1. 純黑純白

ret, th = cv2.threshold(img,127,255,cv.THRESH_BINAR

	Value and Threshold Level
	Threshold Binary
	Threshold Binary, Inverted
	Truncate
	Threshold to Zero, Inverted
	Threshold to Zero

2. 腐蝕擴張 (白色部分)

kernel = np.ones((3,3), np.uint8)

erosion = cv2.erode(img, kernel, iterations = 1)

dilation = cv2.dilate(img, kernel, iterations = 1)
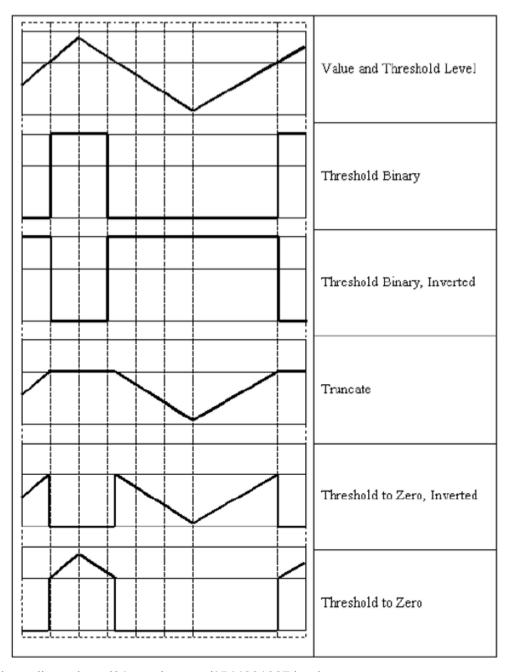
3. 對比樣板

method = 'cv2.TM_CCOEFF_NORMED'

res = cv2.matchTemplate(img, template, method)

4. 對齊影像

MAX_FEATURES=500

orb = cv2.ORB_create(MAX_FEATURES)

keypoints1, descriptors1 = orb.detectAndCompute(img1_gray, None)

keypoints2, descriptors2 = orb.detectAndCompute(im22_gray, None)

	Value and Threshold Level
	Threshold Binary
	Threshold Binary, Inverted
	Truncate
	Threshold to Zero, Inverted
	Threshold to Zero

https://www.itread01.com/content/1544601967.html