -- 8 [label = 5];	5 -- 12 [label = 3];	8 -- 14 [label = 14];	
1 -- 9 [label = 7];	3 -- 9 [label = 10];	5 -- 13 [label = 13];	9 -- 10 [label = 4];	
1 -- 10 [label = 17];	3 -- 10 [label = 19];	5 -- 14 [label = 20];	9 -- 11 [label = 10];	
1 -- 11 [label = 6];	3 -- 11 [label = 11];	6 -- 7 [label = 15];	9 -- 12 [label = 18];	

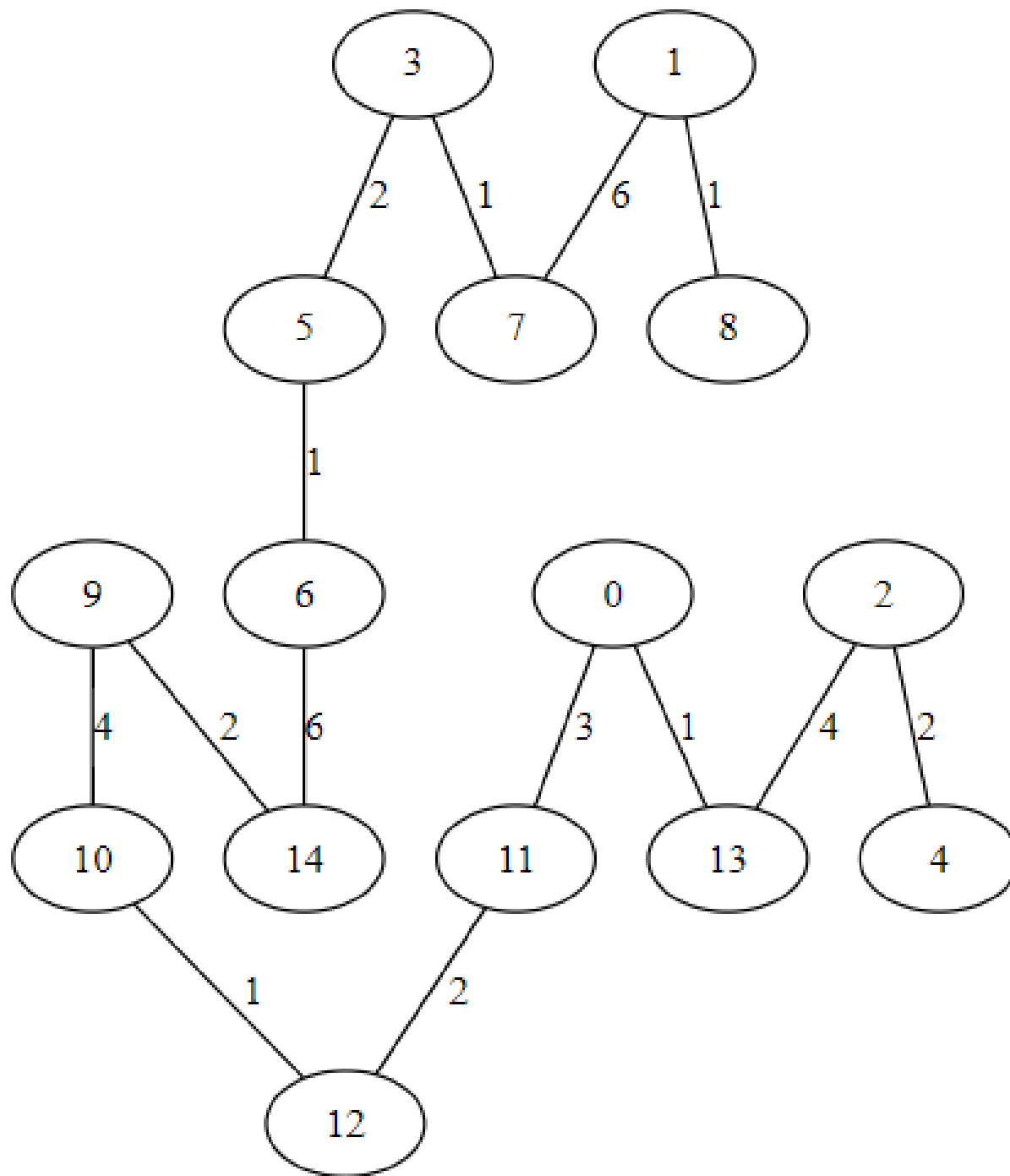
G={15,103}



graph {

```
0 -- 11 [label = 3];
0 -- 13 [label = 1];
1 -- 7 [label = 6];
1 -- 8 [label = 1];
2 -- 4 [label = 2];
2 -- 13 [label = 4];
3 -- 5 [label = 2];
3 -- 7 [label = 1];
5 -- 6 [label = 1];
6 -- 14 [label = 6];
9 -- 10 [label = 4];
9 -- 14 [label = 2];
10 -- 12 [label = 1];
11 -- 12 [label = 2];
```

}



T={15,14}

Complexidade dos Algoritmos

Matrix Adjacência: $O(|V|^2)$

Lista encadeada + árvore binária: $O(|E| \log |V|)$

Referências

<http://www.webgraphviz.com/>

<http://www.geeksforgeeks.org>

<https://en.wikipedia.org>